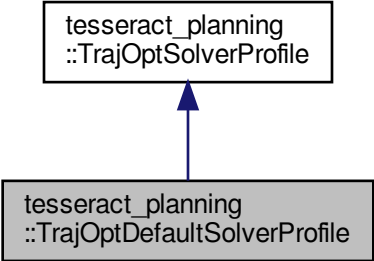


tesseract\_planning  
::TrajOptSolverProfile



```
graph BT; A[tesseract_planning::TrajOptDefaultSolverProfile] --> B[tesseract_planning::TrajOptSolverProfile];
```

tesseract\_planning  
::TrajOptDefaultSolverProfile