01-09-2016

* GUI
  + Brian, Jin
    - Receive GPS, magnetometer, and science data over UDP.
    - Send motor commands
  + Nathan
    - Receive camera feed with Python
  + Payal, Austin, Faith, Devin
    - Google Maps API
    - Map plotting cooridnates (sprites w/ heading)
  + Ryan, Justin
    - Joysticks (Arm, Drive, Science, Cameras)
    - Intuitive Interface (Connect joysticks button, connect rover button)
* Rover
  + Ahmed
    - Script Motors
    - interface w/ sensors and send over UDP
  + Bryan
    - Interface with GPS & magnetometer. Send over UDP
  + Wendy, Maria, Alan
    - anti-skid w/ potentiometer limiting

01-16-2016

* GUI
  + Brian, Jin
  + Nathan
  + Payal, Austin, Faith, Devin
  + Ryan, Justin
* Rover
  + Ahmed
  + Bryan
  + Wendy, Maria, Alan