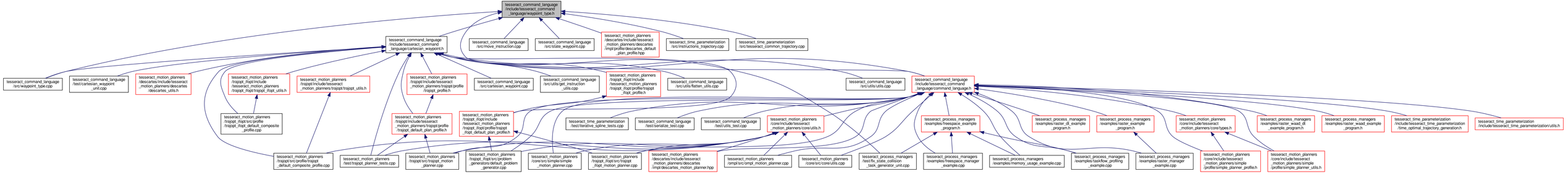
tesseract_command_language /include/tesseract_command _language/waypoint_type.h
tesseract_command_language /include/tesseract_command _language/cartesian_waypoint.h
tesseract_command_language /src/move_instruction.cpp
tesseract_command_language /src/state_waypoint.cpp
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes /impl/profile/descartes_default _plan_profile.hpp
tesseract_time_parameterization /src/instructions_trajectory.cpp
tesseract_time_parameterization /src/tesseract_common_trajectory.cpp
tesseract_command_language /src/waypoint_type.cpp
tesseract_command_language /test/cartesian_waypoint _unit.cpp
tesseract_motion_planners /descartes/include/tesseract _motion_planners/descartes /descartes_utils.h
tesseract_motion_planners /trajopt_ifopt/include /tesseract_motion_planners /trajopt_ifopt/trajopt_ifopt_utils.h
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tesseract_process_managers /examples/memory_usage_example.cpp
tesseract_process_managers /examples/raster_dt_example _program.h
tesseract_process_managers /examples/task/flow_profiling _example.cpp
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tesseract_process_managers /test/fix_state_collision _task_generator_unit.cpp
tesseract_motion_planners /core/include/tesseract _motion_planners/simple /profile/simple_planner_utils.h