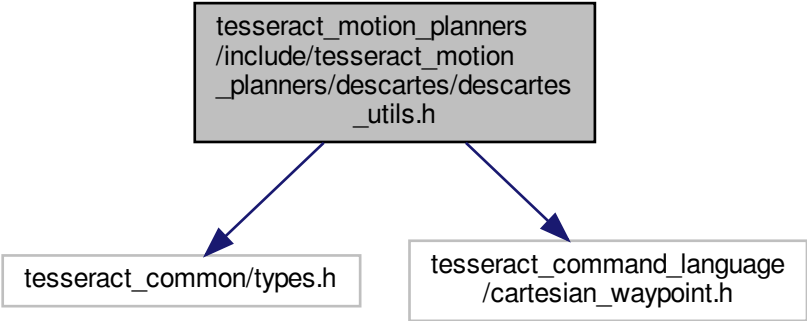


tesseract_motion_planners
/include/tesseract_motion
_planners/descartes/descartes
_utils.h



```
graph TD; A["tesseract_motion_planners  
/include/tesseract_motion  
_planners/descartes/descartes  
_utils.h"] --> B["tesseract_common/types.h"]; A --> C["tesseract_command_language  
/cartesian_waypoint.h"];
```

The diagram illustrates the include relationships for the file `tesseract_motion_planners/include/tesseract_motion_planners/descartes/descartes_utils.h`. It is shown in a grey box at the top. Two blue arrows point from this box to two other boxes below it. The left box, with a white background, contains the path `tesseract_common/types.h`. The right box, also with a white background, contains the path `tesseract_command_language/cartesian_waypoint.h`.

tesseract_common/types.h

tesseract_command_language
/cartesian_waypoint.h