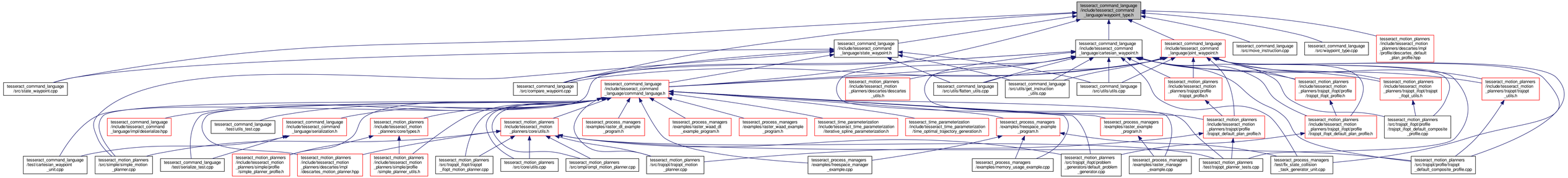
tesseract_command_language /include/tesseract_command _language/waypoint_type.h
tesseract_command_language /include/tesseract_command _language/state_waypoint.h
tesseract_command_language /include/tesseract_command _language/cartesian_waypoint.h
tesseract_command_language /include/tesseract_command _language/joint_waypoint.h
tesseract_command_language /src/move_instruction.cpp
tesseract_command_language /src/waypoint_type.cpp
tesseract_motion_planners /include/tesseract_motion _planners/descartes/impl /profile/descartes_default _plan_profile.hpp
tesseract_command_language /src/state_waypoint.cpp
tesseract_command_language /src/compare_waypoint.cpp
tesseract_command_language /include/tesseract_command _language/command_language.h
tesseract_motion_planners /include/tesseract_motion _planners/descartes/descartes _utils.h
tesseract_command_language /src/utils/flatten_utils.cpp
tesseract_command_language /src/utils/get_instruction _utils.cpp
tesseract_command_language /src/utils/utils.cpp
tesseract_motion_planners /include/tesseract_motion _planners/trajopt/profile /trajopt_profile.h
tesseract_motion_planners /include/tesseract_motion _planners/trajopt_ifopt/profile /trajopt_ifopt_profile.h
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tesseract_command_language /include/tesseract_command _language/impl/deserialize.hpp
tesseract_command_language /test/utils_test.cpp
tesseract_command_language /include/tesseract_command _language/serialization.h
tesseract_motion_planners /include/tesseract_motion _planners/core/types.h
tesseract_motion_planners /include/tesseract_motion _planners/core/utils.h
tesseract_process_managers /examples/raster_dt_example _program.h
tesseract_process_managers /examples/raster_waad_dt _example_program.h
tesseract_process_managers /examples/raster_waad_example _program.h
tesseract_time_parameterization /include/tesseract_time_parameterization /iterative_spline_parameterization.h
tesseract_time_parameterization /include/tesseract_time_parameterization /time_optimal_trajectory_generation.h
tesseract_process_managers /examples/freespace_example _program.h
tesseract_process_managers /examples/raster_example _program.h
tesseract_motion_planners /include/tesseract_motion _planners/trajopt/profile /trajopt_default_plan_profile.h
tesseract_motion_planners /include/tesseract_motion _planners/trajopt_ifopt/profile /trajopt_ifopt_default_plan_profile.h
tesseract_motion_planners /src/trajopt_ifopt/profile /trajopt_ifopt_default_composite _profile.cpp
tesseract_command_language /test/cartesian_waypoint _unit.cpp
tesseract_motion_planners /src/simple/simple_motion _planner.cpp
tesseract_command_language /test/serialize_test.cpp
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tesseract_motion_planners /include/tesseract_motion _planners/descartes/impl /descartes_motion_planner.hpp
tesseract_motion_planners /include/tesseract_motion _planners/simple/profile /simple_planner_utils.h
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tesseract_process_managers /examples/memory_usage_example.cpp
tesseract_motion_planners /src/trajopt_ifopt/problem _generators/default_problem _generator.cpp
tesseract_process_managers /examples/raster_manager _example.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
tesseract_process_managers /test/fk_state_collision _task_generator_unit.cpp
tesseract_motion_planners /src/trajopt/profile/trajopt _default_composite_profile.cpp