

tesseract_motion_planners
/include/tesseract_motion
_planners/ompl/discrete_motion
_validator.h

```
graph TD; A["tesseract_motion_planners  
/include/tesseract_motion  
_planners/ompl/discrete_motion  
_validator.h"] --> B["tesseract_common/macros.h"]; A --> C["ompl/base/MotionValidator.h"]
```

tesseract_common/macros.h

ompl/base/MotionValidator.h