

tesseract\_planning  
::TaskGenerator



```
graph BT; A[tesseract_planning::FixStateBoundsTaskGenerator] --> B[tesseract_planning::TaskGenerator];
```

The diagram illustrates an inheritance relationship. A light gray box at the bottom represents the base class, `tesseract_planning::FixStateBoundsTaskGenerator`. A dark blue arrow points vertically upwards from this box to a white box at the top, which represents the derived class, `tesseract_planning::TaskGenerator`. Both boxes have a black border.

tesseract\_planning  
::FixStateBoundsTaskGenerator