

tesseract_motion_planners
/trajopt_ifopt/include
/tesseract_motion_planners
/trajopt_ifopt/profile/trajopt
_ifopt_default_composite_profile.h

```
graph BT; A["tesseract_motion_planners  
/trajopt_ifopt/src/profile  
/trajopt_ifopt_default_composite  
_profile.cpp"] --> C["tesseract_motion_planners  
/trajopt_ifopt/include  
/tesseract_motion_planners  
/trajopt_ifopt/profile/trajopt  
_ifopt_default_composite_profile.h"]; B["tesseract_motion_planners  
/trajopt_ifopt/src/trajopt  
_ifopt_motion_planner.cpp"] --> C;
```

tesseract_motion_planners
/trajopt_ifopt/src/profile
/trajopt_ifopt_default_composite
_profile.cpp

tesseract_motion_planners
/trajopt_ifopt/src/trajopt
_ifopt_motion_planner.cpp