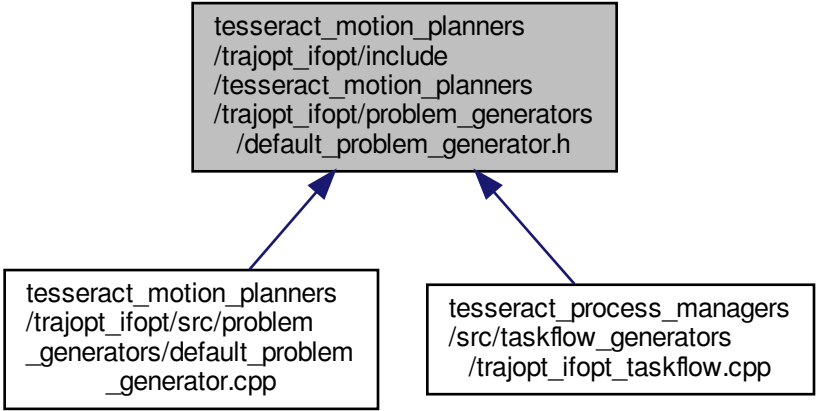


tesseract_motion_planners
/trajopt_ifopt/include
/tesseract_motion_planners
/trajopt_ifopt/problem_generators
/default_problem_generator.h



```
graph BT; A["tesseract_motion_planners<br>/trajopt_ifopt/src/problem<br>_generators/default_problem<br>_generator.cpp"] --> C["tesseract_motion_planners<br>/trajopt_ifopt/include<br>/tesseract_motion_planners<br>/trajopt_ifopt/problem_generators<br>/default_problem_generator.h"]; B["tesseract_process_managers<br>/src/taskflow_generators<br>/trajopt_ifopt_taskflow.cpp"] --> C;
```

tesseract_motion_planners
/trajopt_ifopt/src/problem
_generators/default_problem
_generator.cpp

tesseract_process_managers
/src/taskflow_generators
/trajopt_ifopt_taskflow.cpp