

# **High performance computing in fish school simulation by vortex sheet method**

**Fang Fang**

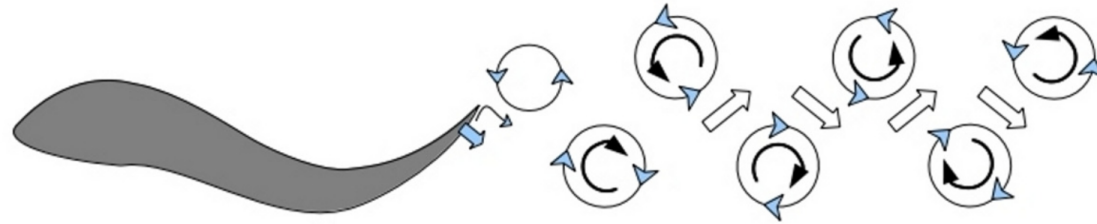
**Applied Math Lab@Courant Inst.**

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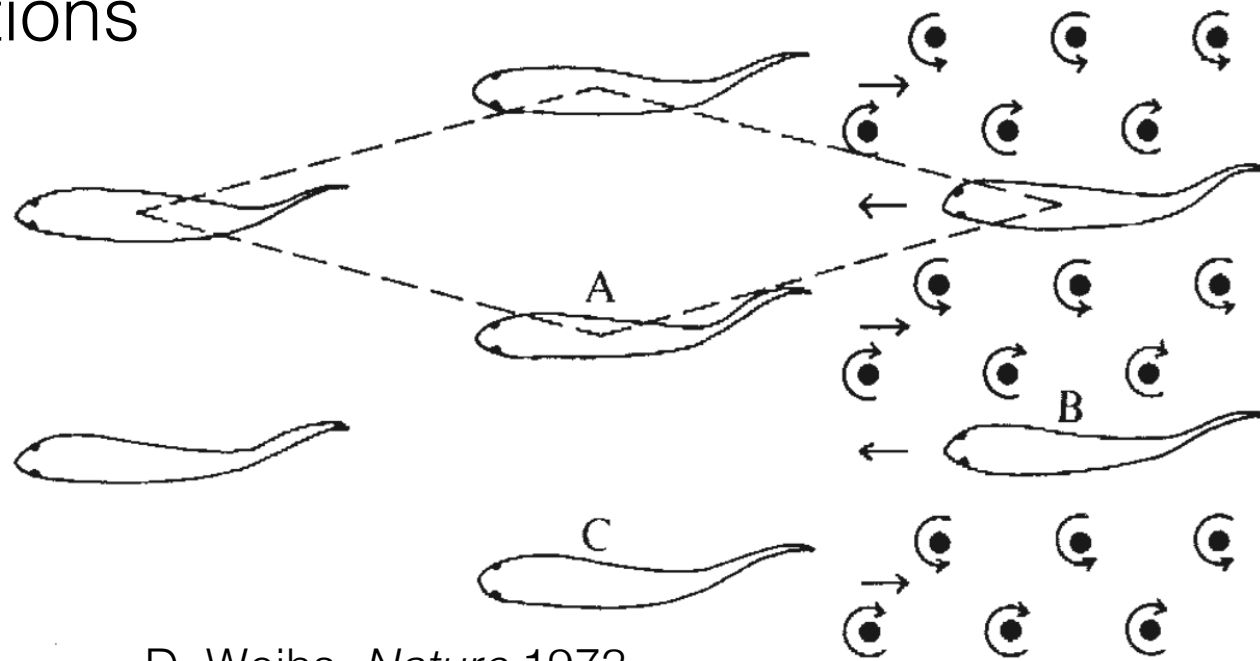
# Hydrodynamics of fish schooling – 2D modeling

- Fish propels itself by shedding fluid vortices



J. Wills, *PeerJ* 2003

- School simulation is complicated — fluid-structure interaction, multi-body interactions

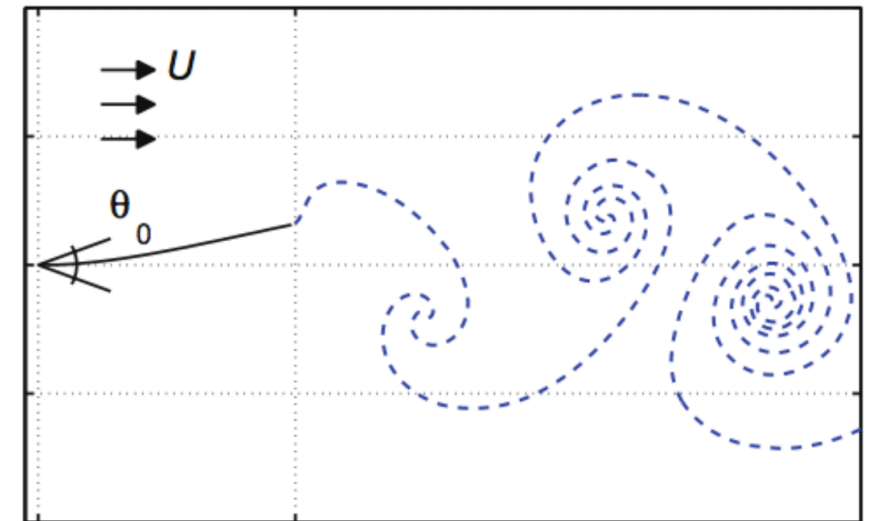


D. Weihs, *Nature* 1973

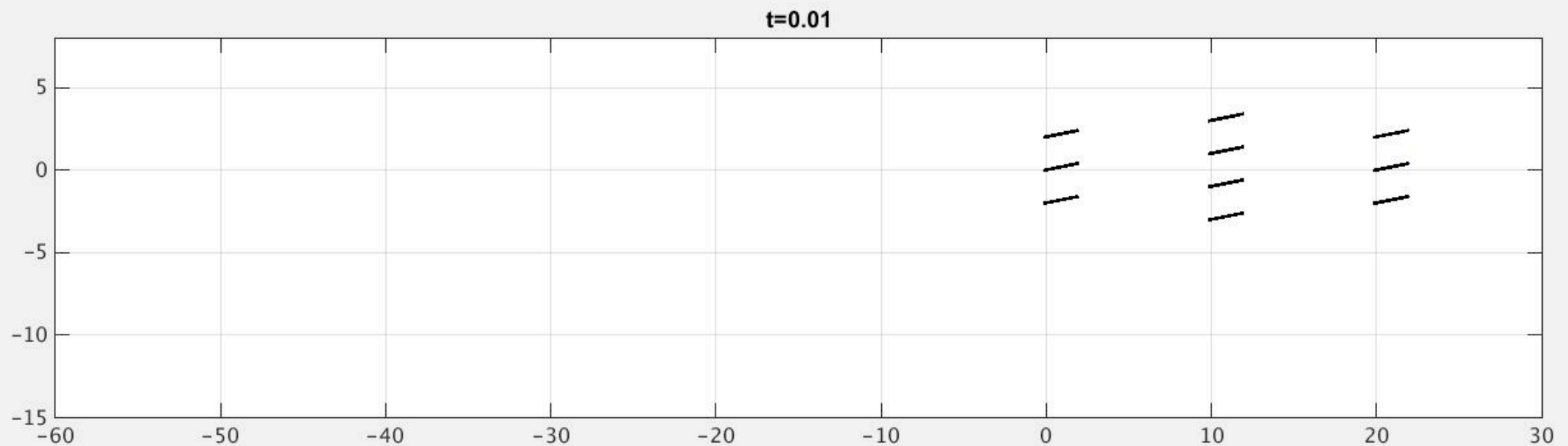
- School simulation is expensive
  - Number of fish in a school can be large,  $N \sim 1000$  or more

# A fish school model using vortex sheet method

- Each fish is modeled as a 1D flapping plate
- Prescribed flapping motion w.r.t. fish head
- Individual fish swims freely under hydrodynamic force and torque
- Fish sheds vorticity (vortex sheet) into fluid from tail, vortex sheet develops in flow



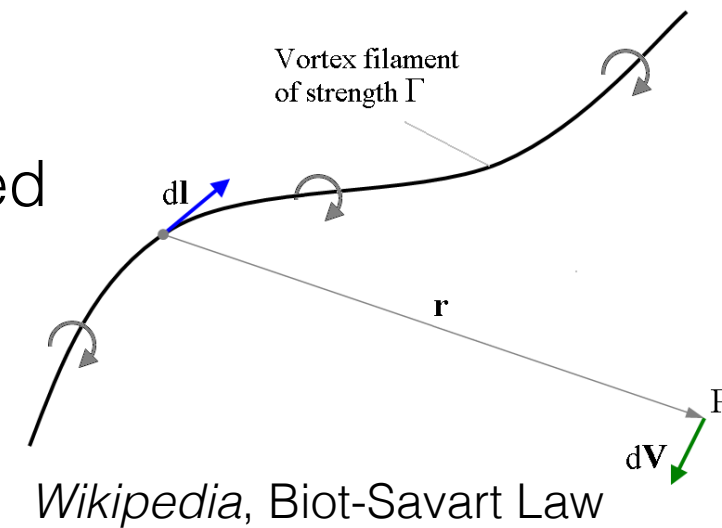
S. Alben, *JCP* 2009



# Sketch of simulation algorithm

- Biot-Savart law:** Evaluate fluid velocity field  $\mathbf{u} = (u, v)$  induced by vortex sheets

$$\overline{w(z, t)} = u(z, t) - iv(z, t) = \frac{1}{2\pi i} \sum_{k=1, \dots, N} \int_{C_k^b + C_k^f} \frac{\gamma_k(s, t)}{z - \zeta_k(s, t)} ds. \quad (1)$$



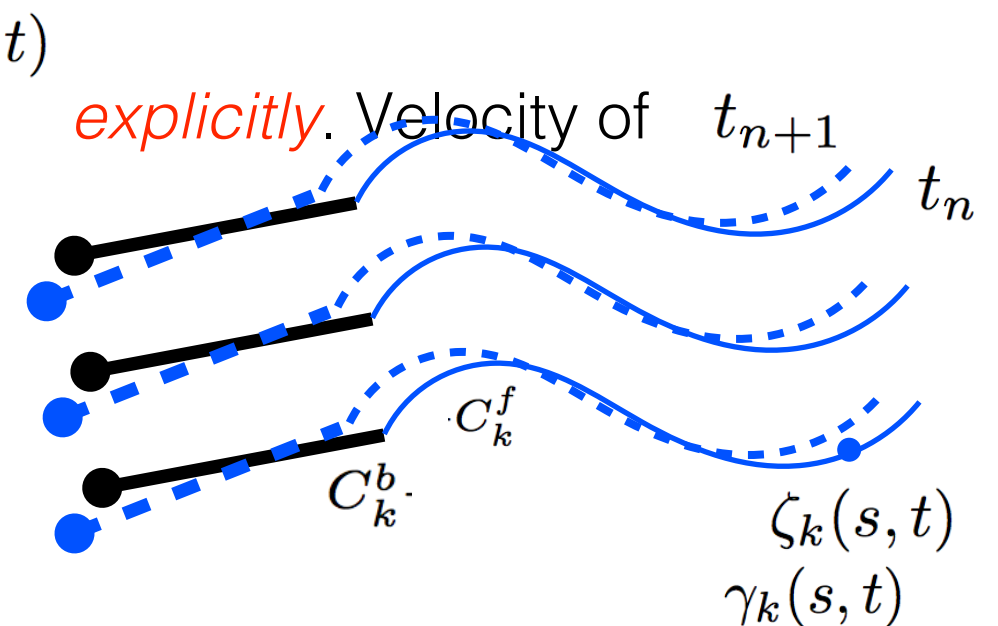
$$t_n \rightarrow t_{n+1}$$

- From time step  $t_n$  to  $t_{n+1}$ :

**Step 1.** Update positions of free vortex sheets  
 sheets are evaluated through (1).

**Expensive!**

$$\zeta^{n+1} = \zeta^n + \frac{3}{2} \Delta t w^n - \frac{1}{2} \Delta t w^{n-1}, \quad w = u + iv$$



**Step 2.** Through a nonlinear quasi-Newton solver, *implicitly* solve for fish position  $\mathbf{X}_k$ , orientation  $\mathbf{p}_k$ , vorticity distribution, and vortex shedding.

$$Re \left( \overline{(w^{n+1} - \dot{\zeta}^{n+1}) \hat{n}^{n+1}} \right) = 0$$

**Expensive!**

$$\mathbf{u} \cdot \hat{\mathbf{n}} = \dot{\mathbf{x}} \cdot \hat{\mathbf{n}}, \quad Re \left( \overline{(w - \dot{\zeta}) \hat{n}} \right) = 0$$

$$m \ddot{\mathbf{X}}_k = \mathbf{F}_k, \quad I \ddot{\mathbf{p}}_k = \mathbf{T}_k$$



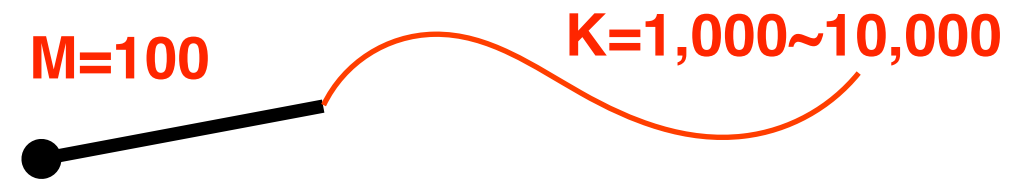
$$\begin{aligned} \frac{\mathbf{X}^{n+1} - \mathbf{X}^n}{\Delta t} &= \frac{1}{2} (\dot{\mathbf{X}}^{n+1} + \dot{\mathbf{X}}^n), \\ m \frac{\dot{\mathbf{X}}^{n+1} - \dot{\mathbf{X}}^n}{\Delta t} &= \frac{1}{2} (\mathbf{F}^{n+1} + \mathbf{F}^n). \end{aligned}$$

# Parallelism of the *explicit* step

# of fish:  $N=10\sim1,000$

# of points on each fish:  $M=100$

# of points on each vortex sheet:  $K=1,000\sim10,000$



Total body points:  $N*M=1,000\sim1e5$

Total vortex sheet points:  $N*K=1e4\sim1e7$

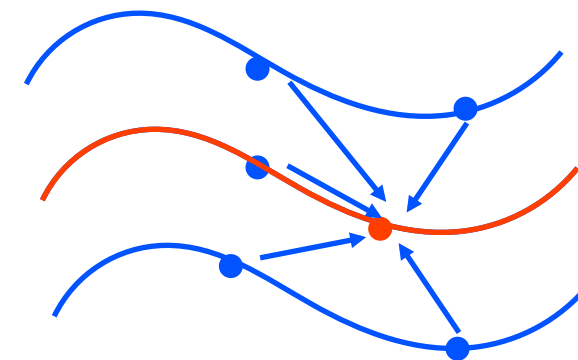
## Parallel evaluations of vortex sheets velocity ( $NK$ targets, $NM+NK$ sources)

- Induced by sheets — FMM summation over kernel  $1/z$ ,  $NK$  points self-interaction

$O(N^2K^2)$  (direct)  $\longrightarrow$   $O(NK*\log NK)$  (FMM) ✓

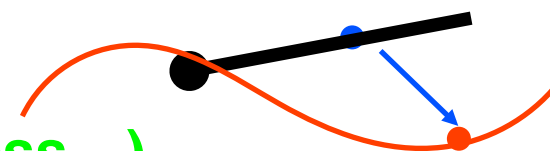
- Correct self sheet interaction with smoothing kernel  $\frac{\bar{z}}{|z|^2+\delta^2}$  parallelize  $O(K^2)$  over  $N$  fish

$O(NK^2)$  (serial)  $\longrightarrow$   $O(K^2)$  (parallel) ✓ (tests shown later)



- Induced by fish bodies — near singular quadrature, singularity subtraction techniques, parallelize  $O(MK)$  over  $N$  fish and  $N$  sheets

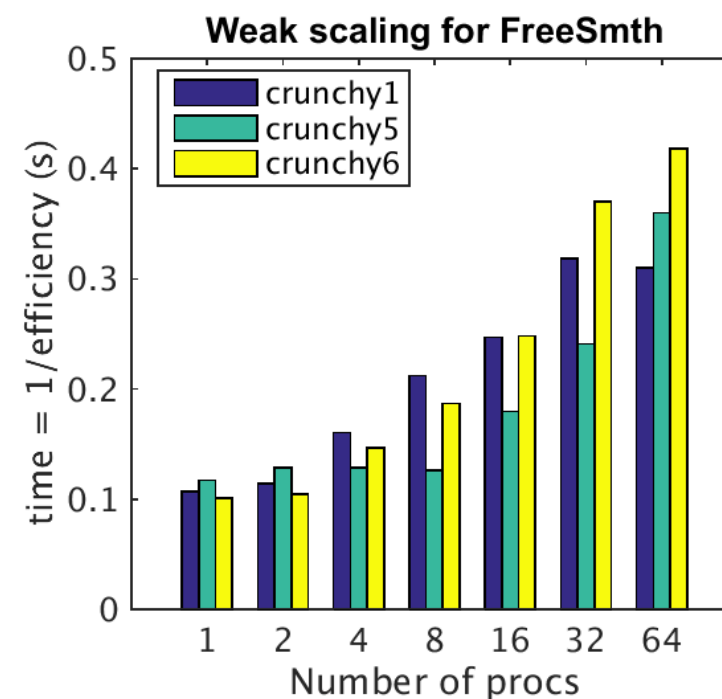
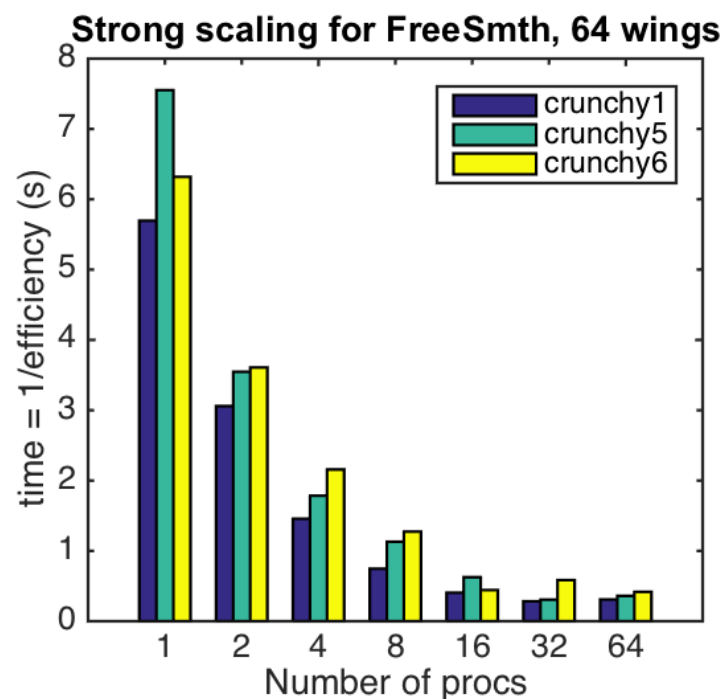
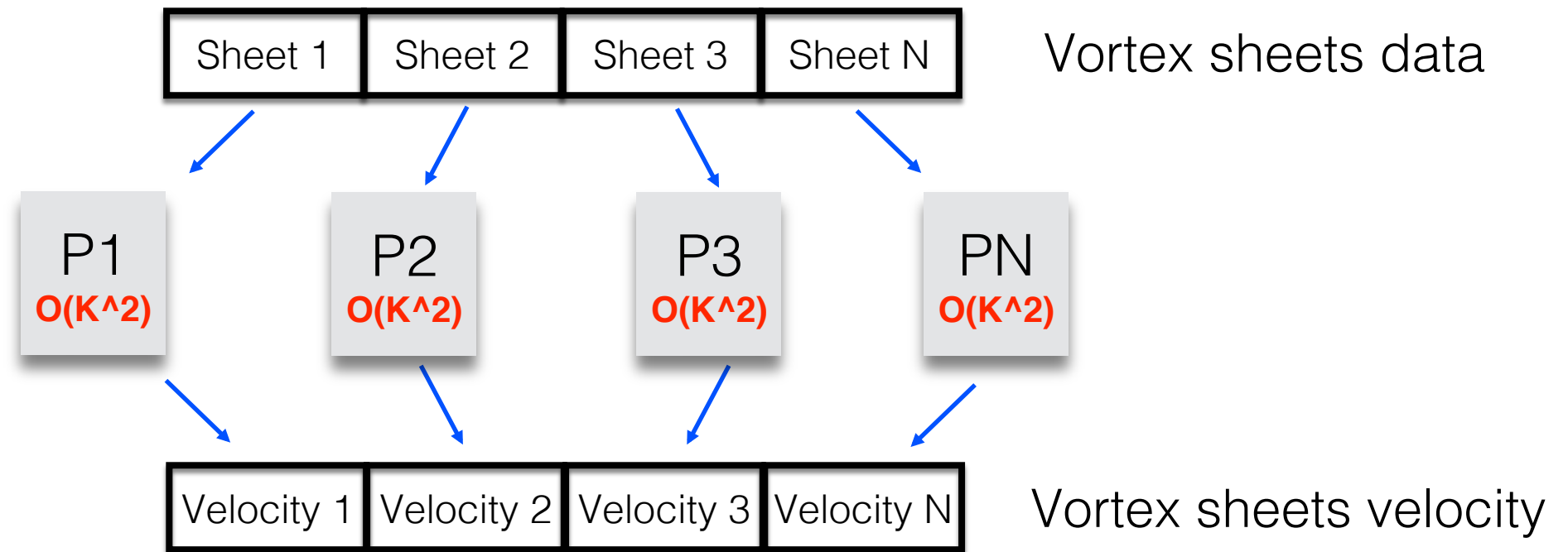
$O(N^2KM)$  (serial)  $\longrightarrow$   $O(MK)$  (parallel) (in progress...)



$O(NK*(NM+NK))$  serial direct  $\longrightarrow$   $O(NK*\log NK)+O(K^2)+O(MK) \sim O(K^2)$  with FMM and parallelism

# Parallelize vortex sheets self-interaction corrections

- Generate **N** fake vortex sheets in Matlab, implement OpenMP with C++, compiled into Matlab mex functions. **K=1,000** points on each sheet,

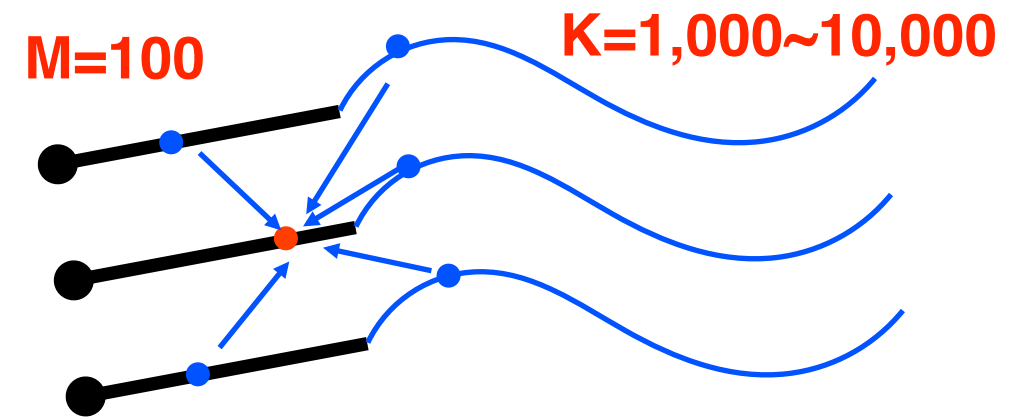


# Parallelism of the *implicit* step

# of fish:  $N=10\sim 1,000$

Total body points:  $N*M=1,000\sim 1e5$

Total vortex sheet points:  $N*K=1e4\sim 1e7$



## Parallelizing evaluations of velocity on fish bodies

- $N$  independent implicit solvers, each solver performs  $P$  newton iterations
- $NP$  calls of single body velocity evaluation, in each call  $M$  targets,  $(N-1)*M+N*K$  sources
- Parallel over  $N$  implicit solvers (in progress...)
- Body velocity induced by other bodies — FMM of kernel  $1/z$ ,  $M$  targets,  $(N-1)*M$  targets

$O(NM^2)$  (direct)  $\longrightarrow$  less than  $O(NM*\log NM)$  (FMM) ✓

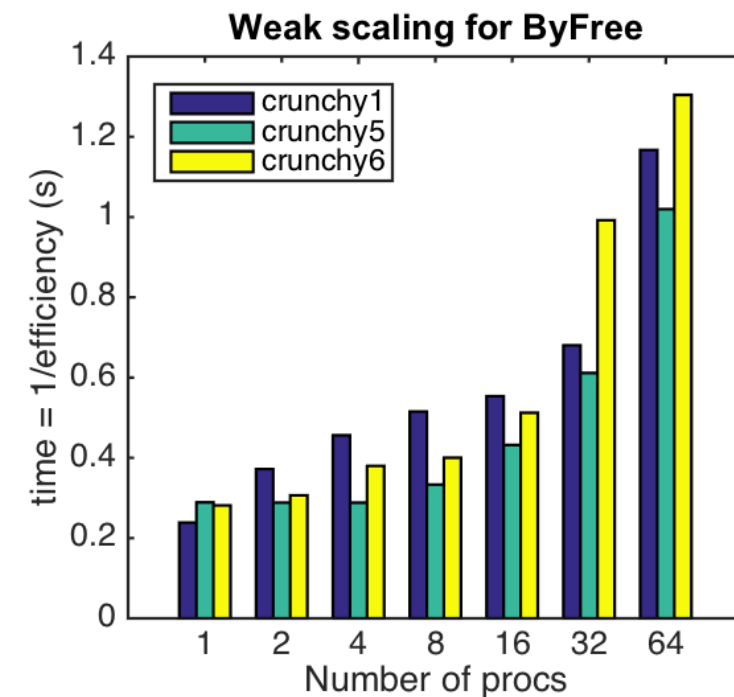
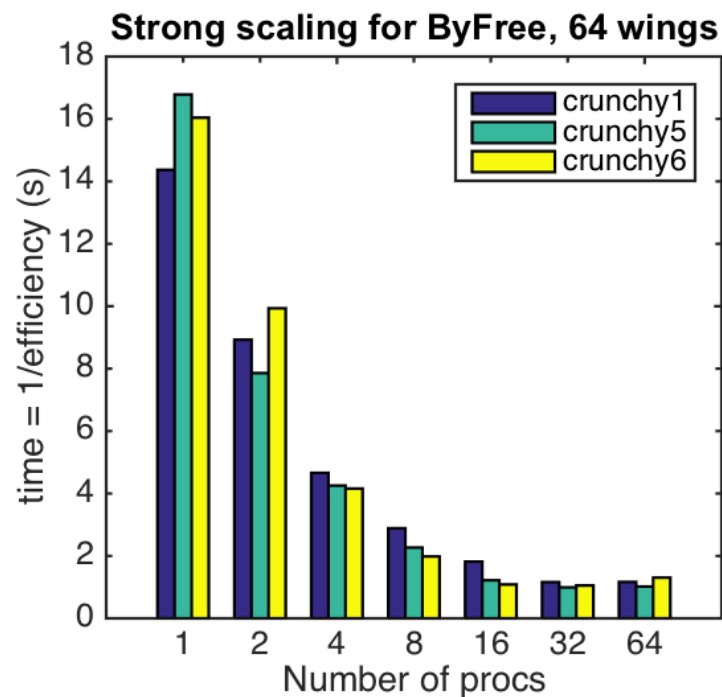
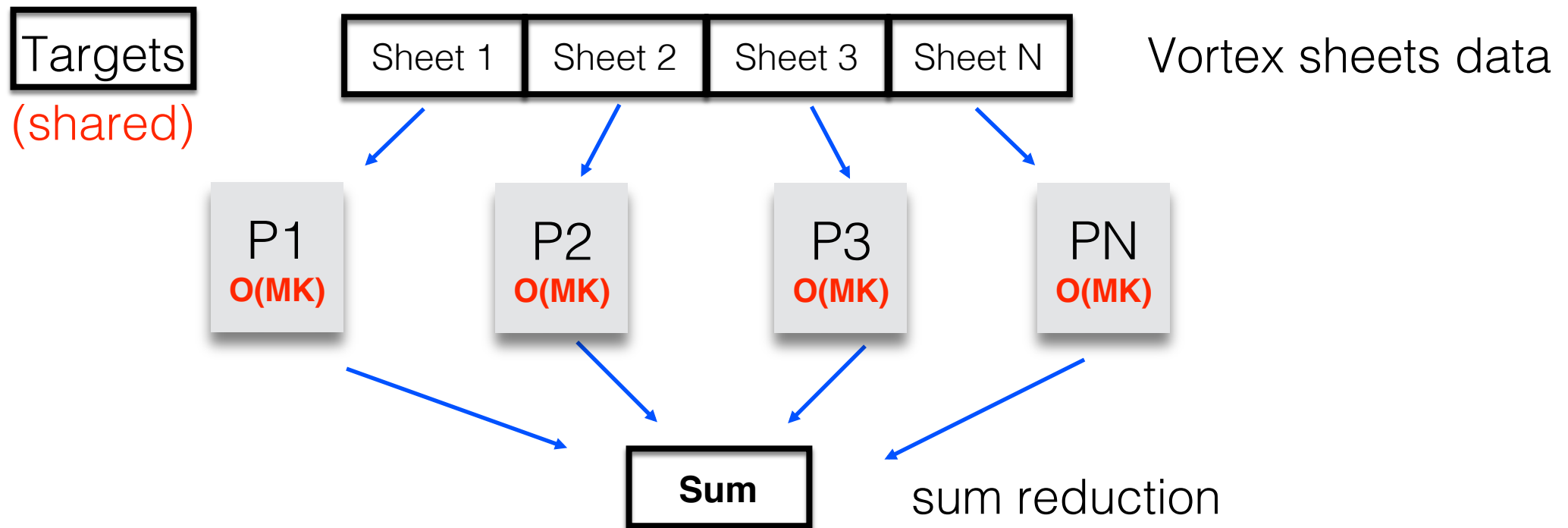
- Body velocity induced by vortex sheets — more accurate quadrature: analytically integrate piecewise linear distribution approximation, parallelize  $O(MK)$  interaction over  $N$  sheets

$O(NMK)$  (serial)  $\longrightarrow$   $O(MK)$  (parallel) ✓ (tests shown later)

$O(NPM*(NM+NK))$  serial direct  $\longrightarrow$   $O(PNM*\log NM)+O(PMK) \sim O(PMK)$  with FMM and parallelism

# Parallelize body velocity calculation induced by sheets

- Generate **N** fake vortex sheets and **M=900** target points in Matlab, implement OpenMP with C++, compiled into Matlab mex functions. **K=1,000** points on each sheet.





# Outlook

- Matlab code with current parallelisms is about 5 times faster, for  $N=10$  fish.
- Complete the parallelisms, implement for larger fish school
- Use kernel independent FMM, or quadrature by expansion (QBX)

## What have I learned?

- Compile C++ OpenMP code into Matlab *mex* function

```
mex -I"../Fish/" -I"../eigen/" -v -largeArrayDims FreeByFreeSmth_mul.  
cpp FreeByFreeSmth_mul_routine.cpp -lmwblas -lrt CFLAGS="$CFLAGS -  
fopenmp" LDFLAGS="$LDFLAGS -fopenmp" CXXOPTIMFLAGS="$CXXOPTIMFLAGS -  
fopenmp"
```

- OpenMP sum reduction with overloaded operator

```
#pragma omp parallel  
{  
    VectorXd private_r = VectorXd::Zero(nt,1), private_i = VectorXd::Zero(nt,1);  
  
    #pragma omp for nowait  
    for (int ib = 0; ib < Nw; ++ib){  
        VectorXd temp_r = VectorXd::Zero(nt,1), temp_i = VectorXd::Zero(nt,1);  
        byfree(zztreal, zztimag, W[ib].zetaf_r, W[ib].zetaf_i, W[ib].gammaf, temp_r, temp_i);  
        private_r += temp_r;  
        private_i += temp_i;  
    }  
  
    #pragma omp critical  
    {  
        pot_r += private_r;  
        pot_i += private_i;  
    }  
}
```

- C++ linear algebra package: Eigen.