

# CANSPY

## A Platform for Auditing CAN Devices

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# Auditing conventional IT systems

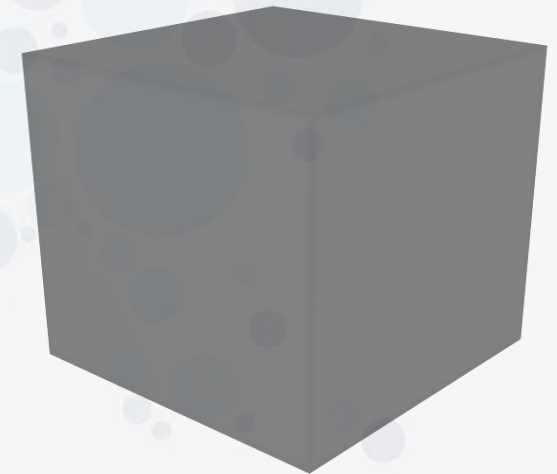
- **Penetration testing**

- A form of security audit
- Assess the risks of intrusion
- Actual tests instead of a review process
- The point of view of a real attacker (the “black-box” approach)
- Relevant evaluation of impact and exploitability

- **Limitations**

- Less time
- Less resources
- More ethics

- **Counter-measure: the “grey-box” approach**



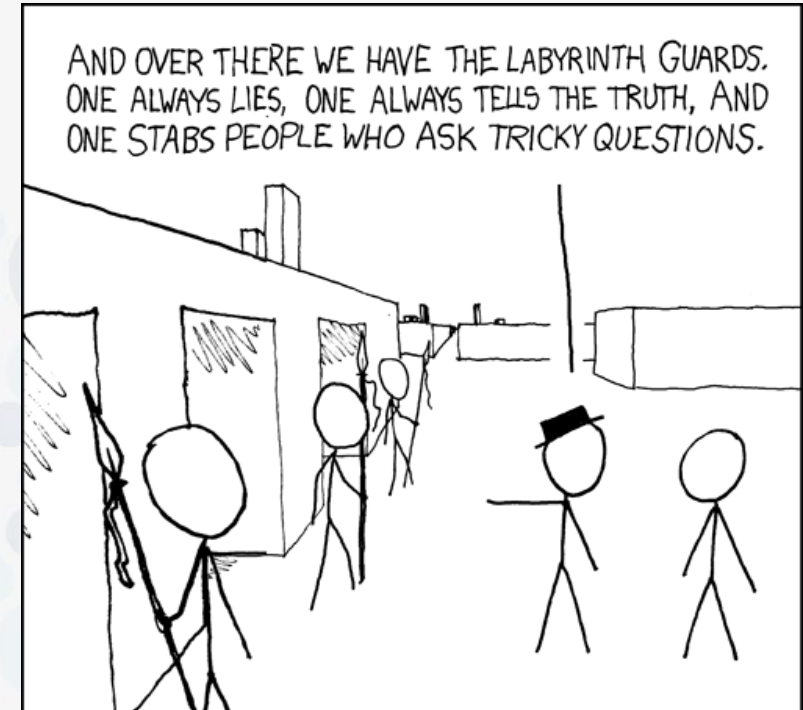
# The CISO's dilemma

- **The hand they are dealt with**

- Huge scope of responsibility
- Continuous changes
- Major security threats
- Risk of substantial damages
- Limited budget

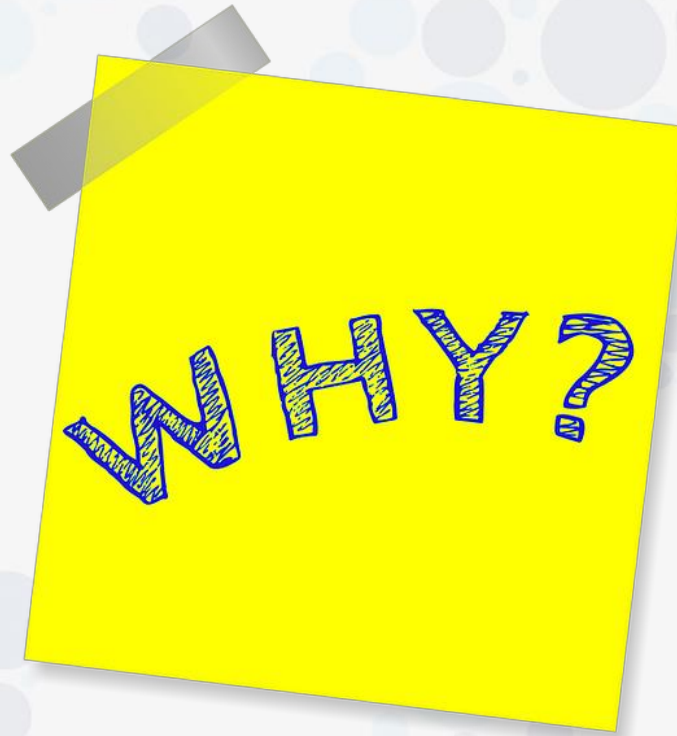
- **Their response**

- They rely on penetration testing
- They welcome the “gray-box” approach
- They rely on risk analysis first and foremost
- They divide perimeters accordingly



# What about car manufacturer ?

- They are starting to include cyber-security along with conventional safety





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www.heise.de/ct/artikel/Beemer-Open-Thyself-Security-vulnerabilities-in-BMW-s-ConnectedDrive-2540957.html

## Beemer, Open Thyself! - Security vulnerabilities in BMW's ConnectedDrive

INFOS ZUM ARTIKEL **WISSEN | HINTERGRUND**

Translation: Fabian A. Scherschel, Dieter Spaar 05.02.2015  
BMW, ConnectedDrive, Security, Sicherheitslücke

**Kapitel**

- 01 Disassembled
- 02 Desoldered
- 03 Looking for the Keys
- 04 Reassembled
- 05 Break-in
- 06 In practice
- 07 Conclusion
- 08 Affected Cars and What to Do About It

**Cars with built-in modems are sending data to their manufacturers - German motorist's club ADAC wanted to know what exactly gets sent. c't connected ADAC with a specialist who analysed the data transmissions, using the example of BMW's ConnectedDrive technology. He discovered security vulnerabilities that even allow unauthorised attackers to open the vehicles.**

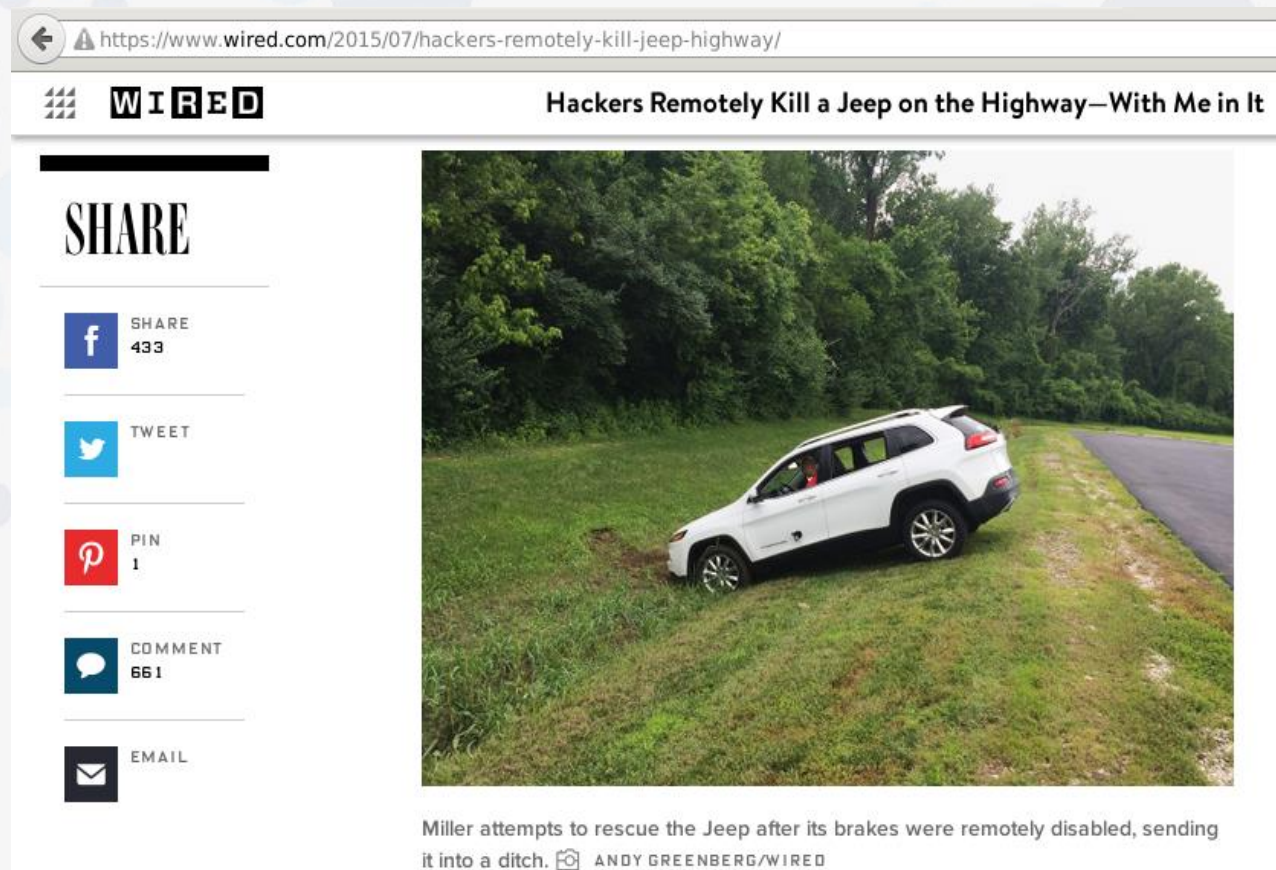
### Angriff auf BMW ConnectedDrive

Wenn der Besitzer in der BMW Remote App die Türerriegelung veranlasst, erhält das Fahrzeug eine SMS vom BMW-Backend. Es holt daraufhin den Öffnungsbefehl von einem Server und führt ihn aus.

```
graph LR; User[User] -- "Besitzer gibt Befehl in BMW Remote App  
„Entriegle Tür“" --> Server[Server]; Server -- "SMS  
„Hole Befehl“" --> Car[Car];
```

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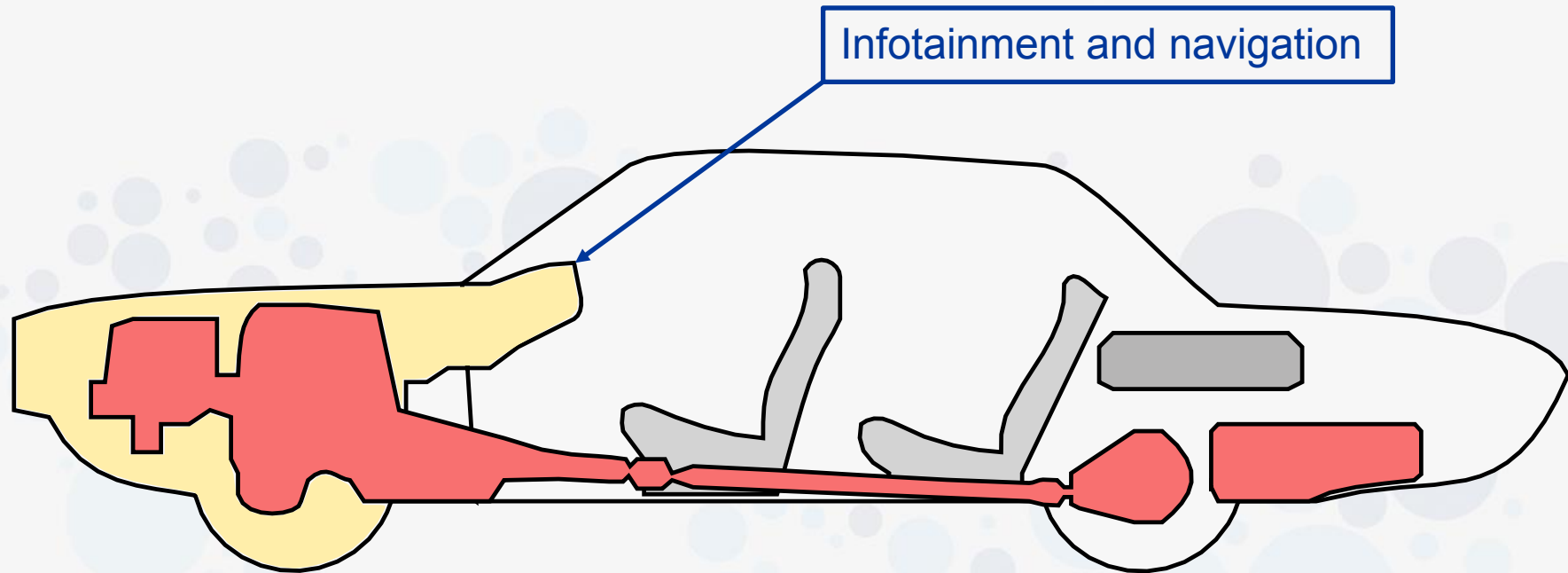
# What about car manufacturer ?

- They are starting to include cyber-security along with conventional safety
- The same approach can be applied
  - For each vehicle
    - Conduct risk analysis
    - Prioritize ECUs
    - Conduct penetration tests accordingly
    - Carry out corrective actions
  - End for
- Some ECUs can be common to several vehicles
- Corrective actions may be difficult to carry out





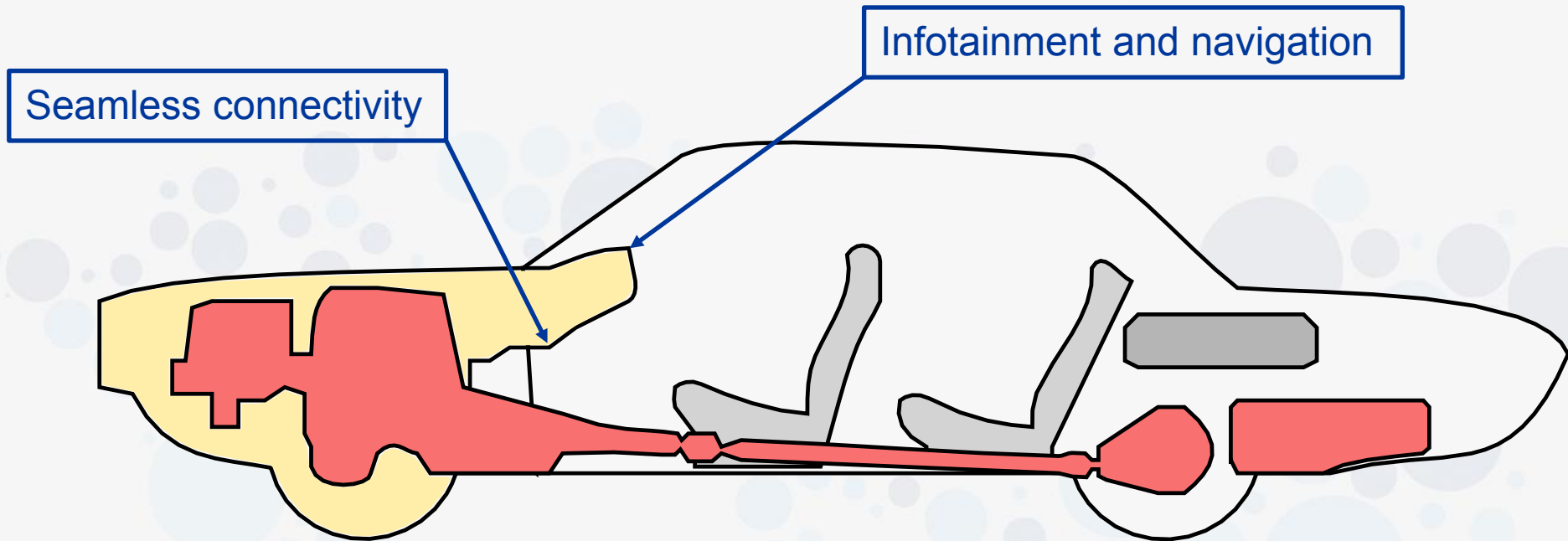
# It always begins with...



- **Consumer-grade connectivity**

- Wi-Fi, Bluetooth and USB
- Nothing new here

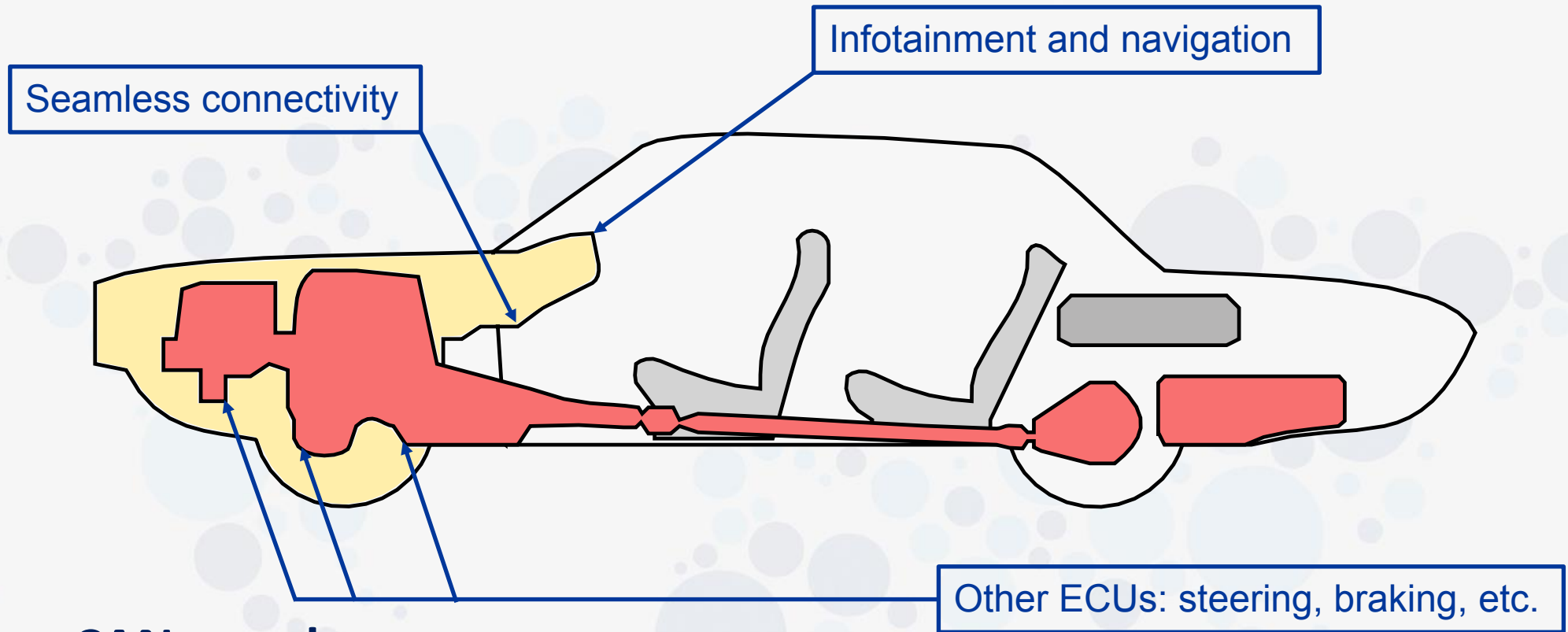
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- **Mobile broadband connectivity**

- Conventional protocols (TCP, HTTP, ...)
- Setting up an IMSI catcher
- Then again, nothing new here

# It always begins with...



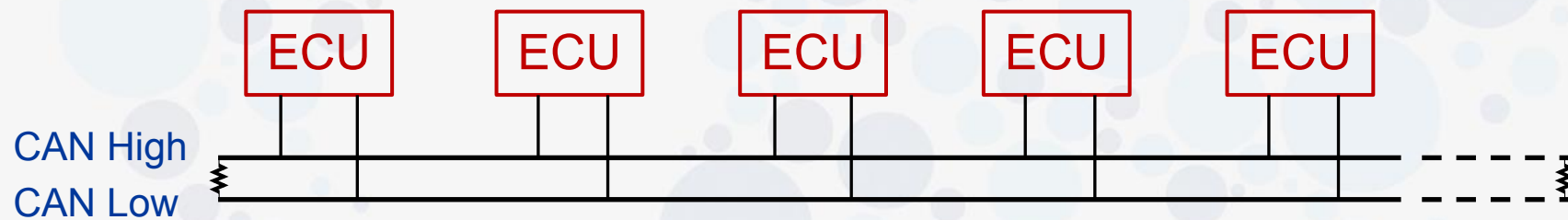
- **CAN attacks**

- Bypass CAN bus segmentation (architecture-dependant)
- Reverse-engineer higher-layer protocols
- Break the Security Access challenge (ISO 14229)

# CAN architectures

- One bus (to rule them all 🍷)

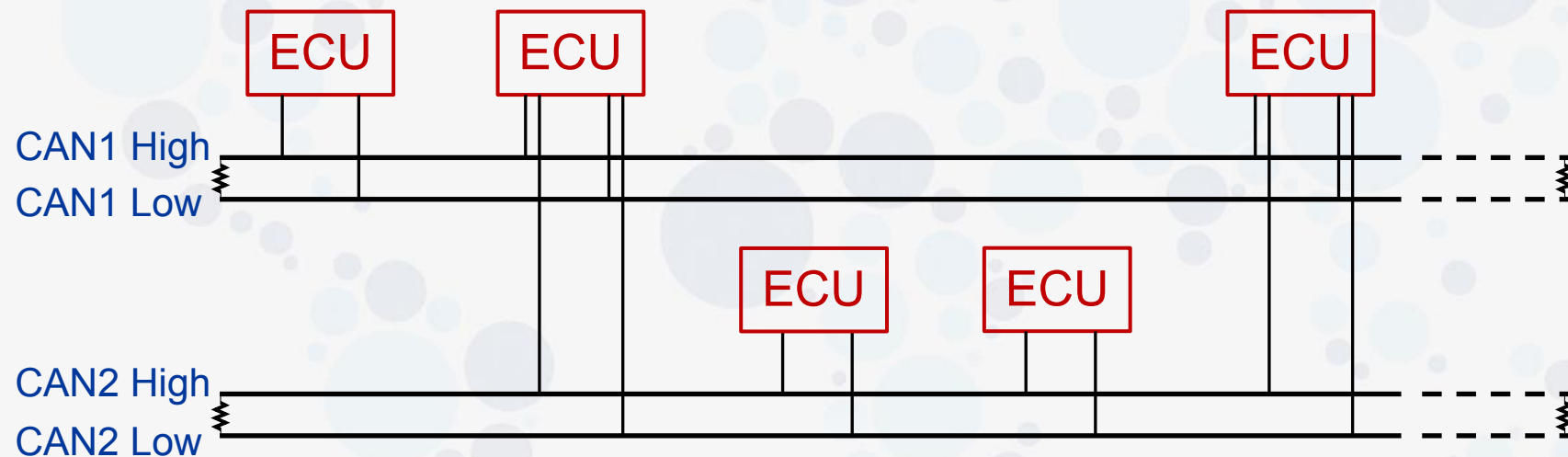
- Less common nowadays
- Congestion issues





# CAN architectures

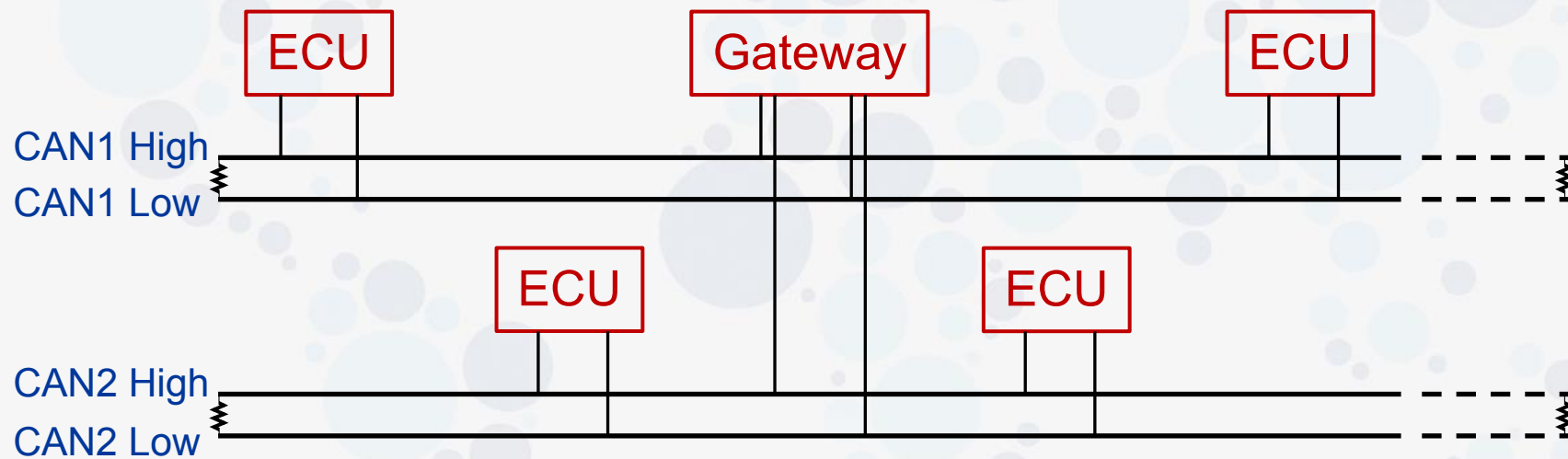
- **Multiple separate buses**
  - Some ECUs have to be connected to multiple buses
  - They can be used to bypass the segmentation



# CAN architectures

- **Multiple interconnected buses**

- A gateway is routing frames between CAN buses
- It may take into account the state of the vehicle
- Both safety and cyber-security are considered



# Crafting CAN attacks

- **Several attack vectors**

- Misuse of intrinsic capabilities (e.g., remote diagnostic tool)
- Exploit a higher-level parsing vulnerability
- Break the Security Access challenge
- Etc.

- **This will imply a substantial amount of work**

- Unsolder EEPROM or identify on-chip debug (JTAG/BDM) and conventional debug (UART/WDBRPC) interfaces
- Extract the firmware
- Reverse-engineer the aforementioned items
- Craft actual attacks

# The Man in the Middle

- **Taking advantage of the client-server model**

- Insert yourself in-between them
- Do not alter traffic until you see something interesting
- Then start to drop/alter/replay/...
- Finalize with targeted reverse-engineering

- **In theory, this is transposable to the CAN bus**

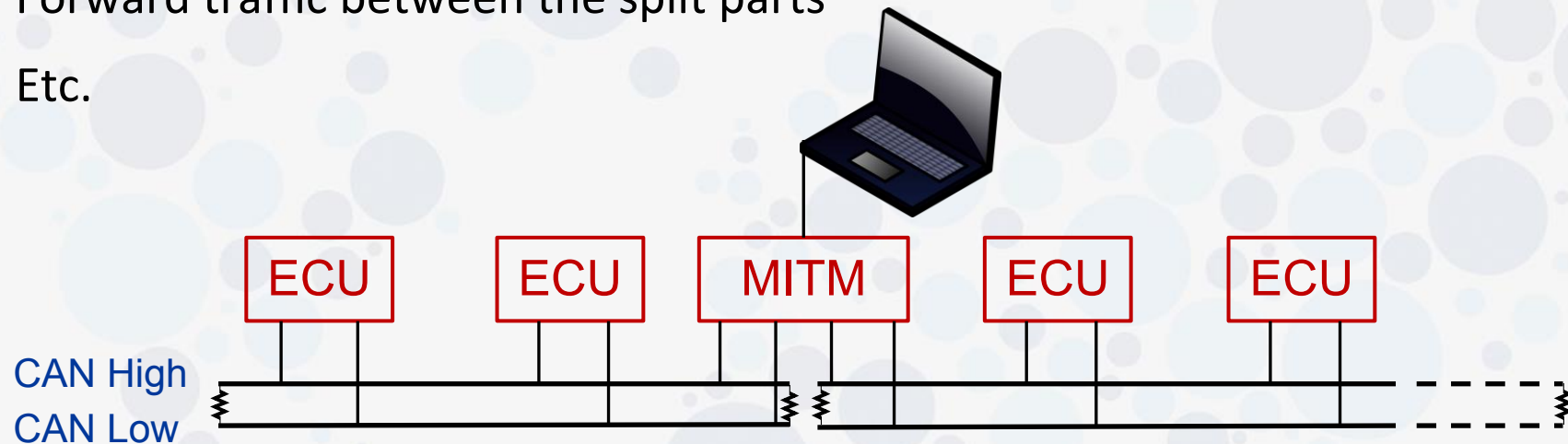
- We are auditing one device
  - We could proxy the traffic from and to that device
- We are working with the car manufacturer
  - We can ask for a restricted devices (e.g., a remote diagnostic tool)
  - This is limited by third-parties intellectual properties



# However, in practice...

- **CAN is a multi-master serial bus**

- Physically cut the bus and insert yourself in-between
- Forward traffic between the split parts
- Etc.



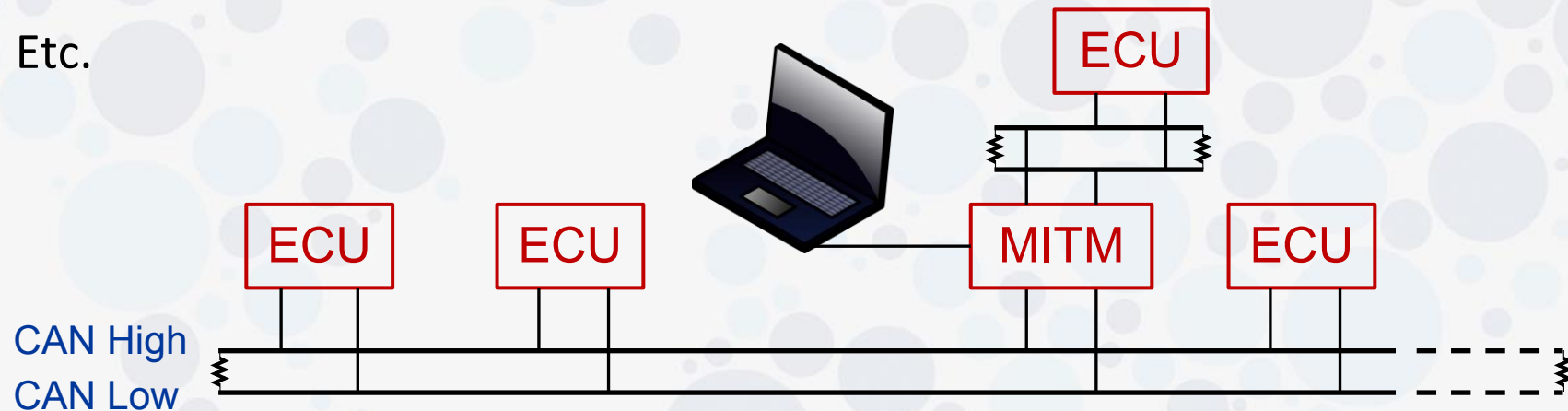
- **2 possible options (other than deep diving into the car)**

- Emulate the car from the point of view of the audited device
- Use an integration bench provided by the car manufacturer

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- **Only one interface to connect to CAN buses**
  - Bridging two devices could add a high latency
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- **Low-end FTDI chip to connect to a computer**
  - This is UART over USB at 115 200 bauds
  - CAN buses can go as far as 1Mbit/s
  - OBD-II is 250 or 500 kbit/s

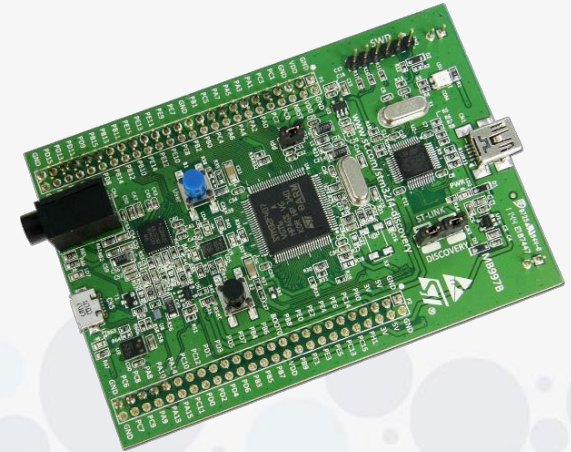


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  - This is UART over USB at 115 200 bauds
  - CAN buses can go as far as 1Mbit/s
  - OBD-II is 250 or 500 kbit/s
- **Lack of a mature and powerful framework**
  - We get frustrated when we cannot use Scapy 😬
  - Federate higher-layers reverse-engineering efforts

# CANSPY hardware

- **STM32F4DISCOVERY board**
  - 168 MHz 32bit ARM Cortex M4
  - COTS (\$20)



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- **STM32F4DIS-BB extension board**
  - 1 RS232 interface
  - 1 Ethernet port
  - 1 SD card drive
  - COTS (\$40)



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  - 168 MHz 32bit ARM Cortex M4
  - COTS (\$20)
- **STM32F4DIS-BB extension board**
  - 1 RS232 interface
  - 1 Ethernet port
  - 1 SD card drive
  - COTS (\$40)
- **DUAL-CAN extension board**
  - Configurable resistors, power supplies and circuit grounds
  - 2 CAN interfaces
  - Custom-made (\$30 worth of PCB and components)





# CANSPY firmware

- **Event-driven scheduler**
  - Asynchronous I/O operations
  - Low latency processing
- **1 functionality == 1 service**
  - Start only what you need
  - Read from all devices, write to only one
  - Inter-service communication
  - Mutual exclusion is possible
- **Autonomous mode**
  - In-built filtering/altering engine
  - SD card for read or write operations
  - Power supply from the car battery
- **Open source licensed**
- **Several services**
  - CAN: Forward/Filter/Inject
  - Ethernet: Wiretap/Bridge
  - SDCard: Capture/Logdump
  - UART: Monitor/Logview/Shell
- **CAN devices**
  - 2 distinct devices
  - Support all standard speeds
  - Throttling mechanisms
    - Dummy frame injection
    - Delaying acknowledgments

# CAN over Ethernet

- **The SocketCAN format**
- **Ethertype 0x88b5**
- **Different MAC addresses**
- **Acknowledgments**

# CAN over Ethernet

- The SocketCAN format
- Ethertype 0x88b5
- Different MAC addresses
- Acknowledgments

```
class SocketCAN(Packet):
    name = "SocketCAN"
    fields_desc = [
        BitEnumField("EFF", 0, 1, {0:"Disabled", 1:"Enabled"}),
        BitEnumField("RTR", 0, 1, {0:"Disabled", 1:"Enabled"}),
        BitEnumField("ERR", 0, 1, {0:"Disabled", 1:"Enabled"}),
        XBitField("id", 1, 29),
        FieldLenField("dlc", None, length_of="data", fmt="B"),
        ByteField("__pad", 0),
        ByteField("__res0", 0),
        ByteField("__res1", 0),
        StrLenField("data", "", length_from = lambda pkt: pkt.dlc),
    ]
    def extract_padding(self, p):
        return "",p

bind_layers(Ether, SocketCAN, type=0x88b5)
```

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- Ethertype 0x88b5
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```
#wireshark -X lua_script:ethcan.lua
```

```
local sll_tab =  
DissectorTable.get("sll.ltype")  
local can_hdl =  
sll_tab.get_dissector(0x000C)  
local eth_tab =  
DissectorTable.get("ethertype")  
eth_tab.add(0x88b5, can_hdl)
```

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class SocketCAN(Packet):  
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    ]  
    def extract_padding(self, p):  
        return "",p  
  
bind_layers(Ether, SocketCAN, type=0x88b5)
```

# The OBD-II use case

- **No need to physically cut anything**
  - Buy a Goodthopter-compatible OBDII-to-DB9 cable
  - Build its female counterpart (\$10 worth of components)
  - Setup the DUAL-CAN extension properly
  - Have fun 😄
- **Several interesting cases**
  - Professional/consumer car diagnostic tools
  - Usage-based policies from insurance companies
  - Air-pollution control from law enforcement
- **They expose sensitive networks/hosts**
- **Demonstration**







# Thank you for your attention