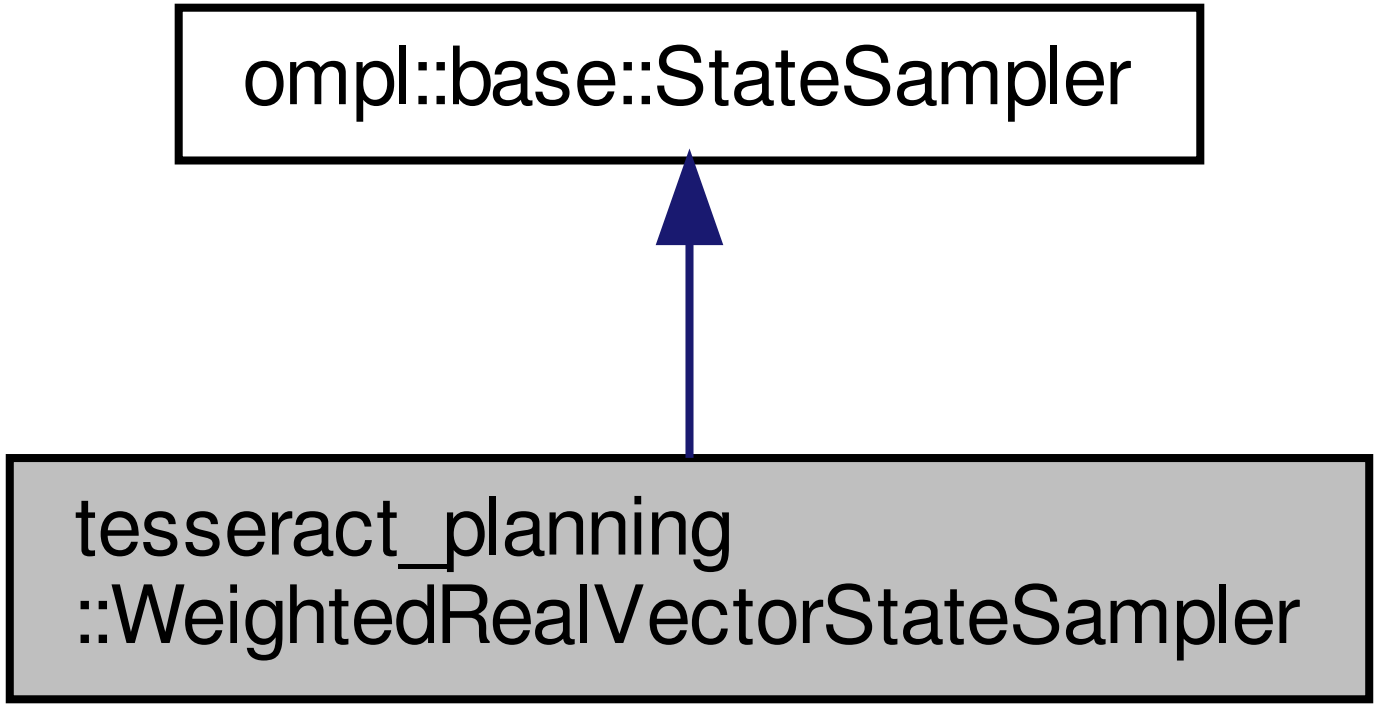
ompl::base::StateSampler
tesseract_planning
::WeightedRealVectorStateSampler