

tesseract_motion_planners
/ompl/include/tesseract
_motion_planners/ompl/state
_collision_validator.h

```
graph BT; A["tesseract_motion_planners/ompl/src/profile/ompl_default_plan_profile.cpp"] --> C["tesseract_motion_planners/ompl/include/tesseract_motion_planners/ompl/state_collision_validator.h"]; B["tesseract_motion_planners/ompl/src/state_collision_validator.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files, `_default_plan_profile.cpp` and `_validator.cpp`, both include the header file `_collision_validator.h`. The header file is located in the `/ompl/include/tesseract_motion_planners/ompl/state` directory, while the source files are in the `/ompl/src/profile/ompl` and `/ompl/src/state_collision` directories, respectively. The header file box is shaded gray, and blue arrows indicate the inclusion relationship from the source files to the header.

tesseract_motion_planners
/ompl/src/profile/ompl
_default_plan_profile.cpp

tesseract_motion_planners
/ompl/src/state_collision
_validator.cpp