

tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::MotionPlannerTaskInfo] --> B[tesseract_planning::TaskInfo];
```

A diagram illustrating a relationship between two classes. At the bottom is a gray rectangular box containing the text 'tesseract_planning' followed by 'MotionPlannerTaskInfo' on the next line. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box above it. The white box contains the text 'tesseract_planning' followed by 'TaskInfo' on the next line. Both boxes have a black border.

tesseract_planning
::MotionPlannerTaskInfo