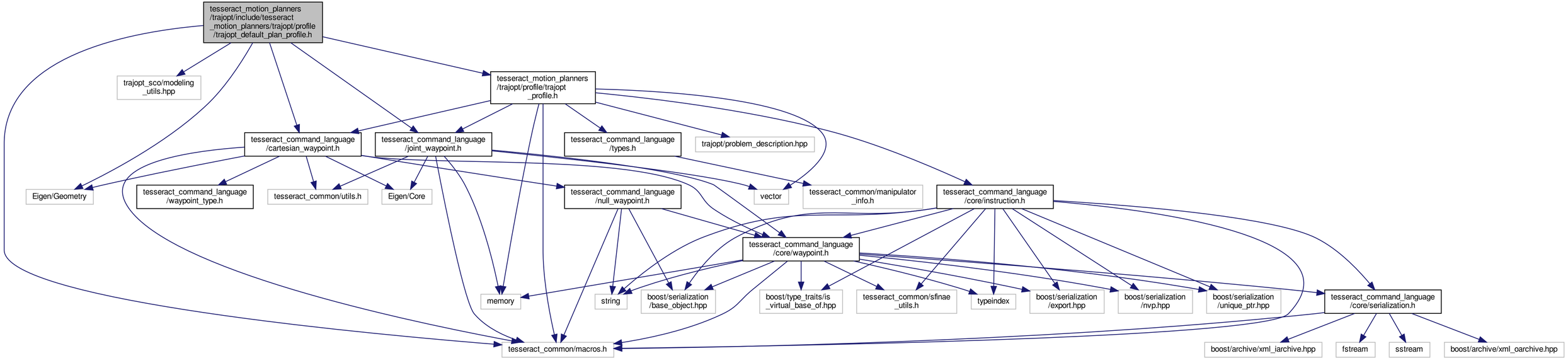
tesseract_motion_planners/trajopt/include/tesseract_motion_planners/trajopt/profile/trajopt_default_plan_profile.h
trajopt_sco/modeling_utils.hpp
tesseract_motion_planners/trajopt/profile/trajopt_profile.h
tesseract_command_language/cartesian_waypoint.h
tesseract_command_language/joint_waypoint.h
tesseract_command_language/types.h
trajopt/problem_description.hpp
Eigen/Geometry
tesseract_command_language/waypoint_type.h
tesseract_common/utils.h
Eigen/Core
tesseract_command_language/null_waypoint.h
vector
tesseract_common/manipulator_info.h
tesseract_command_language/core/instruction.h
tesseract_command_language/core/waypoint.h
memory
string
boost/serialization/base_object.hpp
boost/type_traits/is_virtual_base_of.hpp
tesseract_common/sfinae_utils.h
typeindex
boost/serialization/export.hpp
boost/serialization/nvp.hpp
boost/serialization/unique_ptr.hpp
tesseract_command_language/core/serialization.h
tesseract_common/macros.h
boost/archive/xml_iarchive.hpp
fstream
sstream
boost/archive/xml_oarchive.hpp