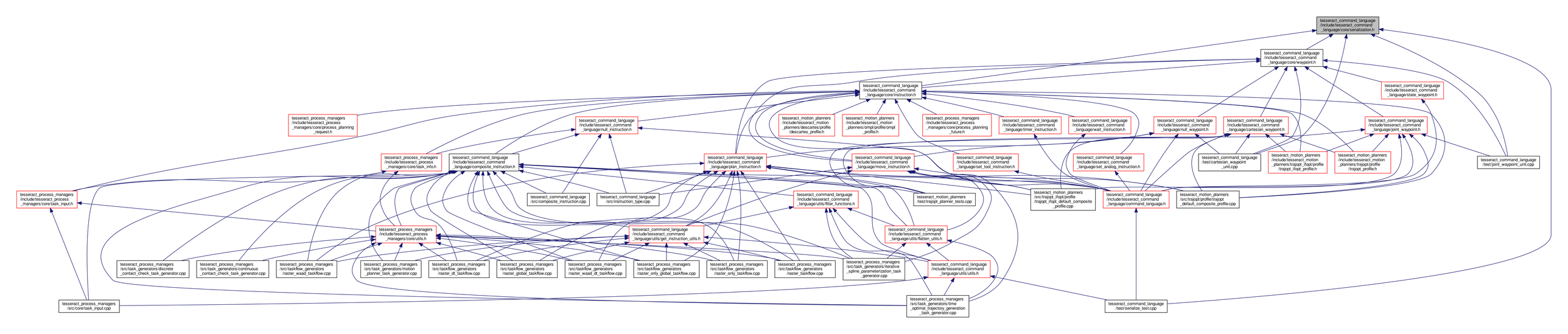
tesseract_command_language/include/tesseract_command_language/core/serialization.h
tesseract_command_language/include/tesseract_command_language/core/waypoint.h
tesseract_command_language/include/tesseract_command_language/core/instruction.h
tesseract_command_language/include/tesseract_command_language/state_waypoint.h
tesseract_process_managers/include/tesseract_process_managers/core/process_planning_request.h
tesseract_command_language/include/tesseract_command_language/null_instruction.h
tesseract_motion_planners/include/tesseract_motion_planners/descartes/profile/descartes_profile.h
tesseract_motion_planners/include/tesseract_motion_planners/ompl/profile/ompl_profile.h
tesseract_process_managers/include/tesseract_process_managers/core/process_planning_future.h
tesseract_command_language/include/tesseract_command_language/timer_instruction.h
tesseract_command_language/include/tesseract_command_language/wait_instruction.h
tesseract_command_language/include/tesseract_command_language/null_waypoint.h
tesseract_command_language/include/tesseract_command_language/cartesian_waypoint.h
tesseract_command_language/include/tesseract_command_language/joint_waypoint.h
tesseract_process_managers/include/tesseract_process_managers/core/task_info.h
tesseract_command_language/include/tesseract_command_language/composite_instruction.h
tesseract_command_language/include/tesseract_command_language/plan_instruction.h
tesseract_command_language/include/tesseract_command_language/move_instruction.h
tesseract_command_language/include/tesseract_command_language/set_tool_instruction.h
tesseract_command_language/include/tesseract_command_language/set_analog_instruction.h
tesseract_command_language/test/cartesian_waypoint_unit.cpp
tesseract_motion_planners/include/tesseract_motion_planners/trajopt_ifopt/profile/trajopt_ifopt_profile.h
tesseract_motion_planners/include/tesseract_motion_planners/trajopt/profile/trajopt_profile.h
tesseract_command_language/test/joint_waypoint_unit.cpp
tesseract_process_managers/include/tesseract_process_managers/core/task_input.h
tesseract_command_language/src/composite_instruction.cpp
tesseract_command_language/src/instruction_type.cpp
tesseract_command_language/include/tesseract_command_language/utils/filter_functions.h
tesseract_motion_planners/test/trajopt_planner_tests.cpp
tesseract_motion_planners/src/trajopt_ifopt/profile/trajopt_ifopt_default_composite_profile.cpp
tesseract_command_language/include/tesseract_command_language/command_language.h
tesseract_motion_planners/src/trajopt/profile/trajopt_default_composite_profile.cpp
tesseract_process_managers/include/tesseract_process_managers/core/utils.h
tesseract_command_language/include/tesseract_command_language/utils/get_instruction_utils.h
tesseract_command_language/include/tesseract_command_language/utils/flatten_utils.h
tesseract_process_managers/src/task_generators/discrete_contact_check_task_generator.cpp
tesseract_process_managers/src/task_generators/continuous_contact_check_task_generator.cpp
tesseract_process_managers/src/taskflow_generators/raster_waad_taskflow.cpp
tesseract_process_managers/src/task_generators/motion_planner_task_generator.cpp
tesseract_process_managers/src/taskflow_generators/raster_dt_taskflow.cpp
tesseract_process_managers/src/taskflow_generators/raster_global_taskflow.cpp
tesseract_process_managers/src/taskflow_generators/raster_waad_dt_taskflow.cpp
tesseract_process_managers/src/taskflow_generators/raster_only_global_taskflow.cpp
tesseract_process_managers/src/taskflow_generators/raster_only_taskflow.cpp
tesseract_process_managers/src/taskflow_generators/raster_taskflow.cpp
tesseract_process_managers/src/task_generators/iterative_spline_parameterization_task_generator.cpp
tesseract_command_language/include/tesseract_command_language/utils/utils.h
tesseract_process_managers/src/core/task_input.cpp
tesseract_process_managers/src/task_generators/time_optimal_trajectory_generation_task_generator.cpp
tesseract_command_language/test/serialize_test.cpp