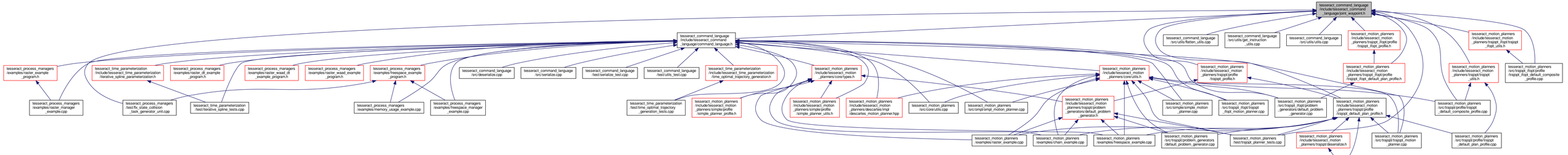
tesseract_command_language /include/tesseract_command_language/joint_waypoint.h
tesseract_command_language /include/tesseract_command_language/command_language.h
tesseract_command_language /src/utils/flatten_utils.cpp
tesseract_command_language /src/utils/get_instruction_utils.cpp
tesseract_command_language /src/utils/utils.cpp
tesseract_motion_planners /include/tesseract_motion_planners/trajopt_ifopt/profile/trajopt_ifopt_profile.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_utils.h
tesseract_process_managers /examples/raster_example_program.h
tesseract_time_parameterization /include/tesseract_time_parameterization/iterative_spline_parameterization.h
tesseract_process_managers /examples/raster_dt_example_program.h
tesseract_process_managers /examples/raster_waad_dt_example_program.h
tesseract_process_managers /examples/raster_waad_example_program.h
tesseract_process_managers /examples/freespace_example_program.h
tesseract_command_language /src/deserialize.cpp
tesseract_command_language /src/serialize.cpp
tesseract_command_language /test/serialize_test.cpp
tesseract_command_language /test/utils_test.cpp
tesseract_time_parameterization /include/tesseract_time_parameterization/time_optimal_trajectory_generation.h
tesseract_motion_planners /include/tesseract_motion_planners/core/types.h
tesseract_motion_planners /include/tesseract_motion_planners/core/utils.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt/profile/trajopt_profile.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt_ifopt/profile/trajopt_ifopt_profile.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_utils.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_default_composite_profile.cpp
tesseract_motion_planners /include/tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_default_plan_profile.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt_ifopt/trajopt_ifopt_utils.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt/profile/trajopt_profile.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt/trajopt_utils.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt/problem_generators/default_problem_generator.h
tesseract_motion_planners /include/tesseract_motion_planners/trajopt/problem_generators/descartes_motion_planner.hpp
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tesseract_motion_planners /include/tesseract_motion_planners/trajopt/problem_generators/simple/simple_motion_planner.h
tesseract_motion_planners /src/core/utils.cpp
tesseract_motion_planners /src/ompl/ompl_motion_planner.cpp
tesseract_motion_planners /src/simple/simple_motion_planner.cpp
tesseract_motion_planners /src/trajopt_ifopt/trajopt_ifopt_motion_planner.cpp
tesseract_motion_planners /src/trajopt_ifopt/problem_generators/default_problem_generator.cpp
tesseract_motion_planners /src/trajopt/profile/trajopt/trajopt_default_plan_profile.h
tesseract_motion_planners /src/trajopt/profile/trajopt/trajopt_default_composite_profile.cpp
tesseract_process_managers /examples/raster_manager_example.cpp
tesseract_process_managers /test/fix_state_collision_task_generator_unit.cpp
tesseract_time_parameterization /test/iterative_spline_tests.cpp
tesseract_process_managers /examples/memory_usage_example.cpp
tesseract_process_managers /examples/freespace_manager_example.cpp
tesseract_time_parameterization /test/time_optimal_trajectory_generation_tests.cpp
tesseract_motion_planners /include/tesseract_motion_planners/simple/profile/simple_planner_profile.h
tesseract_motion_planners /examples/raster_example.cpp
tesseract_motion_planners /examples/chain_example.cpp
tesseract_motion_planners /examples/freespace_example.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
tesseract_motion_planners /include/tesseract_motion_planners/trajopt/deserialize.h
tesseract_motion_planners /src/trajopt/trajopt_motion_planner.cpp
tesseract_motion_planners /test/serialize_test.cpp