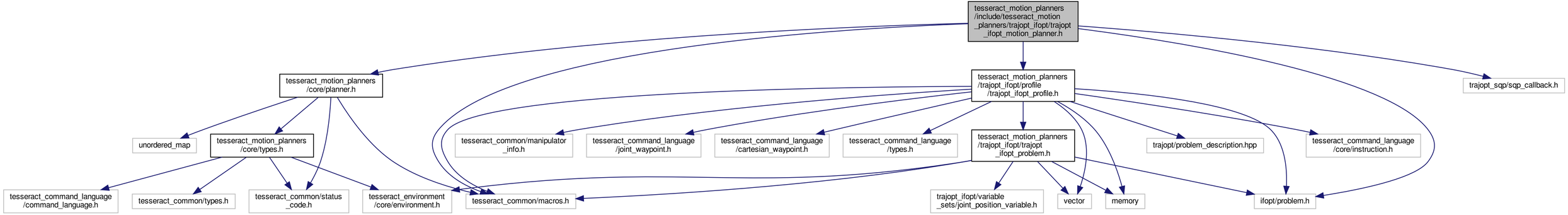
tesseract_motion_planners
/include/tesseract_motion
_planners/trajopt_ifopt/trajopt
_ifopt_motion_planner.h
tesseract_motion_planners
/core/planner.h
tesseract_motion_planners
/trajopt_ifopt/profile
/trajopt_ifopt_profile.h
trajopt_sqp/sqp_callback.h
unordered_map
tesseract_motion_planners
/core/types.h
tesseract_common/manipulator
_info.h
tesseract_command_language
/joint_waypoint.h
tesseract_command_language
/cartesian_waypoint.h
tesseract_command_language
/types.h
tesseract_motion_planners
/trajopt_ifopt/trajopt
_ifopt_problem.h
trajopt/problem_description.hpp
tesseract_command_language
/core/instruction.h
tesseract_command_language
/command_language.h
tesseract_common/types.h
tesseract_common/status
_code.h
tesseract_environment
/core/environment.h
tesseract_common/macros.h
trajopt_ifopt/variable
_sets/joint_position_variable.h
vector
memory
ifopt/problem.h