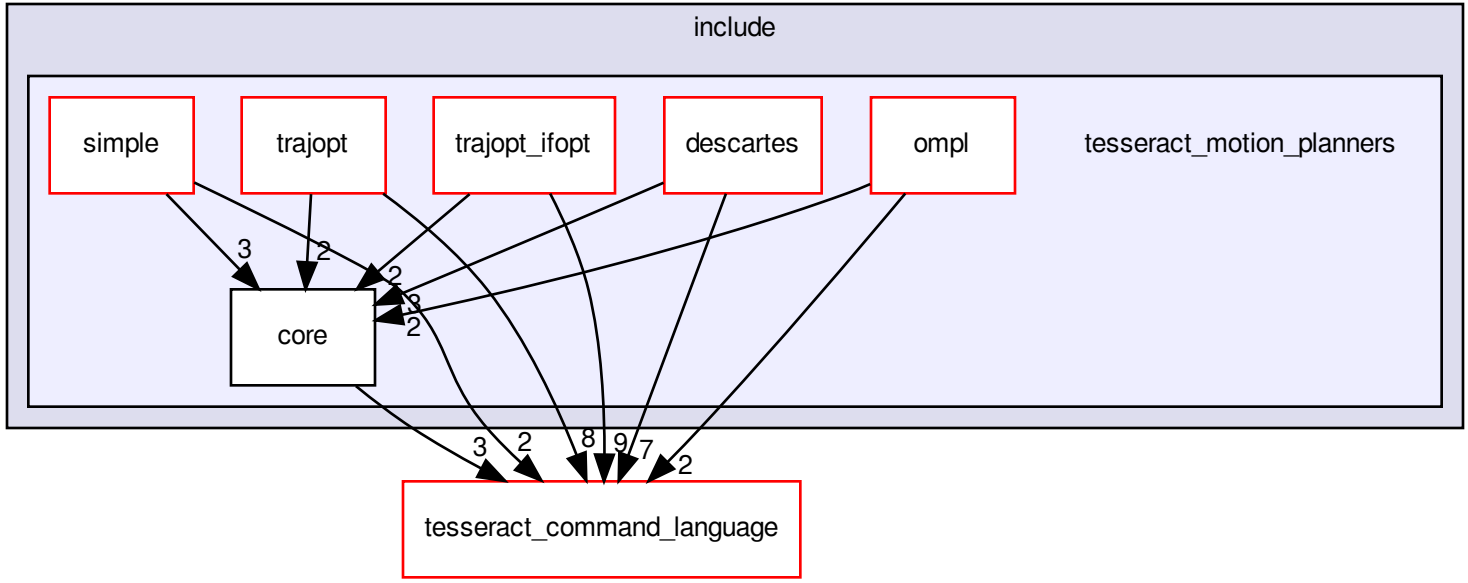
include
tesseract_motion_planners
simple
trajopt
trajopt_ifopt
descartes
ompl
core
tesseract_command_language
3
2
2
3
2
3
2
8
9
7
2