

tesseract_planning
::TaskGenerator



```
graph BT; A[tesseract_planning::CheckInputTaskGenerator] --> B[tesseract_planning::TaskGenerator];
```

The diagram illustrates an inheritance relationship between two classes in the tesseract_planning namespace. A blue arrow points from the base class, tesseract_planning::CheckInputTaskGenerator, to the derived class, tesseract_planning::TaskGenerator. The base class is represented by a gray box, and the derived class is represented by a white box.

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::CheckInputTaskGenerator