

tesseract\_motion\_planners  
/include/tesseract\_motion  
\_planners/trajopt/trajopt  
\_collision\_config.h

```
graph TD; A["tesseract_motion_planners  
/include/tesseract_motion  
_planners/trajopt/trajopt  
_collision_config.h"] --> B["tesseract_common/macros.h"]; A --> C["trajopt/problem_description.hpp"]; A --> D["tinyxml2.h"]; A --> E["boost/algorithm/string.hpp"]; A --> F["tesseract_common/utils.h"];
```

tesseract\_common/macros.h

trajopt/problem\_description.hpp

tinyxml2.h

boost/algorithm/string.hpp

tesseract\_common/utils.h