

tesseract_motion_planners
/trajopt_ifopt/include
/tesseract_motion_planners
/trajopt_ifopt/trajopt_ifopt
_motion_planner.h

```
graph BT; A["tesseract_motion_planners  
/trajopt_ifopt/src/trajopt_ifopt_motion_planner.cpp"] --> C["tesseract_motion_planners  
/trajopt_ifopt/include  
/tesseract_motion_planners  
/trajopt_ifopt/trajopt_ifopt  
_motion_planner.h"]; B["tesseract_process_managers  
/src/taskflow_generators  
/trajopt_ifopt_taskflow.cpp"] --> C;
```

tesseract_motion_planners
/trajopt_ifopt/src/trajopt
_ifopt_motion_planner.cpp

tesseract_process_managers
/src/taskflow_generators
/trajopt_ifopt_taskflow.cpp