

## Compile OpenCV 3.0.0 + OpenCV Contrib for Python on Raspberry Pi 2B

### Step 1:

# update and upgrade before anything further

1. \$ sudo apt-get update
2. \$ sudo apt-get upgrade
3. \$ sudo rpi-update (can be skipped, but recommended)

### Step 2:

\$ sudo apt-get install build-essential cmake pkg-config

### Step 3:

\$ sudo apt-get install libjpeg8-dev libtiff4-dev libjasper-dev libpng12-dev

### Step 4:

\$ sudo apt-get install libgtk2.0-dev

### Step 5:

\$ sudo apt-get install libavcodec-dev libavformat-dev libswscale-dev libv4l-dev

### Step 6:

1. \$ sudo apt-get install libatlas-base-dev gfortran
2. \$ sudo apt-get install python-numpy python-scipy python-matplotlib
3. \$ sudo apt-get install default-jdk ant
4. \$ sudo apt-get install libgtkglext1-dev
5. \$ sudo apt-get install v4l-utils

### Step 7:

# install pip

1. \$ wget https://bootstrap.pypa.io/get-pip.py
2. \$ sudo python get-pip.py

### Step 8:

\$ sudo apt-get install python2.7-dev

### Step 9:

\$ pip install numpy

### Step 10:

# download OpenCV 3.0.0 and unpack it

1. \$ cd ~
2. \$ wget -O opencv.zip https://github.com/Itseez/opencv/archive/3.0.0.zip
3. \$ unzip opencv.zip

# Contrib Libraries

1. \$ wget -O opencv\_contrib.zip [https://github.com/Itseez/opencv\\_contrib/archive/3.0.0.zip](https://github.com/Itseez/opencv_contrib/archive/3.0.0.zip)
2. \$ unzip opencv\_contrib.zip

#### Step 11:

# preparing the build

1. \$ cd ~/opencv-3.0.0/
2. \$ mkdir build
3. \$ cd build
4. \$ cmake -D CMAKE\_BUILD\_TYPE=RELEASE \  
-D CMAKE\_INSTALL\_PREFIX=/usr/local \  
-D INSTALL\_C\_EXAMPLES=ON \  
-D INSTALL\_PYTHON\_EXAMPLES=ON \  
-D OPENCV\_EXTRA\_MODULES\_PATH=~/opencv\_contrib-3.0.0/modules \  
-D BUILD\_EXAMPLES=ON ..

#### Step 12:

# takes about 3.5 to 4 hours

\$ make -j4 (I prefer -j3, because it doesn't use all the cores so it keeps the RasPi cool enough)

#### Step 13:

# installing the build prepared in step 11

1. \$ sudo make install
2. \$ sudo ldconfig

#### Step 14:

1. \$ sudo nano /etc/ld.so.conf.d/opencv.conf

# opencv.conf will be blank, add the following line, then save and exit nano:

/usr/local/lib # enter this in opencv.conf, NOT at the command line  
(leave a blank line at the end of opencv.conf)

# save opencv.conf by pressing ctrl+o

# get back again to the command line by pressing ctrl+x

2. \$ sudo ldconfig

3. \$ sudo nano /etc/bash.bashrc

# add the following lines at the bottom of bash.bashrc

PKG\_CONFIG\_PATH=\$PKG\_CONFIG\_PATH:/usr/local/lib/pkgconfig  
export PKG\_CONFIG\_PATH

# (leave a blank line at the end of bash.bashrc)

# save bash.bashrc changes (ctrl+o), then back at the command line (ctrl+x),

#### Step 15:

# Reboot

```
$ sudo shutdown -r now
```

### **Step 16 Last Step:**

# verifying the installation

Open Python 2 IDLE on RasPi

# Type the following lines in the python shell:

```
>>> import cv2
```

```
>>> print cv2.__version__
```

# the following line should appear then:

```
'3.0.0'
```

**Done**

