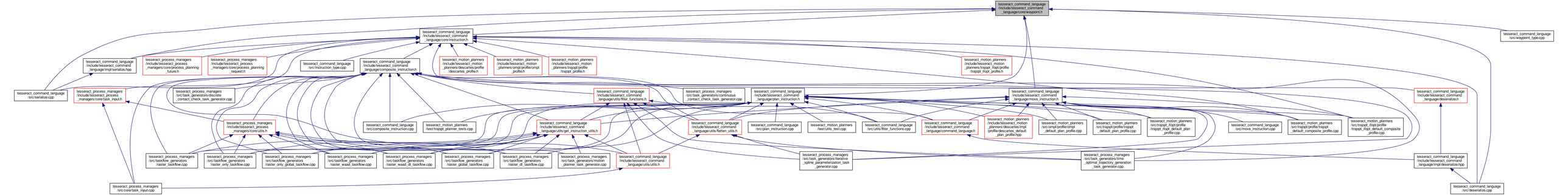
tesseract_command_language /include/tesseract_command _language/core/waypoint.h
tesseract_command_language /include/tesseract_command _language/core/instruction.h
tesseract_command_language /include/tesseract_command _language/impl/serialize.hpp
tesseract_process_managers /include/tesseract_process _managers/core/process_planning _future.h
tesseract_process_managers /include/tesseract_process _managers/core/process_planning _request.h
tesseract_command_language /src/instruction_type.cpp
tesseract_command_language /include/tesseract_command _language/composite_instruction.h
tesseract_motion_planners /include/tesseract_motion _planners/descartes/profile /descartes_profile.h
tesseract_motion_planners /include/tesseract_motion _planners/ompl/profile/ompl _profile.h
tesseract_motion_planners /include/tesseract_motion _planners/trajopt/profile /trajopt_profile.h
tesseract_motion_planners /include/tesseract_motion _planners/trajopt_ifopt/profile /trajopt_ifopt_profile.h
tesseract_command_language /src/waypoint_type.cpp
tesseract_command_language /src/serialize.cpp
tesseract_process_managers /include/tesseract_process _managers/core/task_input.h
tesseract_process_managers /src/task_generators/discrete _contact_check_task_generator.cpp
tesseract_command_language /include/tesseract_command _language/utils/filter_functions.h
tesseract_process_managers /src/task_generators/continuous _contact_check_task_generator.cpp
tesseract_command_language /include/tesseract_command _language/plan_instruction.h
tesseract_command_language /include/tesseract_command _language/move_instruction.h
tesseract_command_language /include/tesseract_command _language/deserialize.h
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tesseract_command_language /src/composite_instruction.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
tesseract_command_language /include/tesseract_command _language/utils/get_instruction_utils.h
tesseract_command_language /include/tesseract_command _language/utils/flatten_utils.h
tesseract_command_language /src/plan_instruction.cpp
tesseract_motion_planners /test/utils_test.cpp
tesseract_command_language /src/utils/filter_functions.cpp
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tesseract_motion_planners /include/tesseract_motion _planners/descartes/ompl /profile/descartes_default _plan_profile.hpp
tesseract_motion_planners /src/ompl/profile/ompl _default_plan_profile.cpp
tesseract_motion_planners /src/trajopt/profile/trajopt _default_plan_profile.cpp
tesseract_motion_planners /src/trajopt/profile/trajopt _default_plan _profile.cpp
tesseract_command_language /src/move_instruction.cpp
tesseract_motion_planners /src/trajopt/profile/trajopt _default_composite_profile.cpp
tesseract_motion_planners /src/trajopt_ifopt/profile /trajopt_ifopt_default_composite _profile.cpp
tesseract_process_managers /src/task_generators/motion _planner_task_generator.cpp
tesseract_command_language /include/tesseract_command _language/utils/utils.h
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tesseract_command_language /src/deserialize.cpp