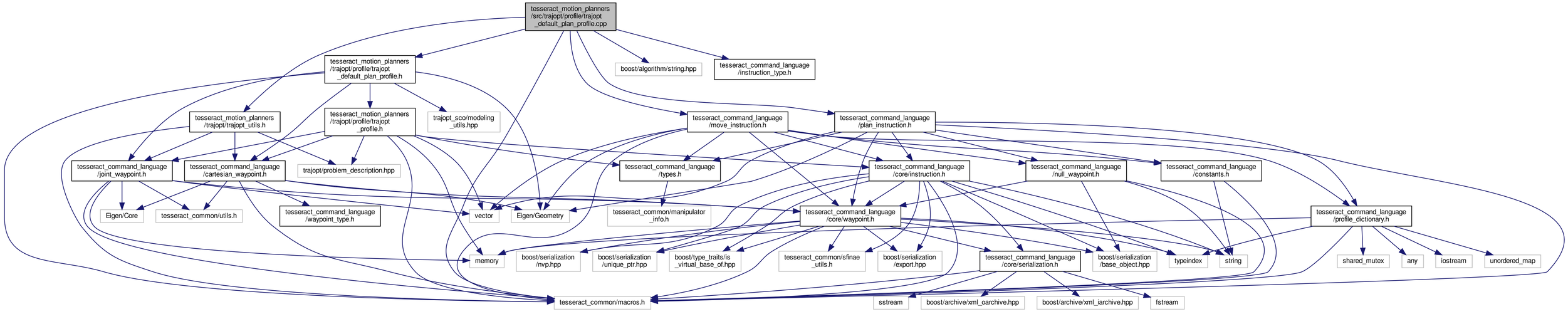
tesseract_motion_planners /src/trajopt/profile/trajopt _default_plan_profile.cpp
tesseract_motion_planners /trajopt/profile/trajopt _default_plan_profile.h
boost/algorithm/string.hpp
tesseract_command_language /instruction_type.h
tesseract_motion_planners /trajopt/trajopt_utils.h
tesseract_motion_planners /trajopt/profile/trajopt _profile.h
trajopt_sco/modeling _utils.hpp
tesseract_command_language /move_instruction.h
tesseract_command_language /plan_instruction.h
tesseract_command_language /joint_waypoint.h
tesseract_command_language /cartesian_waypoint.h
trajopt/problem_description.hpp
tesseract_command_language /types.h
tesseract_command_language /core/instruction.h
tesseract_command_language /null_waypoint.h
tesseract_command_language /constants.h
Eigen/Core
tesseract_common/utils.h
tesseract_command_language /waypoint_type.h
vector
Eigen/Geometry
tesseract_common/manipulator _info.h
tesseract_command_language /core/waypoint.h
tesseract_command_language /profile_dictionary.h
memory
boost/serialization /nvp.hpp
boost/serialization /unique_ptr.hpp
boost/type_traits/is _virtual_base_of.hpp
tesseract_common/sfinae _utils.h
boost/serialization /export.hpp
tesseract_command_language /core/serialization.h
boost/serialization /base_object.hpp
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string
shared_mutex
any
iostream
unordered_map
tesseract_common/macros.h
sstream
boost/archive/xml_oarchive.hpp
boost/archive/xml_iarchive.hpp
fstream