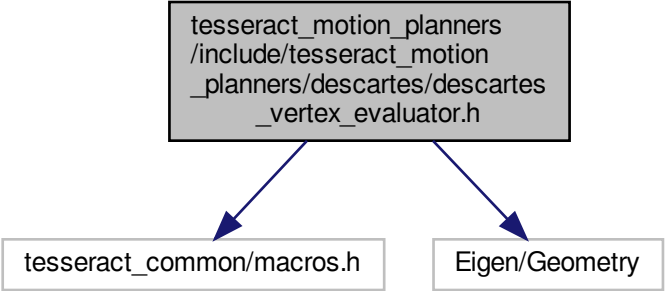


tesseract_motion_planners
/include/tesseract_motion
_planners/descartes/descartes
_vertex_evaluator.h



```
graph TD; A["tesseract_motion_planners  
/include/tesseract_motion  
_planners/descartes/descartes  
_vertex_evaluator.h"] --> B["tesseract_common/macros.h"]; A --> C["Eigen/Geometry"]
```

tesseract_common/macros.h

Eigen/Geometry