

tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::MotionPlannerTaskInfo] --> B[tesseract_planning::TaskInfo];
```

A diagram illustrating a relationship between two classes. At the bottom is a gray rectangular box containing the text 'tesseract_planning' and '::MotionPlannerTaskInfo'. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box above it. The white box contains the text 'tesseract_planning' and '::TaskInfo'. Both boxes have a black border.

tesseract_planning
::MotionPlannerTaskInfo