

tesseract_planning
::OMPLPlannerConfigurator



```
graph BT; A[tesseract_planning::RRTConfigurator] --> B[tesseract_planning::OMPLPlannerConfigurator];
```

The diagram illustrates an inheritance relationship between two C++ classes. A light gray box at the bottom represents the base class, and a white box at the top represents the derived class. A blue arrow points from the base class to the derived class, indicating that the derived class inherits from the base class.

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