

## **QSPI PSRAM**

#### **Specifications**

- Single Supply Voltage
  - o VDD=2.7 to 3.6V
- Interface: SPI/QPI with SDR mode
- Performance: Clock rate up to
  - o 133MHz at VDD=3.0V+/-10%
  - o 109MHz at VDD=3.3V+/-10%
- Organization: 64Mb, 8M x 8bits
- Addressable Bit Range: A[22:0]
- Page Size: 1024 bytes
- Refresh: Self-managed
- Operating Temperature Range:
  - T<sub>OPER</sub> = -40°C to +85°C (standard range)
  - T<sub>OPER</sub> = -40°C to +105°C (extended range)
- Maximum Standby Current:
  - o 350μA @ 105°C
  - 250μA @ 85°C
- Typical Standby Current
  - o 100μA @ 25°C

#### **Features**

- $50\Omega$  Output Drive Strength LVCMOS
- 1K Bytes Wrapped Burst or 32 Bytes Wrapped Burst via toggle command.
- 1K Bytes Wrapped Burst as long as tCEM is met
- Software Reset



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#### 2 Introduction

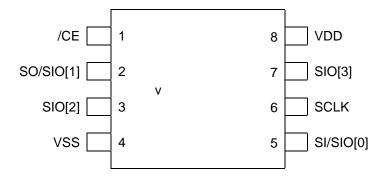
This Pseudo-SRAM device features a high speed, low pin count interface. It has 4 SDR I/O pins and operates in SPI(serial peripheral interface) or QPI (quad peripheral interface) mode with frequencies up to 133 MHz. The data input (A/DQ) to the memory relies on clock (CLK) to latch all instructions, addresses and data. It is most suitable for low-power and low cost portable applications. It incorporates a seamless self-managed refresh mechanism. Hence it does not require the support of DRAM refresh from system host. The self-refresh feature is a special design to maximize performance of memory read operation.



## 3 Package Information

The APS6404L-3SQN is available in standard package including 8-lead SOP-8L(150) and advanced package including 8-lead USON-8L 3x2mm.

## Package Type: SOP/USON (SN, ZR)

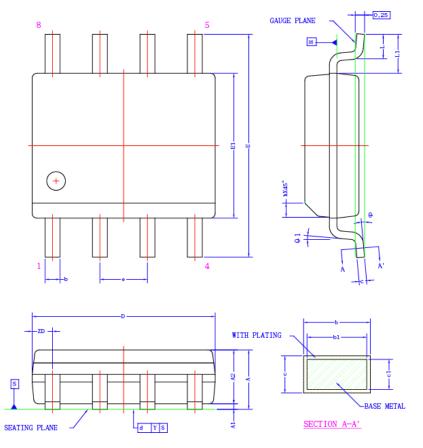


**Top View** 



## 4 Package Outline Drawing

## 4.1 SOP-8L(150), package code SN



	Ι	IMENSION		DIMENSION			
SYMBOL		(MM)		(MIL)			
	MIN.	NOM,	MAX.	MIN.	NOM.	MAX.	
A	1.35	1.60	1.75	53	63	69	
A1	0.10	0.15	0,25	4	6	10	
A2	1.35	1.45	1,55	53	57	61	
ь	0.31	-	0.51	12	-	20	
ь1	0,28	0.40	0.48	11	16	19	
С	0.17	-	0.25	7	-	10	
c1	0.17	0.20	0.23	7	8	9	
D	4.80	4.90	5,00	189	193	197	
E		6.00 BSC		236 BSC			
E1	3.80	3,90	4.00	150	154	157	
е	:	1.27 BSC		50 BSC			
L	0.40	0.66	1.27	16	26	50	
L1		1.05 REF		41 REF			
ZD	1	0.55 REF			22 REF		
h	0.25	0.38	0.50	10	15	20	
Y	-	-	0.10	-	-	4	
0	0"	-	8°	0°	-	8°	
91	0°	-	-	0°	-	-	

#### NOTE :

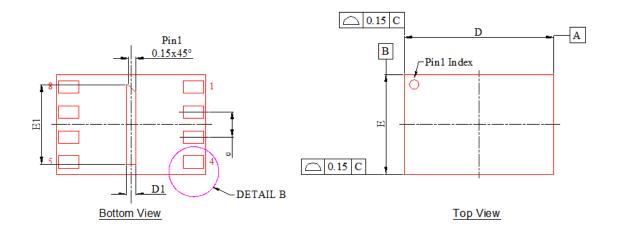
- 1, REFER TO JEDEC STD: MS-012 AA,
- DIMENSION \*D\* DOES NOT INCLUDE WOLD FLASH, PROTRUSION OR GATE BURRS, MOLD FLASH, PROTRUSION AND GATE BURRS SHALL NOT EXCEED 0.15mm PER SIDE,

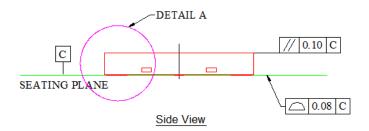
DIMENSION "E1" DOES NOT INCLUDE INTERLEAD WOLD FLASH OR PROTRUSION, INTERLEAD WOLD FLASH OR PROTRUSION SHALL NOT EXCEED 0,25mm PER SIDE.

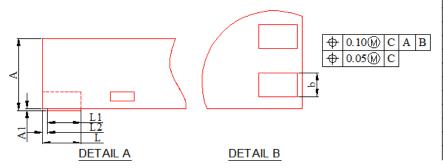
- 'D' AND 'E1' DIMENSIONS ARE DETERMIND AT DATUM H .
- DIMENSION "6" DOES NOT INCLUDE DAMBAR PROTRUSION, ALLOWABLE DAMBAR PROTRUSION SHALL BE 0,10mm TOTAL IN EXCESS OF THE '6" DIMENSION AT MAXIMUM WATERIAL CONDITION,
  - THE DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OF THE POOT,



## 4.2 USON-8L 3x2mm, package code ZR







Symbol	MILLIMETERS					
Symbol	MIN.	NOM.	MAX.			
A	0.40	0.45	0.50			
A1	0.00		0.05			
D	2.90	3.00	3.10			
D1	0.10	0.20	0.30			
E	1.90	2.00	2.10			
E1	1.50	1.60	1.70			
L	0.40	0.45	0.50			
L1	0.30					
L2			0.15			
b	0.20	0.25	0.30			
e	0.50 BSC					

#### NOTE:

- 1. Scale 1:4
- 2. ALL DIMENSIONS AND TOLERANCES TAKE REFERANCE TO JEDEC MO-229
- 3. DIMENSION "b" APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.15MM AND 0.30MM FROM THE TERMINAL TIP. IF THE TERMINAL HAS OPTIONAL RADIUS ON THE OTHER END OF THE TERMINAL, THE DIMENSION B SHOULD NOT BE MEASURED IN THAT RADIUS AREA.



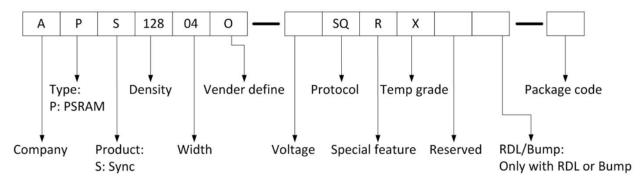
## 5 Ordering Information

**Table 1: Ordering Information** 

Part Number	Temperature Range	Max	Note
APS6404L-3SQN	Tj = -40°C to +85°C	133 MHz*	Bare die, SIP
APS6404L-3SQNX	Tj = -40°C to +105°C	133 MHz*	Bare die, SIP
APS6404L-3SQN-ZR	Tc = -40°C to +85°C	133 MHz*	USON-8
APS6404L-3SQN-SN	Tc = -40°C to +85°C	133 MHz*	SOP-8
APS6404L-3SQNX-SN	Tc = -40°C to +105°C	133 MHz*	SOP-8

Note \*: 133MHz at VDD=3.0V+/-10% 109MHz at VDD=3.3V+/-10%

# IOT\_SQPI\_PN rule





## 6 Signal Table

All signals are listed in Table 2.

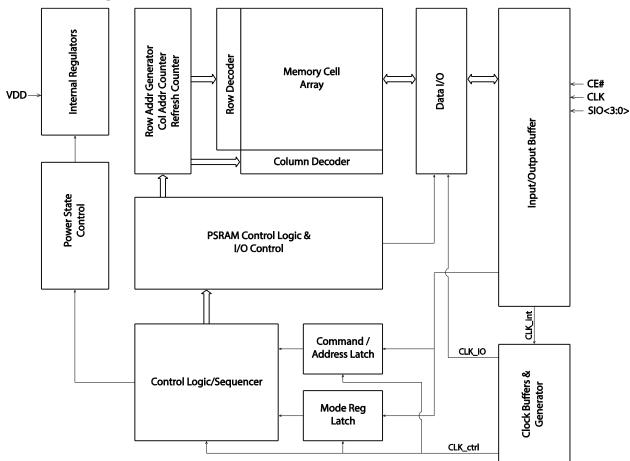
Table 2: Signals Table

Symbol	Туре	SPI Mode	Function	QPI Mode Function	Comments			
VDD	Power		Core sur	pply				
VSS	Ground		Core supply	ground				
CE#	Input	Chip select,	Chip select, active low. When CE#=1, chip is in standby state					
CLK	Input							
SI/SIO[0]	10	Serial Input	IO[0]*	IO[0]* IO[0]				
SO/SIO[1]	Ю	Serial Output	IO[1] *	IO[1] * IO[1]				
SIO[2]	Ю		IO[2]* IO[2]					
SIO[3]	10		IO[3] *	IO[3]				

Note \*: SPI Quad mode



## 7 Block Diagram





#### 8 Power-Up Initialization

SPI/QPI products include an on-chip voltage sensor used to start the self-initialization process. When VDD reaches a stable level at or above minimum VDD, the device will require 150µs and user-issued RESET Operation (see section 14) to complete its self-initialization process. From the beginning of power ramp to the end of the 150µs period, CLK should remain LOW, CE# should remain HIGH (track VDD within 200mV) and SI/SO/SIO[3:0] should remain LOW.

After the Device Reset tRST≥50ns period the device is ready for normal operation.

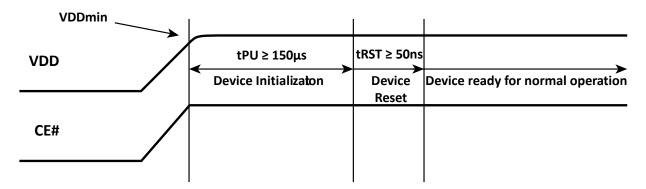


Figure 1. Power-Up Initialization Timing



## 9 Interface Description

#### 9.1 Address Space

SPI/QPI PSRAM device is byte-addressable. 64M device is addressed with A[22:0].

#### 9.2 Page Size

Page size is 1K (CA[9:0]). The device operates in a bursting address sequence back to starting address of same page in a wrap manner.

#### 9.3 Drive Strength

The device powers up in  $50\Omega$ .

#### 9.4 Power-on Status

The device powers up in SPI Mode. It is required to have CE# high before beginning any operations.

#### 9.5 Command/Address Latching Truth Table

The device recognizes the following commands specified by the various input methods.

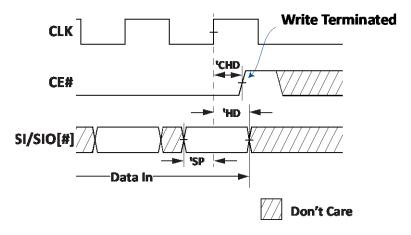
	SPI Mode (QE=0)			QPI Mode (QE=1)							
Command	Code	Cmd	Addr	Wait Cycle	DIO	Max Freq.	Cmd	Addr	Wait Cycle	DIO	Max Freq.
Read	'h03	S	S	0	S	33			N/A		
Fast Read	'h0B	S	S	8	S	133*	Q	Q	4	Q	66
Fast Read Quad	'hEB	S	Q	6	Q	133*	Q	Q	6	Q	133*
Write	'h02	S	S	0	S	133*	Q	Q	0	Q	133*
Quad Write	'h38	S	Q	0	α	133*	same as 'h02				
Enter Quad Mode	'h35	S	-	-	-	133	N/A				
Exit Quad Mode	'hF5			N/A			Q	ı	-	-	133
Reset Enable	'h66	S	-	-	-	133	Q	-	-	-	133
Reset	'h99	S	-	-	-	133	Q	-	-	-	133
Wrap Boundary Toggle	'hC0	S	-	-	-	133	Q		133		
Read ID	'h9F	S	S	0	S	33	N/A				
Remark: S = Serial IO, Q = Quad IO											

Note \*: Max Freq. would be 133MHz at VDD=3.0V+/-10% and 109MHz at VDD= 3.3V+/-10%)



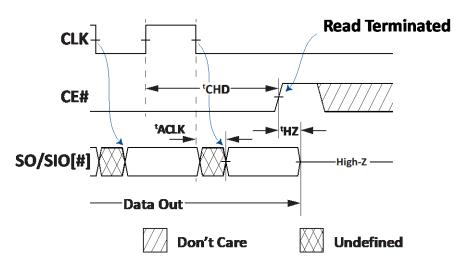
#### 9.6 Command Termination

All Reads & Writes must be completed by raising CE# high immediately afterwards in order to terminate the active command and set the device into standby. Not doing so will block internal refresh operations and cause memory failure.



**Figure 2: Write Command Termination** 

For a memory controller to correctly latch the last piece of data prior to read termination, it is recommended to provide a longer CE# hold time (tCHD > tACLK+tCLK) for a sufficient data window.



**Figure 3: Read Command Termination** 



## 10 Wrap Boundary Toggle Operation

The Wrap Boundary Toggle Operation switches the device's wrapped boundary between 1K Bytes Wrapped Burst or 32 Bytes Wrapped Burst. Note that the default setting is 1K Bytes Wrapped.

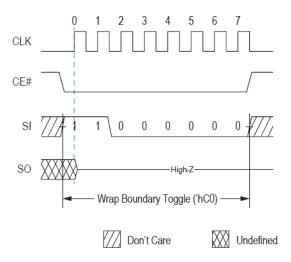


Figure 4: SPI Wrap Boundary Toggle 'hC0

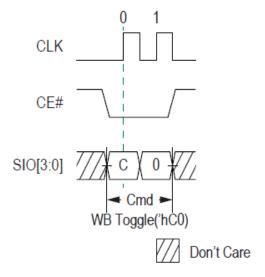


Figure 5: QPI Wrap Boundary Toggle 'hCO



## 11 SPI Mode Operations

The device powers up into SPI mode by default but can also be switched into QPI mode.

## 11.1 SPI Read Operations

For all reads, data will be available <sup>t</sup>ACLK after the falling edge of CLK.

SPI Reads can be done in three ways:

- 1. 'h03: Serial CMD, Serial Addr/IO, slow frequency.
- 2. 'hOB: Serial CMD, Serial Addr/IO, fast frequency.
- 3. 'hEB: Serial CMD, Quad Addr/IO, fast frequency.

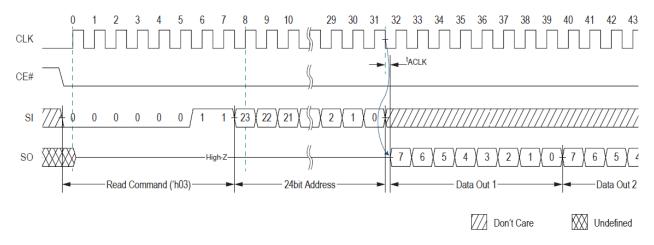


Figure 6: SPI Read 'h03 (max freq 33MHz)

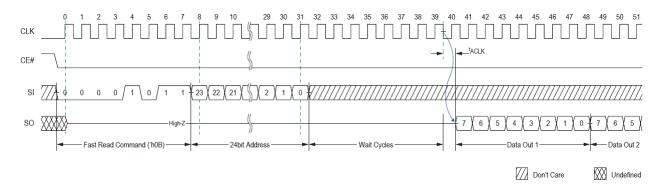


Figure 7: SPI Fast Read 'h0B (max freq 133 MHz)

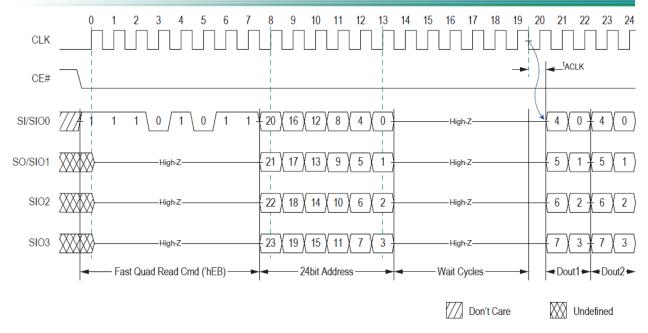


Figure 8: SPI Fast Quad Read 'hEB (max freq 133 MHz)



## 11.2 SPI Write Operations

SPI write command can be input as 'h02 or 'h38.

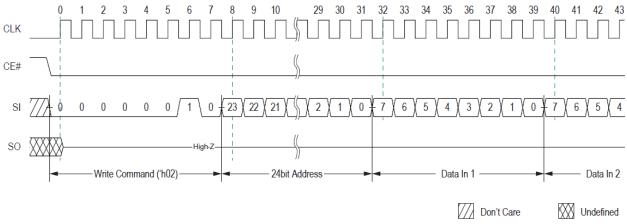


Figure 9: SPI Write 'h02

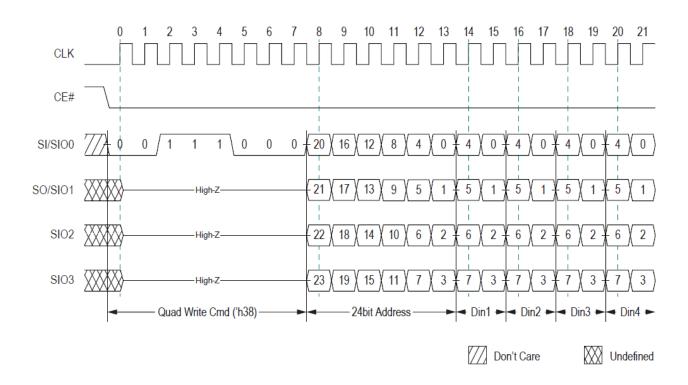


Figure 10: SPI Quad Write 'h38



## 11.3 SPI Quad Mode Enable Operation

This command switches the device into quad IO mode.

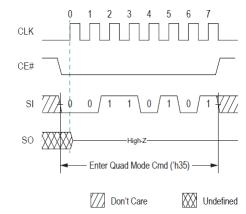


Figure 11: Quad Mode Enable 'h35 (available only in SPI mode)



#### 12 Read ID

Read ID command provides information of vendor ID, known-good-die, device density, and manufacturing ID. Note that Read ID command can be used ONLY as Power up initialization after the device Reset tRST ≥ 50ns right after Global Reset command.



Figure 12: Pre-condition of EID Read

#### 12.1 SPI Read ID Operation

This command is similar to Fast Read, but without the wait cycles and the device outputs EID value instead of data.

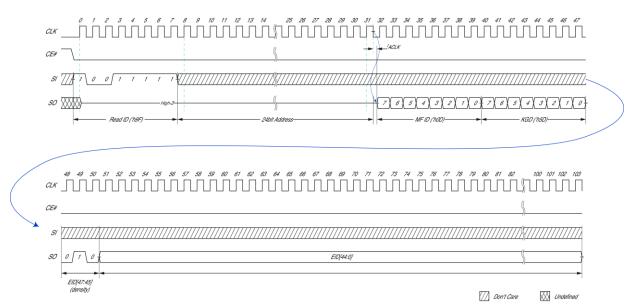


Figure 13: SPI Read ID 'h9F (available only in SPI mode)

Table 3: Known Good Die (KGD)

KGD[7:0]	Known Good Die
'b0101_0101	FAIL
'b0101_1101	PASS

<sup>\*</sup>Note: Default is FAIL die, and only mark PASS after all tests passed.



#### 13 QPI Mode Operations

#### 13.1 QPI Read Operation

For all reads, data will be available <sup>t</sup>ACLK after the falling edge of CLK.

QPI Reads can be done in one of two ways:

- 1. 'hOB: Quad CMD, Quad Addr/IO, slow frequency
- 2. 'hEB: Quad CMD, Quad Addr/IO, fast frequency

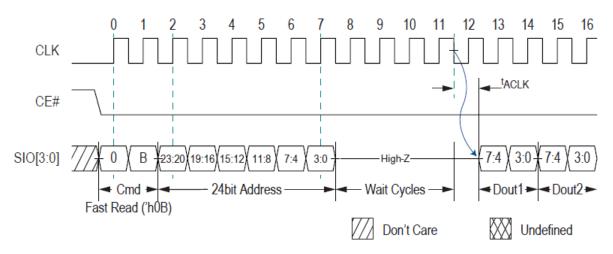


Figure 14: QPI Fast Read 'h0B (max freq 66 MHz)

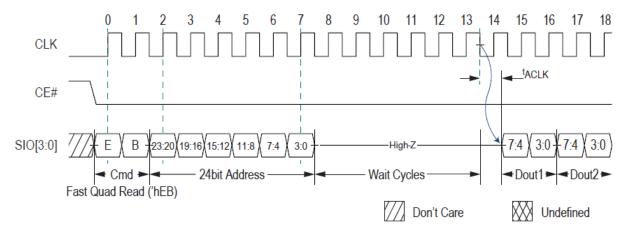


Figure 15: QPI Fast Quad Read 'hEB (max freq 133 MHz)



## 13.2 QPI Write Operation(s)

QPI write command can be input as 'h02 or 'h38.

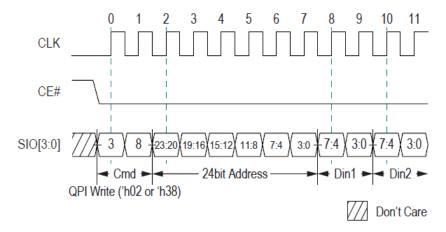


Figure 16: QPI Write 'h02 or 'h38

#### 13.3 QPI Quad Mode Exit operation

This command will switch the device back into serial IO mode.

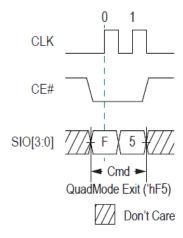


Figure 17: Quad Mode Exit 'hF5 (only available in QPI mode)



#### 14 Reset Operation

The Reset operation is used as a system (software) reset that puts the device in SPI standby mode which is also the default mode after power-up. This operation consists of two commands: Reset-Enable (RSTEN) and Reset (RST).

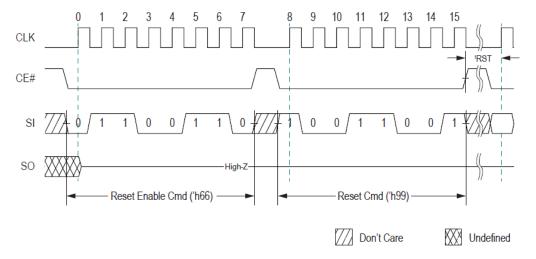


Figure 18: SPI Reset

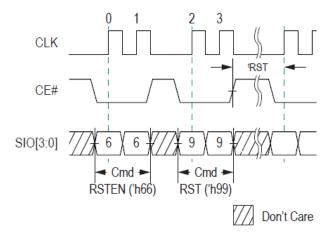


Figure 19: QPI Reset

Reset command has to immediately follow the Reset-Enable command in order for the reset operation to take effect. Any command other than the Reset command after the Reset-Enable command will cause the device to exit Reset-Enable state and abandon reset operation.



## 15 Input/Output Timing

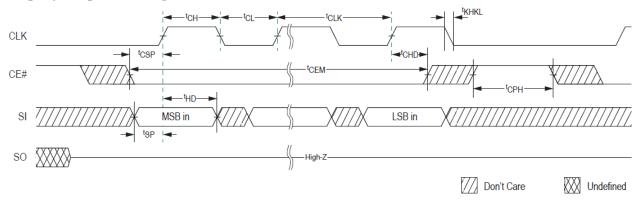


Figure 20: Input Timing

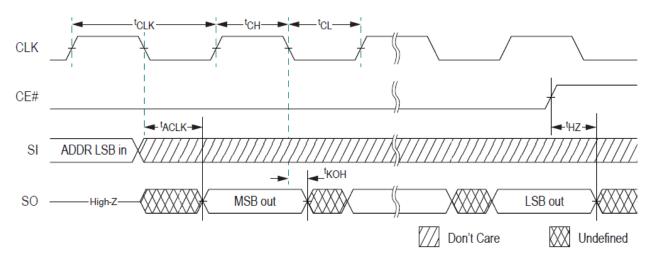


Figure 21: Output Timing



## **16 Electrical Specifications:**

#### 16.1 Absolute Maximum Ratings

**Table 4: Absolute Maximum Ratings** 

Parameter	Symbol	Rating	Unit	Notes
Voltage to any ball except V <sub>DD</sub> relative to V <sub>SS</sub>	VT	-0.4 to V <sub>DD</sub> +0.4	V	
Voltage on V <sub>DD</sub> supply relative to V <sub>SS</sub>	$V_{DD}$	-0.4 to +4.0	V	2
Storage Temperature	T <sub>STG</sub>	-55 to +150	°C	1

Notes 1: Storage temperature refers to the case surface temperature on the center/top side of the PSRAM.

Notes 2: During voltage transitions, all pins may overshoot to -0.5V or VCC+0.5V for period up to 20ns.

#### Caution:

Exposing the device to stress above those listed in Absolute Maximum Ratings could cause permanent damage. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

#### 16.2 Pin Capacitance

**Table 5: Bare Die Pin Capacitance** 

Parameter	Symbol	Min	Max	Unit	Notes
Input Pin Capacitance	CIN		2	pF	VIN=0V
Output Pin Capacitance	COUT		3	pF	VOUT=0V

Note: spec'd at 25°C.

**Table 6: Package Pin Capacitance** 

Parameter	Symbol	Min	Max	Unit	Notes
Input Pin Capacitance	CIN		6	pF	VIN=0V
Output Pin Capacitance	COUT		8	pF	VOUT=0V

Note: spec'd at 25°C.

**Table 7: Load Capacitance** 

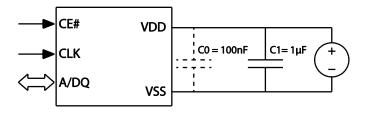
Parameter	Symbol	Min	Max	Unit	Notes
Load Capacitance	$C_L$		15	pF	

Note: System C<sub>L</sub> for the use of package



## 16.3 Decoupling Capacitor Requirement

It is required to have a decoupling capacitor on VDD pin for IO switchings and psram internal transient events. A low ESR  $1\mu$ F ceramic cap is recommended. To minimize parasitic inductance, place the cap as close to VDD pin as possible. An optional  $0.1\mu$ F can further improve high frequency transient response.



## 16.4 Operating Conditions

**Table 8: Operating Characteristics** 

Parameter	Min	Max	Unit	Notes
Operating Temperature (extended)	-40	105	°C	
Operating Temperature (standard)	-40	85	°C	



## 16.5 DC Characteristics

**Table 9: DC Characteristics** 

Symbol	Parameter	Min	Max	Unit	Notes
V <sub>DD</sub>	Supply Voltage	2.7	3.6	V	
V <sub>IH</sub>	Input high voltage	V <sub>DD</sub> -0.4	V <sub>DD</sub> +0.2	V	
VIL	Input low voltage	put low voltage -0.2			
V <sub>OH</sub>	Output high voltage (I <sub>OH</sub> =-0.2mA)	0.8 V <sub>DD</sub>		V	
V <sub>OL</sub>	Output low voltage (IoL=+0.2mA)		0.2 V <sub>DD</sub>	V	
lu	Input leakage current		1	μΑ	
I <sub>LO</sub>	Output leakage current		1	μΑ	
Icc	Read/Write		7	mA	1,2
ISB <sub>EXT</sub>	Standby current (105C)		350	μΑ	3
ISB <sub>STD</sub>	Standby current (85C)		250	μΑ	3

Note 1: Output load current not included.

- 2. 50% bus toggling rate.
- 3. Standby current is measured when CLK is in DC low state.
- 4. Typical ISB<sub>STDroom</sub> 100uA



#### 16.6 AC Characteristics

Table 5: READ/WRITE Timing

Symbol	Parameter	Min	Max	Unit	Notes	
	CLK period - SPI Read ('h03)	30.3			33MHz	
	CLK period - QPI Read ('h0B)	15.1			66MHz	
<sup>t</sup> CLK	CLK period - all other operations PKG 3V	7.5		ns	133MHz*1,2,3	
CER	CLK period - all other operations PKG 3.3V	9.17			109MHz*2,3	
tCH/tCL	Clock high/low width	0.45	0.55	<sup>t</sup> CLK(min)		
tKHKL	CLK rise or fall time		1.5	ns	4	
<sup>t</sup> CPH	CE# HIGH between subsequent burst	18		ns		
	operations					
<sup>t</sup> CEM	CE# low pulse width		3	μs	Extended grade	
			8		Standard grade	
<sup>t</sup> CSP	CE# setup time to CLK rising edge PKG	2.5		ns		
<sup>t</sup> CHD	CE# hold time from CLK rising edge PKG	3.0		ns 2		
<sup>t</sup> SP	Setup time to active CLK edge	2		ns		
tHD	Hold time from active CLK edge	2		ns		
tHZ	Chip disable to DQ output high-Z		5.5	ns		
<sup>t</sup> ACLK	CLK to output delay	2	5.5	ns		
<sup>t</sup> KOH	Data hold time from clock falling edge	1.5		ns		
<sup>t</sup> RST	Time between end of RST CMD to next	50		ns		
	valid CMD					

Note

- 1: Frequency limits are therefore 133MHz (PKG VDD= 3.3V+-10%) max for Wrap 32 Bytes.
- 2: System max  $C_L$  15pF for the use of package.
- 3: For operating frequencies >84MHz, it is highly recommended to utilize CLK falling edge to sample read data or align sampling clock via data pattern tuning (refer to JEDEC JESD84-B50 for an example).
- 4: Measured from 20% to 80% of VDD



## 17 Change Log

Version		Date	Description
1.0		Jul 13, 2017	Initial Version
1.1		Jul 25, 2017	Revised package code and ordering information
1.2		Aug 24, 2017	Corrected package code; Added system max C <sub>L</sub> for the use of package & related tCK and tCHD
1.3		Sep 04, 2017	Added ISBstdroom
1.5		Oct 30, 2017	Enabled QPI Read 'h0B support; changed Min/Max absolute voltage, Vil_min and Vih_max,; defined tCEM for different temperature grade; corrected speed typo. Added USON package ZR
1.6		Nov 13, 2017	Modified spec of ICC & ISB
1.7		Mar 19, 2018	Revised part# of RBX. Temperature -40C
1.8		Jan 07, 2019	Remove WSON and updated POD of USON, add tRST
1.9		Sep 06, 2019	Updated Figure 10, Table 7 and Table 9; added table for Change Log; updated section 9.5 and 16.6; added section 16.3
2.0a		Oct 02, 2019	Updated header, page 1 and Table 1
2.1		Oct 25, 2019	Revised the typo in Page 15, 20 and Table 5; Updated Figure 18 and Figure 19; add section 10
2.2		Nov 21, 2019	Update Table 2, Figure 10 and Figure
2.3		Apr 30, 2020	Modify VDD's description of Table 2
2.4		Oct 12, 2021	Revised tCEM value from 4us to 3us @105C
2.5	Kim/ Gene/ Eric	Jun 17, 2022	Typos correct
2.6	Kim	Oct 28, 2022	Release USON temp. from -25~85 to -40~85