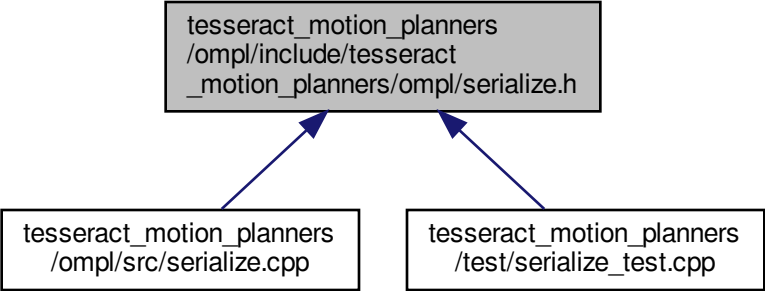


tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/serialize.h



```
graph BT; A["tesseract_motion_planners  
/ompl/src/serialize.cpp"] --> B["tesseract_motion_planners  
/ompl/include/tesseract  
_motion_planners/ompl/serialize.h"]; C["tesseract_motion_planners  
/test/serialize_test.cpp"] --> B;
```

tesseract_motion_planners
/ompl/src/serialize.cpp

tesseract_motion_planners
/test/serialize_test.cpp