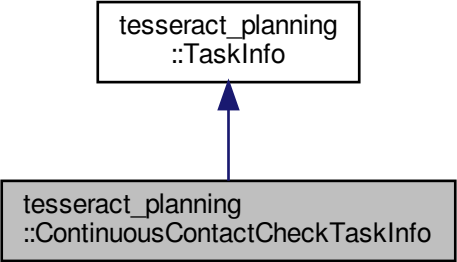


tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::ContinuousContactCheckTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram illustrates an inheritance relationship between two classes in the tesseract_planning namespace. A light gray box at the bottom represents the base class, tesseract_planning::ContinuousContactCheckTaskInfo. A dark gray box at the top represents the derived class, tesseract_planning::TaskInfo. A blue arrow points from the base class box to the derived class box, indicating that ContinuousContactCheckTaskInfo inherits from TaskInfo.

tesseract_planning
::ContinuousContactCheckTaskInfo