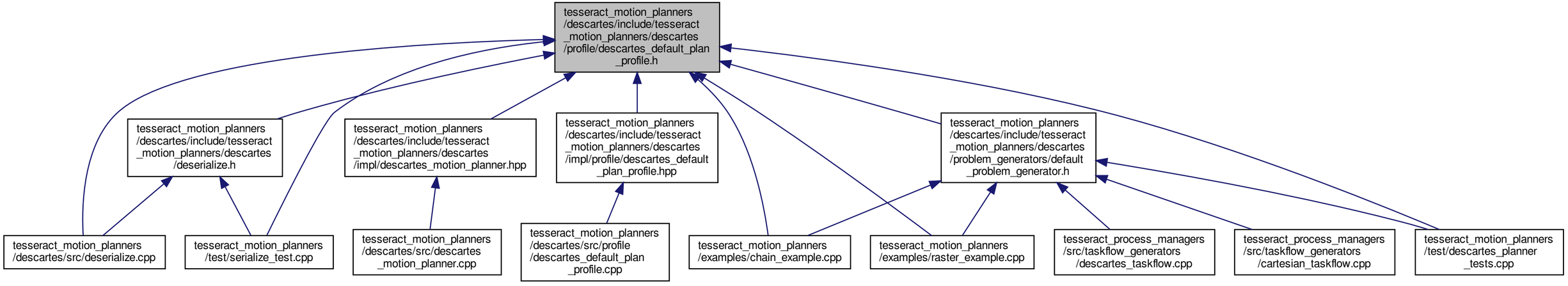
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes /profile/descartes_default_plan _profile.h
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes /deserialize.h
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes /impl/descartes_motion_planner.hpp
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes /impl/profile/descartes_default _plan_profile.hpp
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes /problem_generators/default _problem_generator.h
tesseract_motion_planners /descartes/src/deserialize.cpp
tesseract_motion_planners /test/serialize_test.cpp
tesseract_motion_planners /descartes/src/descartes _motion_planner.cpp
tesseract_motion_planners /descartes/src/profile /descartes_default_plan _profile.cpp
tesseract_motion_planners /examples/chain_example.cpp
tesseract_motion_planners /examples/raster_example.cpp
tesseract_process_managers /src/taskflow_generators /descartes_taskflow.cpp
tesseract_process_managers /src/taskflow_generators /cartesian_taskflow.cpp
tesseract_motion_planners /test/descartes_planner _tests.cpp