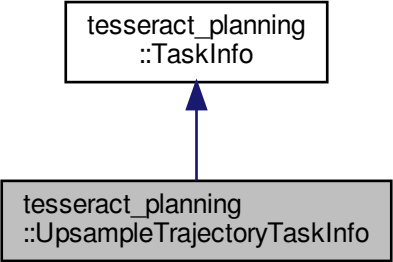


tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::UpsampleTrajectoryTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram illustrates an inheritance relationship between two C++ classes. At the bottom is a gray-shaded box representing the base class, `tesseract_planning::UpsampleTrajectoryTaskInfo`. A blue arrow points vertically from the top center of this box to the bottom center of a white box above it, representing the derived class, `tesseract_planning::TaskInfo`. Both boxes have a black border and contain their respective class names in two lines.

tesseract_planning
::UpsampleTrajectoryTaskInfo