

tesseract_planning
::MotionPlanner



```
classDiagram
    class tesseract_planning_MotionPlanner["tesseract_planning::MotionPlanner"]
    class tesseract_planning_OMPLMotionPlanner["tesseract_planning::OMPLMotionPlanner"]
    tesseract_planning_OMPLMotionPlanner --|> tesseract_planning_MotionPlanner
```

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'tesseract_planning' followed by '::MotionPlanner' on the next line. The bottom box is gray with a black border and contains the text 'tesseract_planning' followed by '::OMPLMotionPlanner' on the next line. A blue arrow points vertically from the top edge of the bottom box to the bottom edge of the top box, indicating an inheritance relationship.

tesseract_planning
::OMPLMotionPlanner