

tesseract\_motion\_planners  
/include/tesseract\_motion  
\_planners/trajopt/profile  
/trajopt\_default\_solver\_profile.h

```
graph BT; A["tesseract_motion_planners  
/src/trajopt/problem_generators  
/default_problem_generator.cpp"] --> C["tesseract_motion_planners  
/include/tesseract_motion_planners/trajopt/profile  
/trajopt_default_solver_profile.h"]; B["tesseract_motion_planners  
/src/trajopt/profile/trajopt  
_default_solver_profile.cpp"] --> C;
```

The diagram illustrates the relationship between two source files and a header file. At the bottom, there are two white boxes with black borders. The left box contains the path 'tesseract\_motion\_planners /src/trajopt/problem\_generators /default\_problem\_generator.cpp'. The right box contains the path 'tesseract\_motion\_planners /src/trajopt/profile/trajopt \_default\_solver\_profile.cpp'. Two blue arrows point from the top of these boxes towards a central gray box at the top. The gray box contains the path 'tesseract\_motion\_planners /include/tesseract\_motion \_planners/trajopt/profile /trajopt\_default\_solver\_profile.h'.

tesseract\_motion\_planners  
/src/trajopt/problem\_generators  
/default\_problem\_generator.cpp

tesseract\_motion\_planners  
/src/trajopt/profile/trajopt  
\_default\_solver\_profile.cpp