

hw1_search_q13_a*_cscs

Question 13: A*-CSCS

2/2 points (ungraded)

Recall that a dictionary, also known as a hashmap, works as follows:

Inserting a key-value pair into a dictionary when the key is not already in the dictionary adds the pair to the dictionary:

```
dict ← an empty dictionary
dict["key"] ← "value"
print dict["key"]
→ "value"
```

Updating the value associated with a dictionary entry is done as follows:

```
dict["key"] ← "new value"
print dict["key"]
→ "new value"
```

We saw that for A^* graph search to be guaranteed to be optimal the heuristic needs to be consistent. In this question we explore a new search procedure using a dictionary for the closed set, A^* -graph-search-with-Cost-Sensitive-Closed-Set (A^* - CSCS).

```
function A*-CSCS-GRAPH-SEARCH(problem, fringe, strategy) return a solution, or failure
  closed ← an empty dictionary
  fringe ← INSERT(MAKE-NODE(INITIAL-STATE[problem]), fringe)
  loop do
    if fringe is empty then return failure
    node ← REMOVE-FRONT(fringe, strategy)
    if GOAL-TEST(problem, STATE[node]) then return node
    if STATE[node] is not in closed or COST[node] < closed[STATE[node]] then
      closed[STATE[node]] ← COST[node]
    for child-node in EXPAND(node, problem) do
      fringe ← INSERT(child-node, fringe)
    end
  end
end
```

Rather than just inserting the last state of a node into the closed set, we now store the last state paired with the cost of the node. Whenever A^* -CSCS considers expanding a node, it checks the closed set. Only if the last state is not a key in the closed set, or the cost of the node is less than the cost associated with the state in the closed set, the node is expanded.

For **regular A^* graph search** which of the following statements are true?

☐ If h is admissible, then A^* graph search finds an optimal solution.

☒ If h is consistent, then A^* graph search finds an optimal solution.



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✓ Correct (2/2 points)

problem

2/2 points (ungraded)

In each of the following parts, select all true statements about A^* -CSCS

☒ If h is admissible, then A^* -CSCS finds an optimal solution.

☒ If h is consistent, then A^* -CSCS finds an optimal solution.



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✓ Correct (2/2 points)

problem

2/2 points (ungraded)

☒ If h is admissible, then A^* - CSCS will expand at most as many nodes as A^* **tree** search.

☒ If h is consistent, then A^* - CSCS will expand at most as many nodes as A^* **tree** search.



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✓ Correct (2/2 points)

problem

2/2 points (ungraded)

☐ If h is admissible, then A^* - CSCS will expand at most as many nodes as A^* **graph** search.

☒ If h is consistent, then A^* - CSCS will expand at most as many nodes as A^* **graph** search.



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✓ Correct (2/2 points)