

# **Complex Networks: Quiz #9**

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## Problem 1

Make a program of Dijkstra's algorithm without built-in functions (dijkstra\_path & dijkstra\_path\_length).

### Answer 1

```
import networkx as nx
import matplotlib.pyplot as plt
import numpy as np
import sys
import functools
import operator

G = nx.Graph()
G.add_nodes_from(range(0, 5))
G.add_weighted_edges_from([(0, 1, 7), (0, 2, 9), (0, 5, 14), (1, 2, 10), (1, 3, 15), (2, 3,
11), (2, 5, 2), (3, 4, 6), (4, 5, 9)])

plt.figure(figsize=(5, 5))
pos = nx.spring_layout(G)
nx.draw_networkx_edges(G, pos)
nx.draw_networkx_nodes(G, pos)
nx.draw_networkx_edge_labels(G, pos, font_size=16, edge_labels={(u, v): d["weight"] for u, v,
d in G.edges(data=True)}})
nx.draw_networkx_labels(G, pos)
plt.axis('off')
plt.show()

# find the smallest one
dist_estimate = [sys.maxsize] * nx.number_of_nodes(G)
# real distance
dist_certainty = [0] * nx.number_of_nodes(G)
dist_estimate[1] = 0

print(dist_estimate)
print(dist_certainty)

#
# please fill in this part (Dijkstra's algorithm)
# calculate the distance from 1 -> 4

n = 0
distance = 0
count = 1
temp_nodes = 0

for visited in dist_certainty:
    if (visited <= 1):
        # find the smallest estimate in G
        for nodes in G:
            if (dist_certainty[nodes] == 0):
                temp_min = dist_estimate[nodes]
                break
        for nodes in G:
            if (dist_certainty[nodes] == 0):
                if (dist_estimate[nodes] <= temp_min and dist_estimate[nodes] < 10000):
                    temp_min = dist_estimate[nodes]
                    temp_node = nodes
        current_distance = temp_min
        current_node = temp_node
```

```

print("In step",count,":")
print("current_distance = ", current_distance)
print("current_node = ", current_node)

#     mark this distance as certain
dist_certainty[current_node] = 1
#     calculate the distance and compare
for neighbor in G.neighbors(current_node):
    if (dist_certainty[neighbor] != 1):
        weight = list(dict.values(G.get_edge_data(current_node,neighbor)))
        current_weight = int(weight[0])
        distance = current_distance + current_weight
        if(distance < dist_estimate[neighbor]):
            dist_estimate[neighbor] = distance

print("dist_estimate",dist_estimate)
print("dist_certainty",dist_certainty)
count = count + 1

#####
# print(dist_estimate)
# print(dist_certainty)
print("From built-in function:")
print(nx.dijkstra_path(G,1,4))
print(nx.dijkstra_path_length(G,1,4))

```

The result is:

```

[9223372036854775807, 0, 9223372036854775807, 9223372036854775807, 9223372036854775807,
9223372036854775807]

[0, 0, 0, 0, 0, 0]
In step 1 :
current_distance = 0
current_node = 1
dist_estimate [7, 0, 10, 15, 9223372036854775807, 9223372036854775807]
dist_certainty [0, 1, 0, 0, 0, 0]
In step 2 :
current_distance = 7
current_node = 0
dist_estimate [7, 0, 10, 15, 9223372036854775807, 21]
dist_certainty [1, 1, 0, 0, 0, 0]
In step 3 :
current_distance = 10
current_node = 2
dist_estimate [7, 0, 10, 15, 9223372036854775807, 12]
dist_certainty [1, 1, 1, 0, 0, 0]
In step 4 :
current_distance = 12
current_node = 5
dist_estimate [7, 0, 10, 15, 21, 12]
dist_certainty [1, 1, 1, 0, 0, 1]
In step 5 :
current_distance = 15
current_node = 3
dist_estimate [7, 0, 10, 15, 21, 12]
dist_certainty [1, 1, 1, 1, 0, 1]
In step 6 :

```

```
current_distance = 21
current_node = 4
dist_estimate [7, 0, 10, 15, 21, 12]
dist_certainty [1, 1, 1, 1, 1, 1]
From built-in function:
[1, 2, 5, 4]
21
```

## Problem 2

Show all the statuses of current estimates and their certainties while Dijkstra's algorithm is performed from vertex 0.

### Answer 2

According to the algorithm above, when the Dijkstra is from vertex 0, change `dist_estimate[0]` to 0.  
The result is:

```
In step 1 :
current_distance = 0
current_node = 0
dist_estimate [0, 7, 9, 9223372036854775807, 9223372036854775807, 14]
dist_certainty [1, 0, 0, 0, 0, 0]
In step 2 :
current_distance = 7
current_node = 1
dist_estimate [0, 7, 9, 22, 9223372036854775807, 14]
dist_certainty [1, 1, 0, 0, 0, 0]
In step 3 :
current_distance = 9
current_node = 2
dist_estimate [0, 7, 9, 20, 9223372036854775807, 11]
dist_certainty [1, 1, 1, 0, 0, 0]
In step 4 :
current_distance = 11
current_node = 5
dist_estimate [0, 7, 9, 20, 20, 11]
dist_certainty [1, 1, 1, 0, 0, 1]
In step 5 :
current_distance = 20
current_node = 4
dist_estimate [0, 7, 9, 20, 20, 11]
dist_certainty [1, 1, 1, 0, 1, 1]
In step 6 :
current_distance = 20
current_node = 3
dist_estimate [0, 7, 9, 20, 20, 11]
dist_certainty [1, 1, 1, 1, 1, 1]
From built-in function:
[0, 2, 5, 4]
20
```

## Problem 3

Start from vertex 1 and show all the statuses & their certainties.

### Answer 3

The result is same as the result in Problem 1:

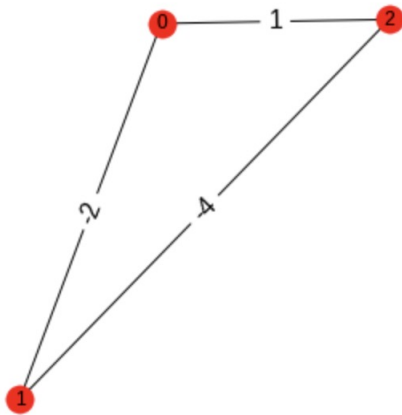
```
In step 1 :
current_distance = 0
current_node = 1
dist_estimate [7, 0, 10, 15, 9223372036854775807, 9223372036854775807]
dist_certainty [0, 1, 0, 0, 0, 0]
In step 2 :
current_distance = 7
current_node = 0
dist_estimate [7, 0, 10, 15, 9223372036854775807, 21]
dist_certainty [1, 1, 0, 0, 0, 0]
In step 3 :
current_distance = 10
current_node = 2
dist_estimate [7, 0, 10, 15, 9223372036854775807, 12]
dist_certainty [1, 1, 1, 0, 0, 0]
In step 4 :
current_distance = 12
current_node = 5
dist_estimate [7, 0, 10, 15, 21, 12]
dist_certainty [1, 1, 1, 0, 0, 1]
In step 5 :
current_distance = 15
current_node = 3
dist_estimate [7, 0, 10, 15, 21, 12]
dist_certainty [1, 1, 1, 1, 0, 1]
In step 6 :
current_distance = 21
current_node = 4
dist_estimate [7, 0, 10, 15, 21, 12]
dist_certainty [1, 1, 1, 1, 1, 1]
From built-in function:
[1, 2, 5, 4]
21
```

## Problem 4

Explain the reasons why Dijkstra's algorithm does not work for negative weight edges.

### Answer 4

Because when we think a vertex is visited and change its value in *dist\_certainty* to 1, it will not be visited anymore. If a vertex is in visited, we will think we have already found the shortest path to this vertex. However, this doesn't work in negative path. For example, if a graph with negative edge is like this:



When we start from vertex 0, we think the shortest path to 1 is -2, but it is actually -3 (from vertex 2 to vertex 1).