

Sebastian Zapata

Houston, TX | (832) 205-4992 | sebzafo@gmail.com | www.linkedin.com/in/sebastian-zapata-15317727b

EDUCATION

University of Texas at Austin, B.S., Electrical and Computer Engineering, Present - May 2027 | GPA: 4.0
Relevant Courses: **E&M**, Mechanics, Multivariable Calculus, Diff eq., Linear Alg., EE, Computing

SKILLS & CERTIFICATIONS

Technical Skills:

- **Hardware: PCB Design** (KiCad), Circuit Design, Signal Processing, **Power** Electronics
- **CAD Software: SolidWorks**, Autodesk Inventor, Fusion360, Onshape
- **Programming:** Proficient in **C**, **Java**

Languages: English (Native), Spanish (Fluent)

Areas: Circuit Design, Firmware Development, Embedded Systems, PCB Design, Testing and Validation

Certifications: AutoDesk Inventor, AutoCAD

Awards: 2024 **HSF Scholar**, FRC Robotics 2023 **State Champion**, SkillsUSA **3rd in Texas**, Vex Robotics **State Semifinalist**

TECHNICAL EXPERIENCE

FSAE Longhorn Racing Electric | *Electronics and Power Systems* UT | August 2024 – Present

- Designing **Power** and control electronics for the Electric Formula car of UT Austin, competing internationally in May
- Designed circuit schematics for Vehicle Control Unit and Wheel speed boards ensuring correct part specifications and board functionality
- Laid out and assembled Vehicle Control Unit (VCU) and Wheel Speed PCBs using KiCad, minimizing **crosstalk** and **signal degradation**, and allowed for 40A+ to be safely delivered to other boards.
- Developed **low level firmware** for the VCU, utilizing torque mapping
- Led **testing and validation** of experimental boards, including CAN bootloading, Flex PCBs, and speaker amplification, utilizing **oscilloscopes**, multimeters and various debugging tools.

Texas Aerial Robotics | *Electronics and CAD Member* UT | August 2024 – Present

- Fully Designed a large lightweight, printable, waterproof, and autonomous octocopter in CAD and collaborated to design a self-landing **vector controlled** mono-copter
- Collaborated to design circuit schematics for the **flight controller** of the self-landing “dart” mono-copter

GW Robotics (FRC) | *Technical Design Lead* Katy | June 2023 – May 2024

- Designed a top-performing robot at the FRC World Championship, leading to selection by the reigning **World Champions** despite operating with less than 20% of the funding of respective top teams.
- Debugged and troubleshot **CAN bus** and **PID** setup and implementation, reducing electrical failure rate to 0, and accelerating competition play by 10%.
- Co-led the design of three complete 125 lb competition robots using CAD software, optimizing space and financial constraints, winning several regional and state competitions
- Designed our first-ever arm, climb, and **PID** shooter mechanisms and swerve drive system
- Led CNC and Manufacturing systems ensuring manufacturability and packaging feasibility of CAD design

High-Speed RC Car Personal Project | *Lead Designer and Manufacturer* June 2024 – Present

- Developed custom **RF transmitter** and receiver connecting user to **ESC module**
- Designed a high-speed 3D printed RC Car with open **differential**, suspension, and **high torque** steering systems
- Designed with durability and practicality of assembly to allow for a top speed of **70 mph**

SkillsUSA | *Additive Manufacturing Competitor* Katy | August 2022 – May 2023

- Designed a 3D printed computer mouse tailored to users with trans-radial amputations creating a financially viable solution
- Finished 3rd place out of 150+ teams in the Texas State SkillsUSA competition

LEADERSHIP EXPERIENCE

GW Robotics (FRC) | *Strategy Officer/ Driver/ Drive Coach* Katy | August 2022 – May 2024

- Led team and alliance strategy optimizing match performance and collaboration, defeating several top 10 teams in Texas
- Trained and coached 20 underclassmen in driving and robotics strategy, contributing to a 300% increase in student involvement and driving prospects for future seasons.
- Designed and implemented a data-driven scouting system that improved team performance through better match preparation and analysis.