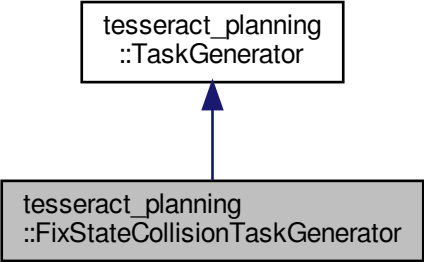


tesseract_planning
::TaskGenerator



tesseract_planning
::FixStateCollisionTaskGenerator