

tesseract_motion_planners
/trajopt/include/tesseract
_motion_planners/trajopt/deserialize.h

```
graph BT; A["tesseract_motion_planners  
/test/serialize_test.cpp"] --> C["tesseract_motion_planners  
/trajopt/include/tesseract  
_motion_planners/trajopt/deserialize.h"]; B["tesseract_motion_planners  
/trajopt/src/deserialize.cpp"] --> C;
```

The diagram illustrates a dependency relationship in a C++ project. At the top, a gray-shaded box represents the header file `tesseract_motion_planners/trajopt/include/tesseract_motion_planners/trajopt/deserialize.h`. Below it, two white boxes represent source files. The left box, `tesseract_motion_planners/test/serialize_test.cpp`, has a blue arrow pointing up to the header file. The right box, `tesseract_motion_planners/trajopt/src/deserialize.cpp`, also has a blue arrow pointing up to the same header file.

tesseract_motion_planners
/test/serialize_test.cpp

tesseract_motion_planners
/trajopt/src/deserialize.cpp