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Outline

- What is ML?
 - ML – Why, What and When?
- Types of Machine Learning
 - Supervised learning
 - Unsupervised learning
 - Semi-supervised learning
 - Reinforcement learning
- Supervised Learning with Linear Regression
- Designing a Learning System

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ML – Why?

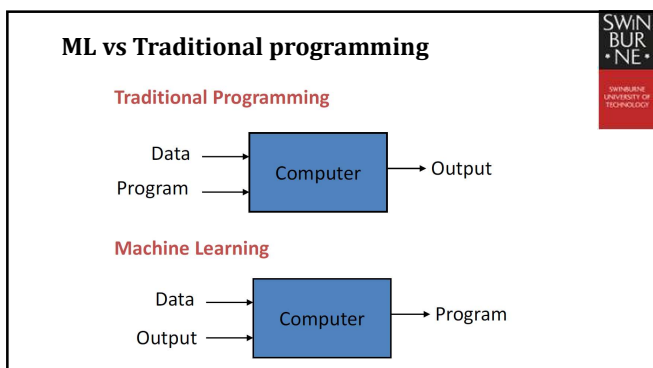
- Big data
 - Large datasets from growth of automation/web. E.g., Web click data, medical records, biology, engineering
- Applications can't program by hand.
 - E.g., Autonomous helicopter, handwriting recognition, most of Natural Language Processing (NLP), Computer Vision.
- Self-customizing programs
 - E.g., Amazon, Netflix product recommendations
- Understanding human learning (brain, real AI).

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ML – What?

- “Learning is any process by which a system improves performance from experience.” - **Herbert Simon**
- “Learning Problem: A computer program is said to learn from **experience E** with respect to some **task T** and some **performance measure P**, if its performance on **T**, as measured by **P**, improves with experience **E**.” - **Tom Mitchell (1998)**

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ML – When to Use Machine Learning??

- Human expertise does not exist (navigating on Mars)
- Humans can't explain their expertise (speech recognition)
- Models must be customized (personalized medicine)
- Models are based on huge amounts of data (genomics)

Learning isn't always useful:

- There is no need to “learn” to calculate payroll

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A classic example of a task that requires machine learning:
It is very hard to say what makes a 2

Slide credit: Geoffrey Hinton

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ML - Examples

- **Recognizing patterns:**
 - Facial identities or facial expressions
 - Handwritten or spoken words
 - Medical images
- **Generating patterns:**
 - Generating images or motion sequences
- **Recognizing anomalies:**
 - Unusual credit card transactions
 - Unusual patterns of sensor readings in a nuclear power plant
- **Prediction:**
 - Future stock prices or currency exchange rates

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State of the Art Applications of Machine Learning

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Autonomous Car Technology

Images and movies taken from Sebastian Thrun's multimedia website

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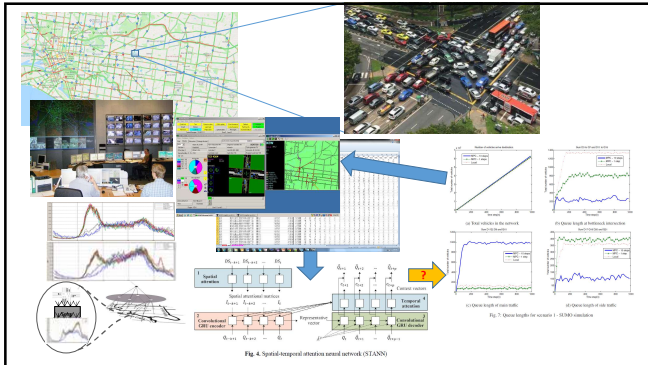
Scene Labeling via Deep Learning

[Farabet et al. ICML 2012, PAMI 2013]

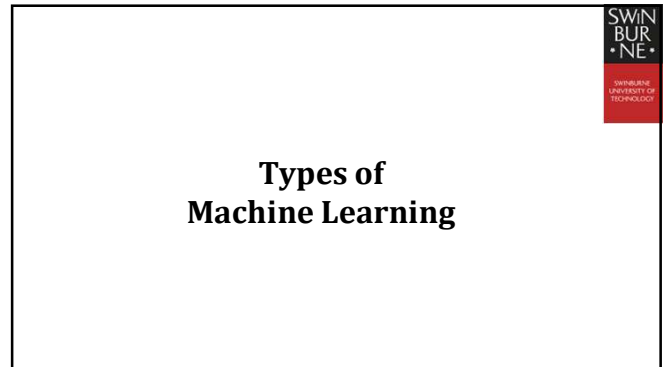
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AI & ML @Swinburne

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Types of Learning

- Supervised (inductive) learning
 - Given: training data + desired outputs (labels)
- Unsupervised learning
 - Given: training data (without desired outputs)
- Semi-supervised learning
 - Given: training data + a few desired outputs
- Reinforcement learning
 - Rewards from sequence of actions

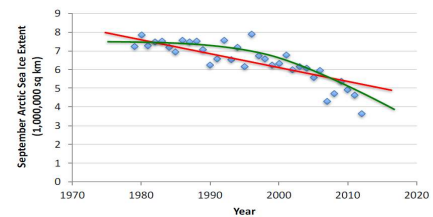
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Supervised Learning: Regression

Given $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$

- Learn a function $f(x)$ to predict y given x

– y is real-valued == regression



Data from G. Witt, Journal of Statistics Education, Volume 21, Number 1 (2013)

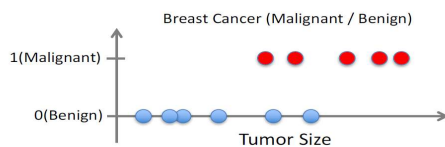
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Supervised Learning: Classification

Given $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$

- Learn a function $f(x)$ to predict y given x

– y is categorical == classification



Based on example by Andrew Ng

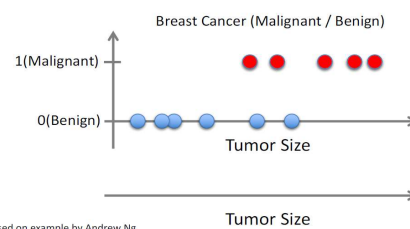
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Supervised Learning: Classification

Given $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$

- Learn a function $f(x)$ to predict y given x

– y is categorical == classification



Based on example by Andrew Ng

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Supervised Learning: Classification

Given $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$

- Learn a function $f(x)$ to predict y given x
- y is categorical \Rightarrow **classification**

Based on example by Andrew Ng

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Unsupervised Learning

Given x_1, x_2, \dots, x_n (without labels)

- Output hidden structure behind the x 's
- E.g., clustering

E.g., <https://news.google.com> uses clustering

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Reinforcement Learning

Given a sequence of states and actions with (delayed) rewards, output a **policy**

- Policy is a mapping from states \rightarrow actions that tells you what to do in a given state

Examples:

- Credit assignment problem
- Game playing
- Robot in a maze
- Balance a pole on your hand

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The Agent-Environment Interface

Agent and environment interact at discrete time steps $t = 0, 1, 2, K$

Agent observes state at step t : $s_t \in S$

produces action at step t : $a_t \in A(s_t)$

gets resulting reward: $r_{t+1} \in \mathbb{R}$

and resulting next state: s_{t+1}

Slide credit: Sutton & Barto

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Reinforcement Learning

Learn policy from user demonstrations

Stanford Autonomous Helicopter
<http://heli.stanford.edu/>

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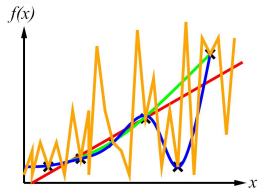
Inductive Learning (Science)

- Simplest form: learn a function from examples
 - A target function: g
 - Examples: input-output pairs $(x, g(x))$
 - E.g. x is an email and $g(x)$ is spam / ham
 - E.g. x is a house and $g(x)$ is its selling price
- Problem:
 - Given a hypothesis space H
 - Given a training set of examples X_i
 - Find a hypothesis $h(x)$ such that $h \sim g$
- Includes:
 - Classification (outputs = class labels)
 - Regression (outputs = real numbers)

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Inductive Learning

- Curve fitting (regression, function approximation):



- Consistency vs. simplicity
- Ockham's razor

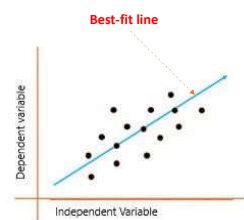
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Supervised Learning with Linear Regression

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Linear Regression (LR)

- A statistical regression method used for predictive analysis
- LR shows the linear relationship between the independent (predictor) variable i.e. X-axis and the dependent (output) variable i.e. Y-axis



Source:
<https://www.analyticsvidhya.com/blog/2021/10/everything-you-need-to-know-about-linear-regression/>

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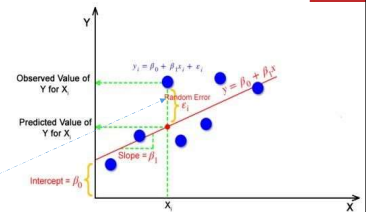
Linear Regression (LR)

- How to compute the **best-fit line**?

$$y = h_{\beta}(x) = \beta_0 + \beta_1 x, \text{ where:}$$

- y = Dependent variable,
- x = Independent variable,
- β_0 = constant/Intercept,
- β_1 = Slope.

For each training example (x_i, y_i) , we can compute the **random error** (or, **residual**) $\epsilon_i = y_{\text{predicted}} - y_i$ where $y_{\text{predicted}} = h_{\beta}(x_i) = \beta_0 + \beta_1 x_i$



Source:
<https://www.analyticsvidhya.com/blog/2021/10/everything-you-need-to-know-about-linear-regression/>

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Linear Regression (LR) - Best-fit Line

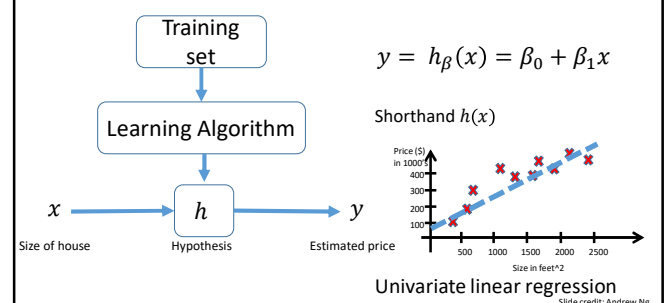
- What is the best fit line, i.e., what are the best values for β_0 and β_1 ?
- Cost Function:**
 - Measuring the error a given line $y = h_{\beta}(x) = \beta_0 + \beta_1 x$ has with respect to a set of training examples $\{(x_1, y_1), \dots, (x_n, y_n)\}$
 - For instance, the **Mean Squared Error (MSE)** cost function:

$$MSE = \frac{1}{n} \sum_{i=1}^n (y_i - (\beta_0 + \beta_1 x_i))^2$$

- The line $y = h_{\beta}(x) = \beta_0 + \beta_1 x$ is "best fit" if MSE is minimised

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Model representation



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• **Hypothesis:** $h_{\beta}(x) = \beta_0 + \beta_1 x$

• **Parameters:** β_0, β_1

• **Cost function:** $J(\beta_0, \beta_1) = \frac{1}{n} \sum_{i=1}^n (h_{\beta}(x_i) - y_i)^2$

• **Goal:** minimize $J(\beta_0, \beta_1)$
 β_0, β_1

Slide credit: Andrew Ng

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Gradient descent

Have some function $J(\beta_0, \beta_1)$

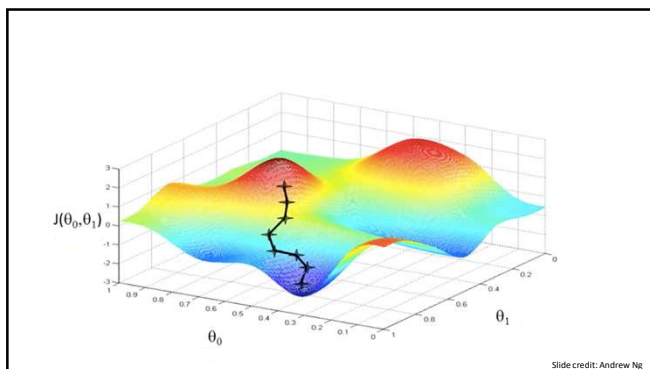
Want $\underset{\beta_0, \beta_1}{\operatorname{argmin}} J(\beta_0, \beta_1)$

Outline:

- Start with some β_0, β_1
- Keep changing β_0, β_1 to reduce $J(\beta_0, \beta_1)$ until we hopefully end up at minimum

Slide credit: Andrew Ng

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Slide credit: Andrew Ng

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Gradient descent

Repeat until convergence {

$$\beta_j := \beta_j - \alpha \frac{\partial}{\partial \beta_j} J(\beta_0, \beta_1) \quad (\text{for } j = 0 \text{ and } j = 1)$$

}

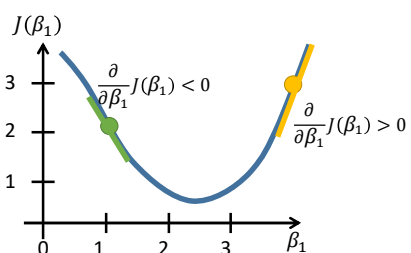
α : Learning rate (step size)

$\frac{\partial}{\partial \beta_j} J(\beta_0, \beta_1)$: derivative (rate of change)

Slide credit: Andrew Ng

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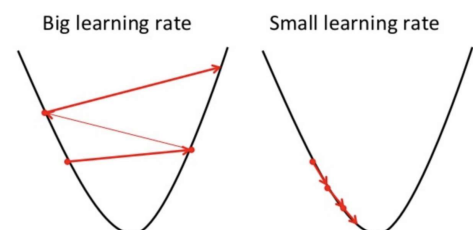
$$\beta_1 := \beta_1 - \alpha \frac{\partial}{\partial \beta_1} J(\beta_1)$$



Slide credit: Andrew Ng

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Learning rate



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Gradient descent for linear regression

Repeat until convergence{

$$\beta_j := \beta_j - \alpha \frac{\partial}{\partial \beta_j} J(\beta_0, \beta_1) \quad (\text{for } j = 0 \text{ and } j = 1)$$

}

• Linear regression model

$$h_{\beta}(x) = \beta_0 + \beta_1 x$$

$$J(\beta_0, \beta_1) = \frac{1}{n} \sum_{i=1}^n (h_{\beta}(x_i) - y_i)^2$$

Slide credit: Andrew Ng

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Computing partial derivative

$$\begin{aligned} \frac{\partial}{\partial \beta_j} J(\beta_0, \beta_1) &= \frac{\partial}{\partial \beta_j} \frac{1}{n} \sum_{i=1}^n (h_{\beta}(x_i) - y_i)^2 \\ &= \frac{\partial}{\partial \beta_j} \frac{1}{n} \sum_{i=1}^n (\beta_0 + \beta_1 x_i - y_i)^2 \end{aligned}$$

$$j = 0: \frac{\partial}{\partial \beta_0} J(\beta_0, \beta_1) = \frac{2}{n} \sum_{i=1}^n (h_{\beta}(x_i) - y_i)$$

$$j = 1: \frac{\partial}{\partial \beta_1} J(\beta_0, \beta_1) = \frac{2}{n} \sum_{i=1}^n (h_{\beta}(x_i) - y_i) x_i$$

Slide credit: Andrew Ng

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Gradient descent for linear regression

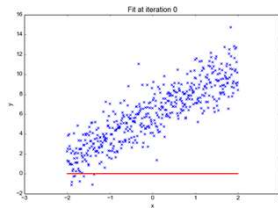
Repeat until convergence {

$$\beta_0 := \beta_0 - \alpha \frac{2}{n} \sum_{i=1}^n (h_{\beta}(x_i) - y_i)$$

$$\beta_1 := \beta_1 - \alpha \frac{2}{n} \sum_{i=1}^n (h_{\beta}(x_i) - y_i) x_i$$

}

Update β_0 and β_1 simultaneously



Slide credit: Andrew Ng

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Regression: How to

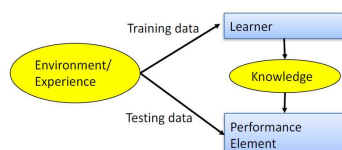
- So, do I have to write a program to calculate the “right” values of **a** and **b** to “minimize” the errors?
- And, how about multi-dimensional datasets?
- Short answer: **Just use an existing library!**
 - E.g., **scikit-learn** (see: <https://scikit-learn.org/stable/>)
 - E.g., **tensorflow** (see: <https://www.tensorflow.org/>)



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Designing a Learning System

- Choose the training experience
- Choose exactly what is to be learned – i.e. the **target function**
- Choose how to **represent** the target function
- Choose a **learning algorithm** to infer the target function from the experience



Based on slide by Ray Mooney



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ML in a Nutshell

- Tens of thousands of machine learning algorithms
 - Hundreds new every year
- Every ML algorithm has three components:
 - **Representation**
 - **Optimization**
 - **Evaluation**



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Various Function Representations

- Numerical functions
 - Linear regression
 - Neural networks
 - Support vector machines
- Symbolic functions
 - Decision trees
 - Rules in propositional logic
 - Rules in first-order predicate logic
- Instance-based functions
 - Nearest-neighbor
 - Case-based
- Probabilistic Graphical Models
 - Naïve Bayes
 - Bayesian networks
 - Hidden-Markov Models (HMMs)
 - Probabilistic Context Free Grammars (PCFGs)
 - Markov networks



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Various Search/Optimization Algorithms

- Gradient descent
 - Perceptron
 - Backpropagation
- Dynamic Programming
 - HMM Learning
 - PCFG Learning
- Divide and Conquer
 - Decision tree induction
 - Rule learning
- Evolutionary Computation
 - Genetic Algorithms (GAs)
 - Genetic Programming (GP)
 - Neuro-evolution



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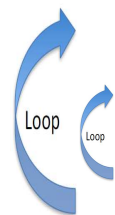
Evaluation

- Accuracy
- Precision and recall
- Squared error
- Likelihood
- Posterior probability
- Cost / Utility
- Margin
- Entropy
- K-L divergence
- etc.



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ML in Practice



- Understand domain, prior knowledge, and goals
- Data gathering, data integration, selection, cleaning, pre-processing, etc.
- Learn models
 - Model Selection
 - Model Training
 - Model Evaluation
- Interpret results
 - Hyperparameter tuning
- Consolidate and deploy discovered knowledge



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Summary

- Learning can be viewed as using **direct or indirect experience** to approximate a chosen **target function**.
- Function approximation can be viewed as a **search** through a space of **hypotheses** (representations of functions) for one that best fits a set of training data.
- Different learning methods assume different hypothesis spaces (representation languages) and/or employ different search techniques.



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ML for a practitioner

- If you:
 - Are a beginner
 - Need quick results
 - Dataset is simple (small and well-structured, e.g. a CSV file)
- Then consider Weka (<https://www.cs.waikato.ac.nz/ml/weka/>)
 - GUI
 - Easy to use



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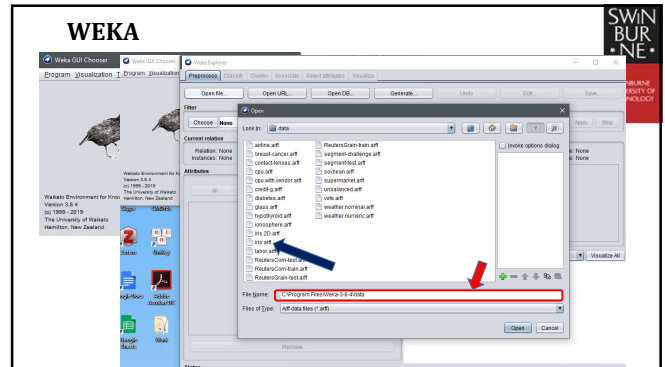
Some resources to get started with WEKA

<https://www.analyticsvidhya.com/learning-paths-data-science-business-analytics-business-intelligence-big-data/weka-gui-learn-machine-learning/>

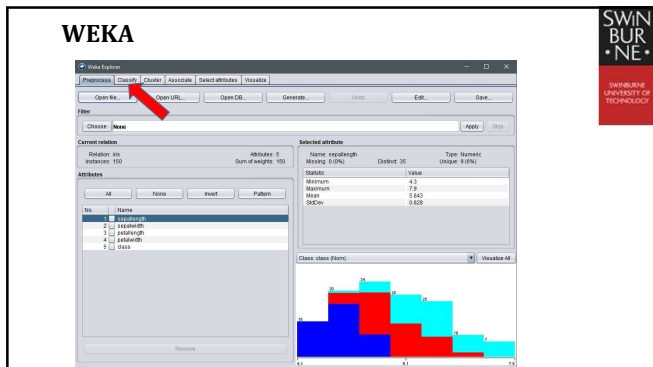
https://www.cs.waikato.ac.nz/ml/weka/Witten_et_al_2016_appendix.pdf



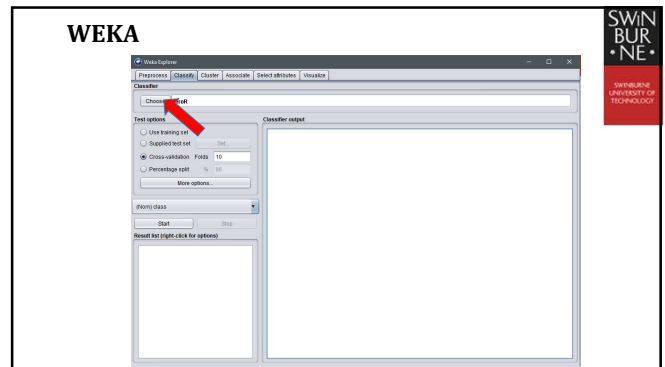
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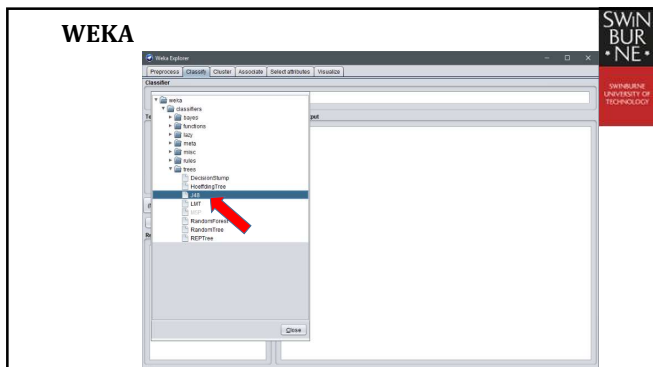
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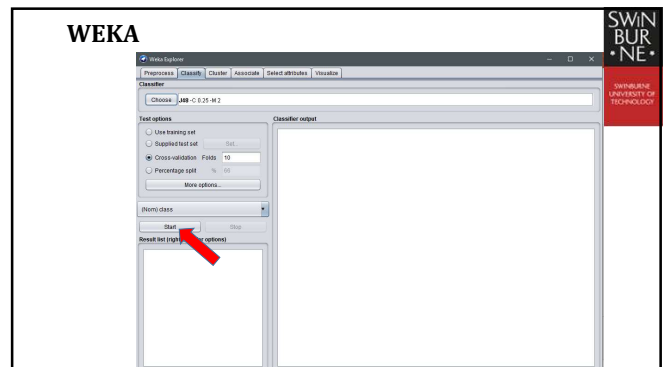
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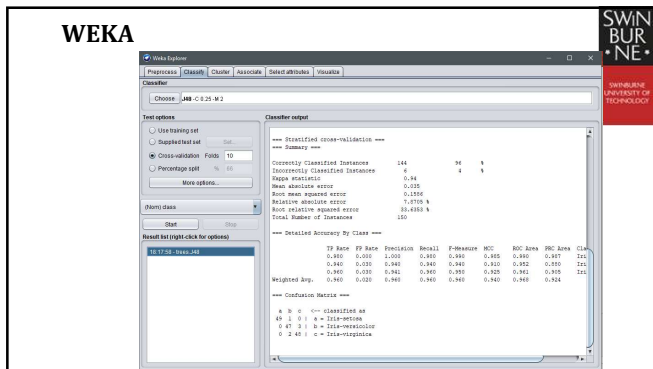
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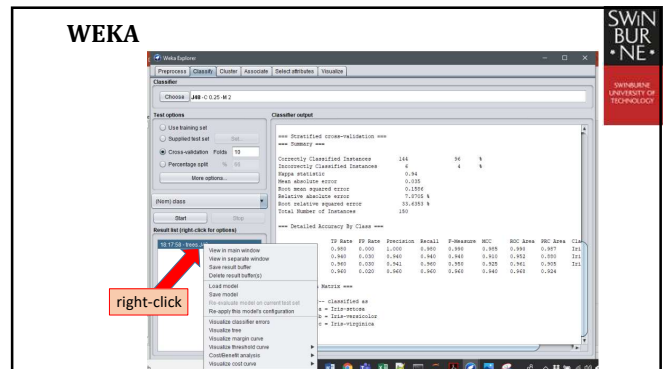
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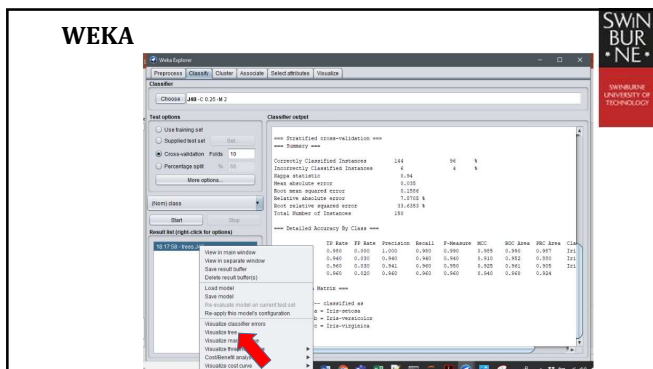
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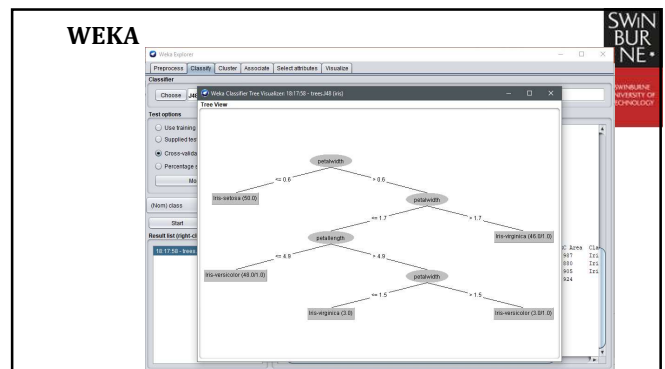
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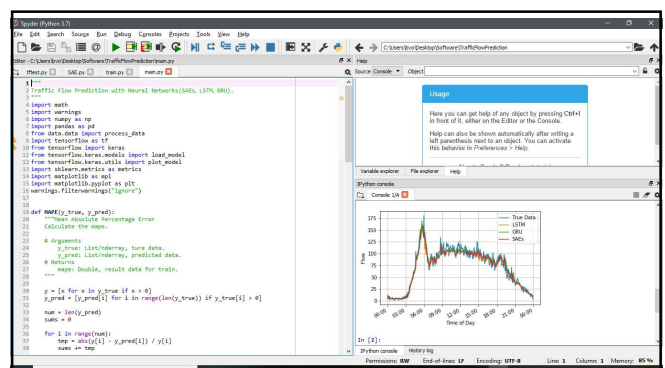


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ML for a practitioner

- If you:
 - Are really serious about ML
 - Are ready to spend substantial amount of time to learn
 - Datasets can be really complex/noisy
- Then it's time to move on to a more serious tools:
 - R, python
 - Needs programming, application integration, libraries (tensorflow, pytorch, numpy, scikit-learn, etc.)!

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