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## Q4: k-CSPs Q4: k-CSPs

Let a k-CSP be a CSP where the solution is allowed to have k violated constraints. We would like to modify the classic CSP algorithm to solve k-CSPs. The classic backtracking algorithm is shown below. To modify it to solve k-CSPs, we need to change line 15. Note that k is used to denote the number of allowable violated constraints.

```
1: function K-CSP-Backtracking(csp, k)
       return Recursive-Backtracking(\{\}, csp, k)
3: end function
1: function Recursive-Backtracking(assignment, csp, k)
2:
       if assignment is complete then
          return assignment
3:
       end if
4:
       var \leftarrow Select-Unassigned-Variable(Variables[csp], assignment, csp)
5:
       for each value in Order-Domain-Values(var, assignment, csp) do
6:
7:
          if value is consistent with assignment given Constraints(csp) then
              add \{var = value\} to assignment
8:
              result \leftarrow Recursive-Backtracking(assignment, csp, k)
9:
              if result \neq failure then
10:
                 return result
11:
12:
              end if
              remove \{var = value\} from assignment
13:
          else
14:
              continue
15:
          end if
16:
       end for
17:
       return failure
19: end function
```

## Part 1

0.0/5.0 points (graded)

If each of the following blocks of code were to replace line 15, which code block(s) would yield a correct algorithm for solving k-CSPS?

```
add \{var = value\} to assignment
n = \text{Get-Total-Number-of-Constraints-Violated}
                 assignment, csp)
if n \leq k then
   if Is-Tree(Unassigned-Variables[csp]) then
       result \leftarrow Tree-Structured-CSP-Algorithm(
                         assignment, csp)
   else
       result \leftarrow Recursive-Backtracking(
                         assignment, csp, k)
   end if
   if result \neq failure then
       return result
   end if
end if
remove \{var = value\} from assignment
```

None of the code blocks

## **Explanation**

For this formulation, we want to only backtrack when more than k constraints are violated. If there are fewer than k, we can assign the current variable to a constrained value and continue the algorithm. The first code block provides the correct implementation. The second option using a tree structured CSP algorithm will incorrectly return failure if there is no solution with only i + 1 constraints violated (where i + 1 may be less than k). The third and fourth option filter the domains of the remaining variables. If a variable's domain is filtered, then the recursive-backtracking call will only consider values in the filtered domain rather than values which violate a constraint, potentially causing the code to miss the solution.



You have used 0 of 2 attempts

**1** Answers are displayed within the problem

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