

tesseract\_motion\_planners  
/ompl/include/tesseract  
\_motion\_planners/ompl/deserialize.h

```
graph BT; A["tesseract_motion_planners /ompl/src/deserialize.cpp"] --> C["tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/deserialize.h"]; B["tesseract_motion_planners /test/serialize_test.cpp"] --> C;
```

The diagram illustrates a dependency structure. At the top is a grey rectangular box containing the path to a header file: `tesseract_motion_planners /ompl/include/tesseract _motion_planners/ompl/deserialize.h`. Below this box are two white rectangular boxes. The box on the left contains the path to a source file: `tesseract_motion_planners /ompl/src/deserialize.cpp`. The box on the right contains the path to another source file: `tesseract_motion_planners /test/serialize_test.cpp`. Two blue arrows originate from the bottom of these two boxes and point upwards to the bottom edge of the top box, indicating that both source files depend on the header file.

tesseract\_motion\_planners  
/ompl/src/deserialize.cpp

tesseract\_motion\_planners  
/test/serialize\_test.cpp