

tesseract\_planning  
::MotionPlanner



```
graph BT; OMPL[tesseract_planning::OMPLMotionPlanner] --> MP[tesseract_planning::MotionPlanner];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray box representing the base class, `tesseract_planning::OMPLMotionPlanner`. A blue arrow points upwards from this box to a white box at the top, which represents the derived class, `tesseract_planning::MotionPlanner`. Both boxes have a black border and contain their respective class names in two lines.

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