

tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::FixStateCollisionTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram illustrates an inheritance relationship between two C++ classes. At the bottom is a gray-shaded box representing the base class, `tesseract_planning::FixStateCollisionTaskInfo`. A blue arrow points vertically upwards from this box to a white box at the top, which represents the derived class, `tesseract_planning::TaskInfo`. This indicates that `FixStateCollisionTaskInfo` inherits from `TaskInfo`.

tesseract_planning
::FixStateCollisionTaskInfo