

tesseract\_planning  
::TaskGenerator



```
graph BT; A[tesseract_planning::MotionPlannerTaskGenerator] --> B[tesseract_planning::TaskGenerator];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray-shaded box representing the base class, `tesseract_planning::MotionPlannerTaskGenerator`. A blue arrow points vertically upwards from this box to a white box at the top, which represents the derived class, `tesseract_planning::TaskGenerator`. This indicates that `MotionPlannerTaskGenerator` inherits from `TaskGenerator`.

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