

tesseract_motion_planners
/include/tesseract_motion
_planners/trajopt/profile
/trajopt_default_solver_profile.h

```
graph BT; A["tesseract_motion_planners  
/src/trajopt/problem_generators  
/default_problem_generator.cpp"] --> C["tesseract_motion_planners  
/include/tesseract_motion_planners/trajopt/profile  
/trajopt_default_solver_profile.h"]; B["tesseract_motion_planners  
/src/trajopt/profile/trajopt  
_default_solver_profile.cpp"] --> C;
```

The diagram illustrates the relationship between two source files and a header file. At the bottom, there are two white boxes with black borders. The left box contains the path 'tesseract_motion_planners /src/trajopt/problem_generators /default_problem_generator.cpp'. The right box contains the path 'tesseract_motion_planners /src/trajopt/profile/trajopt _default_solver_profile.cpp'. Two blue arrows point from the top of these boxes towards a central gray box at the top. The gray box contains the path 'tesseract_motion_planners /include/tesseract_motion _planners/trajopt/profile /trajopt_default_solver_profile.h'.

tesseract_motion_planners
/src/trajopt/problem_generators
/default_problem_generator.cpp

tesseract_motion_planners
/src/trajopt/profile/trajopt
_default_solver_profile.cpp