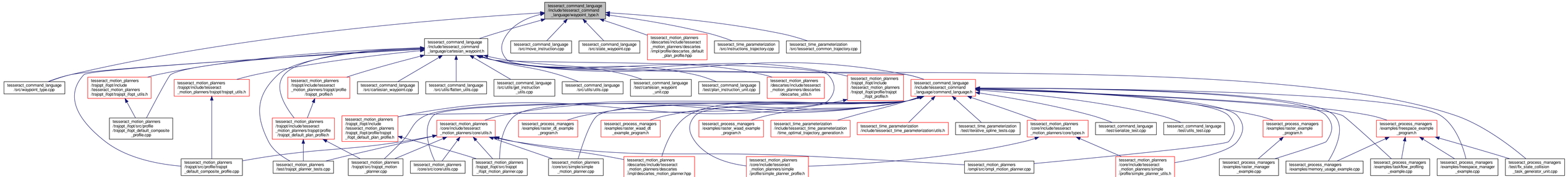
tesseract_command_language/include/tesseract_command_language/waypoint_type.h
tesseract_command_language/include/tesseract_command_language/cartesian_waypoint.h
tesseract_command_language/src/move_instruction.cpp
tesseract_command_language/src/state_waypoint.cpp
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tesseract_time_parameterization/src/instructions_trajectory.cpp
tesseract_time_parameterization/src/tesseract_common_trajectory.cpp
tesseract_command_language/src/waypoint_type.cpp
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tesseract_command_language/src/cartesian_waypoint.cpp
tesseract_command_language/src/utils/flatten_utils.cpp
tesseract_command_language/src/utils/get_instruction_utils.cpp
tesseract_command_language/src/utils/utils.cpp
tesseract_command_language/test/cartesian_waypoint_unit.cpp
tesseract_command_language/test/plan_instruction_unit.cpp
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tesseract_process_managers/examples/raster_dt_example_program.h
tesseract_process_managers/examples/raster_waad_dt_example_program.h
tesseract_process_managers/examples/raster_waad_example_program.h
tesseract_time_parameterization/include/tesseract_time_parameterization/time_optimal_trajectory_generation.h
tesseract_time_parameterization/include/tesseract_time_parameterization/utils.h
tesseract_time_parameterization/test/iterative_spline_tests.cpp
tesseract_motion_planners/core/include/tesseract_motion_planners/core/types.h
tesseract_command_language/test/serialize_test.cpp
tesseract_command_language/test/utils_test.cpp
tesseract_process_managers/examples/raster_example_program.h
tesseract_process_managers/examples/freespace_example_program.h
tesseract_motion_planners/test/trajopt_planner_tests.cpp
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tesseract_motion_planners/core/src/core/utils.cpp
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tesseract_motion_planners/core/src/simple/simple_motion_planner.cpp
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tesseract_process_managers/examples/raster_manager_example.cpp
tesseract_process_managers/examples/memory_usage_example.cpp
tesseract_process_managers/examples/taskflow_profiling_example.cpp
tesseract_process_managers/examples/freespace_manager_example.cpp
tesseract_process_managers/test/fix_state_collision_task_generator_unit.cpp