

tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::MotionPlannerTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'tesseract_planning' followed by '::TaskInfo' on the next line. The bottom box is gray with a black border and contains the text 'tesseract_planning' followed by '::MotionPlannerTaskInfo' on the next line. A blue arrow points vertically from the top of the bottom box to the bottom of the top box, indicating an inheritance or specialization relationship.

tesseract_planning
::MotionPlannerTaskInfo