```
tesseract_motion_planners
/trajopt ifopt/include
/tesseract motion planners
/trajopt ifopt/profile/trajopt
 ifopt default composite profile.h
```

tesseract motion planners /trajopt ifopt/src/problem generators/default problem generator.cpp

tesseract motion planners

profile.cpp

/trajopt ifopt/src/profile

tesseract motion planners /trajopt ifopt/src/trajopt /trajopt ifopt default composite ifopt motion planner.cpp