

```
tesseract_planning  
::TrajOptPlanProfile
```

```
std::vector< std::tuple  
< sco::VectorOfVector  
::func, sco::MatrixOfVector  
::func, sco::ConstraintType,  
Eigen::VectorXd > >
```

constraint\_error\_functions

```
tesseract_planning  
::TrajOptDefaultPlanProfile
```

