

tesseract\_planning  
::MotionPlanner



```
classDiagram
    class tesseract_planning_MotionPlanner["tesseract_planning::MotionPlanner"]
    class tesseract_planning_OMPLMotionPlanner["tesseract_planning::OMPLMotionPlanner"]
    tesseract_planning_OMPLMotionPlanner --|> tesseract_planning_MotionPlanner
```

The diagram illustrates a class hierarchy. At the top is a white box representing the base class 'tesseract\_planning::MotionPlanner'. Below it is a grey box representing the derived class 'tesseract\_planning::OMPLMotionPlanner'. A blue arrow points from the top of the grey box to the bottom of the white box, indicating that 'tesseract\_planning::OMPLMotionPlanner' inherits from 'tesseract\_planning::MotionPlanner'.

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::OMPLMotionPlanner