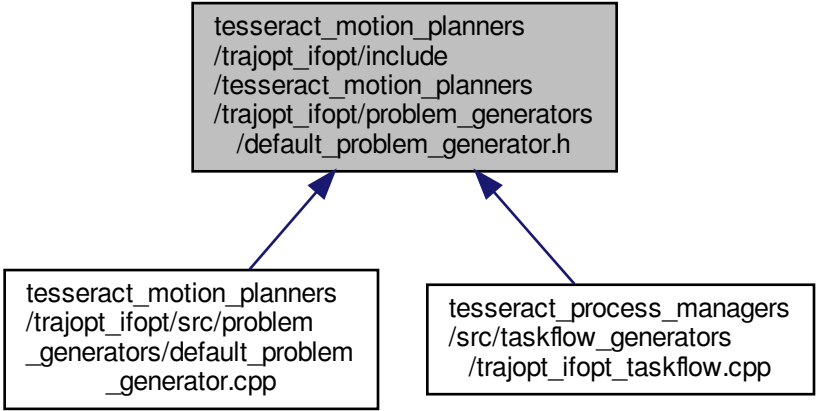


tesseract\_motion\_planners  
/trajopt\_ifopt/include  
/tesseract\_motion\_planners  
/trajopt\_ifopt/problem\_generators  
/default\_problem\_generator.h



```
graph BT; A["tesseract_motion_planners<br>/trajopt_ifopt/src/problem<br>_generators/default_problem<br>_generator.cpp"] --> C["tesseract_motion_planners<br>/trajopt_ifopt/include<br>/tesseract_motion_planners<br>/trajopt_ifopt/problem_generators<br>/default_problem_generator.h"]; B["tesseract_process_managers<br>/src/taskflow_generators<br>/trajopt_ifopt_taskflow.cpp"] --> C;
```

tesseract\_motion\_planners  
/trajopt\_ifopt/src/problem  
\_generators/default\_problem  
\_generator.cpp

tesseract\_process\_managers  
/src/taskflow\_generators  
/trajopt\_ifopt\_taskflow.cpp