

tesseract_planning
::TaskGenerator



```
graph BT; A[tesseract_planning::MotionPlannerTaskGenerator] --> B[tesseract_planning::TaskGenerator];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray rectangular box containing the text 'tesseract_planning' followed by 'MotionPlannerTaskGenerator' on the next line. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box above it. The white box contains the text 'tesseract_planning' followed by 'TaskGenerator' on the next line. Both boxes have a thin black border.

tesseract_planning
::MotionPlannerTaskGenerator