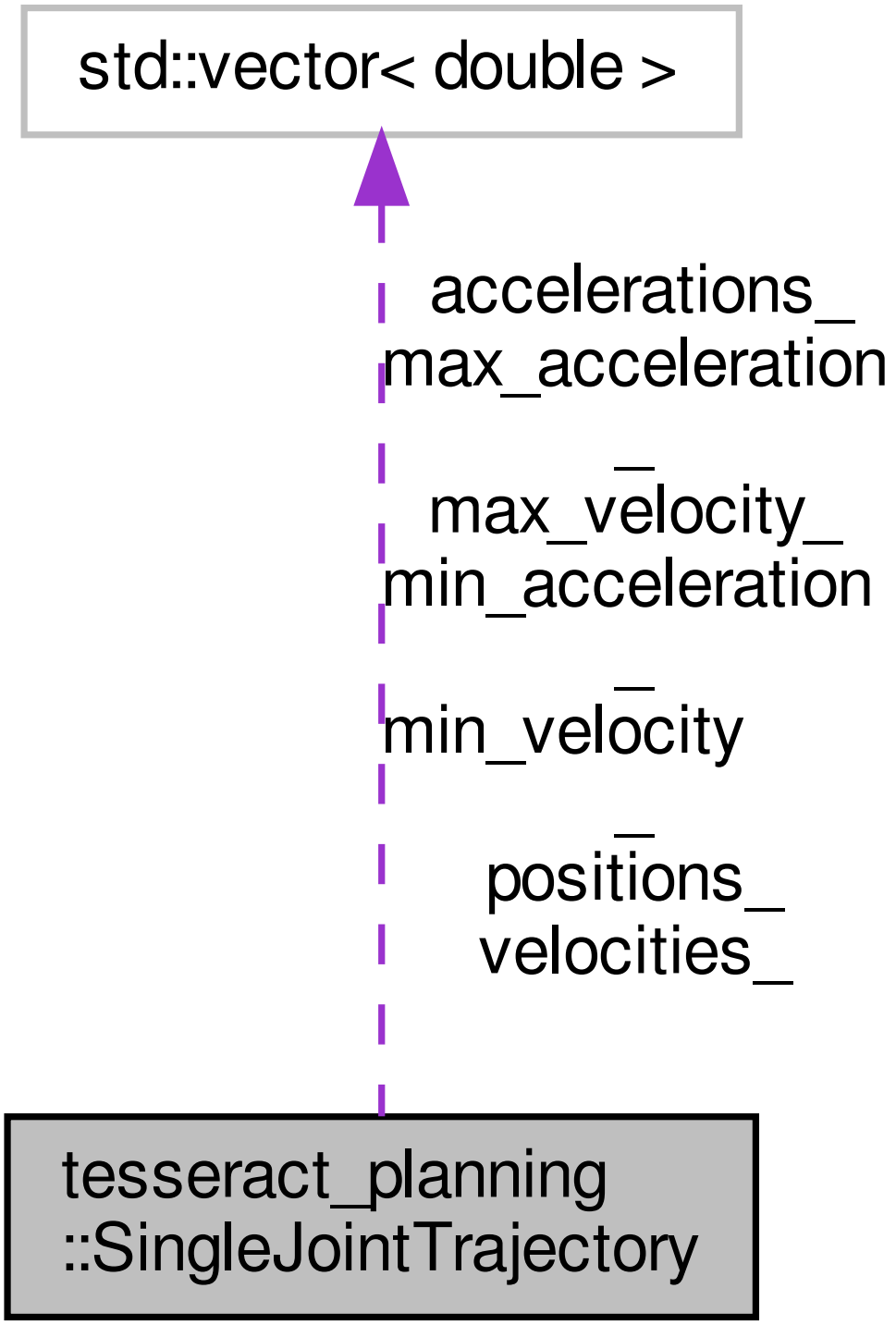
std::vector< double >
accelerations_
max_acceleration_
max_velocity_
min_acceleration_
min_velocity_
positions_
velocities_
tesseract_planning::SingleJointTrajectory