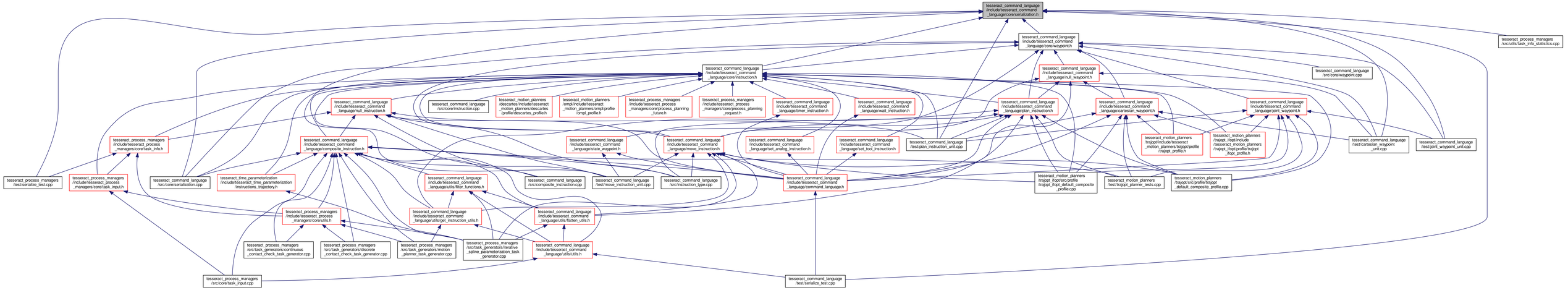
tesseract_command_language /include/tesseract_command _language/core/serialization.h
tesseract_command_language /include/tesseract_command _language/core/waypoint.h
tesseract_process_managers /src/utils/task_info_statistics.cpp
tesseract_command_language /include/tesseract_command _language/core/instruction.h
tesseract_command_language /include/tesseract_command _language/null_waypoint.h
tesseract_command_language /src/core/waypoint.cpp
tesseract_command_language /include/tesseract_command _language/null_instruction.h
tesseract_command_language /src/core/instruction.cpp
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes /profile/descartes_profile.h
tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/profile /ompl_profile.h
tesseract_process_managers /include/tesseract_process _managers/core/process_planning _future.h
tesseract_process_managers /include/tesseract_process _managers/core/process_planning _request.h
tesseract_command_language /include/tesseract_command _language/timer_instruction.h
tesseract_command_language /include/tesseract_command _language/wait_instruction.h
tesseract_command_language /include/tesseract_command _language/plan_instruction.h
tesseract_command_language /include/tesseract_command _language/cartesian_waypoint.h
tesseract_command_language /include/tesseract_command _language/joint_waypoint.h
tesseract_process_managers /include/tesseract_process _managers/core/task_info.h
tesseract_command_language /include/tesseract_command _language/state_waypoint.h
tesseract_command_language /include/tesseract_command _language/move_instruction.h
tesseract_command_language /include/tesseract_command _language/set_analog_instruction.h
tesseract_command_language /include/tesseract_command _language/set_tool_instruction.h
tesseract_command_language /test/plan_instruction_unit.cpp
tesseract_motion_planners /trajopt_ifopt/include /tesseract_motion_planners /trajopt/profile /trajopt_profile.h
tesseract_motion_planners /trajopt_ifopt/include /tesseract_motion_planners /trajopt_ifopt/profile/trajopt _ifopt_profile.h
tesseract_command_language /test/cartesian_waypoint _unit.cpp
tesseract_command_language /test/joint_waypoint_unit.cpp
tesseract_process_managers /test/serialize_test.cpp
tesseract_process_managers /include/tesseract_process _managers/core/task_input.h
tesseract_command_language /src/core/serialization.cpp
tesseract_time_parameterization /include/tesseract_time_parameterization /instructions_trajectory.h
tesseract_command_language /include/tesseract_command _language/utils/filter_functions.h
tesseract_command_language /src/composite_instruction.cpp
tesseract_command_language /test/move_instruction_unit.cpp
tesseract_command_language /src/instruction_type.cpp
tesseract_command_language /include/tesseract_command _language/command_language.h
tesseract_motion_planners /trajopt_ifopt/src/profile /trajopt_ifopt_default_composite _profile.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
tesseract_motion_planners /trajopt/src/profile/trajopt _default_composite_profile.cpp
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tesseract_command_language /include/tesseract_command _language/utils/flatten_utils.h
tesseract_process_managers /src/task_generators/continuous _contact_check_task_generator.cpp
tesseract_process_managers /src/task_generators/discrete _contact_check_task_generator.cpp
tesseract_process_managers /src/task_generators/motion _planner_task_generator.cpp
tesseract_process_managers /src/task_generators/iterative _spline_parameterization_task _generator.cpp
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tesseract_process_managers /src/core/task_input.cpp
tesseract_command_language /test/serialize_test.cpp