

tesseract\_motion\_planners  
/include/tesseract\_motion  
\_planners/ompl/ompl\_motion  
\_planner\_status\_category.h

```
graph BT; A["tesseract_motion_planners  
/src/ompl/ompl_motion_planner.cpp"] --> C["tesseract_motion_planners  
/include/tesseract_motion_planners/ompl/ompl_motion_planner_status_category.h"]; B["tesseract_motion_planners  
/src/ompl/ompl_motion_planner_status_category.cpp"] --> C;
```

The diagram illustrates the relationship between three files in the tesseract\_motion\_planners/ompl directory. At the top is a header file, 'tesseract\_motion\_planners/include/tesseract\_motion\_planners/ompl/ompl\_motion\_planner\_status\_category.h', which is shaded gray. Below it are two source files: 'tesseract\_motion\_planners/src/ompl/ompl\_motion\_planner.cpp' on the left and 'tesseract\_motion\_planners/src/ompl/ompl\_motion\_planner\_status\_category.cpp' on the right. Both source files have blue arrows pointing to the header file, indicating that they include it.

tesseract\_motion\_planners  
/src/ompl/ompl\_motion\_planner.cpp

tesseract\_motion\_planners  
/src/ompl/ompl\_motion\_planner  
\_status\_category.cpp