



Computer Graphics

# Rendering Pipeline

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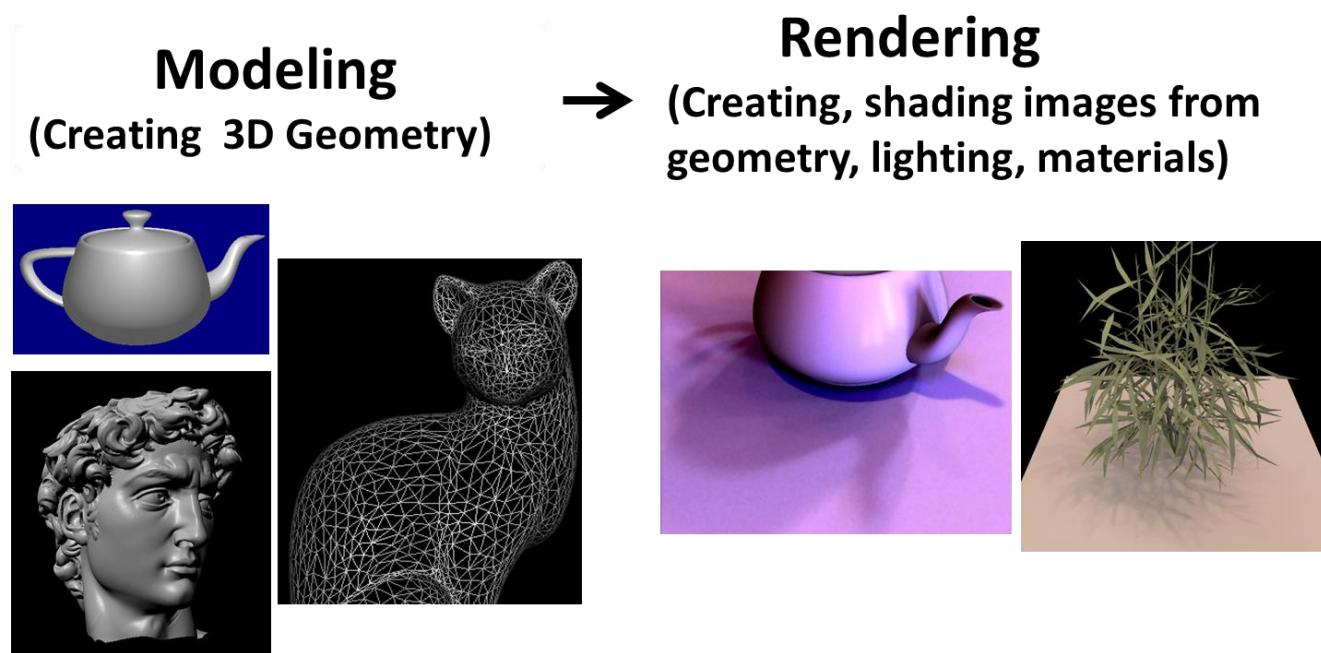
School of Data and Computer Science



# Outline

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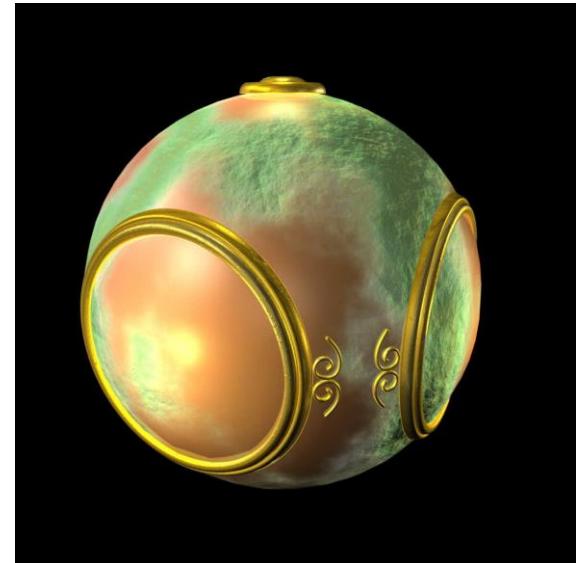
- **Computer Graphics System**
- Physical Imaging System
- Graphics Rendering Pipeline



# Example

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- Where did these images come from?



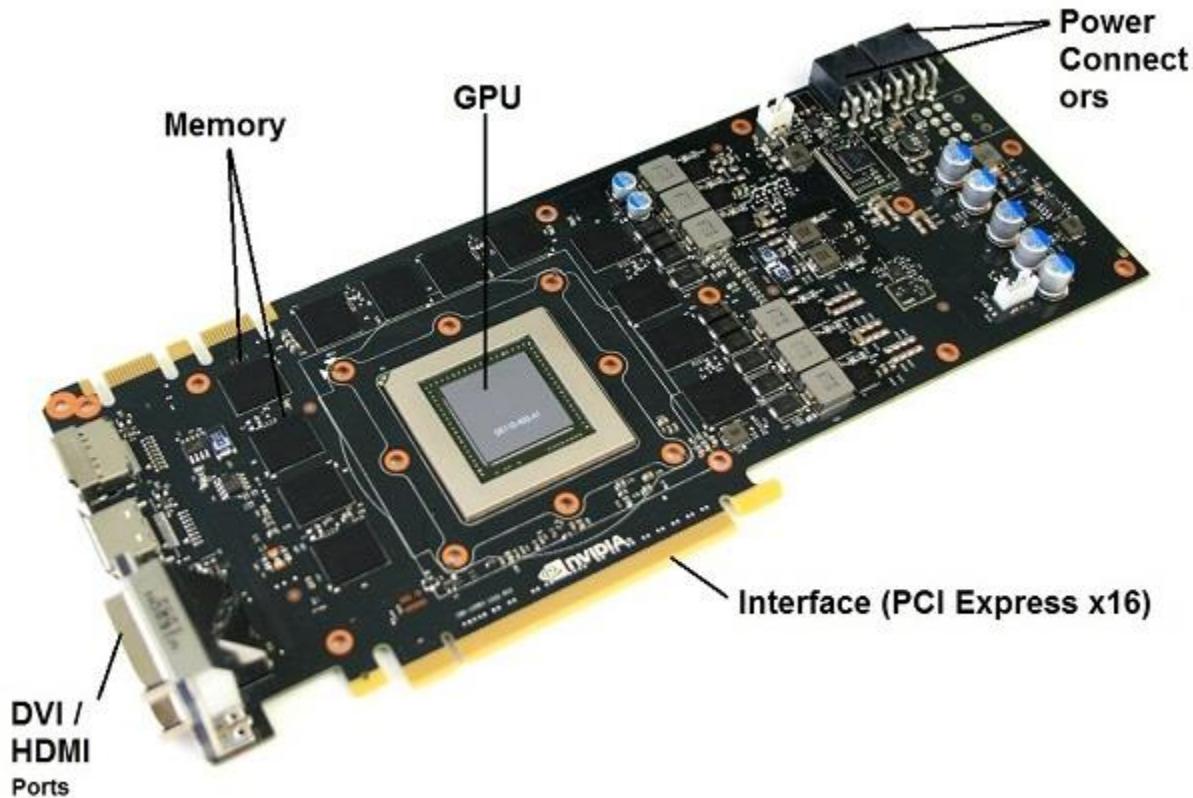
- What hardware/software did we need to produce it?
  - Software: Maya for modeling and rendering but Maya is built on top of OpenGL
  - Hardware: PC with graphics card for modeling and rendering

# Software – Autodesk Maya



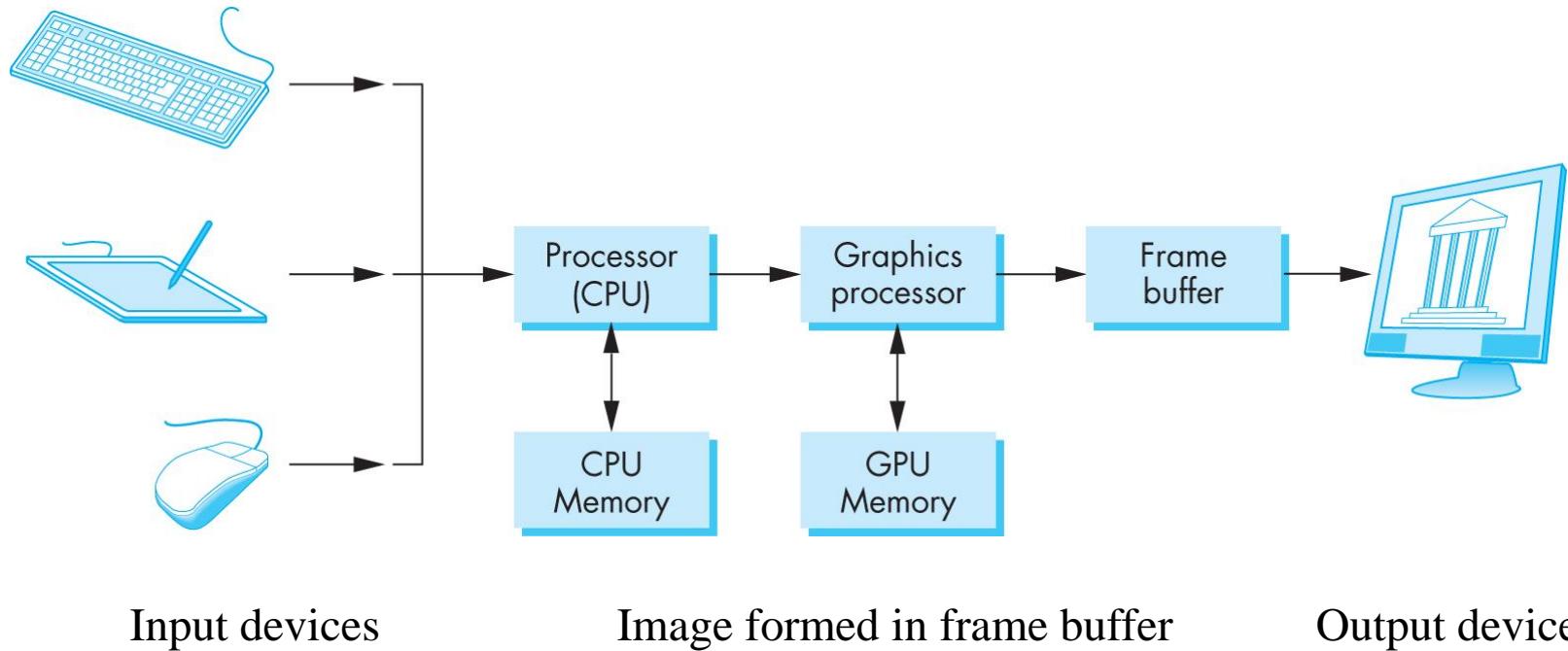
# Hardware - display card

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# A computer graphics system

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Angel and Shreiner: Interactive Computer Graphics 6E © Addison-Wesley 2012



# Input: Consumer devices

**GRAPHIC|S**

G|RAPHICS



# Input: Image & video

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# Input: Image & video

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# The modern era of easy photography

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# Better photography in a simple way

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\$ 5000



\$ 5



Mobile phone camera

Can these two ever be equally good at taking pictures?



# Better photography in a simple way



iPhone 3GS

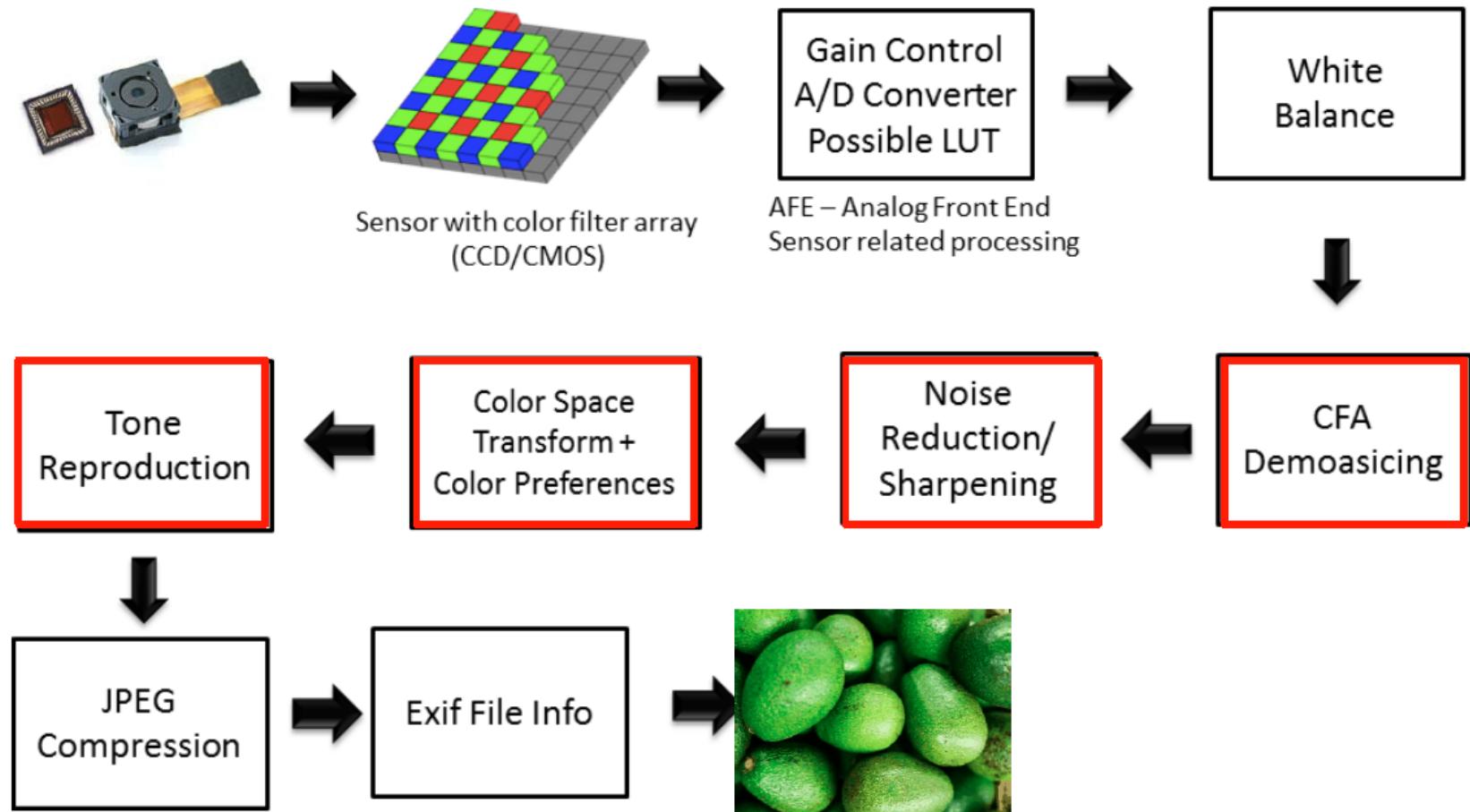


Canon EOS 5D Mark II



# Better photography in a simple way

- A standard model for imaging pipeline

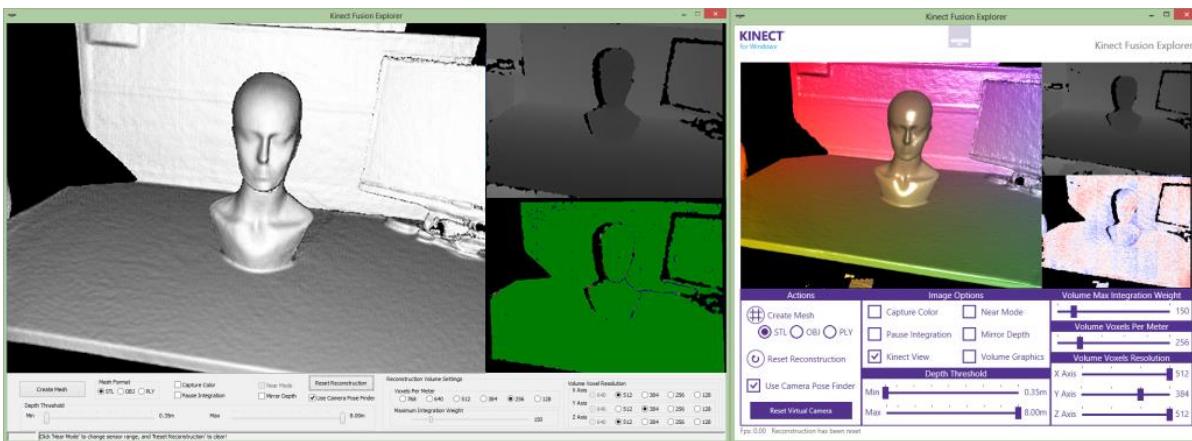
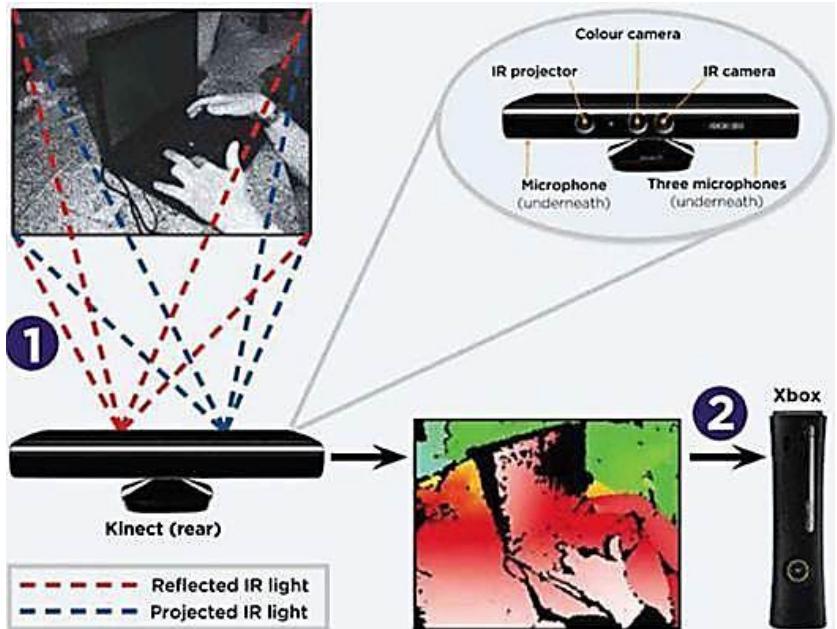


# Input: Shape

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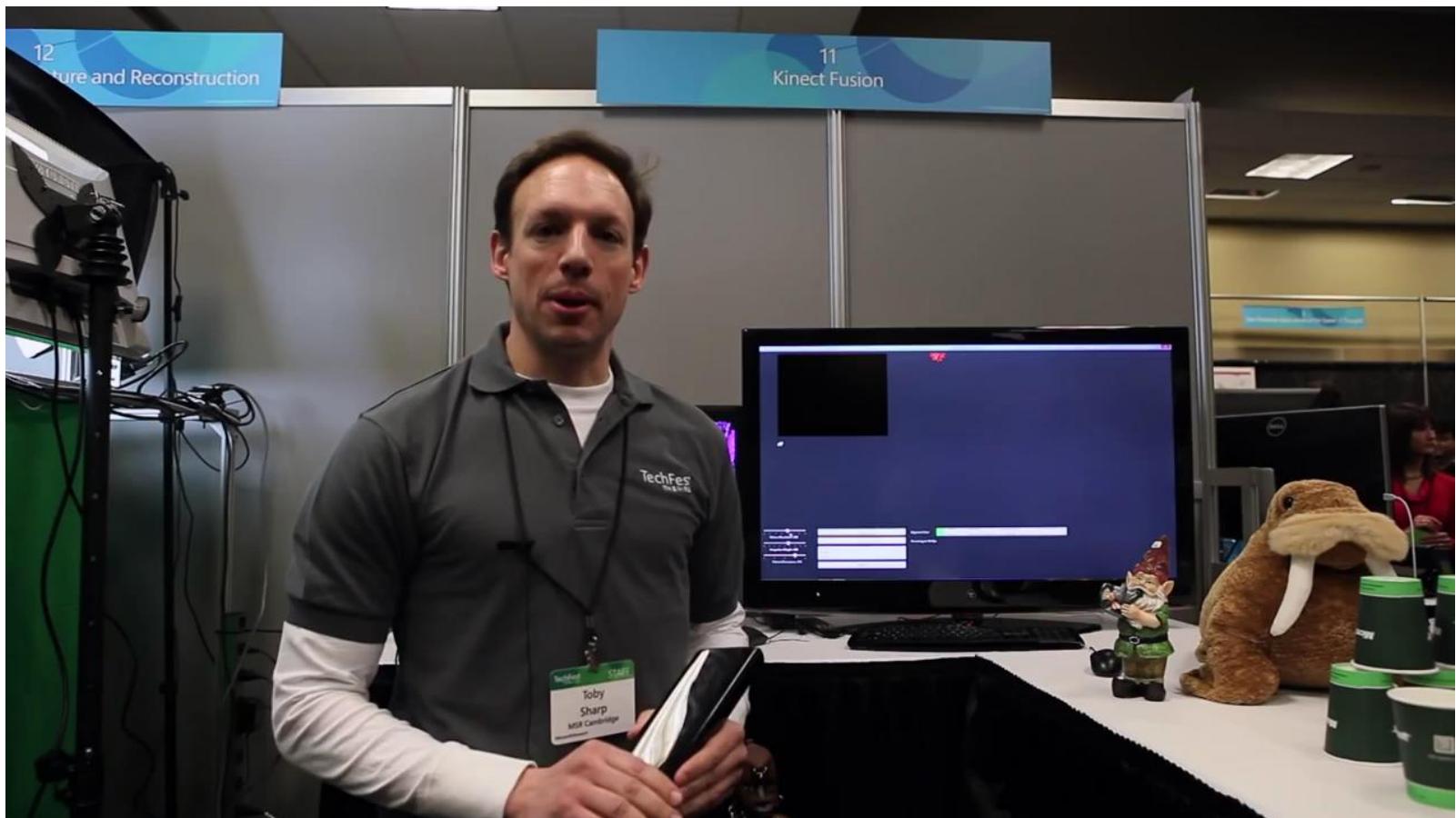


# Kinect Fusion

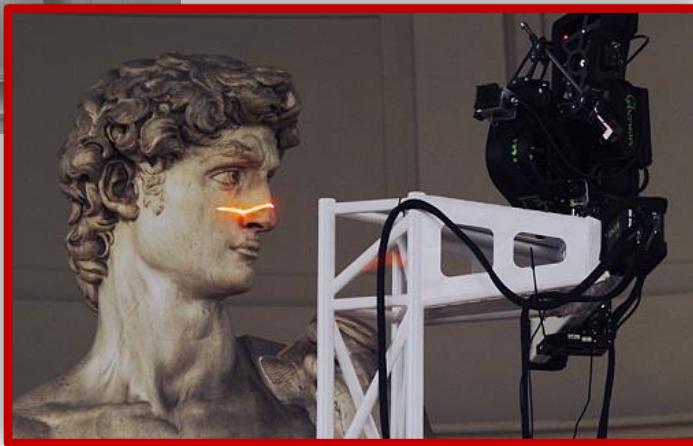
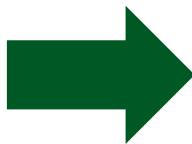


# Shapes from Kinect Fusion

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# 3D Scanning



# Desktop 3D scanner

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# Input: Specialized devices



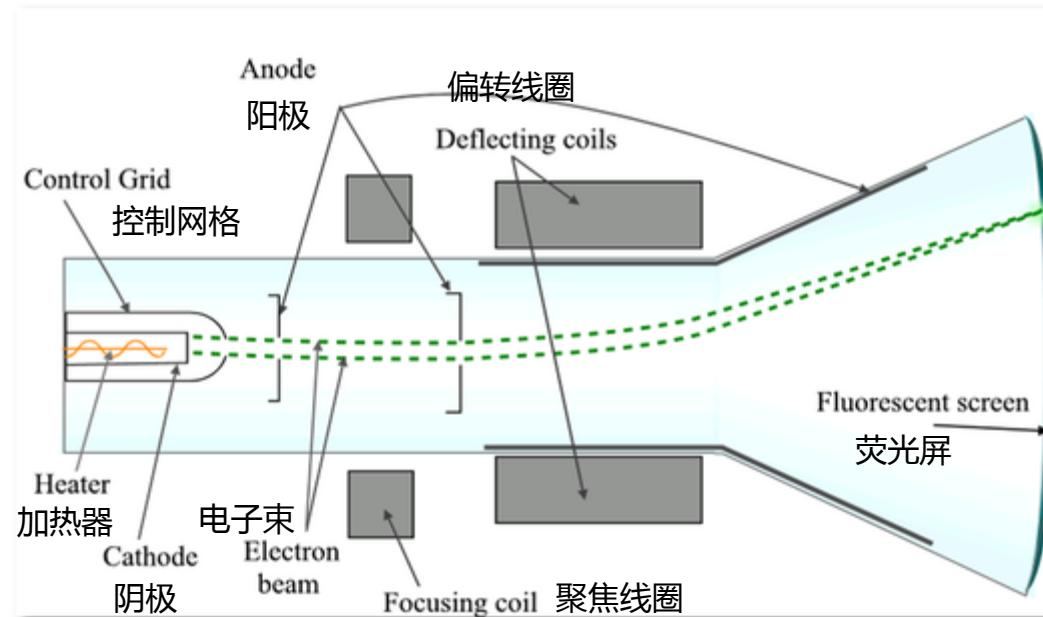
# What about the output device?

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# Display Devices

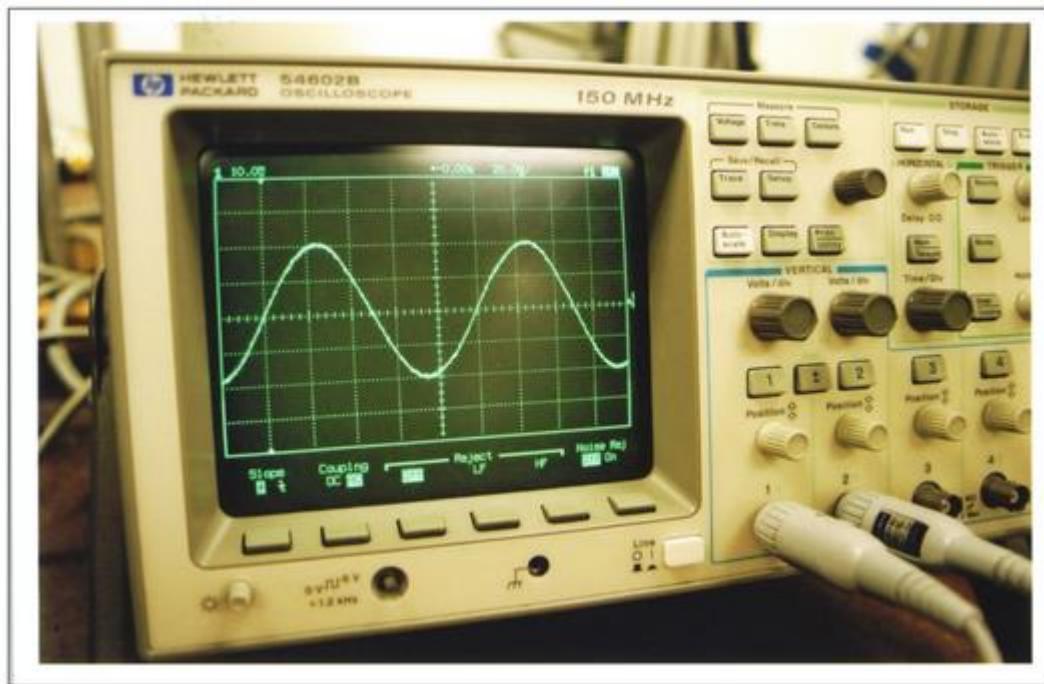
- Cathode Ray Tube (CRT)
  - CRT is a vacuum tube (电子管) containing one or more electron guns, and a phosphorescent screen (磷光屏) used to view images.



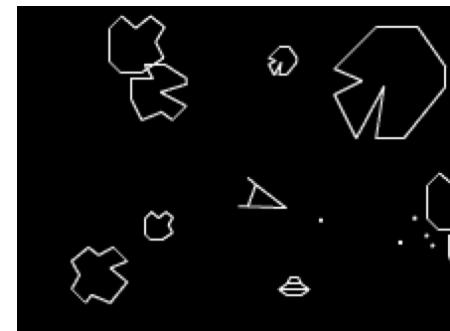
Karl Ferdinand Braun, 1897  
Image courtesy of Wikipedia

# Display Devices

- Vector Displays



HP Oscilloscope



Asteroids, 1979 (行星游戏)

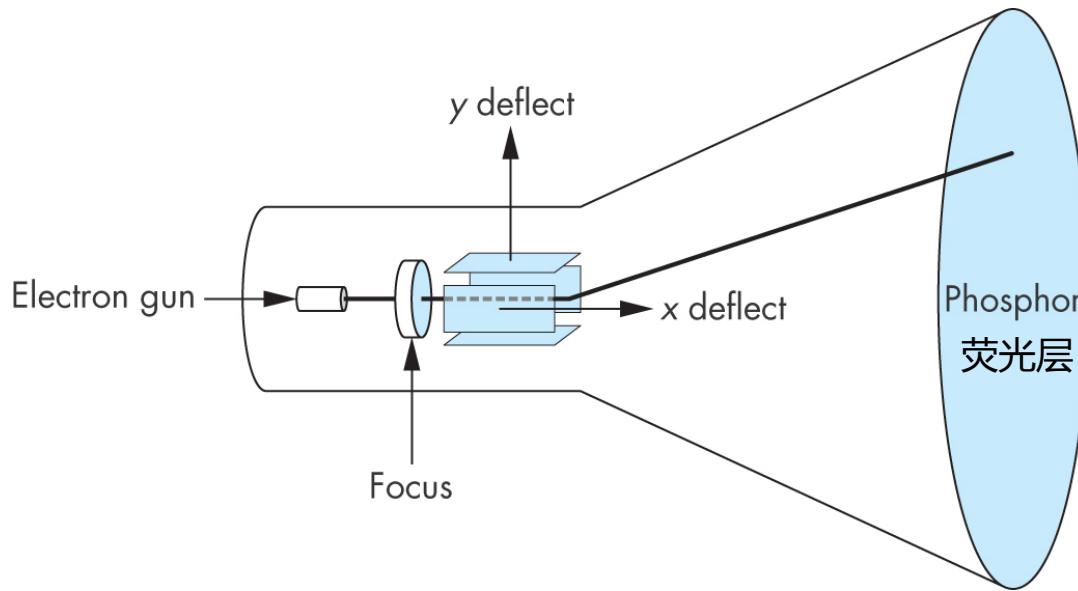


Star Wars, 1983 (星球大战)

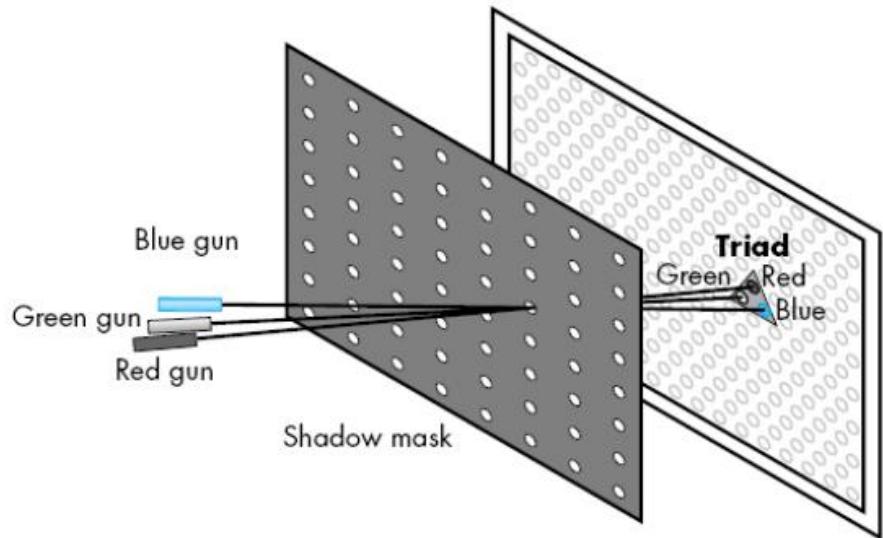
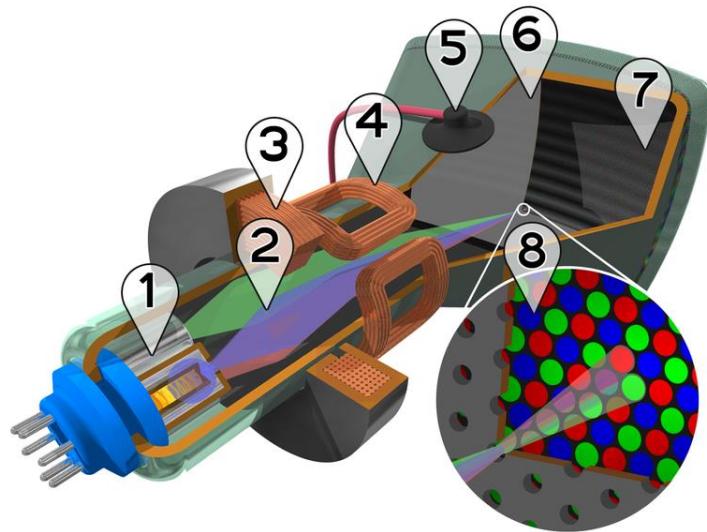


# Display Devices

- Raster Display Devices (光栅显示器)
  - The refresh type raster scan display : Get the pixels from the frame buffer individually and corresponding location on the screen display.
  - Refresh Rate: 刷新率
  - Interlaced scan, Non-Interlaced or Progressive scan: 逐行扫描和隔行扫描



# Color CRT display

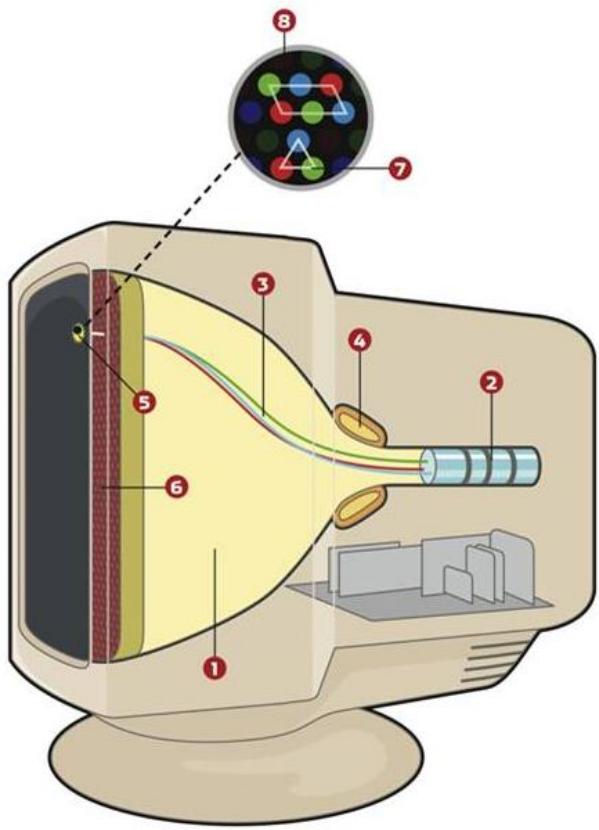


Cutaway rendering of a color CRT:

1. Three electron guns (for red, green, and blue phosphor dots)
2. Electron beams
3. Focusing coils
4. Deflection coils
5. Anode connection
6. Mask for separating beams for red, green, and blue part of displayed image
7. Phosphor layer with red, green, and blue zones
8. Close-up of the phosphor-coated inner side of the screen



# Color CRT display



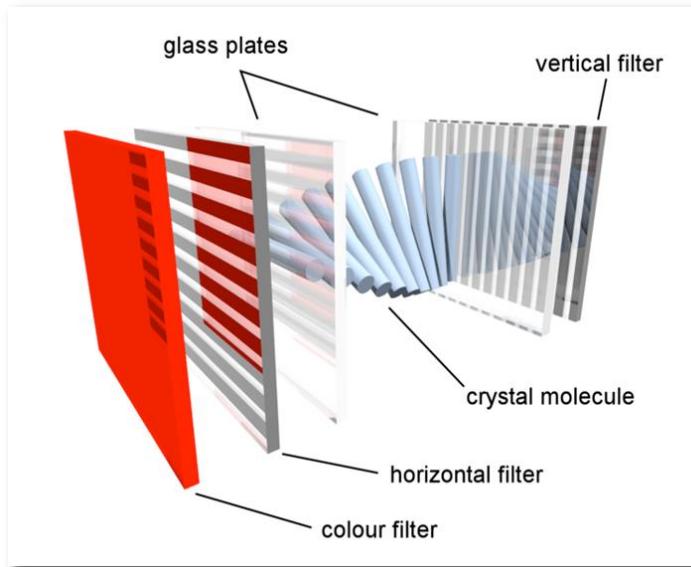
# Display Devices

- **Flat-panel monitors**

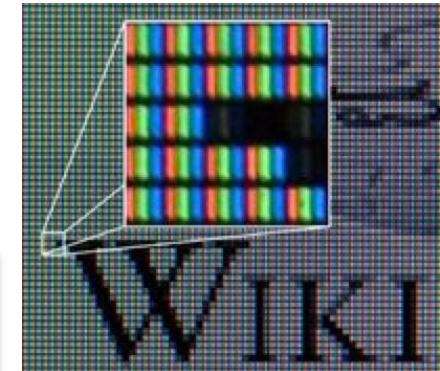
- LED (light-emitting diodes): 发光二级管
- LCD (liquid-crystal displays): 液晶显示器
- Plasma panels: 等离子显示器

- **Advantages:**

- low consumption
- small radiation
- flicker free
- **No geometric distortion**

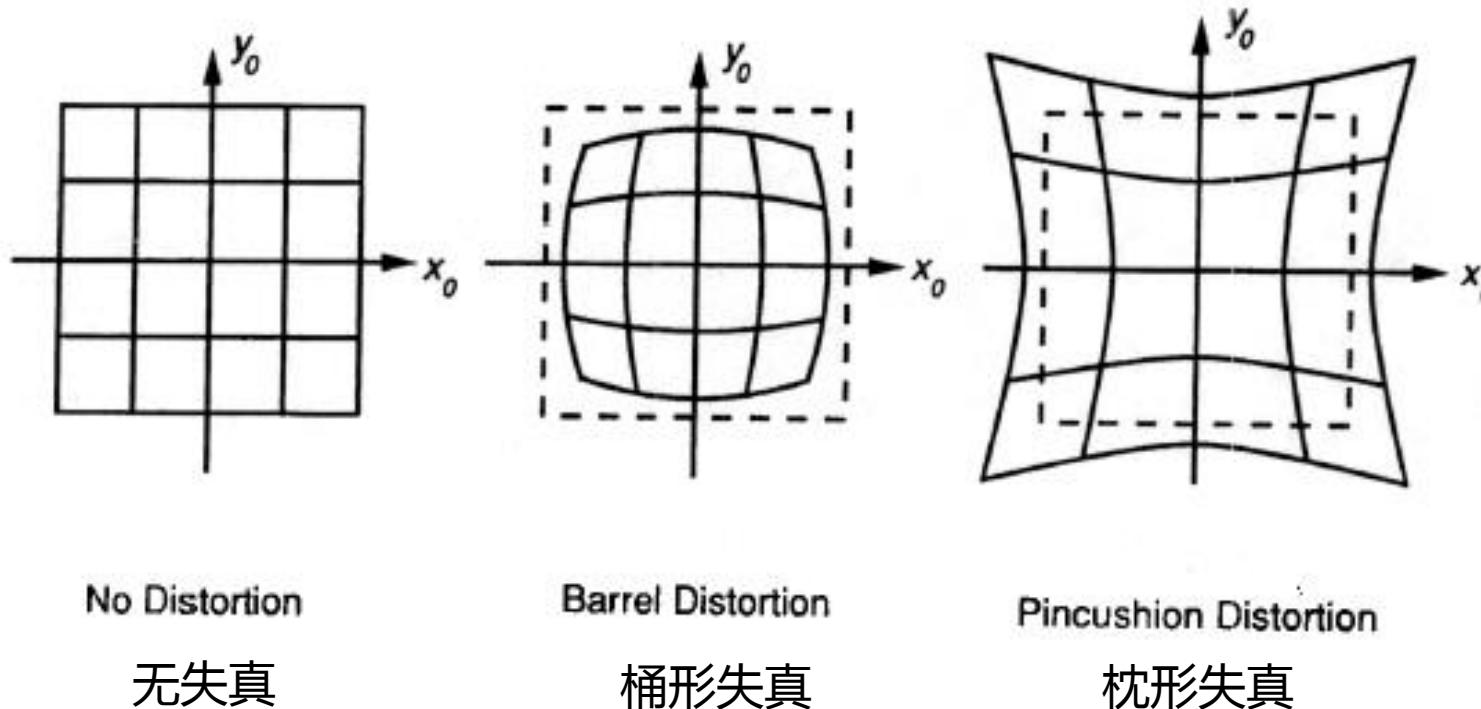


A single subpixel of an LCD display



Close-up of pixels  
on an LCD display

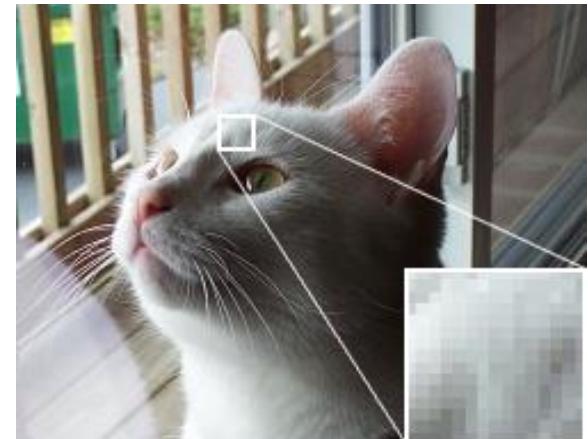
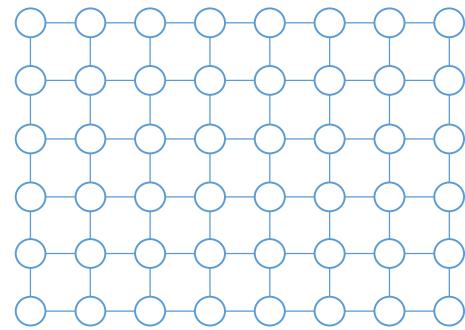
# Geometric distortion in display monitor



# What does “image” mean for us?

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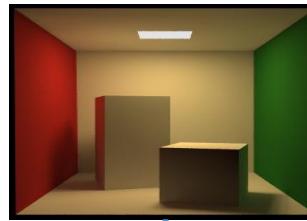
- A 2D domain with samples at regular points (almost always a rectilinear grid)
  - Can have multiple values sampled per point
  - Meaning of samples depend on the application (red, green, blue, opacity, depth, etc.)
- Units also depend on the application
  - e.g., a computed int or float to be mapped to voltage needed for display of a pixel on a screen
  - e.g., as a physical measurement of incoming light (e.g., a camera pixel sensor)



# What is a channel?

- A channel is all the samples of a particular type
- RGB is a common format for image channels
  - Easy to implement in h/w
  - Corresponds approximately to human visual system anatomy (specialized “R, G, and B” cones)
  - Samples represent the intensity of the light at a point for a given wavelength (red, green, or blue)
- The R channel of an image is an image containing just the red samples

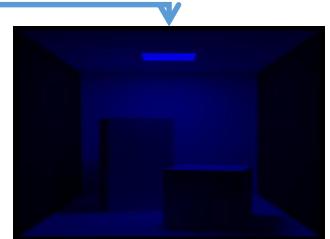
Original RGB image  
3 samples per pixel



Red channel  
1 sample per pixel



Green channel  
1 sample per pixel



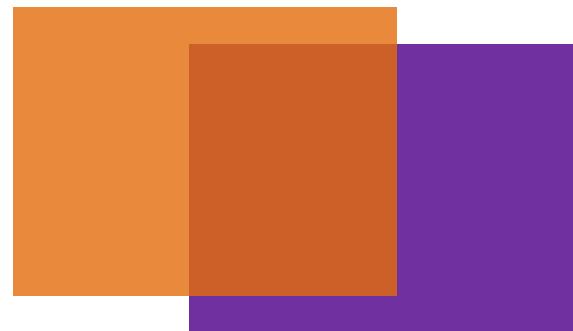
Blue channel  
1 sample per pixel



# The alpha channel

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- In addition to the R, G, and B channels of an image, add a fourth channel called  $\alpha$  (transparency-opacity/translucency)
- Alpha varies between 0 and 1
  - Value of 1 represents a completely opaque pixel, one you cannot see through
  - Value of 0 is a completely transparent pixel
  - Value between  $0 < \alpha < 1$  determines translucency
- Useful for blending images
  - Images with higher alpha values are less transparent
  - Linear interpolation ( $\alpha X + (1 - \alpha)Y$ ) or full Porter-Duff compositing algebra

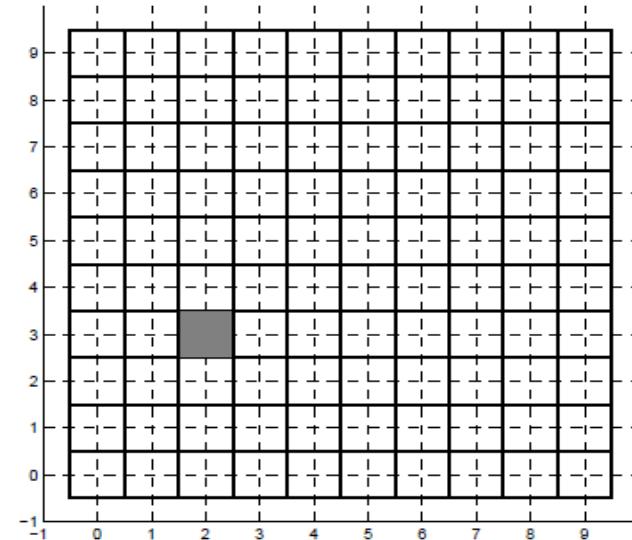


The orange box is drawn on top of the purple box using  $\alpha = 0.8$

# Modeling an image

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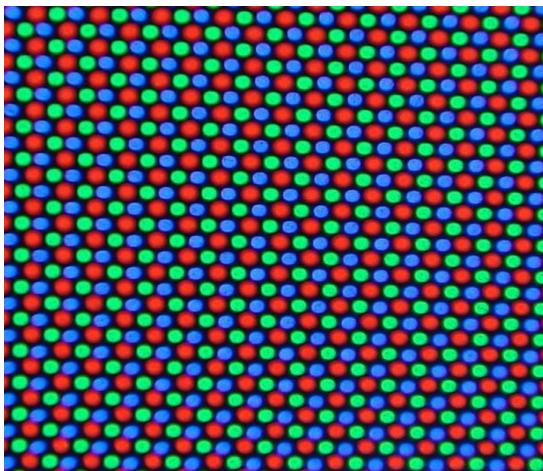
- Model a one-channel  $m \times n$  image as the function  $u(i, j)$ 
  - Maps pairs of integers (pixel coordinates) to real numbers
  - $i$  and  $j$  are integers such that  $0 \leq i < m$  and  $0 \leq j < n$
- Associate each pixel value  $u(i, j)$  to small area around display location with coordinates  $(i, j)$
- A pixel here looks like a square centered over the sample point, but it's just a scalar value and the actual geometry of its screen appearance varies by device
  - Roughly circular spot on CRT
  - Rectangular on LCD panel



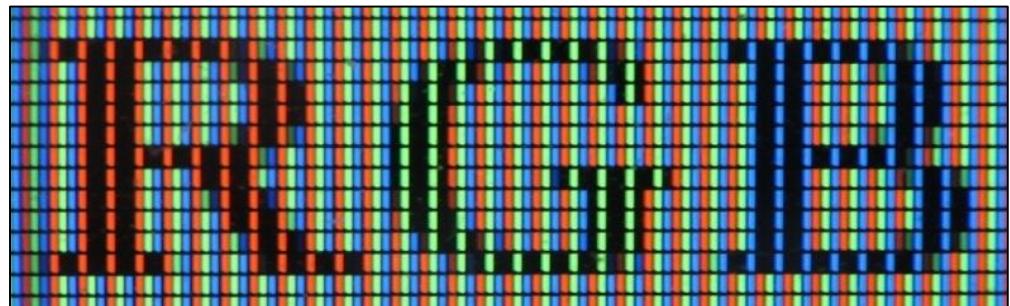
# Pixels

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- Pixels are point samples, not “squares” or “dots”
- Point samples reconstructed for display (often using multiple subpixels for primary colors)



Close-up of a CRT screen

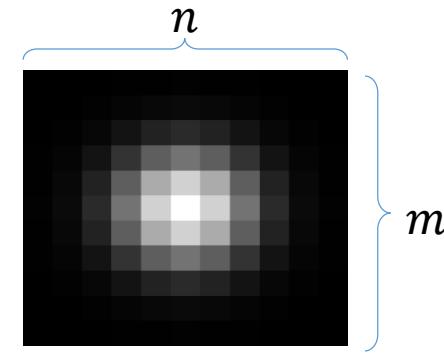
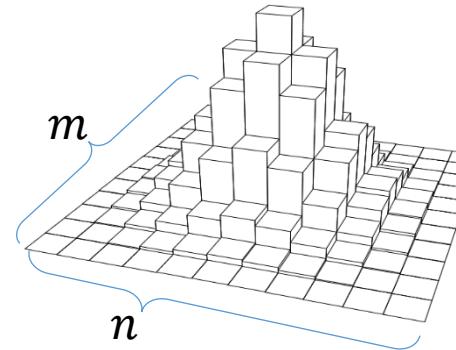


Close-up of an LCD screen



# Discrete Images vs. Continuous Images

- Two kinds of images
  - Discrete
  - Continuous
- Discrete image
  - Function from  $\mathbb{Z}^2$  to  $\mathbb{R}$
  - How images are stored in memory
  - The kind of images we generally deal with as computer scientists

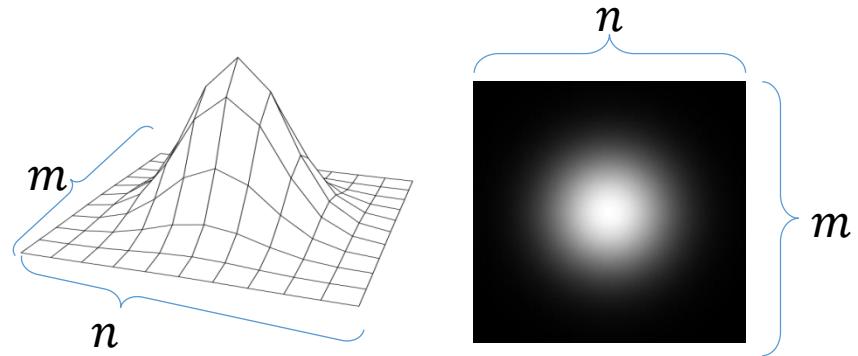


Discrete image  $u(i, j)$



# Discrete Images vs. Continuous Images

- Continuous image
  - Function from  $\mathbb{R}^2$  to  $\mathbb{R}$
  - Images in the real world
  - “Continuous” refers to the domain, not the values (discontinuities could still exist)
- Example: Gaussian distribution
  - $i_0$  and  $j_0$  are the center of the Gaussian
  - $u: \mathbb{Z}^2 \rightarrow \mathbb{R}, u(i,j) = e^{-(i-i_0)^2-(j-j_0)^2}$
  - $v: \mathbb{R}^2 \rightarrow \mathbb{R}, v(i,j) = e^{-(i-i_0)^2-(j-j_0)^2}$
  - $i_0 = (n - 1)/2$  and  $j_0 = (k - 1)/2$  (n odd)
  - Here  $n = 11$  and  $m = 11$



Continuous image  $v(i,j)$



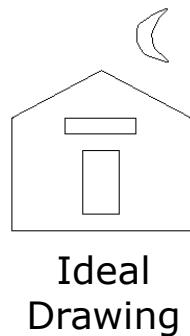
# Graphics Display Hardware

**Vector** (calligraphic, stroke, random-scan)

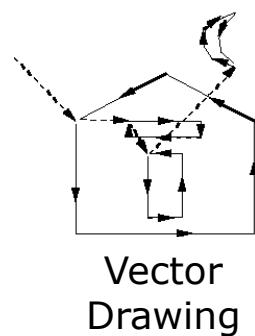
- Driven by display commands
  - (move (x, y), char("A"), line(x, y)...)
- Survives as “scalable vector graphics”

**Raster** (TV, bitmap, pixmap) used in displays and laser printers

- Driven by array of pixels (no semantics, lowest form of representation)
- Note “jaggies” (aliasing errors) due to discrete sampling of continuous primitives



Ideal  
Drawing



Vector  
Drawing



Outline



Filled

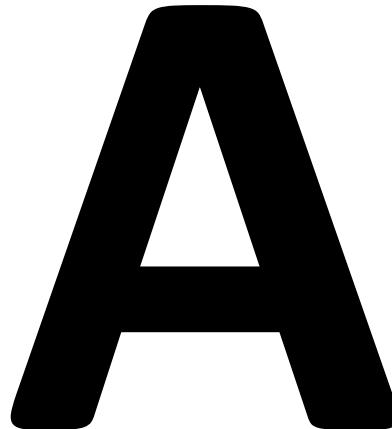
# Graphics Display Hardware

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**Vector** (calligraphic, stroke, random-scan)

- Driven by display commands
  - (move (x, y), char("A") , line(x, y)...)
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A



**Raster** (TV, bitmap, pixmap) used in displays and laser printers

- Driven by array of pixels (no semantics, lowest form of representation)
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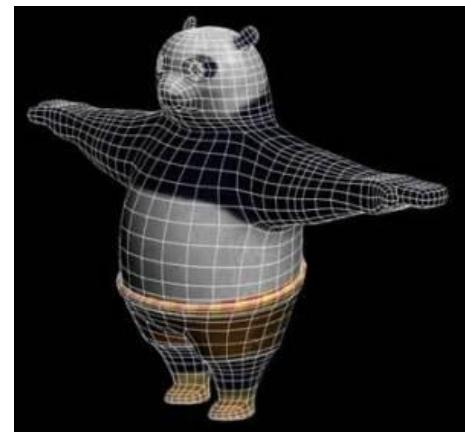
A



# Application Distinctions: Two Basic Paradigms

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Sample-based graphics   vs   Geometry-based graphics



# Sample-based graphics

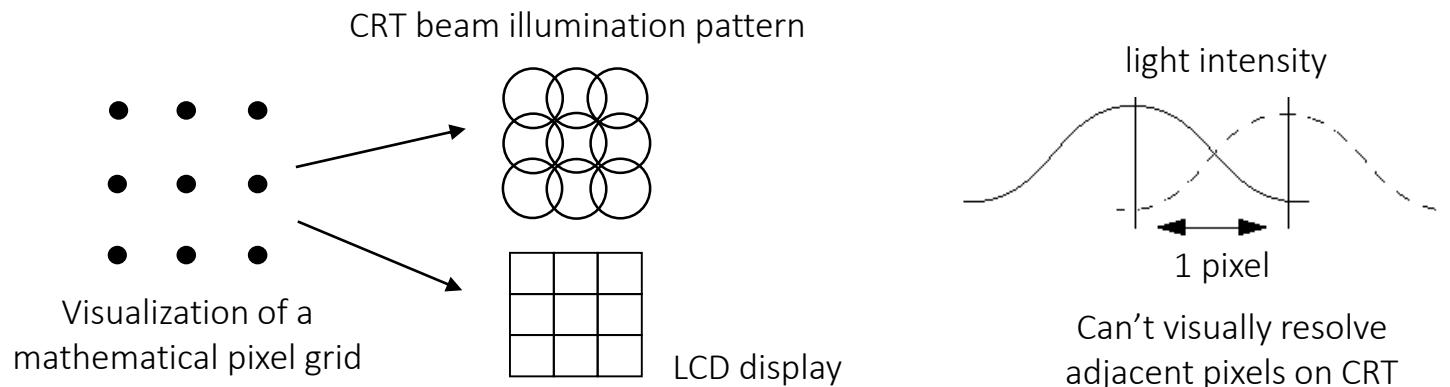
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- **Sample-based graphics:** Discrete samples are used to describe visual information
  - pixels can be created by digitizing images, using a sample-based “painting” program, etc.
  - often some aspect of the physical world is sampled for visualization, e.g., temperature across the US
  - example programs: Adobe Photoshop™, GIMP™ , Adobe AfterEffects™



# Sample-based graphics

- Pixels are point locations with associated sample values, usually of light intensities/colors, transparency, and other control information
- When we sample an image, we sample the point location along the continuous signal and we cannot treat the pixels as little circles or squares, though they may be displayed as such



# Sample-based graphics

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- Samples created directly in **paint-type program**, or by sampling of continuous (analog) **visual materials** (light intensity/color measured at regular intervals) with many devices including:
  - flatbed and drum scanners
  - digital still and motion (video) cameras
- Sample values can also be input numerically (e.g., with numbers from computed dataset)
- Once an image is defined as pixel-array, it can be manipulated
  - **Image editing**: changes made by **user**, such as cutting and pasting sections, brush-type tools, and processing selected areas
  - **Image processing**: algorithmic operations that are performed on image (or pre-selected portion of image) without user intervention. Blurring, sharpening, edge-detection, color balancing, rotating, warping. These are front-end processes to **Computer Vision**.



# Sampling an Image

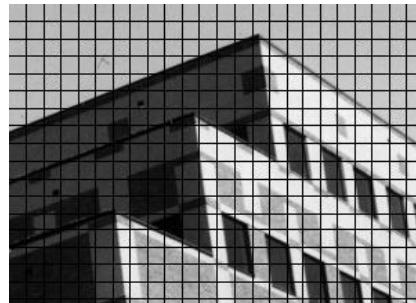
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- Let's do some sampling of the building image



- A color value is measured at every grid point and used to color corresponding grid square

0 = white, 5 = gray, 10 = black



- Crude sampling and image reconstruction method creates blocky image

# What's the Advantage?

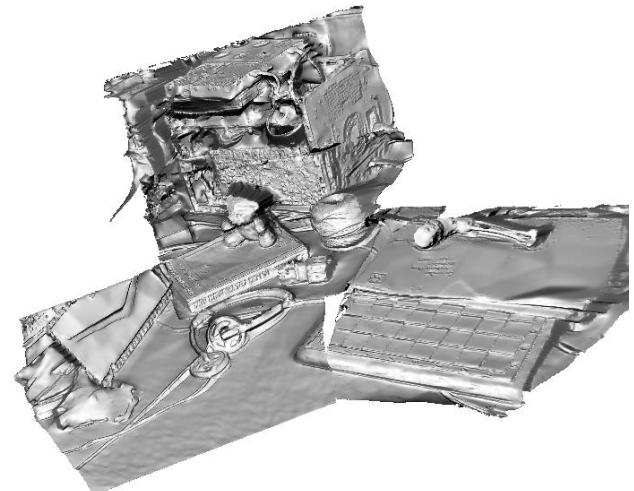
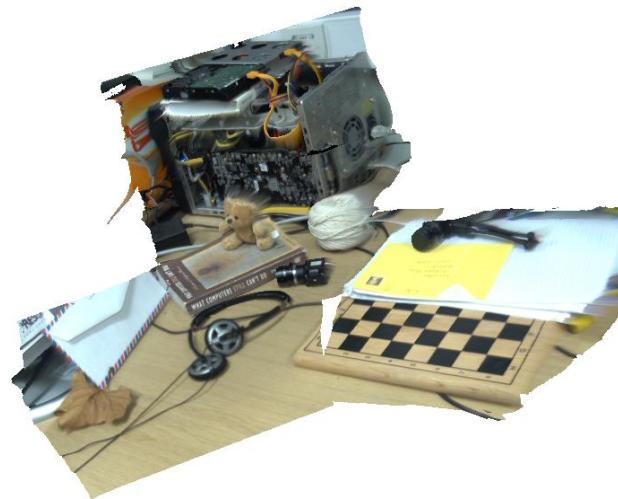
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- Once image is defined in terms of colors at (x, y) locations on grid, can change image easily by altering location or color values
- E.g., if we reverse our mapping above and make 10 = white and 0 = black, the image would look like this:
- Pixel information from one image can be copied and pasted into another, replacing or combining with previously stored pixels



# What's the Disadvantage?

- WYSIAYG (What You See Is All You Get): No additional information
  - no depth information
  - can't examine scene from different point of view
  - at most can play with the individual pixels or groups of pixels to change colors, enhance contrast, find edges, etc.
  - But increasingly great success in image-based rendering to fake 3D scenes and arbitrary camera positions. New images constructed by interpolation, composition, warping and other operations.
  - For a computational and cognitive science perspective, Take Thomas Serre's Computational Vision.

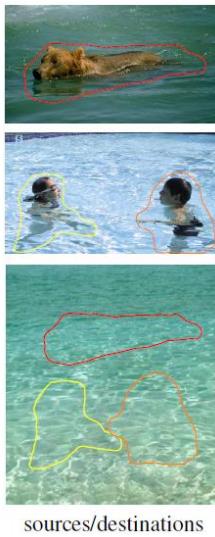


# Question?

- How to recover the high-definition image from a low-resolution sample?



- How to paste some objects into a new image?



sources/destinations



cloning



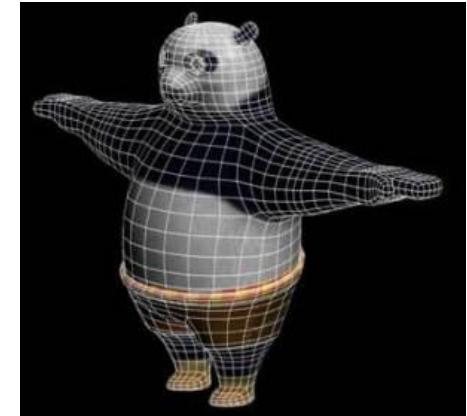
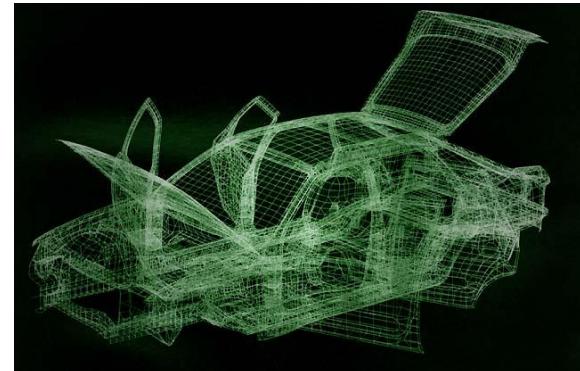
seamless cloning



# Geometry-Based Graphics

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- **Geometry-based graphics** (also called scalable vector graphics or object-oriented graphics): geometrical model is created, along with various appearance attributes, and is then sampled for visualization (rendering, a.k.a image synthesis)
  - often some aspect of physical world is visually simulated, or “synthesized”
  - examples of 2D apps: Adobe Illustrator™, Adobe Freehand™, Corel CorelDRAW™
  - examples of 3D apps: Autodesk’s AutoCAD™, Autodesk’s (formerly Alias | Wavefront’s) Maya™, Autodesk’s 3D Studio Max™



# Geometry-Based Graphics

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- Geometry-based graphics applications
  - **Store mathematical descriptions**, or “models,” of geometric elements (lines, polygons, polyhedrons, polygonal meshes...) and associated attributes (e.g., color, material properties).
  - **Geometric elements** are primitive shapes, primitives for short.
  - **Images** are created via sampling of geometry **for viewing**, but not stored as part of model.
  - Users cannot usually work directly with individual pixels in geometry-based programs; as user manipulates geometric elements, program **resamples** and **redisplays** elements
- Increasingly rendering combines geometry- and sample-based graphics, both as performance hack and to increase quality of final product.
  - geometric characters on painted or scanned scene images



# Image Vectorization

- From Sample-based to Geometry-based Graphics



(a) input raster image



(b) Adobe Live Trace result



(c) subdivision mesh

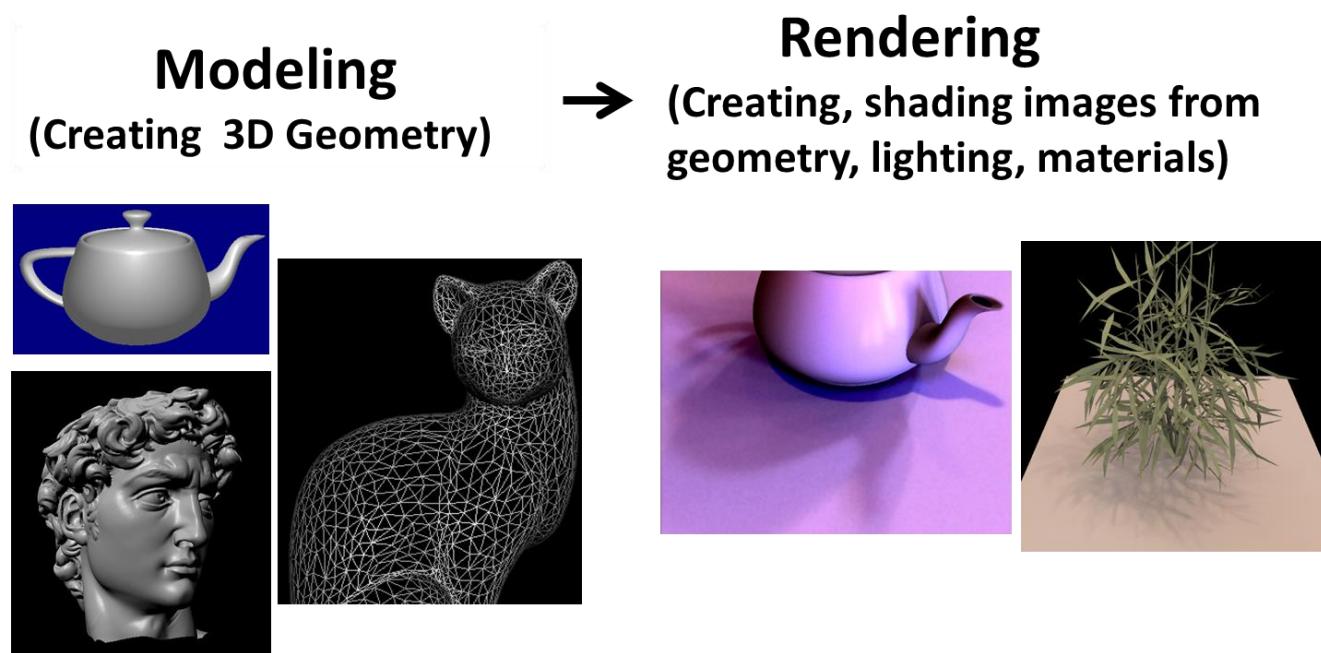


(d) optimized gradient mesh

# Outline

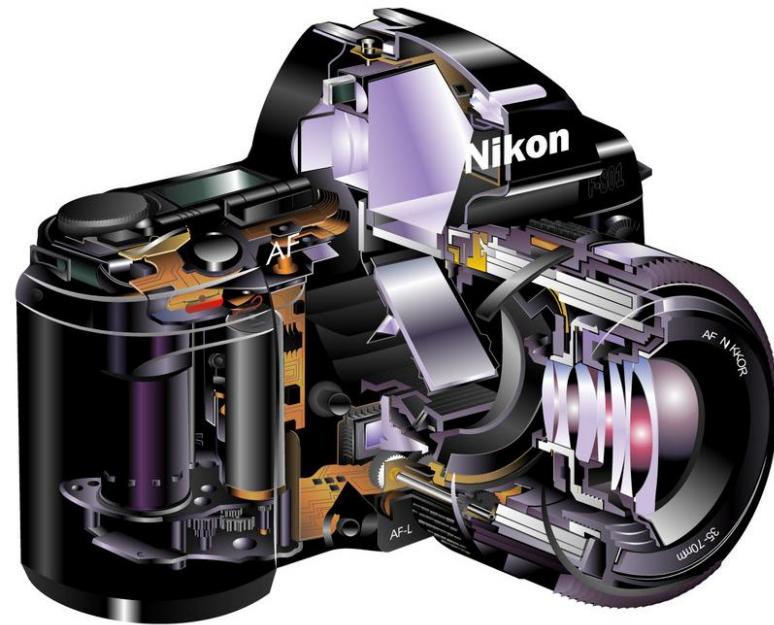
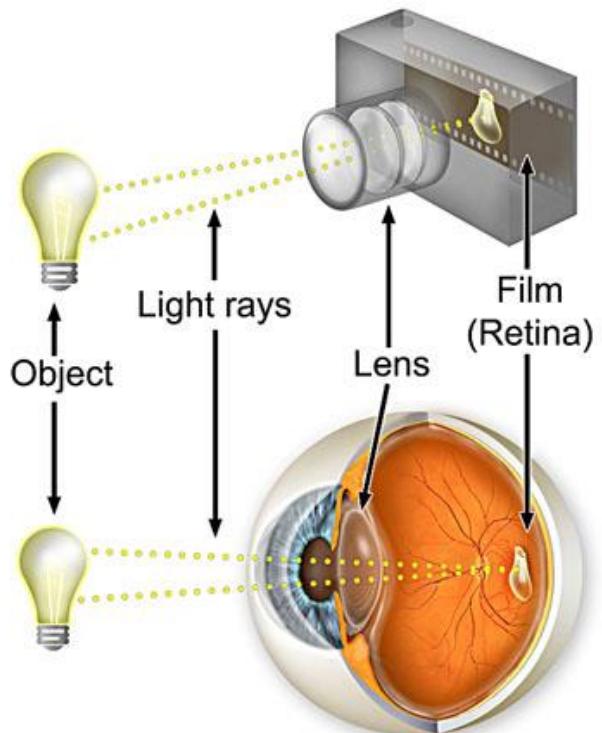
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- Computer Graphics System
- **Physical Imaging System**
- Graphics Rendering Pipeline



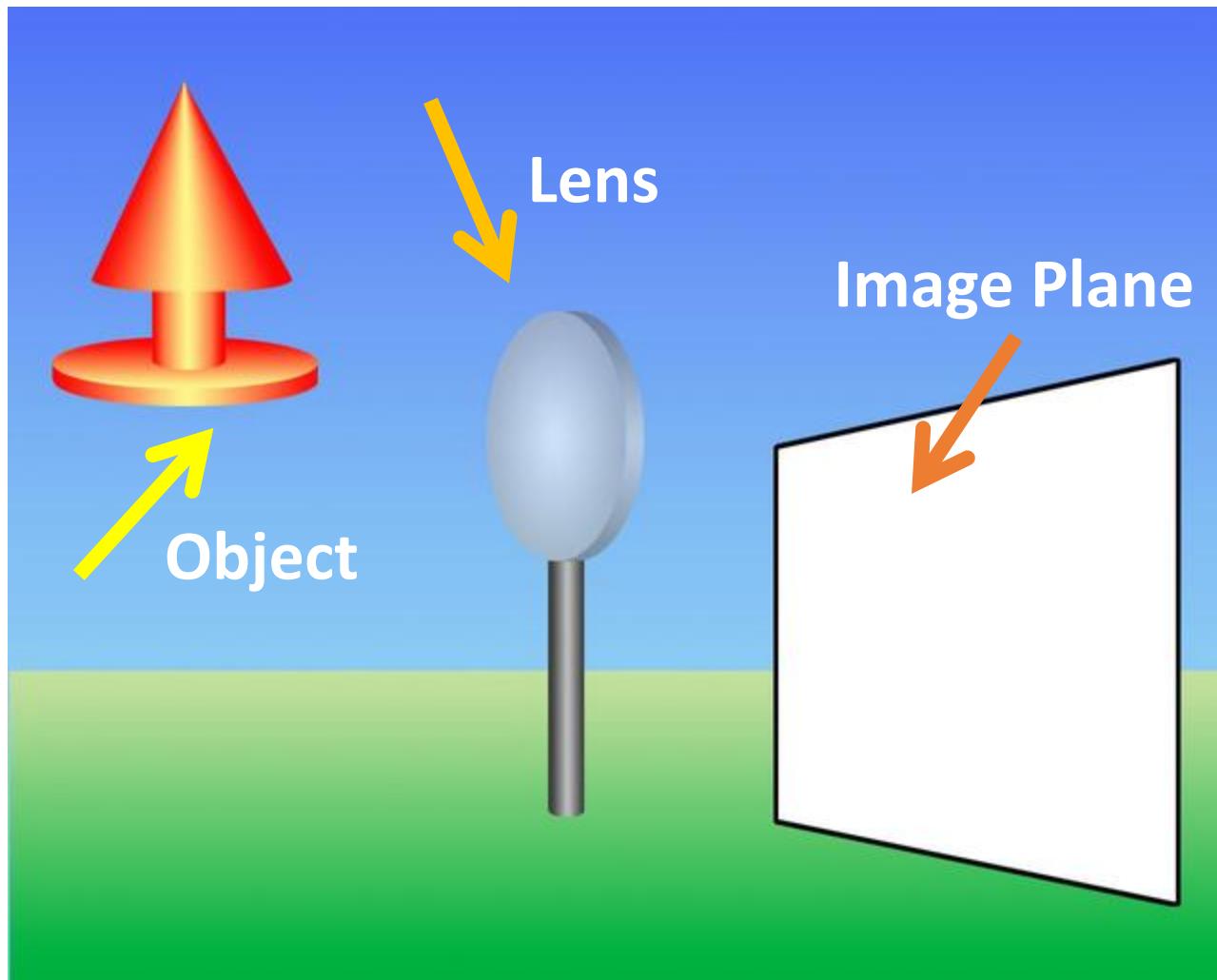
# Physical Imaging System

- Eye(biology)
- Camera: film (chemistry),digital (physical + digital)



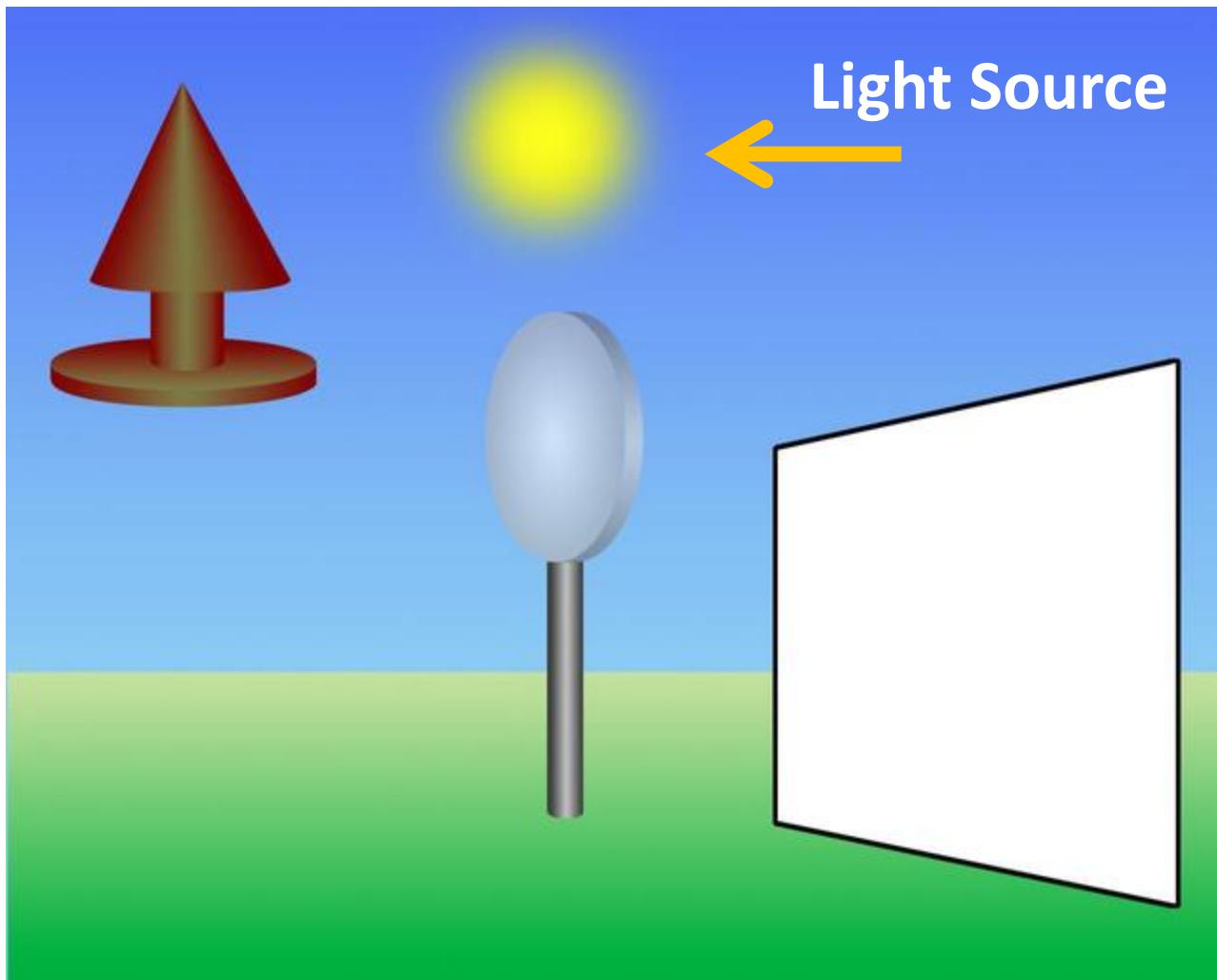
# Imaging Principle

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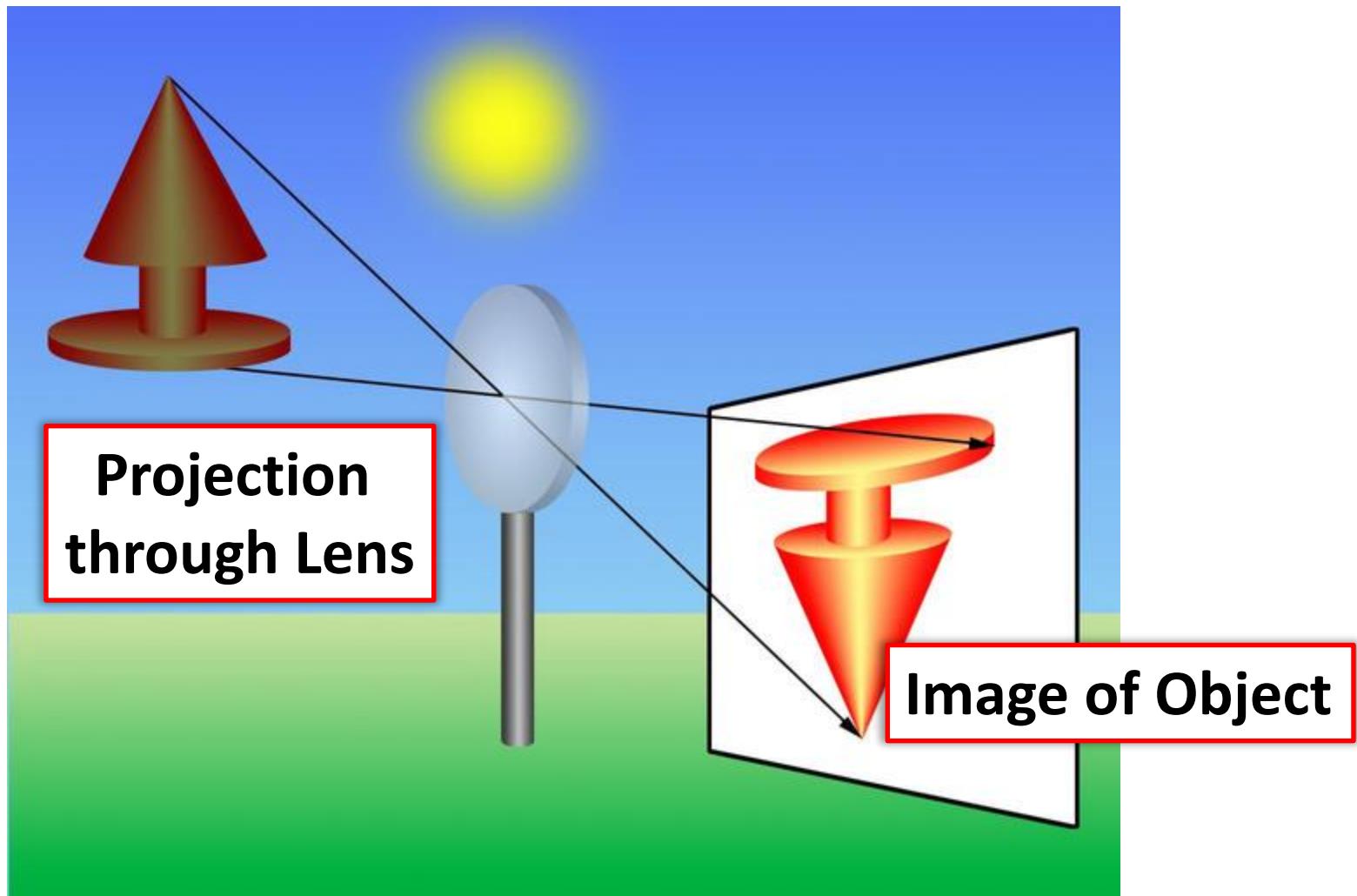
# Imaging Principle

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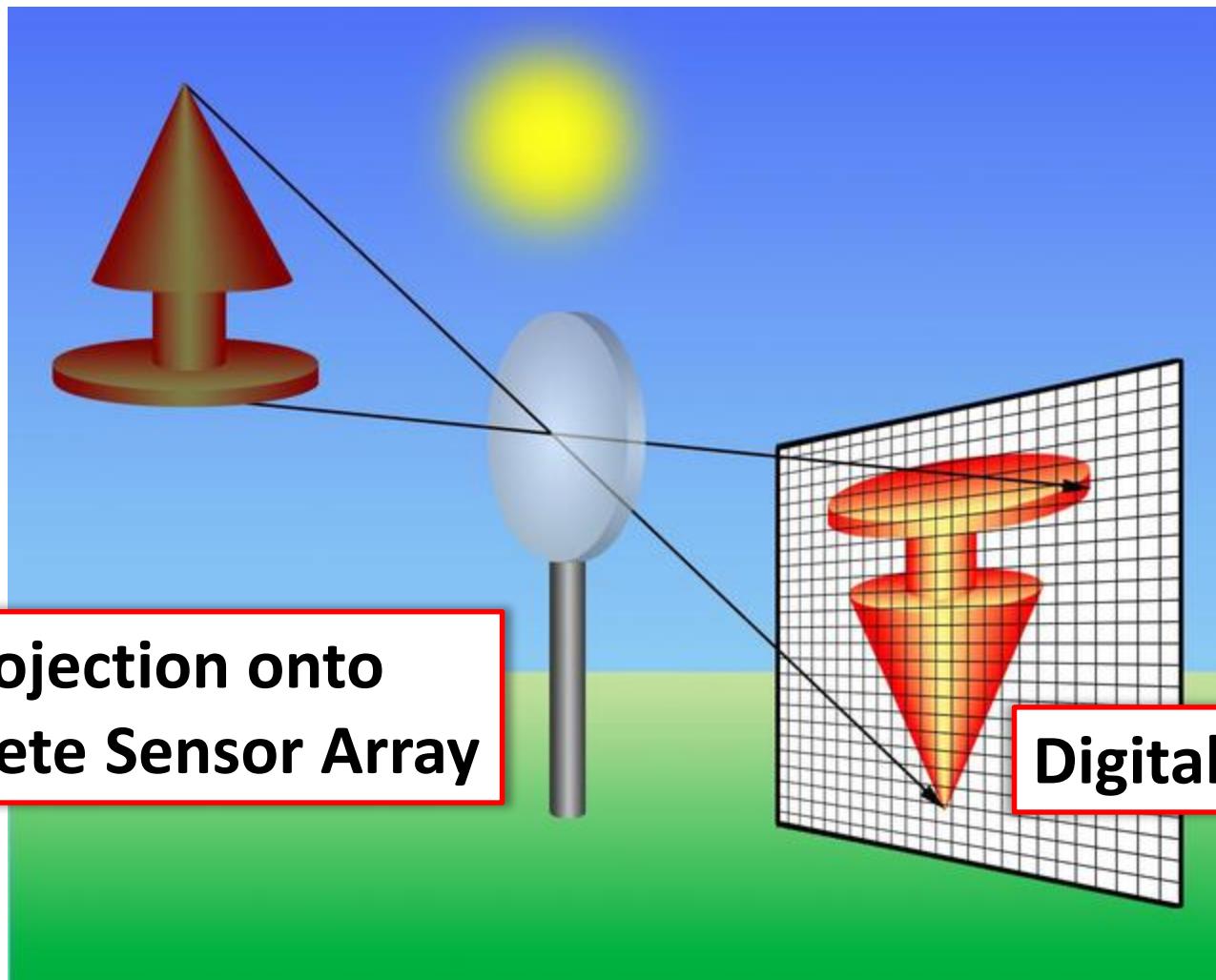


# Imaging Principle

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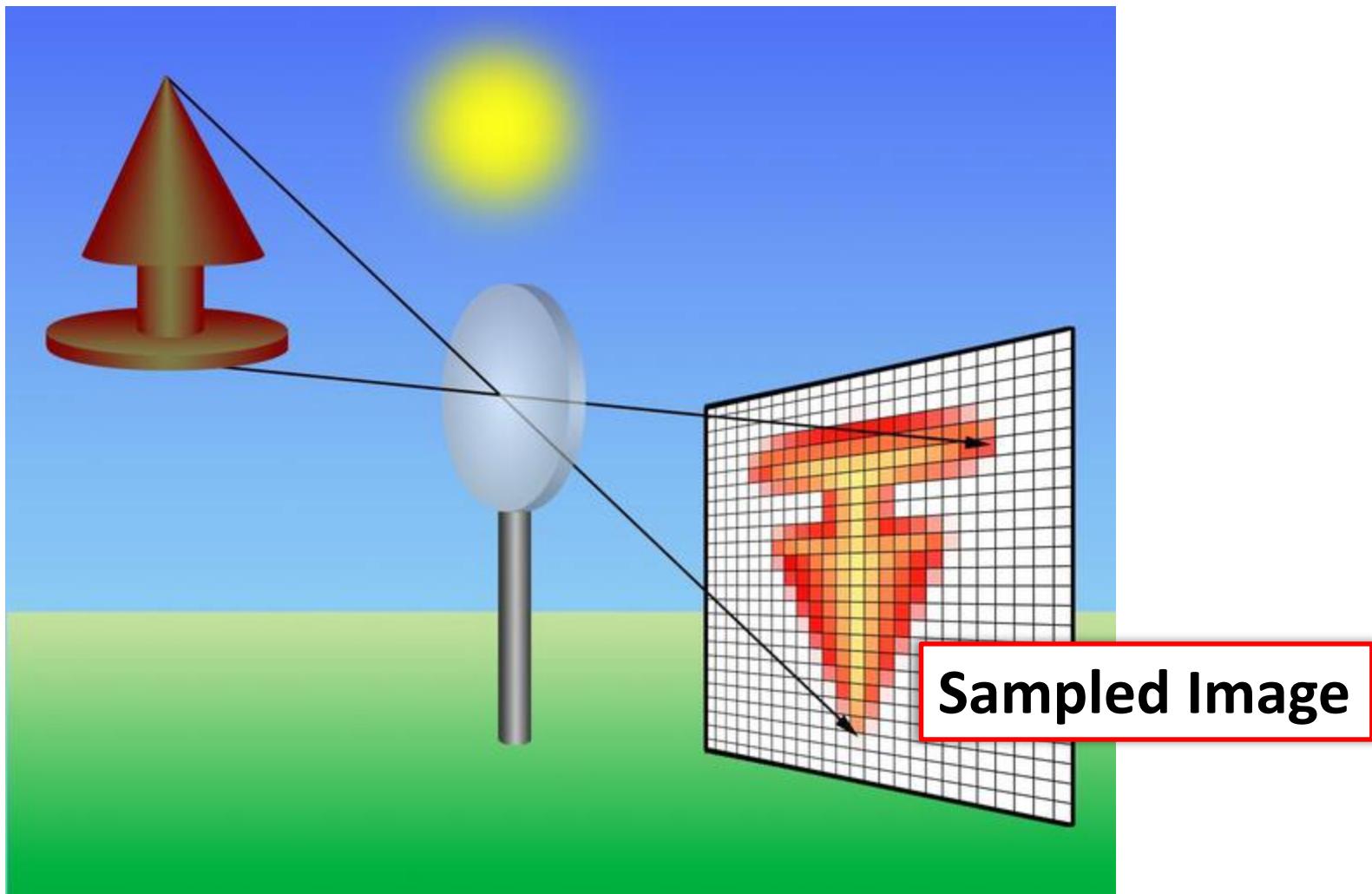


# Imaging Principle



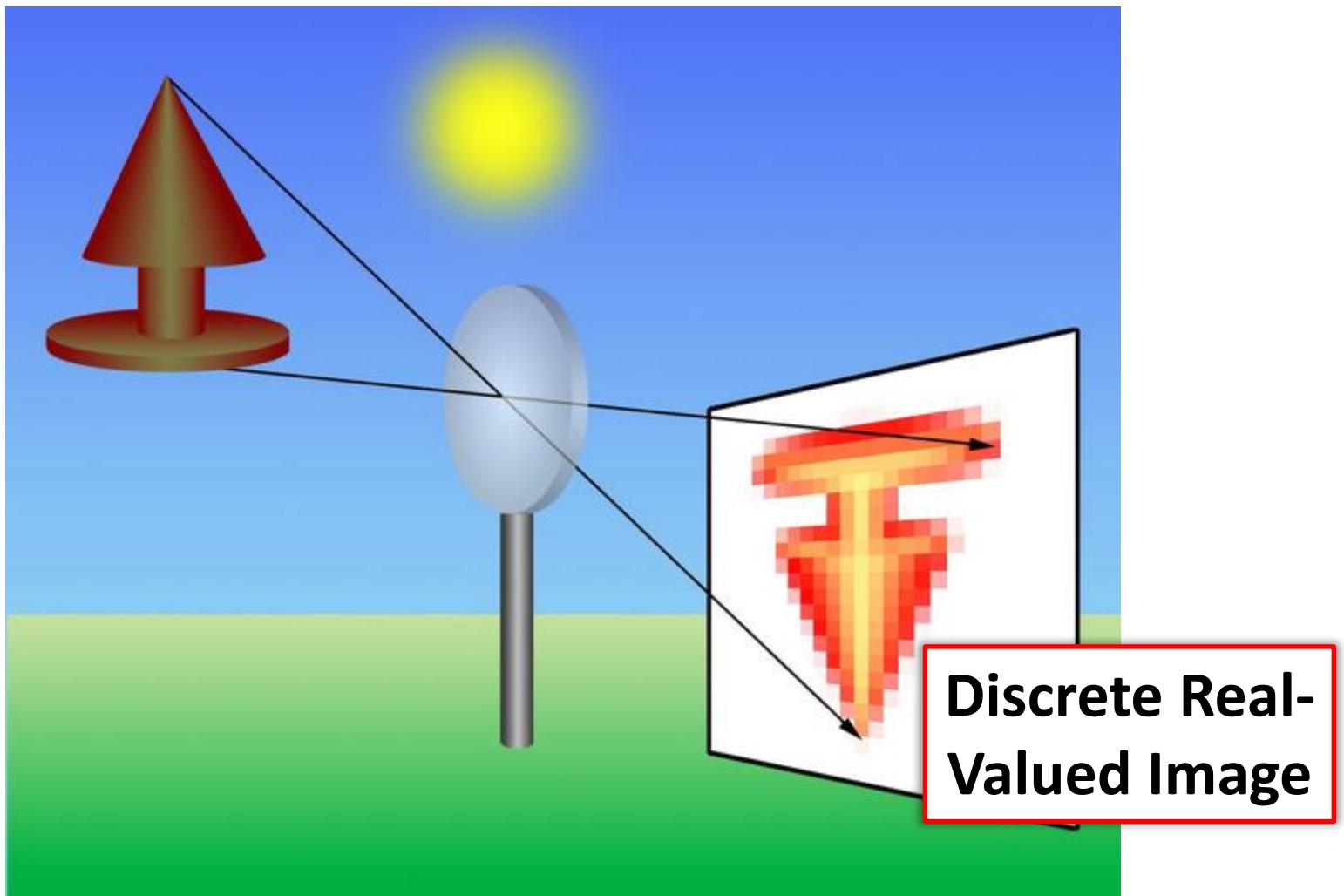
# Imaging Principle

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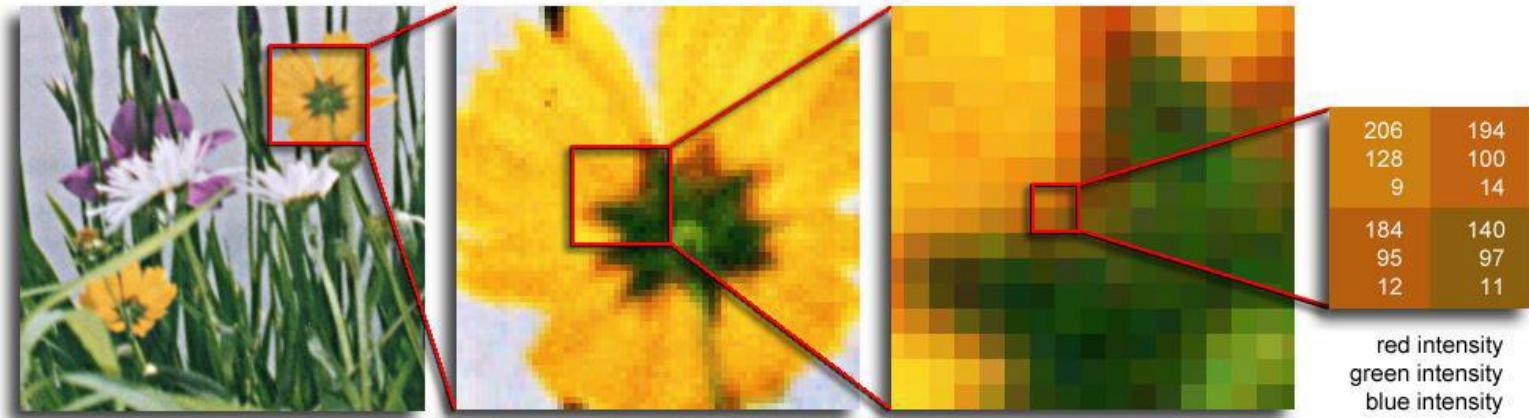
# Imaging Principle

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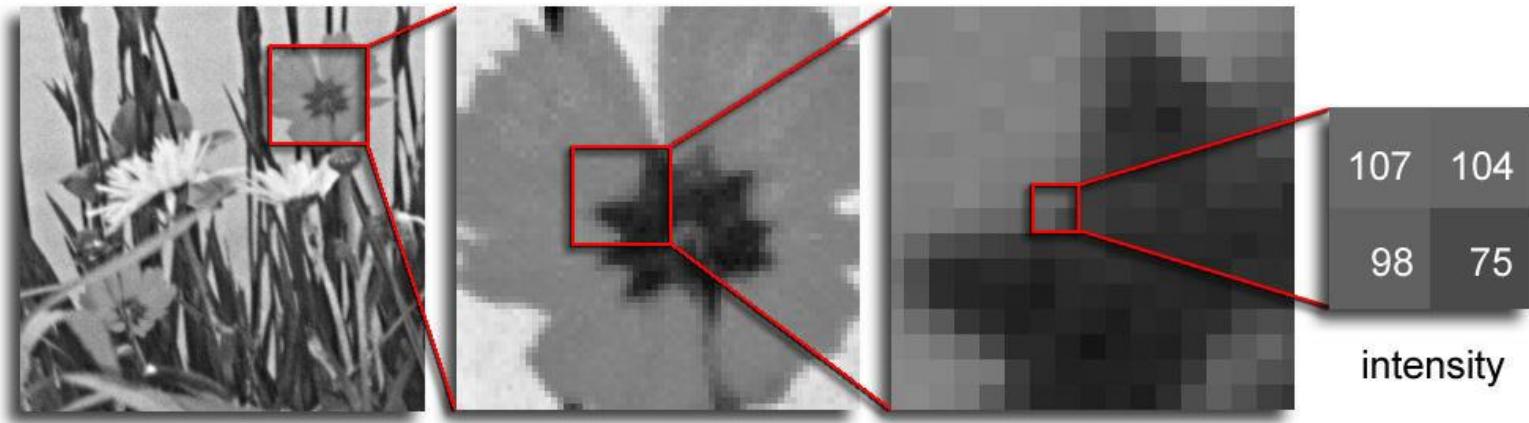


# Digital Image

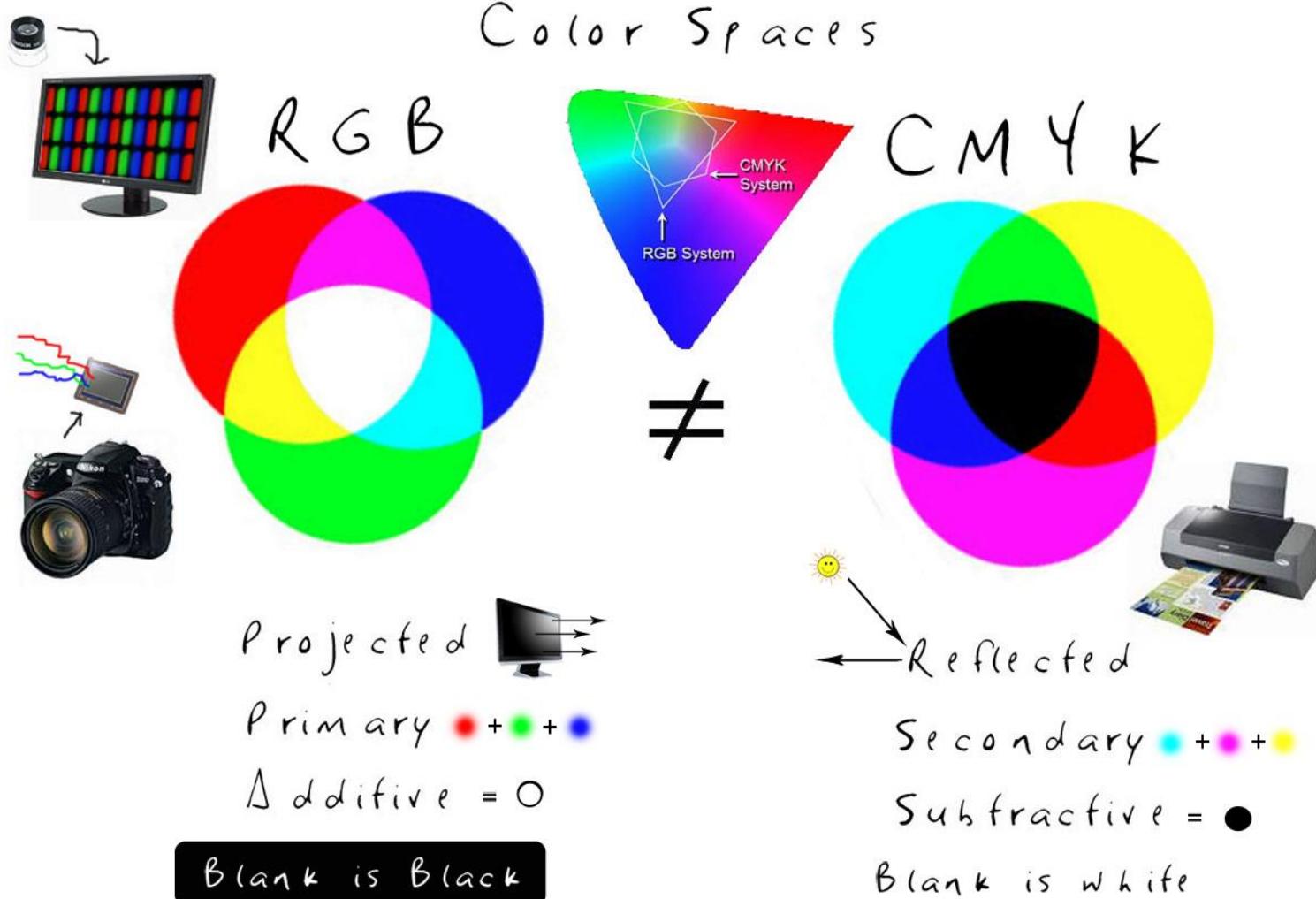
Color  
Image



Grey  
Image

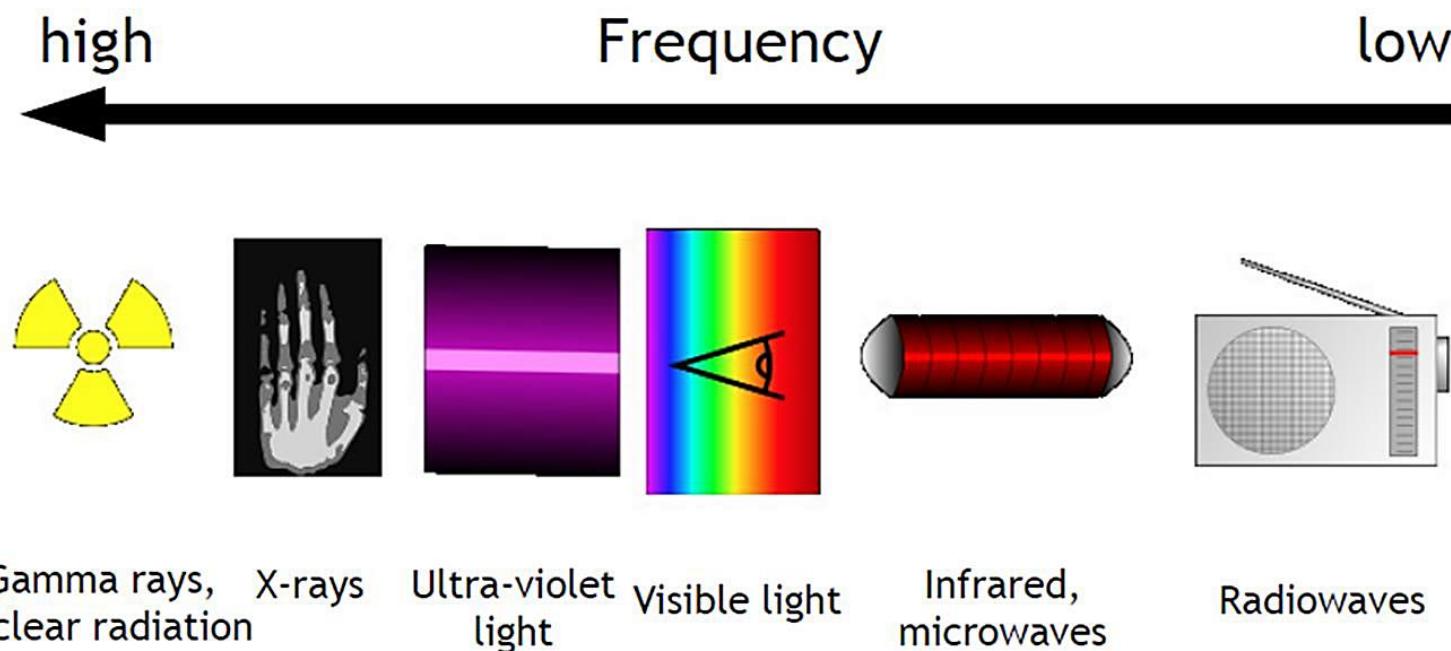


# Color Space



# Light---Visible Light

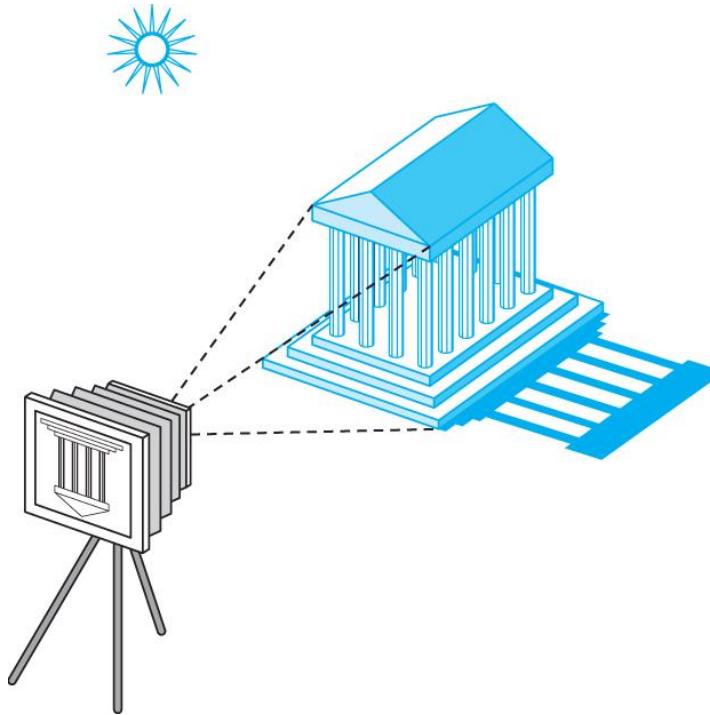
- Light is a part of electromagnetic wave, it is a wave.
- It's visible range: between 350nm and 780nm
  - ▶ Different frequencies



# Image Synthetic Element

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- Object
- Observer
- Light

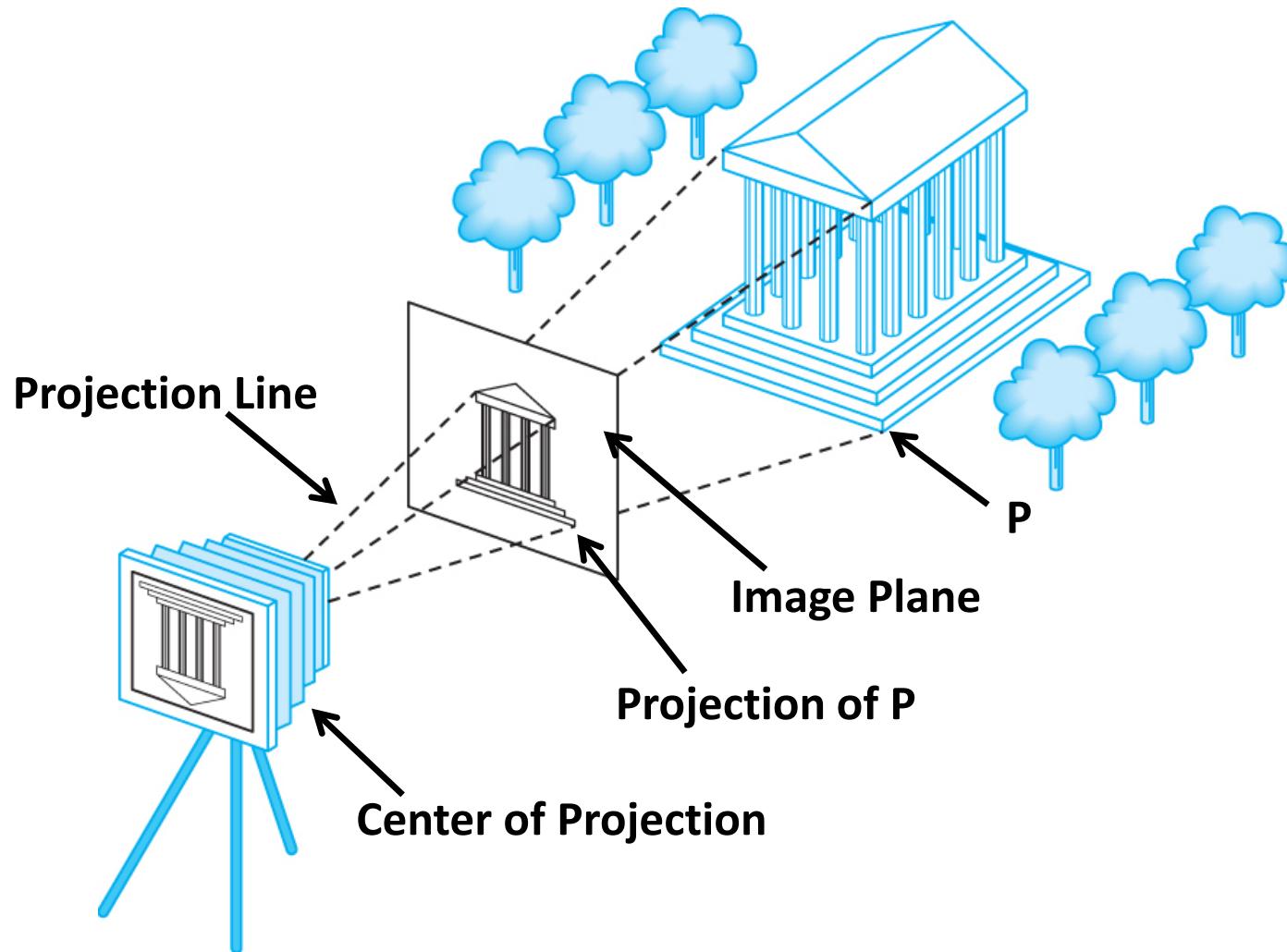


- Properties of Light, material: To determine the effect of light on the object



# Synthetic camera model

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# Advantages of Synthetic camera model

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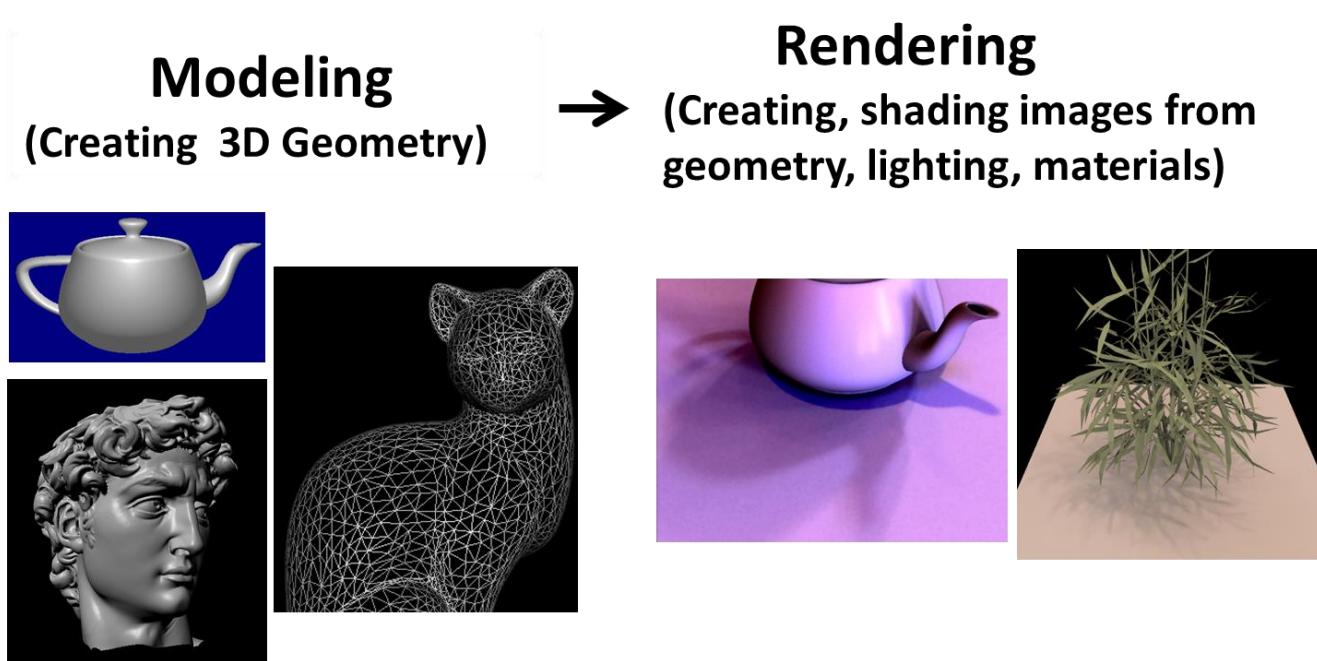
- Object (物体), Observer (观察者) and light (光源) is complete independent
- 2D graphics is a special case of 3D
- Easy to implement by API
  - Set the properties of light, camera and material.
  - To determine the results of image by API.
- Quick hardware implement is supported :OpenGL, Direct 3D etc. is based on this model.



# Outline

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- Computer Graphics System
- Physical Imaging System
- **Graphics Rendering Pipeline**



# Demo - World War Z

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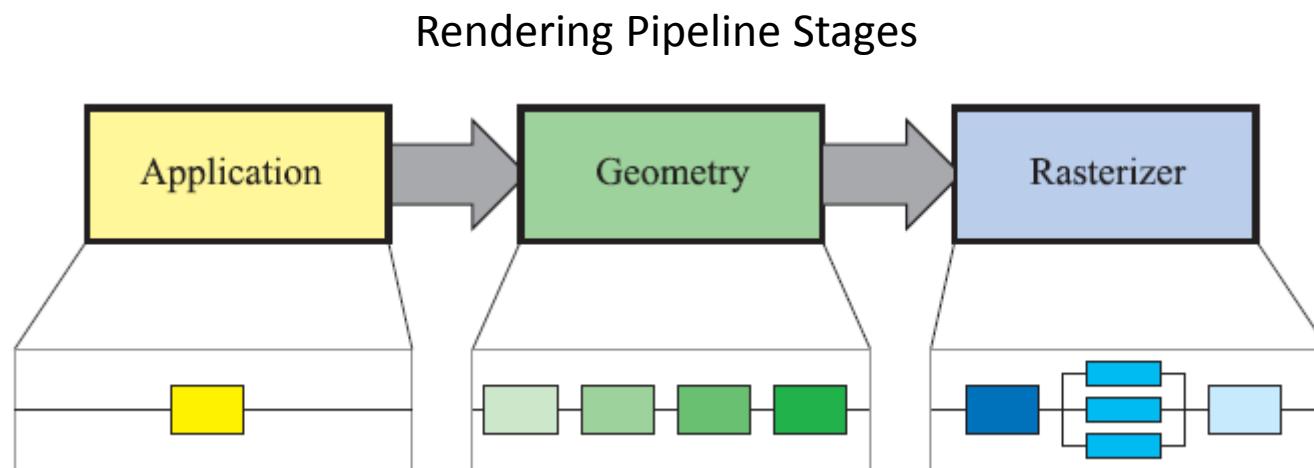
World War Z  
VFX Technical Breakdown



# Graphics Rendering Pipeline

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- What is Rendering?
  - “Rendering is a process that takes as its input a set of objects and produces as its output an array of pixels.”
    - 《Fundamentals of Computer Graphics (3rd Edition)》
- What is the rendering process (Graphic Pipeline)?
  - the sequence of steps used to create a 2D raster representation of a 3D scene.



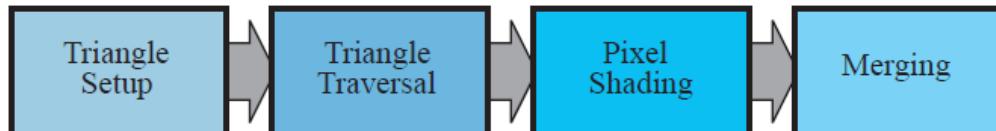
# Rendering Pipeline Stages

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- Application
  - e.g. collision detection, global acceleration algorithms, animation, physics simulation..... (On CPU)
- Geometry
  - Deal with transforms, projection. Computes what is to be draw, how it should be drawn, and where it should be drawn (On GPU)



- Rasterizer
  - Conversion from two-dimensional vertices in screen space – each with a z-value (depth value), and various shading information associated with each vertex – into pixels on the screen (On GPU)



# Rendering Pipeline

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- Abstract model
  - sequence of operations to transform geometric model into digital image
  - graphics hardware workflow
- Underlying API model for programming graphics hardware
  - OpenGL
  - Direct 3D
- Many actual implementations



# Direct 3D Samples

DirectX Sample Browser (June 2010)

[DirectX Developer Center](#) [DirectX SDK Documentation](#) [Windows Graphics Documentation](#)  [search](#) [clear](#)

*show* —  *sort by* —   Auto-launch documentation

**10BitScanout10** C++ (August 2009) [beginner](#) [sample](#) 

This sample produces a linear gray scale test pattern in both 8 and 10 bit color and displays it on multiple monitors to enable direct comparison.

[32-bit Executable](#) [64-bit Executable](#) [Documentation](#) [Install Project](#)

**DDSWithoutD3DX** C++ (August 2009) [intermediate](#) [sample](#) 

DDS texture loading without using the D3DX helper functions.

[32-bit Executable](#) [64-bit Executable](#) [Documentation](#) [Install Project](#)

**HDAO10.1** C++ (August 2009) [intermediate](#) [sample](#) 

This sample, contributed by AMD, presents an innovative technique for achieving High Definition Ambient Occlusion (HDAO). It utilizes Direct3D 10.1 APIs and hardware, making use of the new shader model 4.1 gather4 instruction, to greatly accelerate the performance of this technique.

[32-bit Executable](#) [64-bit Executable](#) [Documentation](#) [Install Project](#)

**TransparencyAA10.1** C++ (August 2009) [intermediate](#) [sample](#) 

This sample, contributed by AMD, presents a technique for achieving MSAA quality rendering for primitives that require transparency. It utilizes Direct3D 10.1 APIs and hardware to make use of the new fixed MSAA sample patterns, and the export of the coverage mask from the pixel shader.



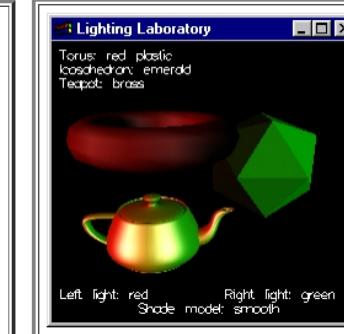
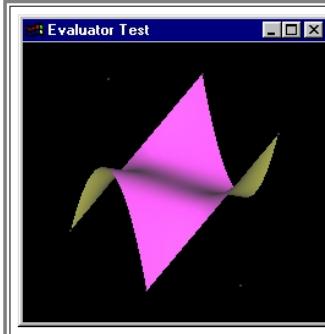
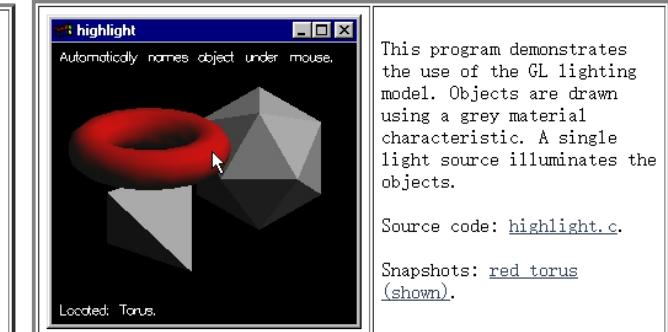
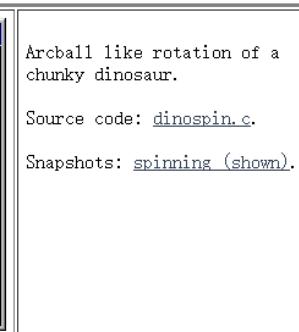
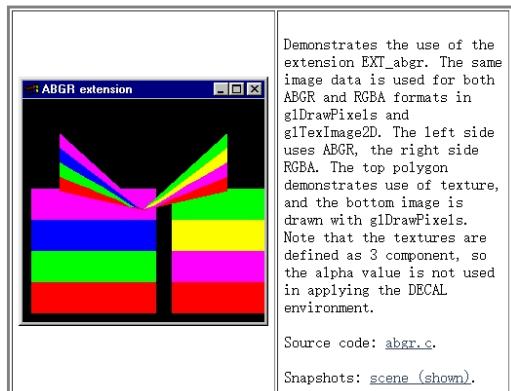
# OpenGL Samples

- Learn OpenGL demos

<https://learnopengl.com/> or <https://learnopengl-cn.github.io/>



[examples.zip](#)



# Samples

## • NVIDIA GameWorks™ Samples Overview

<https://developer.nvidia.com/gameworks-samples-overview>

### NVIDIA GameWorks™ OpenGL Samples

Get the documentation or download the NVIDIA GameWorks™ OpenGL samples here:

[Download >](#)

New Browse or Clone Source from GitHub:

[GitHub >](#)

#### New samples in 2.0:

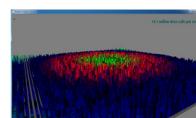
- Blended Antialiasing Sample
- Cascaded Shadow Mapping Sample
- Conservative Rasterization Sample
- Normal-Blended Decal Sample
- Weighted, Blended, Order-independent Transparency Sample

#### Bindless Graphics Sample

- Category: **Performance**

This sample demonstrates the large performance increase in OpenGL that is made possible by 'Bindless Graphics'. These extensions allow applications to draw large numbers of objects with only a few setup calls, rather than a few calls per object, thus reducing the driver overhead necessary to render highly populated scenery.

[Docs >](#)

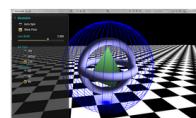


#### ★NEW: Blended AA

- Category: **Performance, Visuals**

This sample implements a two-pass additive blending anti-aliasing technique using Target-Independent Rasterization [TIR], which should give comparable results to MSAA with a reduced memory footprint.

[Docs >](#)



#### Bloom Sample

- Category: **Visuals**

This sample demonstrates creating a glow effect by post-processing the main scene. It heavily leverages FBO render targets across multiple steps/passes with custom effects processing shaders. It also integrates shadow mapping to demonstrate self-illumination cutting through the shadow effects.

[Docs >](#)



### NVIDIA GameWorks™ DirectX Samples

Get the documentation or download the NVIDIA GameWorks™ Direct3D samples here:

[Download >](#)

New Browse or Clone Source from GitHub:

[GitHub >](#)

#### New samples in 1.2:

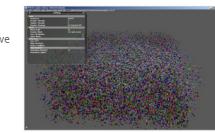
- Antialiased Deferred Rendering
- Motion Blur D3D Advanced Sample

#### D3D Deferred Contexts Sample

- Category: **Performance**

This sample shows how to use D3D11 Deferred Rendering contexts to lower the CPU overhead and improve performance when rendering large numbers of objects per frame, in situations where instancing is not feasible.

[Docs >](#)



#### FXAA 3.11 Sample

- Category: **Performance, Visuals**

This sample presents a high performance and high quality screen-space software approximation to anti-aliasing called FXAA.

[Docs >](#)

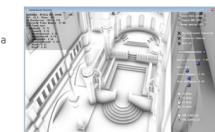


#### Deinterleaved Texturing Sample

- Category: **Performance, Visuals**

This sample demonstrates how a large, sparse and jittered post-processing filter (here a SSAO pass with a 4x4 random texture) can be made more cache-efficient by using a Deinterleaved Texturing approach.

[Docs >](#)



# OpenGL Rendering Pipeline

