

tesseract\_planning  
::TaskGenerator



```
graph BT; A[tesseract_planning::CheckInputTaskGenerator] --> B[tesseract_planning::TaskGenerator];
```

The diagram illustrates an inheritance relationship between two classes in the tesseract\_planning namespace. At the bottom is a gray-shaded box representing the base class, tesseract\_planning::CheckInputTaskGenerator. A blue arrow points vertically upwards from this box to a white box at the top, which represents the derived class, tesseract\_planning::TaskGenerator.

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::CheckInputTaskGenerator