

ompl::base::StateValidity
Checker



```
graph BT; A[tesseract_planning::StateCollisionValidator] --> B[ompl::base::StateValidityChecker];
```

The diagram illustrates an inheritance relationship. A blue arrow points from the bottom box to the top box. The top box is white with a black border and contains the text 'ompl::base::StateValidityChecker'. The bottom box is gray with a black border and contains the text 'tesseract_planning::StateCollisionValidator'.

tesseract_planning
::StateCollisionValidator