# T03 Planning and Uncertainty

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#### 1 Situation Calculus

```
(a) \forall s \forall o \ at(o, l1, s) \rightarrow \neg at(o, l2, s)
(b)s_0 : \neg lightOn(s_0) \land at(b_1, r_2, s_0) \land at(b_2, r_3, s_0) \land at(shakey, r_1, s_0) \land adj(r_1, r_2) \land adj(r_2, r_3)
                  goal: \exists s \ lightOn(s) \land at(b_1, r_1, s) \land at(b_2, r_2, s)
(c) walkTo(loc_1, loc_2):
                  \forall s \ at(shakey, loc_1, s) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(walkto(loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, loc_2, loc_2, 
                  at(shakey, loc_2, do(walkto(loc_1, loc_2), s))
                  push(box, loc_1, loc_2):
                  \forall s \ at(shakey, loc_1, s) \land at(box, loc_1, s) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(push(box, loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(push(box, loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(push(box, loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(push(box, loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(push(box, loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(push(box, loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, do(push(box, loc_1, loc_2), s)) \land adj(loc_1, loc_2) \rightarrow \neg at(shakey, loc_1, loc_2) \rightarrow \neg at(shakey, loc_2, loc_2, loc_2) \rightarrow \neg at(shakey, loc_2, loc_2, loc_2, loc_2) \rightarrow \neg at(shakey, loc_2, lo
                    \neg at(box, loc_1, do(push(box, loc_1, loc_2), s)) \land at(shakey, loc_2, do(push(box, loc_1, loc_2), s))
                  \land at(box, loc_2, do(push(box, loc_1, loc_2), s))
                  turnOn:
                  \forall s \ at(shakey, r_1, s) \land at(b_1, r_1, s) \land at(b_2, r_2, s) \rightarrow lightOn(do(turnOn, s))
(d) 1.\neg lightOn(S_0)
                  2.at(b_1, r_2, S_0)
                  3.at(b_2, r_3, S_0)
                  4.at(shakey, r_1, S_0)
                  5.adj(r_1, r_2)
                  6.adj(r_2,r_3)
                  7.(\neg at(shakey, loc_1, S), \neg adj(loc_1, loc_2), \neg at(shakey, loc_1, do(walkingto(loc_1, loc_2), S)))
                  8.(\neg at(shakey, loc_1, S), \neg adj(loc_1, loc_2), \neg at(shakey, loc_2, do(walkingto(loc_1, loc_2), S)))
                  9.(\neg at(shakey, loc_1, S), \neg at(box, loc_1, S), \neg loc_1, loc_2, \neg at(shakey, loc_1, do(pushing(box, loc_1, loc_2), S)))
                    10.(\neg at(shakey, loc_1, S), \neg at(box, loc_1, S), \neg loc_1, loc_2, \neg at(box, loc_1, do(pushing(box, loc_1, loc_2), S))))
                   11.(\neg at(shakey, loc_1, S), \neg at(box, loc_1, S), \neg loc_1, loc_2, at(shakey, loc_2, do(pushing(box, loc_1, loc_2), S)))
                   12.(\neg at(shakey, loc_1, S), \neg at(box, loc_1, S), \neg loc_1, loc_2, at(box, loc_2, do(pushing(box, loc_1, loc_2), S)))
                   13.(\neg at(shakey, r_1, S), \neg at(b_1, r_1, S), \neg at(b_2, r_2, S), lightOn(do(turnOn, S)))
                    14.(\neg lightOn(z), ans(z))
                    先后令 z = do(turnOn, S), 令 S = do(push(b_1, r_2, r_1, S)), S = do(push(b_2, r_3, r_2, S)), s =
                  do(walkto(r_2, r_3), S), s = do(walkto(r_1, r_2, S), S = S_0, 可归结得到:
                  ans(do(turnOn, do(push(b_1, r_2, r_1), do(push(b_2, r_3, r_2), do(walkto(r_2, r_3), do(walkto(r_1, r_2, S_0))))))
```

### 2 STRIPS and Reachability Analysis

```
(a) KB = \{clear(p2), clear(p3), clear(d1), on(d1, d2), on(d2, d3), on(d3, p1)\}
                        move(x, a, b)
                        Pre: \{on(x, a), clear(x), clear(b), smaller(x, b)\}
                         Add: \{on(x,b), clear(a)\}
                         Dels: \{on(x, a), clear(b)\}
                        moveTwo(x, y, a, b)
                        Pre: \{on(x, y), on(y, a), clear(x), clear(b), smaller(y, b)\}
                        Add: \{on(y,b), clear(a)\}
                        Dels: \{on(y, a), clear(b)\}
                        Goal = \{on(d3, p3), clear(p1), clear(p2), on(d1, d2), on(d2, d3), clear(d1)\}
(b) S_0 = \{clear(p_2), clear(p_3), clear(d_1), on(d_1, d_2), on(d_2, d_3), on(d_3, p_1)\}
                        A_0 = \{move(d_1, d_2, p_2), move(d_1, d_2, p_3), moveTwo(d_1, d_2, d_3, p_2), moveTwo(d_1, d_2, d_3, p_3)\}
                        S_1 = \{clear(p_2), clear(p_3), clear(d_1), on(d_1, d_2), on(d_2, d_3), on(d_3, p_1), on(d_1, p_2), clear(d_2), on(d_1, p_3)\}
                          , on(d_2, p_2), clear(d_3), on(d_2, p_3) \}
                        G = \{on(d3, p3), clear(d3), clear(p2), on(d1, d2), on(d2, d3), clear(d1)\}
                        G_N = \{clear(d3)\}
                        G_P = \{on(d_2, d_3), clear(p_2), on(d_1, d_2), clear(d_1)\}\
                         A = \{moveTwo(d_1, d_2, d_3, p_2)\}\
                        CountAction(G, S_1) = 1 + CountAction(G, S_0)
                        A_1 = \{move(d_1, d_2, p_2), move(d_1, d_2, p_3), moveTwo(d_1, d_2, d_3, p_2), moveTwo(d_1, d_2, d_3, p_3), move(d_1, d_2, d_3), moveTwo(d_1, d_3, d_
                        move(d_2, d_3, p_2), move(d_2, d_3, p_3), move(d_3, p_1, p_2), move(d_3, p_1, p_3), move(d_1, p_2, d_2), move(d_1, p_2, d_3), move(d_2, d_3, p_3), move(d_3, p_1, p_3), move(d_
                        move(d_1, p_2, p_3), move(d_1, p_3, p_2), move(d_1, p_3, d_2), move(d_1, p_3, d_3), move(d_2, p_2, d_3), move(d_2, p_2, p_3), move(d_2, p_2, p_3), move(d_3, p_3, d_3), move(d_
                        move(d_2, p_3, p_2), move(d_1, p_3, d_3), moveTwo(d_2, d_3, p_1, p_2), moveTwo(d_2, d_3, p_1, p_3)
```

$$S_{2} = \{clear(p_{1}), clear(p_{2}), clear(p_{3}), clear(d_{1}), clear(d_{2}), clear(d_{3}), on(d_{1}, d_{2}), on(d_{2}, d_{3}), on(d_{1}, p_{1}), on(d_{1}, p_{2}), on(d_{1}, p_{3}), on(d_{2}, p_{1}), on(d_{2}, p_{2}), (d_{2}, p_{3}), on(d_{3}, p_{1}), on(d_{3}, p_{2}), on(d_{3}, p_{3}), \}$$

$$G = \{on(d_{3}, p_{3}), clear(d_{3}), clear(p_{2}), on(d_{1}, d_{2}), on(d_{2}, p_{3}), clear(d_{1})\}$$

$$G_{N} = \{on(d_{3}, p_{3})\}$$

$$G_{P} = \{clear(d_{3})\}$$

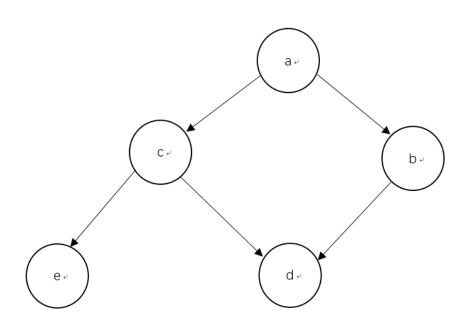
$$A = \{move(d_{3}, p_{1}, p_{3})\}$$

$$CountAction(G, S_{2}) = 1 + CountAction(G, S_{1}) = 2$$

# 3 Bayesian Networks

1.

(a)



(b) 通过链式法则,有:

$$p(a,c,e)=p(e|a,c)p(c|a)p(a)$$
  
由独立假设,得: 
$$p(a,c,e)=p(e|c)p(c|a)p(a)$$

(c) 
$$P(a, b, c | \neg d, e) = 0.009$$
  
 $P(a, b, \neg c | \neg d, e) = 0.006$ 

$$P(a, \neg b, c | \neg d, e) = 0.048$$

$$P(a, \neg b, \neg c | \neg d, e) = 0.048$$

$$P(\neg a, b, c | \neg d, e) = 0.003$$

$$P(\neg a, b, \neg c | \neg d, e) = 0.003$$

$$P(\neg a, \neg b, c | \neg d, e) = 0.065$$

$$P(\neg a, \neg b, \neg c | \neg d, e) = 0.819$$

(d)由(c)可知,

$$P(a|\neg d, e) = P(a, b, c|\neg d, e) + P(a, b, \neg c|\neg d, e) + P(a, \neg b, c|\neg d, e) + P(a, \neg b, \neg c|\neg d, e) = 0.111 < 0.2$$

故,当一名学生没有奖学金,但是在同学之中受欢迎时,他沉迷游戏的概率下降。

2.

#### (a) $relevant \ variables : A, B, C, E$

 $elimination \ order: A, B, C, E$ 

Step1: Compute & Add 
$$f_1(b,c) = \sum_a f(a)f(a,b,c)$$

Remove: f(a), f(a, b, c)

Step2: Compute & Add 
$$f_2(c) = \sum_b f(b) f_1(b, c)$$

 $Remove: f(b), f_1(b, c)$ 

Step3: Compute & Add 
$$f_3(e) = \sum_c f_2(c) f(c, e)$$

 $Remove: f_2(c), f(c, e)$ 

$$P(e) = 0.5032$$

#### (b) Restriction : replace f(c, f) with $f_4(C) = f(c, \neg f)$

Step 1 and Step 2 are the same as part(a)

Step3: Compute & Add 
$$f_3(e) = \sum_c f_2(c) f_4(c) f(c, e)$$

*Remove* :  $f_2(c), f_4(c), f(c, e)$ 

$$P(e|\neg(f)) = 0.6912$$