

tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::DiscreteContactCheckTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram illustrates an inheritance relationship between two classes in the tesseract_planning namespace. A blue arrow points from the base class, tesseract_planning::DiscreteContactCheckTaskInfo, to the derived class, tesseract_planning::TaskInfo.

tesseract_planning
::DiscreteContactCheckTaskInfo