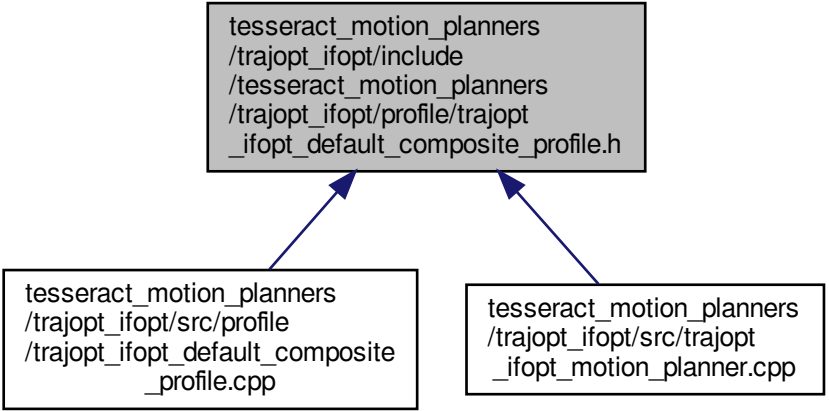


tesseract_motion_planners
/trajopt_ifopt/include
/tesseract_motion_planners
/trajopt_ifopt/profile/trajopt
_ifopt_default_composite_profile.h



```
graph BT; A["tesseract_motion_planners<br>/trajopt_ifopt/src/profile<br>/trajopt_ifopt_default_composite<br>_profile.cpp"] --> C["tesseract_motion_planners<br>/trajopt_ifopt/include<br>/tesseract_motion_planners<br>/trajopt_ifopt/profile/trajopt<br>_ifopt_default_composite_profile.h"]; B["tesseract_motion_planners<br>/trajopt_ifopt/src/trajopt<br>_ifopt_motion_planner.cpp"] --> C;
```

tesseract_motion_planners
/trajopt_ifopt/src/profile
/trajopt_ifopt_default_composite
_profile.cpp

tesseract_motion_planners
/trajopt_ifopt/src/trajopt
_ifopt_motion_planner.cpp