

tesseract\_planning  
::OMPLPlannerConfigurator



```
graph BT; A[tesseract_planning::RRTConfigurator] --> B[tesseract_planning::OMPLPlannerConfigurator];
```

The diagram illustrates an inheritance relationship between two C++ classes. A light gray box at the bottom represents the base class, `tesseract_planning::RRTConfigurator`. A dark gray box at the top represents the derived class, `tesseract_planning::OMPLPlannerConfigurator`. A blue arrow points from the top of the base class box to the bottom of the derived class box, indicating that `OMPLPlannerConfigurator` inherits from `RRTConfigurator`.

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