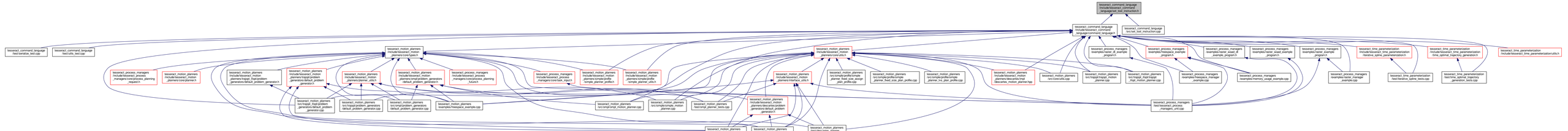
tessract_command_language /include/tessract_command_language/set_tool_instruction.h
tessract_command_language /include/tessract_command_language/command_language.h
tessract_command_language /test/set_tool_instruction.cpp
tessract_command_language /test/utils_test.cpp
tessract_command_language /test/serialize_test.cpp
tessract_motion_planners /include/tessract_motion_planners/core/types.h
tessract_motion_planners /include/tessract_motion_planners/core/utils.h
tessract_process_managers /include/tessract_process_managers/core/process_planning_request.h
tessract_motion_planners /include/tessract_motion_planners/core/planner.h
tessract_motion_planners /include/tessract_motion_planners/trajopt_ifopt/problem_generators/default_problem_generator.h
tessract_motion_planners /include/tessract_motion_planners/trajopt_ifopt/problem_generators/default_problem_generator.h
tessract_motion_planners /include/tessract_motion_planners/trajopt_ifopt/problem_generators/default_problem_generator.cpp
tessract_motion_planners /include/tessract_motion_planners/trajopt_problem_generators/default_problem_generator.h
tessract_motion_planners /include/tessract_motion_planners/trajopt_problem_generators/default_problem_generator.cpp
tessract_motion_planners /include/tessract_motion_planners/simple/problem_generators/default_problem_generator.h
tessract_motion_planners /include/tessract_motion_planners/simple/