```
Step 1:
# update and upgrade before anything further
$ sudo apt-get update
$ sudo apt-get upgrade
$ sudo rpi-update (can be skipped, but recommended)
Step 2:
$ sudo apt-get install build-essential cmake pkg-config
Step 3:
\$ sudo apt-get install libjpeg8-dev libtiff4-dev libjasper-dev libpng12-dev
Step 4:
$ sudo apt-get install libgtk2.0-dev
Step 5:
$ sudo apt-get install libavcodec-dev libavformat-dev libswscale-dev libv41-
Step 6:
$ sudo apt-get install libatlas-base-dev gfortran
$ sudo apt-get install python-numpy python-scipy python-matplotlib
$ sudo apt-get install default-jdk ant
$ sudo apt-get install libgtkglext1-dev
$ sudo apt-get install v4l-utils
Step 7:
# install pip
$ wget https://bootstrap.pypa.io/get-pip.py
$ sudo python get-pip.py
Step 8:
$ sudo apt-get install python2.7-dev
Step 9:
$ pip install numpy
# download OpenCV 3.0.0 and unpack it
$ cd ~
$ wget -O opencv.zip https://github.com/Itseez/opencv/archive/3.0.0.zip
$ unzip opencv.zip
# Contrib Libraries
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$ wget -O opencv contrib.zip
https://github.com/Itseez/opencv contrib/archive/3.0.0.zip
$ unzip opencv contrib.zip
Step 11:
# preparing the build
$ cd ~/opencv-3.0.0/
$ mkdir build
$ cd build
$ cmake -D CMAKE BUILD TYPE=RELEASE \
       -D CMAKE INSTALL PREFIX=/usr/local \
       -D INSTALL C EXAMPLES=ON \
       -D INSTALL PYTHON EXAMPLES=ON \
       -D OPENCV EXTRA MODULES PATH=~/opencv contrib-3.0.0/modules \
       -D BUILD EXAMPLES=ON ..
Step 12:
# takes about 3.5 to 4 hours
$ make -j4 (I prefer -j3, because it doesn't use all the cores so it keeps
the RasPi cool enough)
Step 13:
# installing the build prepared in step 11
$ sudo make install
$ sudo ldconfig
Step 14:
$ sudo nano /etc/ld.so.conf.d/opencv.conf
# opency.conf will be blank, add the following line, then save and exit nano:
/usr/local/lib
                        # enter this in opency.conf, NOT at the command line
                       (leave a blank line at the end of opency.conf)
# save opency.conf by pressing ctrl+o
# get back again to the command line by pressing ctrl+x
$ sudo ldconfig
$ sudo nano /etc/bash.bashrc
# add the following lines at the bottom of bash.bashrc
PKG CONFIG PATH=$PKG CONFIG PATH:/usr/local/lib/pkgconfig
export PKG CONFIG PATH
# (leave a blank line at the end of bash.bashrc)
# save bash.bashrc changes (ctrl+o), then back at the command line (ctrl+x),
Step 15:
# Reboot
```

```
$ sudo shutdown -r now

Step 16 Last Step:
# verifying the installation

Open Python 2 IDLE on RasPi
# Type the following lines in the python shell:

>>> import cv2
>>> print cv2.__version__
# the following line should appear then:
'3.0.0'
```

Done