

tesseract\_motion\_planners  
/trajopt\_ifopt/include  
/tesseract\_motion\_planners  
/trajopt\_ifopt/trajopt\_ifopt  
\_motion\_planner.h

```
graph BT; A["tesseract_motion_planners  
/trajopt_ifopt/src/trajopt_ifopt_motion_planner.cpp"] --> C["tesseract_motion_planners  
/trajopt_ifopt/include  
/tesseract_motion_planners  
/trajopt_ifopt/trajopt_ifopt  
_motion_planner.h"]; B["tesseract_process_managers  
/src/core/default_process_planners.cpp"] --> C;
```

tesseract\_motion\_planners  
/trajopt\_ifopt/src/trajopt  
\_ifopt\_motion\_planner.cpp

tesseract\_process\_managers  
/src/core/default\_process  
\_planners.cpp