```
tesseract_motion_planners
/trajopt_ifopt/include
/tesseract_motion_planners
/trajopt_ifopt/profile/trajopt
_ifopt_default_plan_profile.h
```

tesseract_motion_planners
/trajopt_ifopt/src/problem
_generators/default_problem
_generator.cpp

tesseract_motion_planners
/trajopt_ifopt/src/profile
/trajopt_ifopt_default_plan
_profile.cpp

tesseract_motion_planners
/trajopt_ifopt/src/trajopt
ifopt motion planner.cpp