

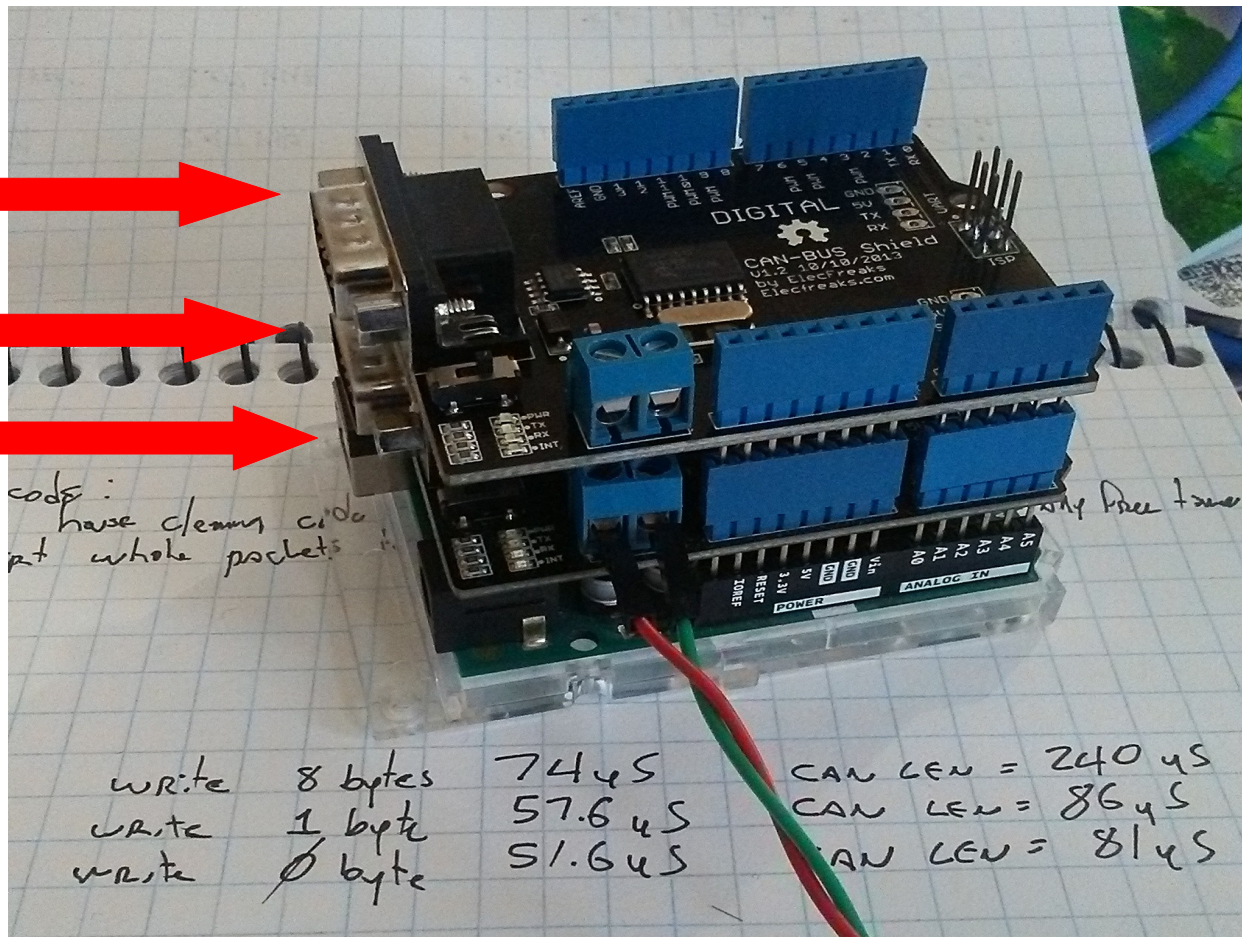
CAN0

CAN1

Arduino Uno  
Serial 1E6 BAUD

DB9 Connectors

- 1 - GND
- 2 - GND
- 3 - CANH
- 4 -
- 5 - CANL
- 6 -
- 7 -
- 8 -
- 9 - +12V in



CAN0 (Top)

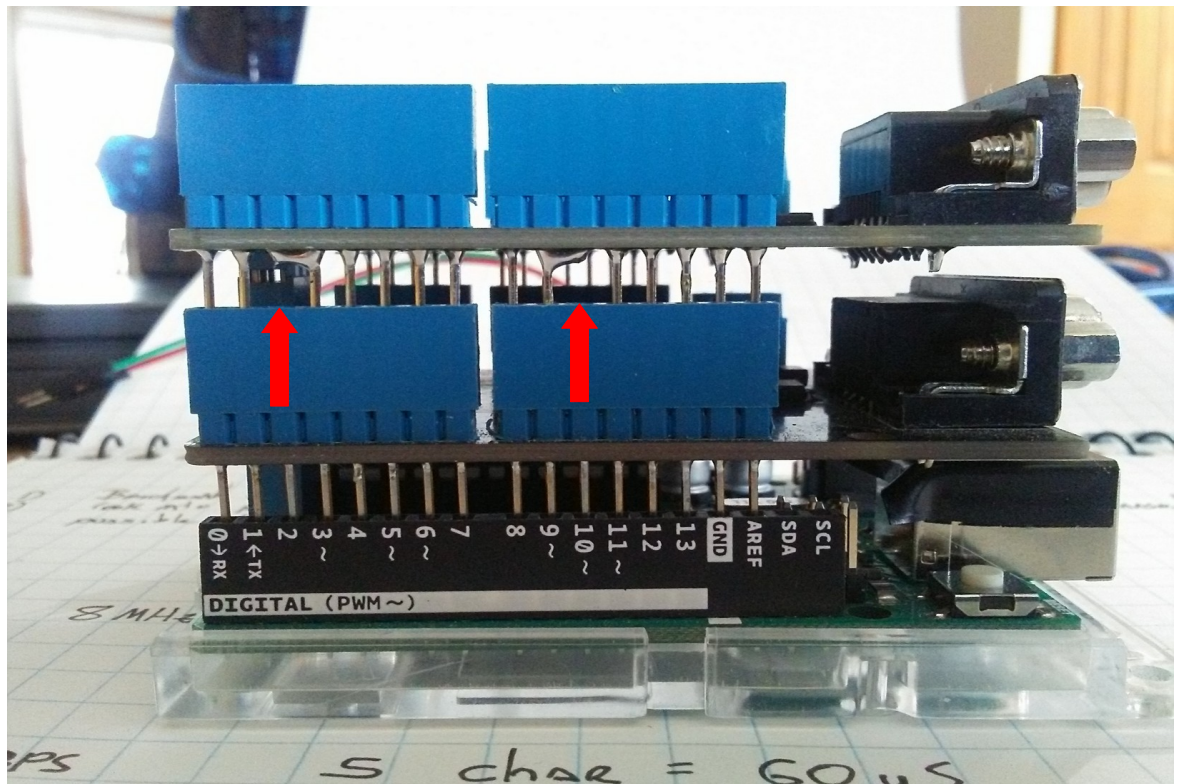
CS - Arduino Pin 9  
INT - Arduino Pin 3  
(Note clipped pins  
and solder bridges)

CAN1 (Bottom)

CS - Arduino Pin 10  
INT - Arduino Pin 2

CAN Modules:  
CAN-BUS Shield  
V1.2 10/10/2013  
By: ElecFreaks  
ElecFreaks.com

Sourced from: Amazon  
Cost: ~\$16.00 each



## **CANBUS Bridge Settings**

Notes:

1. Settings are updated by sending single char values to serial port.
2. Setting are saved to the Arduino EEPROM.

### **3 output modes available for each CAN channel:**

- 1 = CAN0 no output
- 2 = CAN0 Source, CAN ID
- 3 = CAN0 Source, CAN ID, Packet Data

- A = CAN1 no output
- B = CAN1 Source, CAN ID
- C = CAN1 Source, CAN ID, Packet Data

Note: Outputting packet data when the CAN speeds are over 125K will slow down CAN packet transfers. It is recommended to only show the source and CAN ID over 125K. Outputting packet data will cause the RX buffers to overrun in high traffic situations.

#### **Output Mode 1, B:**

Source – CAN ID (HEX)

- Source 0, 1, 2 = CAN0, number = transmit buffer
- Source 4 = no transmit buffers available
- Source 5 = invalid ID
- Source 6 = invalid length

- Source A, B, C = CAN1, number = transmit buffer
- Source E = no transmit buffers available
- Source F = invalid ID
- Source G = invalid length

#### **Output Mode 2, C:**

Source – CAN ID (HEX) – Packet Data (HEX)

- Source 0, 1, 2 = CAN0, number = transmit buffer
- Source 4 = no transmit buffers available
- Source 5 = invalid ID
- Source 6 = invalid length

- Source A, B, C = CAN1, number = transmit buffer
- Source E = no transmit buffers available
- Source F = invalid ID
- Source G = invalid length

Note: monitor the output buffer, using 2 or more output buffers is an indication of high amounts of traffic

### **Changing CAN speeds:**

- 6 = CAN0,1 80Kbps
- 7 = CAN0,1 83.333Kbps
- 8 = CAN0,1 125Kbps
- 9 = CAN0,1 500Kbps



Example data from a 2008 Dodge Durango radio on CAN0, BCM simulator on CAN1. Settings = 73C.

7 = 83.333Kbps

3 = CAN0 Source, CAN ID, Packet Data

C = CAN1 Source, CAN ID, Packet Data

SRC	ID	B0	B1	B2	B3	B4	B5	B6	B7
A	000	41	00	00	00	00	00		
A	015	55	79	06	FF	00	00		
A	1AF	03	83	00	C0	10	2C	08	00
A	210	02	C8	00	00	00	00		
A	3EC	09	29	2D					
0	3D0	07	0A	0A	0F	0A	0B	FF	
0	3AE	1D	30	00	00	1D	30	00	00
0	3A5	00	FF	FF	FF	00	FF	FF	FF
0	326	00	00	01	0F	07	00	00	00
0	190	01	0D	05	00	10	00	07	
0	18C	00	03	89	21	00	FF	FF	FF
0	0F0	00	00	00	00				
0	416	FC	16	3F	FF	FF	FF	FF	FF
A	000	41	00	00	00	00	00		
A	015	55	79	06	FF	00	00		
A	1AF	03	83	00	C0	10	2C	08	00
A	210	02	C8	00	00	00	00		
A	3EC	09	29	2E					
0	3D0	07	0A	0A	0F	0A	0B	FF	
0	3AE	1D	30	00	00	1D	30	00	00
0	3A5	00	FF	FF	FF	00	FF	FF	FF
0	326	00	00	01	0F	07	00	00	00
0	190	01	0D	05	00	10	00	07	
0	18C	00	03	89	21	00	FF	FF	FF
0	0F0	00	00	00	00				
0	416	FC	16	3F	FF	FF	FF	FF	FF

Note: A DB9 breakout board makes connecting cables to the CAN1 board easier.

Sourced from Amazon

