

tesseract\_motion\_planners  
/include/tesseract\_motion  
\_planners/trajopt\_ifopt/profile  
/trajopt\_ifopt\_default\_plan\_profile.h

```
graph BT; A["tesseract_motion_planners  
/src/trajopt_ifopt/problem  
_generators/default_problem  
_generator.cpp"] --> C["tesseract_motion_planners  
/include/tesseract_motion  
_planners/trajopt_ifopt/profile  
/trajopt_ifopt_default_plan_profile.h"]; B["tesseract_motion_planners  
/src/trajopt_ifopt/profile  
/trajopt_ifopt_default_plan  
_profile.cpp"] --> C;
```

tesseract\_motion\_planners  
/src/trajopt\_ifopt/problem  
\_generators/default\_problem  
\_generator.cpp

tesseract\_motion\_planners  
/src/trajopt\_ifopt/profile  
/trajopt\_ifopt\_default\_plan  
\_profile.cpp