

## Costa's tools

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# Chapter 1

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## Chapter 4

# Namespace Documentation

### 4.1 CommonTools Namespace Reference

#### Enumerations

- enum [VTKSurfaceMeshFormats](#) {  
    [UnknownType](#), [VTKPolyDataType](#), [VTKXMLPolyDataType](#), [STLType](#),  
    [PLYType](#) }  
    Valid volume formats io functions can handle.
- enum [VTKVolumeMeshFormats](#) { [UnknownVolumeType](#), [VTKUnstructuredGridType](#) }  
    Valid volume formats io functions can handle.

#### Functions

- void [SaveVtkShortArray](#) (const char \*filename, vtkShortArray \*the\_array)  
    Save a vtk short array using a specific format.
- void [LoadVtkShortArray](#) (const char \*filename, vtkShortArray \*the\_array)  
    Load a vtk short array using a specific format.
- vtkPolyData \* [GetShapeSubSurface](#) (vtkPolyData \*inputShape, unsigned int nSubPart)  
    Call to [GetShapeSubSurface\( \)](#) with nSubPart-0.1, nSubPart+0.1.
- vtkPolyData \* [GetShapeSubSurface](#) (vtkPolyData \*inputShape, double tholdLower, double tholdUpper)  
    Apply threshold to extract the subpart, apply [vtkDataSetSurfaceFilter](#) and [vtkCleanPolyData](#).
- vtkPolyData \* [CloseSurface](#) (vtkPolyData \*shape)  
    Closes only 1 hole, make sure there are no more.
- vtkPolyData \* [GenerateHoleCover](#) (vtkPolyData \*edge)  
    Generate a cover for a small hole. Uses centroid.
- void [SavePolydata](#) (vtkPolyData \*poly, const char \*filename, bool binary=false)  
    Save polydata to a file.
- void [SaveImage](#) (vtkDataSet \*image, const char \*filename)  
    Save image to a file.
- vtkImageData \* [LoadImage](#) (const char \*filename)  
    Load image from a file.
- void [SaveUnstructuredGrid](#) (vtkUnstructuredGrid \*grid, const char \*filename)  
    Save unstructured grid to a file.
- void [SavePoints](#) (vtkPoints \*pts, const char \*filename)  
    Save vtkPoints to a file.
- bool [FileExists](#) (const char \*filename, bool no\_exception=false)

- Check if file exists and throw an exception if needed.*

  - void [ReadFilelist](#) (const char \*file, std::vector< std::string > &list, bool check\_existence=false)

*Generate a filelist.*
- vtkPolyData \* [Points2Polydata](#) (vtkPoints \*points, double scalar)

*Saves points such that they can e visualized in paraview also saves a scalar corresponding to a position so it is easy to see the ordering of points (if sampling is correct) if scalars != NULL, the corresponding scalar values will be assigned to the points.*
- vtkPolyData \* [Points2Polydata](#) (vtkPoints \*points, const double \*scalars=NULL)

*Saves points such that they can e visualized in paraview also saves a scalar corresponding to a position so it is easy to see the ordering of points.*
- void [ExportPolyDataPoints](#) (vtkPolyData \*shape, vnl\_vector< double > &points)

*extract points from polydata*
- void [ExportPolyDataPoints](#) (vtkPolyData \*shape, vnl\_matrix< double > &points)

*extract points from polydata*
- void [ImportPolyDataPoints](#) (vtkPolyData \*shape, vnl\_vector< double > &points)

*copy points to polydata*
- void [ImportPolyDataPoints](#) (vtkPolyData \*shape, vnl\_matrix< double > &points)

*copy points to polydata*
- void [GenerateDecimationScript](#) (const char \*filename, int nfaces)

*generate a Meshlab script for mesh decimation, specify number of faces*
- void [ScaleShape](#) (vtkPolyData \*shapein, vtkPolyData \*shapeout, float scale, bool centerAfterScale=false)

*Rescale polydata.*
- void [ShrinkImage](#) (vtkDataSet \*imagein, vtkDataSet \*imageout, int factor)

*Resize image.*
- void [ScaleVolume](#) (vtkUnstructuredGrid \*volumein, vtkUnstructuredGrid \*volumeout, float scale)

*Resize unstructured grid.*
- vtkPolyData \* [LoadShapeFromFile](#) (const char \*shapeFileName)

*Load polydata from file.*
- vtkUnstructuredGrid \* [LoadVolumeFromFile](#) (const char \*volumeFileName)

*Load unstructured grid from file.*
- void [SaveVolumeToFile](#) (vtkUnstructuredGrid \*volumePt, const char \*volumeFileName, const char \*header)

*Save unstructured grid to file.*
- void [SaveShapeToFile](#) (vtkPolyData \*shapePt, const char \*shapeFileName, const char \*header=NULL)

*Save polydata to file.*
- void [GetP2S](#) (vtkPolyData \*manualPt, vtkPolyData \*segmentedPt, double &mean, double &std\_dev, double &max, double &last, bool b\_array)

*Calculate point-to-surface distance.*
- void [GetP2P](#) (vtkPolyData \*manualPt, vtkPolyData \*segmentedPt, double &mean, double &std\_dev, double &max, double &last, bool b\_array)

*Calculate point-to-point distance.*
- vtkPolyData \* [GetP2S](#) (vtkPolyData \*shapePt1, vtkPolyData \*shapePt2, std::vector< vnl\_vector< double > > &distances)

*Calculate point-to-surface distance.*
- vtkPolyData \* [GetP2S](#) (vtkPolyData \*shapePt1, vtkPolyData \*shapePt2, vnl\_vector< double > &distances)

*Calculate point-to-surface distance.*
- void [GetS2S](#) (vtkPolyData \*shapePt1, vtkPolyData \*shapePt2, std::vector< vnl\_vector< double > > &distances)

*Calculate surface-to-surface distance.*
- bool [CheckSaveFileExtension](#) (const char \*shapeFileName)

*check if the file has valid extension for saving. To remove one day.*

- [VTKVolumeMeshFormats GetTypeOfVTKVolumeData](#) (const char \*volumeFileName)  
*identify volume data type*
- [VTKSurfaceMeshFormats GetTypeOfVTKData](#) (const char \*shapeFileName)  
*identify VTK data type*
- int [laplace3D\\_voxelsize](#) (vtkImageData \*inputImage, vtkImageData \*outputImage, int iterations)  
*Explicit solution to Laplace Eq. (c) Ruben Cardenes + Constantine Butakoff.*

### 4.1.1 Enumeration Type Documentation

#### 4.1.1.1 enum CommonTools::VTKSurfaceMeshFormats

Valid volume formats io functions can handle.

Enumerator:

***UnknownType***  
***VTKPolyDataType***  
***VTKXMLPolyDataType***  
***STLType***  
***PLYType***

#### 4.1.1.2 enum CommonTools::VTKVolumeMeshFormats

Valid volume formats io functions can handle.

Enumerator:

***UnknownVolumeType***  
***VTKUnstructuredGridType***

### 4.1.2 Function Documentation

#### 4.1.2.1 bool CommonTools::CheckSaveFileExtension ( const char \* shapeFileName )

check if the file has valid extension for saving. To remove one day.

#### 4.1.2.2 vtkPolyData \* CommonTools::CloseSurface ( vtkPolyData \* shape )

Closes only 1 hole, make sure there are no more.

#### 4.1.2.3 void CommonTools::ExportPolyDataPoints ( vtkPolyData \* shape, vnl\_vector< double > & points )

extract points from polydata

#### 4.1.2.4 void CommonTools::ExportPolyDataPoints ( vtkPolyData \* shape, vnl\_matrix< double > & points )

extract points from polydata

#### 4.1.2.5 bool CommonTools::FileExists ( const char \* filename, bool no\_exception = false )

Check if file exists and throw an exception if needed.

4.1.2.6 `void CommonTools::GenerateDecimationScript ( const char * filename, int nfaces )`

generate a Meshlab script for mesh decimation, specify number of faces

4.1.2.7 `vtkPolyData * CommonTools::GenerateHoleCover ( vtkPolyData * edge )`

Generate a cover for a small hole. Uses centroid.

4.1.2.8 `void CommonTools::GetP2P ( vtkPolyData * manualPt, vtkPolyData * segmentedPt, double & mean, double & std_dev, double & max, double & last, bool b_array )`

Calculate point-to-point distance.

4.1.2.9 `void CommonTools::GetP2S ( vtkPolyData * manualPt, vtkPolyData * segmentedPt, double & mean, double & std_dev, double & max, double & last, bool b_array )`

Calculate point-to-surface distance.

4.1.2.10 `vtkPolyData * CommonTools::GetP2S ( vtkPolyData * shapePt1, vtkPolyData * shapePt2, std::vector< vnl_vector< double > > & distances )`

Calculate point-to-surface distance.

4.1.2.11 `vtkPolyData * CommonTools::GetP2S ( vtkPolyData * shapePt1, vtkPolyData * shapePt2, vnl_vector< double > & distances )`

Calculate point-to-surface distance.

4.1.2.12 `void CommonTools::GetS2S ( vtkPolyData * shapePt1, vtkPolyData * shapePt2, std::vector< vnl_vector< double > > & distances )`

Calculate surface-to-surface distance.

4.1.2.13 `vtkPolyData * CommonTools::GetShapeSubSurface ( vtkPolyData * inputShape, unsigned int nSubPart )`

Call to [GetShapeSubSurface\( \)](#) with *nSubPart*-0.1, *nSubPart*+0.1.

4.1.2.14 `vtkPolyData * CommonTools::GetShapeSubSurface ( vtkPolyData * inputShape, double tholdLower, double tholdUpper )`

Apply threshold to extract the subpart, apply `vtkDataSetSurfaceFilter` and `vtkCleanPolyData`.

#### Note

The caller to this function should delete the output shape

4.1.2.15 `CommonTools::VTKSurfaceMeshFormats CommonTools::GetVTKData ( const char * shapeFileName )`

identify VTK data type

**4.1.2.16** `CommonTools::VTKVolumeMeshFormats CommonTools::GetTypeOfVTKVolumeData ( const char * volumeFileName )`

identify volume data type

**4.1.2.17** `void CommonTools::ImportPolyDataPoints ( vtkPolyData * shape, vnl_vector< double > & points )`

copy points to polydata

**4.1.2.18** `void CommonTools::ImportPolyDataPoints ( vtkPolyData * shape, vnl_matrix< double > & points )`

copy points to polydata

**4.1.2.19** `int CommonTools::laplace3D_voxelsize ( vtkImageData * inputImage, vtkImageData * outputImage, int iterations )`

Explicit solution to Laplace Eq. (c) Ruben Cardenes + Constantine Butakoff.

Explicit solution to Laplace Eq. (c) Ruben Cardenes + Constantine Butakoff 3 Outside domain 1 Exterior boundary 0 Interior boundary 2 Inside domain

**4.1.2.20** `vtkImageData * CommonTools::LoadImage ( const char * filename )`

Load image from a file.

**4.1.2.21** `vtkPolyData * CommonTools::LoadShapeFromFile ( const char * shapeFileName )`

Load polydata from file.

**4.1.2.22** `vtkUnstructuredGrid * CommonTools::LoadVolumeFromFile ( const char * volumeFileName )`

Load unstructured grid from file.

**4.1.2.23** `void CommonTools::LoadVtkShortArray ( const char * filename, vtkShortArray * the_array )`

Load a vtk short array using a specific format.

#### Note

If there's an error, an `std::exception` is thrown

**4.1.2.24** `vtkPolyData * CommonTools::Points2Polydata ( vtkPoints * points, double scalar )`

Saves points such that they can be visualized in paraview also saves a scalar corresponding to a position so it is easy to see the ordering of points (if sampling is correct) if scalars != NULL, the corresponding scalar values will be assigned to the points.

#### Note

The caller to this function should call `points->Delete()`

4.1.2.25 `vtkPolyData * CommonTools::Points2Polydata ( vtkPoints * points, const double * scalars = NULL )`

Saves points such that they can be visualized in paraview also saves a scalar corresponding to a position so it is easy to see the ordering of points.

(if sampling is correct) if `scalars != NULL`, the corresponding scalar values will be assigned to the points

#### Note

The caller to this function should call `points->Delete()`

4.1.2.26 `void CommonTools::ReadFilelist ( const char * file, std::vector< std::string > & list, bool check_existence = false )`

Generate a filelist.

4.1.2.27 `void CommonTools::SaveImage ( vtkDataSet * image, const char * filename )`

Save image to a file.

4.1.2.28 `void CommonTools::SavePoints ( vtkPoints * pts, const char * filename )`

Save `vtkPoints` to a file.

4.1.2.29 `void CommonTools::SavePolydata ( vtkPolyData * poly, const char * filename, bool binary = false )`

Save polydata to a file.

4.1.2.30 `void CommonTools::SaveShapeToFile ( vtkPolyData * shapePt, const char * shapeFileName, const char * header = NULL )`

Save polydata to file.

4.1.2.31 `void CommonTools::SaveUnstructuredGrid ( vtkUnstructuredGrid * grid, const char * filename )`

Save unstructured grid to a file.

4.1.2.32 `void CommonTools::SaveVolumeToFile ( vtkUnstructuredGrid * volumePt, const char * volumeFileName, const char * header )`

Save unstructured grid to file.

4.1.2.33 `void CommonTools::SaveVtkShortArray ( const char * filename, vtkShortArray * the_array )`

Save a vtk short array using a specific format.

#### Note

If there's an error, an `std::exception` is thrown

4.1.2.34 `void CommonTools::ScaleShape ( vtkPolyData * shapein, vtkPolyData * shapeout, float scale, bool centerAfterScale = false )`

Rescale polydata.

4.1.2.35 `void CommonTools::ScaleVolume ( vtkUnstructuredGrid * volumein, vtkUnstructuredGrid * volumeout, float scale )`

Resize unstructured grid.

4.1.2.36 `void CommonTools::ShrinkImage ( vtkDataSet * imagein, vtkDataSet * imageout, int factor )`

Resize image.

## 4.2 itk Namespace Reference

### Classes

- class [BinaryThinningImageFilter3D](#)  
*This filter computes one-pixel-wide skeleton of a 3D input image.*
- class [ImageToVTKImageFilter](#)  
*Converts an ITK image into a VTK image and plugs a itk data pipeline to a VTK datapipeline.*





## Chapter 5

# Class Documentation

### 5.1 itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage > Class Template Reference

This filter computes one-pixel-wide skeleton of a 3D input image.

```
#include <itkBinaryThinningImageFilter3D.h>
```

#### Public Types

- typedef [BinaryThinningImageFilter3D](#) [Self](#)
- typedef [ImageToImageFilter](#)  
  < TInputImage, TOutputImage > [Superclass](#)
- typedef [SmartPointer](#)< [Self](#) > [Pointer](#)
- typedef [SmartPointer](#)< const [Self](#) > [ConstPointer](#)
- typedef TInputImage [InputImageType](#)
- typedef TOutputImage [OutputImageType](#)
- typedef InputImageType::RegionType [RegionType](#)
- typedef RegionType::IndexType [IndexType](#)
- typedef InputImageType::PixelType [InputImagePixelType](#)
- typedef OutputImageType::PixelType [OutputImagePixelType](#)
- typedef RegionType::SizeType [SizeType](#)
- typedef  
  InputImageType::ConstPointer [InputImagePointer](#)
- typedef OutputImageType::Pointer [OutputImagePointer](#)
- typedef  
  ConstantBoundaryCondition  
  < TInputImage > [ConstBoundaryConditionType](#)
- typedef NeighborhoodIterator  
  < TInputImage,  
  [ConstBoundaryConditionType](#) > [NeighborhoodIteratorType](#)
- typedef  
  NeighborhoodIteratorType::NeighborhoodType [NeighborhoodType](#)

#### Public Member Functions

- [itkNewMacro](#) ([Self](#))
- [itkTypeMacro](#) ([BinaryThinningImageFilter3D](#), [ImageToImageFilter](#))
- [OutputImageType](#) \* [GetThinning](#) (void)
- [itkStaticConstMacro](#) (InputImageDimension, unsigned int, TInputImage::ImageDimension)
- [itkStaticConstMacro](#) (OutputImageDimension, unsigned int, TOutputImage::ImageDimension)

## Protected Member Functions

- [BinaryThinningImageFilter3D](#) ()
- virtual [~BinaryThinningImageFilter3D](#) ()
- void [PrintSelf](#) (std::ostream &os, Indent indent) const
- void [GenerateData](#) ()
- void [PrepareData](#) ()
- void [ComputeThinImage](#) ()
- bool [isEulerInvariant](#) ([NeighborhoodType](#) neighbors, int \*LUT)
- void [fillEulerLUT](#) (int \*LUT)
- bool [isSimplePoint](#) ([NeighborhoodType](#) neighbors)
- void [Octree\\_labeling](#) (int octant, int label, int \*cube)

### 5.1.1 Detailed Description

```
template<class TInputImage, class TOutputImage>class itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >
```

This filter computes one-pixel-wide skeleton of a 3D input image.

This class is parametrized over the type of the input image and the type of the output image.

The input is assumed to be a binary image. All non-zero valued voxels are set to 1 internally to simplify the computation. The filter will produce a skeleton of the object. The output background values are 0, and the foreground values are 1.

A 26-neighbourhood configuration is used for the foreground and a 6-neighbourhood configuration for the background. Thinning is performed symmetrically in order to guarantee that the skeleton lies medial within the object.

This filter is a parallel thinning algorithm and is an implementation of the algorithm described in:

T.C. Lee, R.L. Kashyap, and C.N. Chu. Building skeleton models via 3-D medial surface/axis thinning algorithms. Computer Vision, Graphics, and Image Processing, 56(6):462–478, 1994.

To do: Make use of multi-threading.

#### Author

Hanno Homann, Oxford University, Wolfson Medical Vision Lab, UK.

#### See Also

[MorphologyImageFilter](#)

### 5.1.2 Member Typedef Documentation

```
5.1.2.1 template<class TInputImage , class TOutputImage > typedef ConstantBoundaryCondition< TInputImage >
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::ConstBoundaryConditionType
```

Boundary condition type for the neighborhood iterator

```
5.1.2.2 template<class TInputImage , class TOutputImage > typedef SmartPointer<const Self>
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::ConstPointer
```

```
5.1.2.3 template<class TInputImage , class TOutputImage > typedef RegionType::IndexType
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::IndexType
```

Type for the index of the input image.

5.1.2.4 `template<class TInputImage , class TOutputImage > typedef InputImageType::PixelType  
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::InputImagePixelType`

Type for the pixel type of the input image.

5.1.2.5 `template<class TInputImage , class TOutputImage > typedef InputImageType::ConstPointer  
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::InputImagePointer`

Pointer Type for input image.

5.1.2.6 `template<class TInputImage , class TOutputImage > typedef TInputImage itk::BinaryThinningImageFilter3D<  
TInputImage, TOutputImage >::InputImageType`

Type for input image.

5.1.2.7 `template<class TInputImage , class TOutputImage > typedef NeighborhoodIterator<TInputImage,  
ConstBoundaryConditionType> itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage  
>::NeighborhoodIteratorType`

Neighborhood iterator type

5.1.2.8 `template<class TInputImage , class TOutputImage > typedef NeighborhoodIteratorType::NeighborhoodType  
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::NeighborhoodType`

Neighborhood type

5.1.2.9 `template<class TInputImage , class TOutputImage > typedef OutputImageType::PixelType  
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::OutputImagePixelType`

Type for the pixel type of the input image.

5.1.2.10 `template<class TInputImage , class TOutputImage > typedef OutputImageType::Pointer  
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::OutputImagePointer`

Pointer Type for the output image.

5.1.2.11 `template<class TInputImage , class TOutputImage > typedef TOutputImage itk::BinaryThinningImageFilter3D<  
TInputImage, TOutputImage >::OutputImageType`

Type for output image: Skelenton of the object.

5.1.2.12 `template<class TInputImage , class TOutputImage > typedef SmartPointer<Self>  
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::Pointer`

5.1.2.13 `template<class TInputImage , class TOutputImage > typedef InputImageType::RegionType  
itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::RegionType`

Type for the region of the input image.

```
5.1.2.14 template<class TInputImage , class TOutputImage > typedef BinaryThinningImageFilter3D
        itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::Self
```

Standard class typedefs.

```
5.1.2.15 template<class TInputImage , class TOutputImage > typedef RegionType::SizeType
        itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::SizeType
```

Type for the size of the input image.

```
5.1.2.16 template<class TInputImage , class TOutputImage > typedef ImageToImageFilter<TInputImage,TOutputImage>
        itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::Superclass
```

### 5.1.3 Constructor & Destructor Documentation

```
5.1.3.1 template<class TInputImage , class TOutputImage > itk::BinaryThinningImageFilter3D< TInputImage,
        TOutputImage >::BinaryThinningImageFilter3D ( ) [protected]
```

```
5.1.3.2 template<class TInputImage , class TOutputImage > virtual itk::BinaryThinningImageFilter3D< TInputImage,
        TOutputImage >::~~BinaryThinningImageFilter3D ( ) [inline],[protected],[virtual]
```

### 5.1.4 Member Function Documentation

```
5.1.4.1 template<class TInputImage , class TOutputImage > void itk::BinaryThinningImageFilter3D< TInputImage,
        TOutputImage >::ComputeThinImage ( ) [protected]
```

Compute thinning Image.

```
5.1.4.2 template<class TInputImage , class TOutputImage > void itk::BinaryThinningImageFilter3D< TInputImage,
        TOutputImage >::fillEulerLUT ( int * LUT ) [protected]
```

```
5.1.4.3 template<class TInputImage , class TOutputImage > void itk::BinaryThinningImageFilter3D< TInputImage,
        TOutputImage >::GenerateData ( ) [protected]
```

Compute thinning Image.

```
5.1.4.4 template<class TInputImage , class TOutputImage > OutputImageType* itk::BinaryThinningImageFilter3D<
        TInputImage, TOutputImage >::GetThinning ( void )
```

Get Skelenton by thinning image.

```
5.1.4.5 template<class TInputImage , class TOutputImage > bool itk::BinaryThinningImageFilter3D< TInputImage,
        TOutputImage >::isEulerInvariant ( NeighborhoodType neighbors, int * LUT ) [protected]
```

isEulerInvariant [Lee94]

```
5.1.4.6 template<class TInputImage , class TOutputImage > bool itk::BinaryThinningImageFilter3D< TInputImage,
        TOutputImage >::isSimplePoint ( NeighborhoodType neighbors ) [protected]
```

isSimplePoint [Lee94]

5.1.4.7 `template<class TInputImage , class TOutputImage > itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::itkNewMacro ( Self )`

Method for creation through the object factory

5.1.4.8 `template<class TInputImage , class TOutputImage > itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::itkStaticConstMacro ( InputImageDimension , unsigned int, TInputImage::ImageDimension )`

ImageDimension enumeration

5.1.4.9 `template<class TInputImage , class TOutputImage > itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::itkStaticConstMacro ( OutputImageDimension , unsigned int, TOutputImage::ImageDimension )`

5.1.4.10 `template<class TInputImage , class TOutputImage > itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::itkTypeMacro ( BinaryThinningImageFilter3D< TInputImage, TOutputImage > , ImageToImageFilter )`

Run-time type information (and related methods).

5.1.4.11 `template<class TInputImage , class TOutputImage > void itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::Octree_Labeling ( int octant, int label, int * cube ) [protected]`

Octree\_labeling [Lee94]

5.1.4.12 `template<class TInputImage , class TOutputImage > void itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::PrepareData ( ) [protected]`

Prepare data.

5.1.4.13 `template<class TInputImage , class TOutputImage > void itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >::PrintSelf ( std::ostream & os, Indent indent ) const [protected]`

The documentation for this class was generated from the following file:

- </home/costa/Data/Code/C/apps/imported/itkBinaryThinningImageFilter3D.h>

## 5.2 BITMAPFILEHEADER Struct Reference

### Public Attributes

- char [Signature](#) [2]
- [uint32\\_t](#) FileSize
- [uint32\\_t](#) reserved
- [uint32\\_t](#) DataOffset

### 5.2.1 Member Data Documentation

5.2.1.1 [uint32\\_t](#) BITMAPFILEHEADER::DataOffset

5.2.1.2 [uint32\\_t](#) BITMAPFILEHEADER::FileSize

5.2.1.3 `uint32_t` `BITMAPFILEHEADER::reserved`

5.2.1.4 `char` `BITMAPFILEHEADER::Signature[2]`

The documentation for this struct was generated from the following file:

- `/home/costa/Data/Code/C/apps/imported/pgm2itkvol/mcimage.c`

## 5.3 BITMAPINFOHEADER Struct Reference

### Public Attributes

- `uint32_t` `Size`
- `uint32_t` `Width`
- `uint32_t` `Height`
- `uint16_t` `Planes`
- `uint16_t` `BitCount`
- `uint32_t` `Compression`
- `uint32_t` `ImageSize`
- `uint32_t` `XpixelsPerM`
- `uint32_t` `YpixelsPerM`
- `uint32_t` `ColorsUsed`
- `uint32_t` `ColorsImportant`

### 5.3.1 Member Data Documentation

5.3.1.1 `uint16_t` `BITMAPINFOHEADER::BitCount`

5.3.1.2 `uint32_t` `BITMAPINFOHEADER::ColorsImportant`

5.3.1.3 `uint32_t` `BITMAPINFOHEADER::ColorsUsed`

5.3.1.4 `uint32_t` `BITMAPINFOHEADER::Compression`

5.3.1.5 `uint32_t` `BITMAPINFOHEADER::Height`

5.3.1.6 `uint32_t` `BITMAPINFOHEADER::ImageSize`

5.3.1.7 `uint16_t` `BITMAPINFOHEADER::Planes`

5.3.1.8 `uint32_t` `BITMAPINFOHEADER::Size`

5.3.1.9 `uint32_t` `BITMAPINFOHEADER::Width`

5.3.1.10 `uint32_t` `BITMAPINFOHEADER::XpixelsPerM`

5.3.1.11 `uint32_t` `BITMAPINFOHEADER::YpixelsPerM`

The documentation for this struct was generated from the following file:

- `/home/costa/Data/Code/C/apps/imported/pgm2itkvol/mcimage.c`

## 5.4 dcomplex Struct Reference

Complex number, represented by doubles.

```
#include <mccodimage.h>
```

### Public Attributes

- double [re](#)  
*real part*
- double [im](#)  
*imaginary part*

#### 5.4.1 Detailed Description

Complex number, represented by doubles.

#### 5.4.2 Member Data Documentation

##### 5.4.2.1 double dcomplex::im

imaginary part

##### 5.4.2.2 double dcomplex::re

real part

The documentation for this struct was generated from the following file:

- [/home/costa/Data/Code/C/apps/imported/pgm2itkvol/mccodimage.h](#)

## 5.5 fcomplex Struct Reference

Complex number, represented by floats.

```
#include <mccodimage.h>
```

### Public Attributes

- float [re](#)  
*real part*
- float [im](#)  
*imaginary part*

#### 5.5.1 Detailed Description

Complex number, represented by floats.

#### Note

'fcomplex' is necessary because of msvc

## 5.5.2 Member Data Documentation

### 5.5.2.1 float fcomplex::im

imaginary part

### 5.5.2.2 float fcomplex::re

real part

The documentation for this struct was generated from the following file:

- </home/costa/Data/Code/C/apps/imported/pgm2itkvol/mccodimage.h>

## 5.6 itk::ImageToVTKImageFilter< TInputImage > Class Template Reference

Converts an ITK image into a VTK image and plugs a itk data pipeline to a VTK datapipeline.

```
#include <itkImageToVTKImageFilter.h>
```

### Public Types

- typedef [ImageToVTKImageFilter](#) Self
- typedef ProcessObject [Superclass](#)
- typedef SmartPointer< [Self](#) > [Pointer](#)
- typedef SmartPointer< const [Self](#) > [ConstPointer](#)
- typedef TInputImage [InputImageType](#)
- typedef  
InputImageType::ConstPointer [InputImagePointer](#)
- typedef VTKImageExport  
< [InputImageType](#) > [ExporterFilterType](#)
- typedef ExporterFilterType::Pointer [ExporterFilterPointer](#)

### Public Member Functions

- [itkNewMacro](#) (Self)
- [itkTypeMacro](#) ([ImageToVTKImageFilter](#), ProcessObject)
- vtkImageData \* [GetOutput](#) () const
- void [SetInput](#) (const [InputImageType](#) \*)
- vtkImageImport \* [GetImporter](#) () const
- [ExporterFilterType](#) \* [GetExporter](#) () const
- void [Update](#) ()
- const std::vector< double > & [getvtest](#) () const
- int [testsize](#) ()
- std::vector< double > [addvector](#) (const std::vector< double > &v)
- const std::vector< double > & [addtest](#) (double toto)
- std::vector< double > [tralala](#) ()

### Protected Member Functions

- [ImageToVTKImageFilter](#) ()
- virtual [~ImageToVTKImageFilter](#) ()



### 5.6.1 Detailed Description

```
template<class TInputImage> class itk::ImageToVTKImageFilter< TInputImage >
```

Converts an ITK image into a VTK image and plugs a itk data pipeline to a VTK datapipeline.

This class puts together an itkVTKImageExporter and a vtkImageImporter. It takes care of the details related to the connection of ITK and VTK pipelines. The User will perceive this filter as an adaptor to which an itk::Image can be plugged as input and a vtkImage is produced as output.

### 5.6.2 Member Typedef Documentation

5.6.2.1 `template<class TInputImage > typedef SmartPointer<const Self> itk::ImageToVTKImageFilter< TInputImage >::ConstPointer`

5.6.2.2 `template<class TInputImage > typedef ExporterFilterType::Pointer itk::ImageToVTKImageFilter< TInputImage >::ExporterFilterPointer`

5.6.2.3 `template<class TInputImage > typedef VTKImageExport< InputImageType> itk::ImageToVTKImageFilter< TInputImage >::ExporterFilterType`

5.6.2.4 `template<class TInputImage > typedef InputImageType::ConstPointer itk::ImageToVTKImageFilter< TInputImage >::InputImagePointer`

5.6.2.5 `template<class TInputImage > typedef TInputImage itk::ImageToVTKImageFilter< TInputImage >::InputImageType`

Some typedefs.

5.6.2.6 `template<class TInputImage > typedef SmartPointer<Self> itk::ImageToVTKImageFilter< TInputImage >::Pointer`

5.6.2.7 `template<class TInputImage > typedef ImageToVTKImageFilter itk::ImageToVTKImageFilter< TInputImage >::Self`

Standard class typedefs.

5.6.2.8 `template<class TInputImage > typedef ProcessObject itk::ImageToVTKImageFilter< TInputImage >::Superclass`

### 5.6.3 Constructor & Destructor Documentation

5.6.3.1 `template<class TInputImage > itk::ImageToVTKImageFilter< TInputImage >::ImageToVTKImageFilter ( )`  
[protected]

5.6.3.2 `template<class TInputImage > virtual itk::ImageToVTKImageFilter< TInputImage >::~~ImageToVTKImageFilter ( )` [protected], [virtual]

### 5.6.4 Member Function Documentation

5.6.4.1 `template<class TInputImage > const std::vector<double>& itk::ImageToVTKImageFilter< TInputImage >::addtest ( double toto )` [inline]

5.6.4.2 `template<class TInputImage > std::vector<double> itk::ImageToVTKImageFilter< TInputImage >::addvector ( const std::vector< double > & v ) [inline]`

5.6.4.3 `template<class TInputImage > ExporterFilterType* itk::ImageToVTKImageFilter< TInputImage >::GetExporter ( ) const`

Return the internal ITK image exporter filter. This is intended to facilitate users the access to methods in the exporter

5.6.4.4 `template<class TInputImage > vtkImageImport* itk::ImageToVTKImageFilter< TInputImage >::GetImporter ( ) const`

Return the internal VTK image importer filter. This is intended to facilitate users the access to methods in the importer

5.6.4.5 `template<class TInputImage > vtkImageData* itk::ImageToVTKImageFilter< TInputImage >::GetOutput ( ) const`

Get the output in the form of a vtkImage. This call is delegated to the internal vtkImageImporter filter

5.6.4.6 `template<class TInputImage > const std::vector<double>& itk::ImageToVTKImageFilter< TInputImage >::getvtest ( ) const [inline]`

5.6.4.7 `template<class TInputImage > itk::ImageToVTKImageFilter< TInputImage >::itkNewMacro ( Self )`

Method for creation through the object factory.

5.6.4.8 `template<class TInputImage > itk::ImageToVTKImageFilter< TInputImage >::itkTypeMacro ( ImageToVTKImageFilter< TInputImage > , ProcessObject )`

Run-time type information (and related methods).

5.6.4.9 `template<class TInputImage > void itk::ImageToVTKImageFilter< TInputImage >::SetInput ( const InputImageType * )`

Set the input in the form of an itk::Image

5.6.4.10 `template<class TInputImage > int itk::ImageToVTKImageFilter< TInputImage >::testsize ( ) [inline]`

5.6.4.11 `template<class TInputImage > std::vector<double> itk::ImageToVTKImageFilter< TInputImage >::tralala ( ) [inline]`

5.6.4.12 `template<class TInputImage > void itk::ImageToVTKImageFilter< TInputImage >::Update ( )`

This call delegate the update to the importer

The documentation for this class was generated from the following file:

- [/home/costa/Data/Code/C/apps/imported/itkImageToVTKImageFilter.h](#)

## 5.7 RGBFILEHEADER Struct Reference

### Public Attributes

- uint16\_t [magic](#)
- uint8\_t [compression](#)
- uint8\_t [bytespercha](#)
- uint16\_t [dim](#)
- uint16\_t [width](#)
- uint16\_t [height](#)
- uint16\_t [components](#)
- uint32\_t [mincol](#)
- uint32\_t [maxcol](#)
- uint32\_t [dummy](#)
- char [name](#) [80]
- uint32\_t [cmaptype](#)

### 5.7.1 Member Data Documentation

5.7.1.1 [uint8\\_t RGBFILEHEADER::bytespercha](#)

5.7.1.2 [uint32\\_t RGBFILEHEADER::cmaptype](#)

5.7.1.3 [uint16\\_t RGBFILEHEADER::components](#)

5.7.1.4 [uint8\\_t RGBFILEHEADER::compression](#)

5.7.1.5 [uint16\\_t RGBFILEHEADER::dim](#)

5.7.1.6 [uint32\\_t RGBFILEHEADER::dummy](#)

5.7.1.7 [uint16\\_t RGBFILEHEADER::height](#)

5.7.1.8 [uint16\\_t RGBFILEHEADER::magic](#)

5.7.1.9 [uint32\\_t RGBFILEHEADER::maxcol](#)

5.7.1.10 [uint32\\_t RGBFILEHEADER::mincol](#)

5.7.1.11 [char RGBFILEHEADER::name\[80\]](#)

5.7.1.12 [uint16\\_t RGBFILEHEADER::width](#)

The documentation for this struct was generated from the following file:

- [/home/costa/Data/Code/C/apps/imported/pgm2itkvol/mcimage.c](#)

## 5.8 sorting\_struct Struct Reference

### Public Attributes

- double [value](#)
- int [index](#)

## 5.8.1 Member Data Documentation

5.8.1.1 `int sorting_struct::index`

5.8.1.2 `double sorting_struct::value`

The documentation for this struct was generated from the following file:

- [/home/costa/Data/Code/C/apps/MRIRemesh.cpp](#)

## 5.9 xvimage Struct Reference

The image class for the C functions.

```
#include <mccodimage.h>
```

### Public Attributes

- `char * name`  
*Dummy - not used anymore.*
- `index_t row_size`  
*Size of a row (number of columns)*
- `index_t col_size`  
*Size of a column (number of rows)*
- `index_t depth_size`  
*Number of planes (for 3d images)*
- `index_t time_size`  
*Number of (2d or 3d) images.*
- `index_t num_data_bands`  
*Number of bands per data pixel, or number of bands per image, or dimension of vector data, or number of elements in a vector.*
- `index_t d`  
*The dimension of the image.*
- `int32_t data_storage_type`  
*Storage type for disk data.*
- `double xdim`  
*Voxel dimensions in real world.*
- `double ydim`
- `double zdim`
- `double origin_x`  
*Origin in real world.*
- `double origin_y`
- `double origin_z`
- `index_t xmin`  
*Region of interest: x coordinates.*
- `index_t xmax`
- `index_t ymin`  
*Region of interest: y coordinates.*
- `index_t ymax`
- `index_t zmin`  
*Region of interest: z coordinates.*
- `index_t zmax`
- `void * image_data`  
*Pointer on raw data.*

### 5.9.1 Detailed Description

The image class for the C functions.

This class holds the image data for the C functions of Pink.

### 5.9.2 Member Data Documentation

#### 5.9.2.1 `index_t xvimage::col_size`

Size of a column (number of rows)

#### 5.9.2.2 `index_t xvimage::d`

The dimension of the image.

#### 5.9.2.3 `int32_t xvimage::data_storage_type`

Storage type for disk data.

#### 5.9.2.4 `index_t xvimage::depth_size`

Number of planes (for 3d images)

#### 5.9.2.5 `void* xvimage::image_data`

Pointer on raw data.

#### 5.9.2.6 `char* xvimage::name`

Dummy - not used anymore.

#### 5.9.2.7 `index_t xvimage::num_data_bands`

Number of bands per data pixel, or number of bands per image, or dimension of vector data, or number of elements in a vector.

#### 5.9.2.8 `double xvimage::origin_x`

Origin in real world.

#### 5.9.2.9 `double xvimage::origin_y`

#### 5.9.2.10 `double xvimage::origin_z`

#### 5.9.2.11 `index_t xvimage::row_size`

Size of a row (number of columns)

**5.9.2.12 index\_t ximage::time\_size**

Number of (2d or 3d) images.

**5.9.2.13 double ximage::xdim**

Voxel dimensions in real world.

**5.9.2.14 index\_t ximage::xmax****5.9.2.15 index\_t ximage::xmin**

Region of interest: x coordinates.

**5.9.2.16 double ximage::ydim****5.9.2.17 index\_t ximage::ymax****5.9.2.18 index\_t ximage::ymin**

Region of interest: y coordinates.

**5.9.2.19 double ximage::zdim****5.9.2.20 index\_t ximage::zmax****5.9.2.21 index\_t ximage::zmin**

Region of interest: z coordinates.

The documentation for this struct was generated from the following file:

- </home/costa/Data/Code/C/apps/imported/pgm2itkvol/mccodimage.h>

## Chapter 6

# File Documentation

### 6.1 /home/costa/Data/Code/C/apps/Blob.cpp File Reference

Active surfaces. An active surfaces implementation that fits a 3D blob to a set of points. Under construction.

```
#include <vtkSmartPointer.h>
#include "CommonTools.h"
#include <vtkPolyData.h>
#include <vtkPolyDataNormals.h>
#include <vtkDoubleArray.h>
#include <vtkMassProperties.h>
#include <vtkCurvatures.h>
#include <vtkPointData.h>
#include <vtkSphereSource.h>
#include <vtkDataSetSurfaceFilter.h>
#include <vtkPoints.h>
#include <vtkPointLocator.h>
#include <vtkTriangle.h>
#include <vtkCellData.h>
#include <vtkCellArray.h>
#include <vtkType.h>
#include <vector>
#include <iostream>
```

#### Functions

- void [ApproximateCurvature](#) (vtkPolyData \*mesh, vtkDoubleArray \*normals)  
*A function that aproximates curvature.*
- void [GetPointNeighbors](#) (vtkPolyData \*mesh, vtkIdType ptid, vtkIdList \*ptIds)  
*A function that gets point's neighbors.*
- int [main](#) (int argc, char \*\*argv)

#### 6.1.1 Detailed Description

Active surfaces. An active surfaces implementation that fits a 3D blob to a set of points. Under construction.

#### 6.1.2 Function Documentation

**6.1.2.1 void ApproximateCurvature ( vtkPolyData \* mesh, vtkDoubleArray \* normals )**

A function that approximates curvature.

**6.1.2.2 void GetPointNeighbors ( vtkPolyData \* mesh, vtkIdType ptid, vtkIdList \* ptlds )**

A function that gets point's neighbors.

**6.1.2.3 int main ( int argc, char \*\* argv )**

## 6.2 /home/costa/Data/Code/C/apps/chaste2vtk.cpp File Reference

Convert chaste .ele .node tetrahedral mesh to VTK unstructured grid (only for Oxford Rabbit)

```
#include <vtkSmartPointer.h>
#include <vtkUnstructuredGridWriter.h>
#include <vtkUnstructuredGrid.h>
#include <vtkType.h>
#include <vtkTetra.h>
#include <vtkIntArray.h>
#include <vtkCellData.h>
#include <vtkCellArray.h>
#include <stdio.h>
#include <stdlib.h>
#include <iostream>
#include <vn1/vn1_vector.h>
#include "CommonTools.h"
```

### Functions

- void [ReadChasteNodes](#) (const char \*filename, vtkPoints \*pts)  
*Reads binary chaste .node file and stores into vtkPoints.*
- void [ReadChasteElements](#) (const char \*filename, vtkCellArray \*cells, vtkIntArray \*scalars)  
*Reads binary chaste .ele file of tetrahedra and stores into vtkCells, it also retrieves the first scalar array.*
- int [main](#) (int argc, char \*\*argv)

### 6.2.1 Detailed Description

Convert chaste .ele .node tetrahedral mesh to VTK unstructured grid (only for Oxford Rabbit)

### 6.2.2 Function Documentation

**6.2.2.1 int main ( int argc, char \*\* argv )**

**6.2.2.2 void ReadChasteElements ( const char \* filename, vtkCellArray \* cells, vtkIntArray \* scalars )**

Reads binary chaste .ele file of tetrahedra and stores into vtkCells, it also retrieves the first scalar array.

**6.2.2.3 void ReadChasteNodes ( const char \* filename, vtkPoints \* pts )**

Reads binary chaste .node file and stores into vtkPoints.



## 6.3 /home/costa/Data/Code/C/apps/CloseBVMesh.cpp File Reference

Closes biventricular mesh by connecting endocardial edge to epicardial at the base. Does not close ventricles.

```
#include "CommonTools.h"
#include <vtkSmartPointer.h>
#include <vtkPolyData.h>
#include <vtkPolyDataConnectivityFilter.h>
#include <vtkFeatureEdges.h>
#include <vtkDelaunay2D.h>
#include <vtkCell.h>
#include <vtkPointData.h>
#include <vtkCellArray.h>
#include <vtkShortArray.h>
#include <vtkCellData.h>
#include <vtkAppendPolyData.h>
#include <vtkCleanPolyData.h>
#include <vtkCellLocator.h>
#include <vtkPolygon.h>
#include <vtkStripper.h>
```

### Functions

- void [CopyCellScalars](#) (vtkPolyData \*src, vtkPolyData \*tgt, char \*scalars\_name, int fill\_value)  
*Copies cell scalars from source mesh to the target.*
- vtkPolygon \* [PolyData2Polygon](#) (vtkPolyData \*pd)  
*Convert vtkPolyData polygon to vtkPolygon.*
- int [PointInPolygon](#) (double x[3], vtkPolygon \*pg)  
*Verify if a point is in vtkPolygon.*
- double [PolygonBoundaryArea](#) (vtkPolygon \*polygon)  
*Calculate area of a vtkPolygon.*
- vtkPolyData \* [FillSmallHoles](#) (vtkPolyData \*pd)  
*Fills small holes in vtkPolyData by connecting vertices to the centroid.*
- int [main](#) (int argc, char \*argv[])

#### 6.3.1 Detailed Description

Closes biventricular mesh by connecting endocardial edge to epicardial at the base. Does not close ventricles. It was made for Rafa's biventricular model. The mesh must have epicardium, rv endo and lv endo separable. No scalars are necessary. The scalars must be vtkShortArray!!! (type short)

#### 6.3.2 Function Documentation

6.3.2.1 void [CopyCellScalars](#) ( vtkPolyData \* src, vtkPolyData \* tgt, char \* scalars\_name, int fill\_value )

Copies cell scalars from source mesh to the target.

6.3.2.2 vtkPolyData \* [FillSmallHoles](#) ( vtkPolyData \* pd )

Fills small holes in vtkPolyData by connecting vertices to the centroid.

6.3.2.3 `int main ( int argc, char * argv[] )`

6.3.2.4 `int PointInPolygon ( double x[3], vtkPolygon * pg )`

Verify if a point is in vtkPolygon.

6.3.2.5 `vtkPolygon * PolyData2Polygon ( vtkPolyData * pd )`

Convert vtkPolyData polygon to vtkPolygon.

6.3.2.6 `double PolygonBoundaryArea ( vtkPolygon * polygon )`

Calculate area of a vtkPolygon.

## 6.4 /home/costa/Data/Code/C/apps/CommonTools.cpp File Reference

```
#include <vtkCleanPolyData.h>
#include <vtkThreshold.h>
#include <vtkDataSetSurfaceFilter.h>
#include <vtkPolyDataWriter.h>
#include <vtkTriangleFilter.h>
#include <vtkAppendPolyData.h>
#include <vtkDelaunay2D.h>
#include <vtkCellArray.h>
#include <vtkFloatArray.h>
#include <vtkPointData.h>
#include <vtkCellData.h>
#include <vtkDataSetWriter.h>
#include <vtkTransform.h>
#include <vtkTransformPolyDataFilter.h>
#include <vtkImageGaussianSmooth.h>
#include <vtkImageShrink3D.h>
#include <vtkImageData.h>
#include <vtkShortArray.h>
#include <vtkPolyData.h>
#include <vtkDataSet.h>
#include <vtkPoints.h>
#include <vtkStripper.h>
#include <vtkCutter.h>
#include <vtkPointLocator.h>
#include <vtkPlane.h>
#include <vtkStringArray.h>
#include <vtkSmartPointer.h>
#include <vtkDataArray.h>
#include <vtkDataSetReader.h>
#include <vtkFeatureEdges.h>
#include <vtkTransformFilter.h>
#include <vtkUnstructuredGrid.h>
#include <vtkPolyDataConnectivityFilter.h>
#include <vtkPLYReader.h>
#include <vtkSTLReader.h>
#include <vtkPolyDataReader.h>
#include <vtkXMLPolyDataReader.h>
#include <vtkUnstructuredGridReader.h>
#include <itkSYS/SystemTools.hxx>
#include <vtkUnstructuredGridWriter.h>
#include <vtkPLYWriter.h>
#include <vtkSTLWriter.h>
#include <vtkXMLPolyDataWriter.h>
#include <vtkIVWriter.h>
#include <vtkCellLocator.h>
#include "CommonTools.h"
#include <stdio.h>
#include <stdlib.h>
#include <fstream>
#include <stdexcept>
#include <vn1/vn1_matrix.h>
```

## 6.5 /home/costa/Data/Code/C/apps/CommonTools.h File Reference

Some common functions.

```
#include <vector>
#include <vn1/vn1_vector.h>
#include <vtkImageData.h>
```

### Namespaces

- namespace [CommonTools](#)

### Enumerations

- enum [CommonTools::VTKSurfaceMeshFormats](#) {  
[CommonTools::UnknownType](#), [CommonTools::VTKPolyDataType](#), [CommonTools::VTKXMLPolyDataType](#),  
[CommonTools::STLType](#),  
[CommonTools::PLYType](#) }  
*Valid volume formats io functions can handle.*
- enum [CommonTools::VTKVolumeMeshFormats](#) { [CommonTools::UnknownVolumeType](#), [CommonTools::VT-  
KUnstructuredGridType](#) }  
*Valid volume formats io functions can handle.*

### Functions

- void [CommonTools::SaveVtkShortArray](#) (const char \*filename, vtkShortArray \*the\_array)  
*Save a vtk short array using a specific format.*
- void [CommonTools::LoadVtkShortArray](#) (const char \*filename, vtkShortArray \*the\_array)  
*Load a vtk short array using a specific format.*
- vtkPolyData \* [CommonTools::GetShapeSubSurface](#) (vtkPolyData \*inputShape, unsigned int nSubPart)  
*Call to [GetShapeSubSurface\( \)](#) with nSubPart-0.1, nSubPart+0.1.*
- vtkPolyData \* [CommonTools::GetShapeSubSurface](#) (vtkPolyData \*inputShape, double tholdLower, double tholdUpper)  
*Apply threshold to extract the subpart, apply vtkDataSetSurfaceFilter and vtkCleanPolyData.*
- vtkPolyData \* [CommonTools::CloseSurface](#) (vtkPolyData \*shape)  
*Closes only 1 hole, make sure there are no more.*
- vtkPolyData \* [CommonTools::GenerateHoleCover](#) (vtkPolyData \*edge)  
*Generate a cover for a small hole. Uses centroid.*
- void [CommonTools::SavePolydata](#) (vtkPolyData \*poly, const char \*filename, bool binary=false)  
*Save polydata to a file.*
- void [CommonTools::SaveImage](#) (vtkDataSet \*image, const char \*filename)  
*Save image to a file.*
- vtkImageData \* [CommonTools::LoadImage](#) (const char \*filename)  
*Load image from a file.*
- void [CommonTools::SaveUnstructuredGrid](#) (vtkUnstructuredGrid \*grid, const char \*filename)  
*Save unstructured grid to a file.*
- void [CommonTools::SavePoints](#) (vtkPoints \*pts, const char \*filename)  
*Save vtkPoints to a file.*
- bool [CommonTools::FileExists](#) (const char \*filename, bool no\_exception=false)  
*Check if file exists and throw an exception if needed.*

- void [CommonTools::ReadFilelist](#) (const char \*file, std::vector< std::string > &list, bool check\_existence=false)  
*Generate a filelist.*
- vtkPolyData \* [CommonTools::Points2Polydata](#) (vtkPoints \*points, double scalar)  
*Saves points such that they can e visualized in paraview also saves a scalar corresponding to a position so it is easy to see the ordering of points (if sampling is correct) if scalars != NULL, the corresponding scalar values will be assigned to the points.*
- vtkPolyData \* [CommonTools::Points2Polydata](#) (vtkPoints \*points, const double \*scalars=NULL)  
*Saves points such that they can e visualized in paraview also saves a scalar corresponding to a position so it is easy to see the ordering of points.*
- void [CommonTools::ExportPolyDataPoints](#) (vtkPolyData \*shape, vnl\_vector< double > &points)  
*extract points from polydata*
- void [CommonTools::ExportPolyDataPoints](#) (vtkPolyData \*shape, vnl\_matrix< double > &points)  
*extract points from polydata*
- void [CommonTools::ImportPolyDataPoints](#) (vtkPolyData \*shape, vnl\_vector< double > &points)  
*copy points to polydata*
- void [CommonTools::ImportPolyDataPoints](#) (vtkPolyData \*shape, vnl\_matrix< double > &points)  
*copy points to polydata*
- void [CommonTools::GenerateDecimationScript](#) (const char \*filename, int nfases)  
*generate a Meshlab script for mesh decimation, specify number of faces*
- void [CommonTools::ScaleShape](#) (vtkPolyData \*shapein, vtkPolyData \*shapeout, float scale, bool center-AfterScale=false)  
*Rescale polydata.*
- void [CommonTools::ShrinkImage](#) (vtkDataSet \*imagein, vtkDataSet \*imageout, int factor)  
*Resize image.*
- void [CommonTools::ScaleVolume](#) (vtkUnstructuredGrid \*volumein, vtkUnstructuredGrid \*volumeout, float scale)  
*Resize unstructured grid.*
- vtkPolyData \* [CommonTools::LoadShapeFromFile](#) (const char \*shapeFileName)  
*Load polydata from file.*
- vtkUnstructuredGrid \* [CommonTools::LoadVolumeFromFile](#) (const char \*volumeFileName)  
*Load unstructured grid from file.*
- void [CommonTools::SaveVolumeToFile](#) (vtkUnstructuredGrid \*volumePt, const char \*volumeFileName, const char \*header)  
*Save unstructured grid to file.*
- void [CommonTools::SaveShapeToFile](#) (vtkPolyData \*shapePt, const char \*shapeFileName, const char \*header=NULL)  
*Save polydata to file.*
- void [CommonTools::GetP2S](#) (vtkPolyData \*manualPt, vtkPolyData \*segmentedPt, double &mean, double &std\_dev, double &max, double &last, bool b\_array)  
*Calculate point-to-surface distance.*
- void [CommonTools::GetP2P](#) (vtkPolyData \*manualPt, vtkPolyData \*segmentedPt, double &mean, double &std\_dev, double &max, double &last, bool b\_array)  
*Calculate point-to-point distance.*
- vtkPolyData \* [CommonTools::GetP2S](#) (vtkPolyData \*shapePt1, vtkPolyData \*shapePt2, std::vector< vnl\_vector< double > > &distances)  
*Calculate point-to-surface distance.*
- vtkPolyData \* [CommonTools::GetP2S](#) (vtkPolyData \*shapePt1, vtkPolyData \*shapePt2, vnl\_vector< double > &distances)  
*Calculate point-to-surface distance.*
- void [CommonTools::GetS2S](#) (vtkPolyData \*shapePt1, vtkPolyData \*shapePt2, std::vector< vnl\_vector< double > > &distances)

*Calculate surface-to-surface distance.*

- bool [CommonTools::CheckSaveFileExtension](#) (const char \*shapeFileName)  
*check if the file has valid extension for saving. To remove one day.*
- VTKVolumeMeshFormats [CommonTools::GetTypeOfVTKVolumeData](#) (const char \*volumeFileName)  
*identify volume data type*
- VTKSurfaceMeshFormats [CommonTools::GetTypeOfVTKData](#) (const char \*shapeFileName)  
*identify VTK data type*
- int [CommonTools::laplace3D\\_voxelsize](#) (vtkImageData \*inputImage, vtkImageData \*outputImage, int iterations)  
*Explicit solution to Laplace Eq. (c) Ruben Cardenes + Constantine Butakoff.*

### 6.5.1 Detailed Description

Some common functions.

## 6.6 /home/costa/Data/Code/C/apps/CreateImageMask.cpp File Reference

Create mask for a given shape with user defined dimensions.

```
#include <vtkPolyData.h>
#include <vtkPolyDataToImageStencil.h>
#include <vtkImageStencil.h>
#include <vtkImageData.h>
#include <vtkDataSet.h>
#include <vtkDataSetReader.h>
#include <vtkDataSetWriter.h>
#include <vtkSmartPointer.h>
#include "vtkTransform.h"
#include "vtkTransformPolyDataFilter.h"
#include "CommonTools.h"
#include <stdlib.h>
#include <stdio.h>
#include <iostream>
```

### Functions

- int [main](#) (int argc, char \*\*argv)

### 6.6.1 Detailed Description

Create mask for a given shape with user defined dimensions.

### 6.6.2 Function Documentation

#### 6.6.2.1 int main ( int argc, char \*\* argv )

## 6.7 /home/costa/Data/Code/C/apps/ExtractShapeRegion.cpp File Reference

Extract a part of polydata.

```
#include <vtkCell.h>
#include <vtkIdList.h>
#include <vtkCleanPolyData.h>
#include <vtkPointData.h>
#include <vtkShortArray.h>
#include <vtkPolyData.h>
#include <vtkSTLReader.h>
#include <vtkXMLPolyDataReader.h>
#include <vtkPolyDataWriter.h>
#include <vtkPolyDataReader.h>
#include <vtkObject.h>
#include "CommonTools.h"
#include <vtkstd/exception>
#include <vtkFeatureEdges.h>
#include <vn1/vn1_matrix.h>
#include <vn1/vn1_vector.h>
#include <vn1/algo/vn1_svd_economy.h>
#include <vtkXMLPolyDataWriter.h>
#include <vtkPoints.h>
#include <vtkCellArray.h>
#include <vtkAppendPolyData.h>
```

## Functions

- int [main](#) (int argc, char \*argv[])

### 6.7.1 Detailed Description

Extract a part of polydata.

### 6.7.2 Function Documentation

#### 6.7.2.1 int main ( int argc, char \* argv[] )

## 6.8 /home/costa/Data/Code/C/apps/GenerateVolumetricLVMesh.cpp File Reference

Generate volumetric mesh of Left Ventricle.

```

#include <vtkCleanPolyData.h>
#include <vtkPolyData.h>
#include <vtkPolyDataReader.h>
#include <vtkIVWriter.h>
#include <vtkFloatArray.h>
#include <vtkPointData.h>
#include <vtkLookupTable.h>
#include "CommonTools.h"
#include "vtkSmartPointer.h"
#include <vector>
#include "vtkCellLocator.h"
#include "vtkPolyDataNormals.h"
#include "vnl/vnl_vector.h"
#include "vnl/vnl_matrix.h"
#include "vnl/vnl_cross.h"
#include "vtkGenericCell.h"
#include "vtkWedge.h"
#include "vtkIdList.h"
#include "vtkCell.h"
#include "vtkUnstructuredGrid.h"
#include "vtkUnstructuredGridWriter.h"
#include "vtkCellType.h"
#include "vtkCellData.h"
#include "vtkImageEuclideanDistance.h"
#include "vtkPolyDataToImageStencil.h"
#include "vtkImageStencil.h"
#include "vtkImageGradient.h"
#include "vtkImageContinuousErode3D.h"
#include "vtkImageContinuousDilate3D.h"
#include "vtkShortArray.h"
#include "vtkCellArray.h"
#include "vtkStreamTracer.h"
#include "vtkImageMathematics.h"
#include "vtkImageCast.h"
#include "vtkAssignAttribute.h"
#include "vtkSplineFilter.h"

```

## Macros

- `#define FIELD_DT 0`
- `#define FIELD_LAPLACE 1`

## Functions

- void [GenerateLayersAlongNormals](#) (vtkPoints \*layers, vtkPolyData \*epi, vtkPolyData \*endo, int nLayers)  
*generate points between epi and endo along surface normals*
- void [GenerateLayersAlongField](#) (vtkPoints \*layers, vtkPolyData \*epi, vtkPolyData \*endo, int nLayers, int field\_type=0, float VoxelSize=0.5, int laplace\_iterations=100)  
*generate points between epi and endo along vector field*
- void [GenerateImageMask](#) (vtkImageData \*res\_image, float fg, float bg, vtkPolyData \*endo, vtkPolyData \*epi, float VoxelSize=0.5)  
*generate mask given epi and endo*
- void [GenerateLocalCoordinateCircLongit](#) (vtkUnstructuredGrid \*volmesh, int nLayers, int nPointsPerLevel)  
*generate local coordinates*



- void [GenerateLocalCoordinateRadial](#) (vtkUnstructuredGrid \*volmesh, int nLayers)  
*generate local coordinates*
- void [usage](#) (char \*exe)
- int [main](#) (int argc, char \*\*argv)

### 6.8.1 Detailed Description

Generate volumetric mesh of Left Ventricle.

### 6.8.2 Macro Definition Documentation

6.8.2.1 `#define FIELD_DT 0`

6.8.2.2 `#define FIELD_LAPLACE 1`

### 6.8.3 Function Documentation

6.8.3.1 void [GenerateImageMask](#) ( vtkImageData \* *res\_image*, float *fg*, float *bg*, vtkPolyData \* *endo*, vtkPolyData \* *epi*, float *VoxelSize* = 0.5 )

generate mask given epi and endo

6.8.3.2 void [GenerateLayersAlongField](#) ( vtkPoints \* *layers*, vtkPolyData \* *epi*, vtkPolyData \* *endo*, int *nLayers*, int *field\_type* = 0, float *VoxelSize* = 0.5, int *laplace\_iterations* = 100 )

generate points between epi and endo along vector field

6.8.3.3 void [GenerateLayersAlongNormals](#) ( vtkPoints \* *layers*, vtkPolyData \* *epi*, vtkPolyData \* *endo*, int *nLayers* )

generate points between epi and endo along surface normals

6.8.3.4 void [GenerateLocalCoordinateCircLongit](#) ( vtkUnstructuredGrid \* *volmesh*, int *nLayers*, int *nPointsPerLevel* )

generate local coordinates

6.8.3.5 void [GenerateLocalCoordinateRadial](#) ( vtkUnstructuredGrid \* *volmesh*, int *nLayers* )

generate local coordinates

6.8.3.6 int [main](#) ( int *argc*, char \*\* *argv* )

6.8.3.7 void [usage](#) ( char \* *exe* )

## 6.9 /home/costa/Data/Code/C/apps/imported/itkBinaryThinningImageFilter3D.h File Reference

```
#include <itkNeighborhoodIterator.h>
#include <itkImageToImageFilter.h>
#include <itkImageRegionIteratorWithIndex.h>
#include <itkConstantBoundaryCondition.h>
#include "itkBinaryThinningImageFilter3D.hxx"
```

## Classes

- class [itk::BinaryThinningImageFilter3D< TInputImage, TOutputImage >](#)

*This filter computes one-pixel-wide skeleton of a 3D input image.*

## Namespaces

- namespace [itk](#)

## 6.10 /home/costa/Data/Code/C/apps/imported/itkImageToVTKImageFilter.h File Reference

```
#include "itkVTKImageExport.h"
#include "vtkImageImport.h"
#include "vtkImageData.h"
#include <vector>
#include "itkImageToVTKImageFilter.txx"
```

## Classes

- class [itk::ImageToVTKImageFilter< TInputImage >](#)

*Converts an ITK image into a VTK image and plugs a itk data pipeline to a VTK datapipeline.*

## Namespaces

- namespace [itk](#)

## 6.11 /home/costa/Data/Code/C/apps/imported/LabelBranches3D.cpp File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include <string.h>
#include <vector>
#include <iostream>
#include <sys/time.h>
#include <itkImage.h>
#include <itkImageFileReader.h>
#include <itkImageFileWriter.h>
#include <itkImageRegionIterator.h>
```

## Macros

- `#define FLT_MAX 3.40282347e+38F;`

## Functions

- void [print\\_timing](#) (FILE \*fp, struct timeval start, struct timeval end)
- int [mapIndex3D](#) (int r, int c, int z, int nr, int nc, int nz)
- int [maptox](#) (int mapindex, int max1, int max2)
- int [maptoy](#) (int mapindex, int max1, int max2)
- int [maptoz](#) (int mapindex, int max1, int max2)
- void [reserve\\_memory\\_triple\\_float](#) (float \*\*\*out, int max1, int max2, int max3)
- void [reserve\\_memory\\_triple\\_int](#) (int \*\*\*out, int max1, int max2, int max3)
- int [find\\_maximun](#) (float \*a, int num)
- int [findmaximum\\_centerline](#) (float \*maps, std::vector< int > index\_esqueleto)
- void [CheckConnect](#) (unsigned char \*\*\*input, unsigned char \*output, int max1, int max2, int max3)
- float [distance](#) (int mapindex1, int mapindex2, int max1, int max2)
- int [check\\_neighborhood](#) (int index\_a, int index\_b, int max1, int max2)
- void [LabelBranchesNew](#) (unsigned short \*vol\_esqueleto, int max1, int max2, int max3)
- void [LabelBranchs](#) (unsigned short \*vol\_esqueleto, int max1, int max2, int max3)
- int [check\\_num\\_connected\\_neighbors](#) (std::vector< int > neigh, int max1, int max2)
- int [CheckPointState](#) (unsigned short \*vol\_esqueleto, int mapindex, int max1, int max2, int max3, int &index\_pto\_triple\_aux)
- void [FindTriplePoints](#) (std::vector< int > index\_esqueleto, unsigned short \*vol\_esqueleto, std::vector< int > &ptos\_extremos, int max1, int max2, int max3)
- int [comp\\_conexas](#) (std::vector< int > index\_esqueleto, unsigned short \*vol\_esqueleto, int max1, int max2, int max3)
- int [find\\_shorter\\_branch](#) (std::vector< int > &vec\_index\_esq, unsigned short \*output, int num\_comp)
- void [Relabeling](#) (unsigned short \*output, int max1, int max2, int max3)
- int [main](#) (int argc, char \*argv[])

## Variables

- int [verbose](#)
- int [debug](#)

### 6.11.1 Macro Definition Documentation

- 6.11.1.1 `#define FLT_MAX 3.40282347e+38F;`

### 6.11.2 Function Documentation

- 6.11.2.1 `int check_neighborhood ( int index_a, int index_b, int max1, int max2 )`
- 6.11.2.2 `int check_num_connected_neighbors ( std::vector< int > neigh, int max1, int max2 )`
- 6.11.2.3 `void CheckConnect ( unsigned char *** input, unsigned char * output, int max1, int max2, int max3 )`
- 6.11.2.4 `int CheckPointState ( unsigned short * vol_esqueleto, int mapindex, int max1, int max2, int max3, int & index_pto_triple_aux )`
- 6.11.2.5 `int comp_conexas ( std::vector< int > index_esqueleto, unsigned short * vol_esqueleto, int max1, int max2, int max3 )`
- 6.11.2.6 `float distance ( int mapindex1, int mapindex2, int max1, int max2 )`
- 6.11.2.7 `int find_maximun ( float * a, int num )`

- 6.11.2.8 `int find_shorter_branch ( std::vector< int > & vec_index_esq, unsigned short * output, int num_comp )`
- 6.11.2.9 `int findmaximum_centerline ( float * maps, std::vector< int > index_esqueleto )`
- 6.11.2.10 `void FindTriplePoints ( std::vector< int > index_esqueleto, unsigned short * vol_esqueleto, std::vector< int > & ptos_extremos, int max1, int max2, int max3 )`
- 6.11.2.11 `void LabelBranchs ( unsigned short * vol_esqueleto, int max1, int max2, int max3 )`
- 6.11.2.12 `void LabelBranchsNew ( unsigned short * vol_esqueleto, int max1, int max2, int max3 )`
- 6.11.2.13 `int main ( int argc, char * argv[] )`
- 6.11.2.14 `int mapIndex3D ( int r, int c, int z, int nr, int nc, int nz )`
- 6.11.2.15 `int maptox ( int mapindex, int max1, int max2 )`
- 6.11.2.16 `int maptoy ( int mapindex, int max1, int max2 )`
- 6.11.2.17 `int maptoz ( int mapindex, int max1, int max2 )`
- 6.11.2.18 `void print_timing ( FILE * fp, struct timeval start, struct timeval end )`
- 6.11.2.19 `void Relabeling ( unsigned short * output, int max1, int max2, int max3 )`
- 6.11.2.20 `void reserve_memory_triple_float ( float *** out, int max1, int max2, int max3 )`
- 6.11.2.21 `void reserve_memory_triple_int ( int *** out, int max1, int max2, int max3 )`

### 6.11.3 Variable Documentation

- 6.11.3.1 `int debug`
- 6.11.3.2 `int verbose`

## 6.12 /home/costa/Data/Code/C/apps/imported/pgm2itkvol/itkvol2pgm.cxx File Reference

```
#include <stdio.h>
#include <stdint.h>
#include <sys/types.h>
#include <stdlib.h>
#include <assert.h>
#include <mcimage.h>
#include <mccodimage.h>
#include "itkImage.h"
#include "itkImageFileReader.h"
#include "itkImageRegionIterator.h"
```

### Macros

- `#define VERBOSE`

## Functions

- int [main](#) (int argc, char \*\*argv)

## 6.12.1 Macro Definition Documentation

### 6.12.1.1 #define VERBOSE

## 6.12.2 Function Documentation

### 6.12.2.1 int main ( int argc, char \*\* argv )

## 6.13 /home/costa/Data/Code/C/apps/imported/pgm2itkvol/mccodimage.h File Reference

This file hold the basic type declarations used in the C functions of Pink.

```
#include <stdint.h>
#include "mcimage.h"
```

## Classes

- struct [fcomplex](#)  
*Complex number, represented by floats.*
- struct [dcomplex](#)  
*Complex number, represented by doubles.*
- struct [xvimage](#)  
*The image class for the C functions.*

## Macros

- #define [NDG\\_MAX](#) 255 /\* niveau de gris max \*/
- #define [NDG\\_MIN](#) 0 /\* niveau de gris min \*/
- #define [VFF\\_TYP\\_BIT](#) 0 /\* pixels are on or off (binary image)\*/
- #define [VFF\\_TYP\\_1\\_BYTE](#) 1 /\* pixels are byte ([uint8\\_t](#)) \*/
- #define [VFF\\_TYP\\_2\\_BYTE](#) 2 /\* pixels are two byte ([int16\\_t](#)) \*/
- #define [VFF\\_TYP\\_4\\_BYTE](#) 4 /\* pixels are four byte ([int32\\_t](#)) \*/
- #define [VFF\\_TYP\\_FLOAT](#) 5 /\* pixels are float (single precision)\*/
- #define [VFF\\_TYP\\_DOUBLE](#) 6 /\* pixels are float (double precision)\*/
- #define [VFF\\_TYP\\_COMPLEX](#) 7 /\* pixels are complex (single precision)\*/
- #define [VFF\\_TYP\\_DCOMPLEX](#) 8 /\* pixels are complex (double precision)\*/
- #define [SCHARDATA](#)(l) (([int8\\_t](#)\*)(l->image\_data))
- #define [UCHARDATA](#)(l) (([uint8\\_t](#)\*)(l->image\_data))
- #define [SSHORTDATA](#)(l) (([int16\\_t](#)\*)(l->image\_data))
- #define [USHORTDATA](#)(l) (([uint16\\_t](#)\*)(l->image\_data))
- #define [SLONGDATA](#)(l) (([int32\\_t](#)\*)(l->image\_data))
- #define [ULONGDATA](#)(l) (([uint32\\_t](#)\*)(l->image\_data))
- #define [FLOATDATA](#)(l) (([float](#)\*)(l->image\_data))
- #define [DOUBLEDATA](#)(l) (([double](#)\*)(l->image\_data))
- #define [COMPLEXDATA](#)(l) (([fcomplex](#)\*)(l->image\_data))
- #define [DCOMPLEXDATA](#)(l) (([dcomplex](#)\*)(l->image\_data))
- #define [colsize](#)(l) ((l->col\_size))
- #define [rowsize](#)(l) ((l->row\_size))

- `#define depth(l) ((l)->depth_size)`
- `#define tsize(l) ((l)->time_size)`
- `#define nbands(l) ((l)->num_data_bands)`
- `#define datatype(l) ((l)->data_storage_type)`
- `#define pixel(l, x, y) (((uint8_t*)((l)->image_data))[(y)*(l)->row_size+(x)])`
- `#define voxel(l, x, y, z) (((uint8_t*)((l)->image_data))[(z)*(l)->col_size+(y))*(l)->row_size+(x)])`
- `#define lpixel(l, x, y) (((uint32_t*)((l)->image_data))[(y)*(l)->row_size+(x)])`
- `#define lvoxel(l, x, y, z) (((uint32_t*)((l)->image_data))[(z)*(l)->col_size+(y))*(l)->row_size+(x)])`
- `#define EST 0`
- `#define NORD 2`
- `#define OUEST 4`
- `#define SUD 6`
- `#define NORD_EST 1`
- `#define NORD_OUEST 3`
- `#define SUD_OUEST 5`
- `#define SUD_EST 7`
- `#define DEVANT 8`
- `#define DERRIERE 10`
- `#define nonbord(p, rs, N) ((p%rs!=rs-1)&&(p>=rs)&&(p%rs!=0)&&(p<N-rs))`
- `#define nonbord3d(p, rs, ps, N) ((p>=ps)&&(p<N-ps)&&(p%ps>=rs)&&(p%ps<ps-rs)&&(p%rs!=0)&&(p%rs!=rs-1))`
- `#define ACCEPTED_TYPES1(l, T0)`
- `#define ACCEPTED_TYPES2(l, T0, T1)`
- `#define ACCEPTED_TYPES3(l, T0, T1, T2)`
- `#define ACCEPTED_TYPES4(l, T0, T1, T2, T3)`
- `#define ACCEPTED_TYPES5(l, T0, T1, T2, T3, T4)`
- `#define ACCEPTED_TYPES6(l, T0, T1, T2, T3, T4, T5)`
- `#define ACCEPTED_TYPES7(l, T0, T1, T2, T3, T4, T5, T6)`
- `#define COMPARE_SIZE(l0, l1)`
- `#define ONLY_2D(l)`
- `#define ONLY_3D(l)`

## Typedefs

- `typedef struct xvimage xvimage`

## Functions

- `int32_t voisin (index_t i, int32_t k, index_t rs, index_t nb)`
- `int32_t voisin2 (index_t i, int32_t k, index_t rs, index_t nb)`
- `int32_t voisin6 (index_t i, int32_t k, index_t rs, index_t n, index_t nb)`
- `int32_t bord (index_t i, index_t rs, index_t nb)`
- `int32_t bord3d (index_t i, index_t rs, index_t ps, index_t nb)`
- `int32_t voisin26 (index_t i, int32_t k, index_t rs, index_t n, index_t nb)`
- `int32_t voisin18 (index_t i, int32_t k, index_t rs, index_t n, index_t nb)`
- `int32_t voisins4 (index_t i, index_t j, index_t rs)`
- `int32_t voisins8 (index_t i, index_t j, index_t rs)`
- `int32_t voisins6 (index_t i, index_t j, index_t rs, index_t ps)`
- `int32_t voisins18 (index_t i, index_t j, index_t rs, index_t ps)`
- `int32_t voisins26 (index_t i, index_t j, index_t rs, index_t ps)`
- `int32_t voisin5 (index_t i, int32_t k, index_t rs, index_t nb)`
- `int32_t voisin6b (index_t i, int32_t k, index_t rs, index_t nb, index_t par)`
- `int32_t voisinNESO (index_t i, int32_t k, index_t rs, index_t nb)`
- `int32_t voisinNOSE (index_t i, int32_t k, index_t rs, index_t nb)`

- [int32\\_t voisin14b](#) ([index\\_t i](#), [int32\\_t k](#), [index\\_t rs](#), [index\\_t ps](#), [index\\_t N](#))
- [int32\\_t voisinONAV](#) ([index\\_t i](#), [int32\\_t k](#), [index\\_t rs](#), [index\\_t ps](#), [index\\_t N](#))
- [int32\\_t voisinENAR](#) ([index\\_t i](#), [int32\\_t k](#), [index\\_t rs](#), [index\\_t ps](#), [index\\_t N](#))
- [int32\\_t voisinENAV](#) ([index\\_t i](#), [int32\\_t k](#), [index\\_t rs](#), [index\\_t ps](#), [index\\_t N](#))
- [int32\\_t voisinONAR](#) ([index\\_t i](#), [int32\\_t k](#), [index\\_t rs](#), [index\\_t ps](#), [index\\_t N](#))
- [uint32\\_t maskvois26](#) ([uint8\\_t \\*F](#), [uint32\\_t bitmask](#), [index\\_t i](#), [index\\_t rs](#), [index\\_t ps](#), [index\\_t N](#))
- [int32\\_t sont4voisins](#) ([index\\_t p](#), [index\\_t q](#), [index\\_t rs](#))
- [int32\\_t sont8voisins](#) ([index\\_t p](#), [index\\_t q](#), [index\\_t rs](#))
- [int32\\_t sont6voisins](#) ([index\\_t p](#), [index\\_t q](#), [index\\_t rs](#), [index\\_t ps](#))
- [int32\\_t sont18voisins](#) ([index\\_t p](#), [index\\_t q](#), [index\\_t rs](#), [index\\_t ps](#))
- [int32\\_t sont26voisins](#) ([index\\_t p](#), [index\\_t q](#), [index\\_t rs](#), [index\\_t ps](#))
- [int32\\_t voisin125](#) ([index\\_t i](#), [int32\\_t k](#), [index\\_t rs](#), [index\\_t ps](#), [index\\_t N](#))

### 6.13.1 Detailed Description

This file hold the basic type declarations used in the C functions of Pink. Pink

#### Author

Michel Couprie

### 6.13.2 Macro Definition Documentation

#### 6.13.2.1 #define ACCEPTED\_TYPES1( I, T0 )

##### Value:

```
if (datatype(I) != T0)
{
    fprintf(stderr, "%s: bad image type\n", F_NAME);
    return 0;
}
```

#### 6.13.2.2 #define ACCEPTED\_TYPES2( I, T0, T1 )

##### Value:

```
if ( (datatype(I) != T0) && (datatype(I) != T1) )
{
    fprintf(stderr, "%s: bad image type\n", F_NAME);
    return 0;
}
```

#### 6.13.2.3 #define ACCEPTED\_TYPES3( I, T0, T1, T2 )

##### Value:

```
if ( (datatype(I) != T0) && (datatype(I) != T1) && (datatype(I) != T2) )
{
    fprintf(stderr, "%s: bad image type\n", F_NAME);
    return 0;
}
```

#### 6.13.2.4 #define ACCEPTED\_TYPES4( I, T0, T1, T2, T3 )

**Value:**

```
if ( (datatype(I)!=T0) && (datatype(I)!=T1) && (datatype
    (I)!=T2) \
    && (datatype(I)!=T3) )
{
    fprintf(stderr, "%s: bad image type\n", F_NAME);
    return 0;
}
```

#### 6.13.2.5 #define ACCEPTED\_TYPES5( I, T0, T1, T2, T3, T4 )

**Value:**

```
if ( (datatype(I)!=T0) && (datatype(I)!=T1) && (datatype
    (I)!=T2) \
    && (datatype(I)!=T3) && (datatype(I)!=T4) )
{
    fprintf(stderr, "%s: bad image type\n", F_NAME);
    return 0;
}
```

#### 6.13.2.6 #define ACCEPTED\_TYPES6( I, T0, T1, T2, T3, T4, T5 )

**Value:**

```
if ( (datatype(I)!=T0) && (datatype(I)!=T1) && (datatype
    (I)!=T2) \
    && (datatype(I)!=T3) && (datatype(I)!=T4) && (datatype
    (I)!=T5) ) \
{
    fprintf(stderr, "%s: bad image type\n", F_NAME);
    return 0;
}
```

#### 6.13.2.7 #define ACCEPTED\_TYPES7( I, T0, T1, T2, T3, T4, T5, T6 )

**Value:**

```
if ( (datatype(I)!=T0) && (datatype(I)!=T1) && (datatype
    (I)!=T2) \
    && (datatype(I)!=T3) && (datatype(I)!=T4) && (datatype
    (I)!=T5) \
    && (datatype(I)!=T6) )
{
    fprintf(stderr, "%s: bad image type\n", F_NAME);
    return 0;
}
```

#### 6.13.2.8 #define colsize( I ) ((I)->col\_size)

#### 6.13.2.9 #define COMPARE\_SIZE( I0, I1 )

**Value:**

```
if (rowsize(I0)!=rowsize(I1) && rowsize(I0)!=rowsize
    (I1) && depth(I0)!=depth(I1) \
    && (tsize(I0) != tsize(I1) ) && (nbands(I0) != nbands
    (I1) ) )
{
    fprintf(stderr, "%s: incompatible image sizes\n", F_NAME);
    return 0;
}
```



- 6.13.2.10 `#define COMPLEXDATA( I ) ((fcomplex*)((I)->image_data))`
- 6.13.2.11 `#define datatype( I ) ((I)->data_storage_type)`
- 6.13.2.12 `#define DCOMPLEXDATA( I ) ((dcomplex*)((I)->image_data))`
- 6.13.2.13 `#define depth( I ) ((I)->depth_size)`
- 6.13.2.14 `#define DERRIERE 10`
- 6.13.2.15 `#define DEVANT 8`
- 6.13.2.16 `#define DOUBLEDATA( I ) ((double*)((I)->image_data))`
- 6.13.2.17 `#define EST 0`
- 6.13.2.18 `#define FLOATDATA( I ) ((float*)((I)->image_data))`
- 6.13.2.19 `#define lpixel( I, x, y ) (((uint32_t*)((I)->image_data))[(y)*(I)->row_size+(x)])`
- 6.13.2.20 `#define lvoxel( I, x, y, z ) (((uint32_t*)((I)->image_data))[(z)*(I)->col_size+(y))*(I)->row_size+(x)])`
- 6.13.2.21 `#define nbands( I ) ((I)->num_data_bands)`
- 6.13.2.22 `#define NDG_MAX 255 /* niveau de gris max */`
- 6.13.2.23 `#define NDG_MIN 0 /* niveau de gris min */`
- 6.13.2.24 `#define nonbord( p, rs, N ) ((p%rs!=rs-1)&&(p>=rs)&&(p%rs!=0)&&(p<N-rs))`
- 6.13.2.25 `#define nonbord3d( p, rs, ps, N ) ((p>=ps)&&(p<N-ps)&&(p%ps>=rs)&&(p%ps<ps-rs)&&(p%rs!=0)&&(p%rs!=rs-1))`
- 6.13.2.26 `#define NORD 2`
- 6.13.2.27 `#define NORD_EST 1`
- 6.13.2.28 `#define NORD_OUEST 3`
- 6.13.2.29 `#define ONLY_2D( I )`

**Value:**

```
if (depth(I) != 1)
{
    fprintf(stderr, "%s: only for 2D images\n", F_NAME);
    return 0;
}
```

- 6.13.2.30 `#define ONLY_3D( I )`

**Value:**

```
if (depth(I) == 1)
{
    fprintf(stderr, "%s: only for 3D images\n", F_NAME);
    return 0;
}
```

6.13.2.31 `#define OUEST 4`

6.13.2.32 `#define pixel( I, x, y ) (((uint8_t*)((I)->image_data))[(y)*(I)->row_size+(x)])`

6.13.2.33 `#define rowsize( I ) ((I)->row_size)`

6.13.2.34 `#define SCHARDATA( I ) ((int8_t*)((I)->image_data))`

6.13.2.35 `#define SLONGDATA( I ) ((int32_t*)((I)->image_data))`

6.13.2.36 `#define SSHORTDATA( I ) ((int16_t*)((I)->image_data))`

6.13.2.37 `#define SUD 6`

6.13.2.38 `#define SUD_EST 7`

6.13.2.39 `#define SUD_OUEST 5`

6.13.2.40 `#define tsize( I ) ((I)->time_size)`

6.13.2.41 `#define UCHARDATA( I ) ((uint8_t*)((I)->image_data))`

6.13.2.42 `#define ULONGDATA( I ) ((uint32_t*)((I)->image_data))`

6.13.2.43 `#define USHORTDATA( I ) ((uint16_t*)((I)->image_data))`

6.13.2.44 `#define VFF_TYP_1_BYTE 1 /* pixels are byte (uint8_t) */`

6.13.2.45 `#define VFF_TYP_2_BYTE 2 /* pixels are two byte (int16_t) */`

6.13.2.46 `#define VFF_TYP_4_BYTE 4 /* pixels are four byte (int32_t) */`

6.13.2.47 `#define VFF_TYP_BIT 0 /* pixels are on or off (binary image) */`

6.13.2.48 `#define VFF_TYP_COMPLEX 7 /* pixels are complex (single precision) */`

6.13.2.49 `#define VFF_TYP_DCOMPLEX 8 /* pixels are complex (double precision) */`

6.13.2.50 `#define VFF_TYP_DOUBLE 6 /* pixels are float (double precision) */`

6.13.2.51 `#define VFF_TYP_FLOAT 5 /* pixels are float (single precision) */`

6.13.2.52 `#define voxel( I, x, y, z ) (((uint8_t*)((I)->image_data))[(z)*(I)->col_size+(y))*(I)->row_size+(x)])`

### 6.13.3 Typedef Documentation

6.13.3.1 `typedef struct xvimage xvimage`

### 6.13.4 Function Documentation

6.13.4.1 `int32_t bord ( index_t i, index_t rs, index_t nb )`

6.13.4.2 `int32_t bord3d ( index_t i, index_t rs, index_t ps, index_t nb )`

6.13.4.3 `uint32_t maskvois26 ( uint8_t * F, uint32_t bitmask, index_t i, index_t rs, index_t ps, index_t N )`

- 6.13.4.4 `int32_t sont18voisins ( index_t p, index_t q, index_t rs, index_t ps )`
- 6.13.4.5 `int32_t sont26voisins ( index_t p, index_t q, index_t rs, index_t ps )`
- 6.13.4.6 `int32_t sont4voisins ( index_t p, index_t q, index_t rs )`
- 6.13.4.7 `int32_t sont6voisins ( index_t p, index_t q, index_t rs, index_t ps )`
- 6.13.4.8 `int32_t sont8voisins ( index_t p, index_t q, index_t rs )`
- 6.13.4.9 `int32_t voisin ( index_t i, int32_t k, index_t rs, index_t nb )`
- 6.13.4.10 `int32_t voisin125 ( index_t i, int32_t k, index_t rs, index_t ps, index_t N )`
- 6.13.4.11 `int32_t voisin14b ( index_t i, int32_t k, index_t rs, index_t ps, index_t N )`
- 6.13.4.12 `int32_t voisin18 ( index_t i, int32_t k, index_t rs, index_t n, index_t nb )`
- 6.13.4.13 `int32_t voisin2 ( index_t i, int32_t k, index_t rs, index_t nb )`
- 6.13.4.14 `int32_t voisin26 ( index_t i, int32_t k, index_t rs, index_t n, index_t nb )`
- 6.13.4.15 `int32_t voisin5 ( index_t i, int32_t k, index_t rs, index_t nb )`
- 6.13.4.16 `int32_t voisin6 ( index_t i, int32_t k, index_t rs, index_t n, index_t nb )`
- 6.13.4.17 `int32_t voisin6b ( index_t i, int32_t k, index_t rs, index_t nb, index_t par )`
- 6.13.4.18 `int32_t voisinENAR ( index_t i, int32_t k, index_t rs, index_t ps, index_t N )`
- 6.13.4.19 `int32_t voisinENAV ( index_t i, int32_t k, index_t rs, index_t ps, index_t N )`
- 6.13.4.20 `int32_t voisinNESO ( index_t i, int32_t k, index_t rs, index_t nb )`
- 6.13.4.21 `int32_t voisinNOSE ( index_t i, int32_t k, index_t rs, index_t nb )`
- 6.13.4.22 `int32_t voisinONAR ( index_t i, int32_t k, index_t rs, index_t ps, index_t N )`
- 6.13.4.23 `int32_t voisinONAV ( index_t i, int32_t k, index_t rs, index_t ps, index_t N )`
- 6.13.4.24 `int32_t voisins18 ( index_t i, index_t j, index_t rs, index_t ps )`
- 6.13.4.25 `int32_t voisins26 ( index_t i, index_t j, index_t rs, index_t ps )`
- 6.13.4.26 `int32_t voisins4 ( index_t i, index_t j, index_t rs )`
- 6.13.4.27 `int32_t voisins6 ( index_t i, index_t j, index_t rs, index_t ps )`
- 6.13.4.28 `int32_t voisins8 ( index_t i, index_t j, index_t rs )`

## 6.14 /home/costa/Data/Code/C/apps/imported/pgm2itkvol/mcimage.c File Reference

```
#include <stdio.h>
#include <stdint.h>
#include <stdlib.h>
#include <sys/stat.h>
#include <sys/types.h>
#include <string.h>
#include <ctype.h>
#include <assert.h>
#include <mcutil.h>
#include <mcimage.h>
#include <mccodimage.h>
```

### Classes

- struct [BITMAPFILEHEADER](#)
- struct [BITMAPINFOHEADER](#)
- struct [RGBFILEHEADER](#)

### Macros

- #define [INT32\\_MAX](#) (2147483647)
- #define [BUFFERSIZE](#) 10000
- #define [WARN\\_HUGE](#)
- #define [F\\_NAME](#) "allocimage"
- #define [F\\_NAME](#) "allocmultimage"
- #define [F\\_NAME](#) "razimage"
- #define [F\\_NAME](#) "allocheader"
- #define [F\\_NAME](#) "showheader"
- #define [F\\_NAME](#) "copyimage"
- #define [F\\_NAME](#) "copy2image"
- #define [F\\_NAME](#) "equalimages"
- #define [F\\_NAME](#) "convertgen"
- #define [F\\_NAME](#) "convertlong"
- #define [F\\_NAME](#) "convertfloat"
- #define [F\\_NAME](#) "list2image"
- #define [F\\_NAME](#) "image2list"
- #define [F\\_NAME](#) "writeimage"
- #define [F\\_NAME](#) "writerawimage"
- #define [F\\_NAME](#) "writese"
- #define [F\\_NAME](#) "writeascimage"
- #define [F\\_NAME](#) "printimage"
- #define [F\\_NAME](#) "writergbimage"
- #define [F\\_NAME](#) "writergbascimage"
- #define [F\\_NAME](#) "writelongimage"
- #define [F\\_NAME](#) "readimage"
- #define [F\\_NAME](#) "readheader"
- #define [F\\_NAME](#) "readse"
- #define [F\\_NAME](#) "readrgbimage"
- #define [F\\_NAME](#) "readlongimage"
- #define [F\\_NAME](#) "readbmp"
- #define [F\\_NAME](#) "writebmp"

- `#define F_NAME "readrgb"`
- `#define F_NAME "writelst2"`
- `#define F_NAME "writelst3"`

## Functions

- `__pink__inline FILE * pink_fopen_read (char *filename)`
- `__pink__inline FILE * pink_fopen_write (char *filename)`
- `struct ximage * allocimage (char *name, index_t rs, index_t cs, index_t ds, int32_t dt)`  
*Allocates an image object with the given size and type.*
- `struct ximage * allocmultimage (char *name, index_t rs, index_t cs, index_t ds, index_t ts, index_t nb, int32_t dt)`
- `void razimage (struct ximage *f)`  
*fills the image with zeros description Sets every pixel of the image to binary zero.*
- `struct ximage * allocheader (char *name, index_t rs, index_t cs, index_t d, int32_t t)`
- `int32_t showheader (char *name)`
- `void freeimage (struct ximage *image)`  
*Frees an image object.*
- `struct ximage * copyimage (struct ximage *f)`
- `int32_t copy2image (struct ximage *dest, struct ximage *source)`
- `int32_t equalimages (struct ximage *im1, struct ximage *im2)`
- `int32_t convertgen (struct ximage **f1, struct ximage **f2)`
- `int32_t convertlong (struct ximage **f1)`
- `int32_t convertfloat (struct ximage **f1)`
- `void list2image (struct ximage *image, double *P, index_t n)`
- `double * image2list (struct ximage *image, index_t *n)`
- `void writeimage (struct ximage *image, char *filename)`  
*Writes an image to disk.*
- `void writerawimage (struct ximage *image, char *filename)`
- `void writese (struct ximage *image, char *filename, index_t x, index_t y, index_t z)`
- `void writeascimage (struct ximage *image, char *filename)`
- `void printimage (struct ximage *image)`
- `void writergbimage (struct ximage *redimage, struct ximage *greenimage, struct ximage *blueimage, char *filename)`
- `void writergbascimage (struct ximage *redimage, struct ximage *greenimage, struct ximage *blueimage, char *filename)`
- `void writelongimage (struct ximage *image, char *filename)`
- `struct ximage * readimage (const char *filename)`  
*Reads an image from a file.*
- `struct ximage * readheader (char *filename)`
- `struct ximage * readse (char *filename, index_t *x, index_t *y, index_t *z)`
- `int32_t readrgbimage (char *filename, struct ximage **r, struct ximage **g, struct ximage **b)`
- `struct ximage * readlongimage (char *filename)`
- `void freadushort (uint16_t *ptr, FILE *fd)`
- `void freadulong (uint32_t *ptr, FILE *fd)`
- `int32_t readbmp (char *filename, struct ximage **r, struct ximage **g, struct ximage **b)`
- `void fwriteushort (uint16_t us, FILE *fd)`
- `void fwriteulong (uint32_t ul, FILE *fd)`
- `void writebmp (struct ximage *redimage, struct ximage *greenimage, struct ximage *blueimage, char *filename)`
- `int32_t readrgb (char *filename, struct ximage **r, struct ximage **g, struct ximage **b)`
- `void writelist2 (char *filename, int32_t *x, int32_t *y, int32_t npoints)`
- `void writelist3 (char *filename, int32_t *x, int32_t *y, int32_t *z, int32_t npoints)`

## 6.14.1 Macro Definition Documentation

6.14.1.1 `#define BUFFERSIZE 10000`

6.14.1.2 `#define F_NAME "allocimage"`

6.14.1.3 `#define F_NAME "allocmultimage"`

6.14.1.4 `#define F_NAME "razimage"`

6.14.1.5 `#define F_NAME "allocheader"`

6.14.1.6 `#define F_NAME "showheader"`

6.14.1.7 `#define F_NAME "copyimage"`

6.14.1.8 `#define F_NAME "copy2image"`

6.14.1.9 `#define F_NAME "equalimages"`

6.14.1.10 `#define F_NAME "convertgen"`

6.14.1.11 `#define F_NAME "convertlong"`

6.14.1.12 `#define F_NAME "convertfloat"`

6.14.1.13 `#define F_NAME "list2image"`

6.14.1.14 `#define F_NAME "image2list"`

6.14.1.15 `#define F_NAME "writeimage"`

6.14.1.16 `#define F_NAME "writerawimage"`

6.14.1.17 `#define F_NAME "writese"`

6.14.1.18 `#define F_NAME "writeascimage"`

6.14.1.19 `#define F_NAME "printimage"`

6.14.1.20 `#define F_NAME "writergbimage"`

6.14.1.21 `#define F_NAME "writergbascimage"`

6.14.1.22 `#define F_NAME "writelongimage"`

6.14.1.23 `#define F_NAME "readimage"`

6.14.1.24 `#define F_NAME "readheader"`

6.14.1.25 `#define F_NAME "readse"`

6.14.1.26 `#define F_NAME "readrgbimage"`

6.14.1.27 `#define F_NAME "readlongimage"`

6.14.1.28 `#define F_NAME "readbmp"`

6.14.1.29 `#define F_NAME "writebmp"`

6.14.1.30 `#define F_NAME "readrgb"`

6.14.1.31 `#define F_NAME "writelist2"`

6.14.1.32 `#define F_NAME "writelist3"`

6.14.1.33 `#define INT32_MAX (2147483647)`

6.14.1.34 `#define WARN_HUGE`

## 6.14.2 Function Documentation

6.14.2.1 `struct ximage* allocheader ( char * name, index_t rs, index_t cs, index_t d, int32_t t )` [read]

6.14.2.2 `struct ximage* allocimage ( char * name, index_t rs, index_t cs, index_t ds, int32_t t )` [read]

Allocates an image object with the given size and type.

### Parameters

<i>name</i>	Not used
<i>rs</i>	x-size
<i>cs</i>	y-size
<i>ds</i>	z-size
<i>t</i>	t-size

### Returns

The pointer to the image.

6.14.2.3 `struct ximage* allocmultimage ( char * name, index_t rs, index_t cs, index_t ds, index_t ts, index_t nb, int32_t dt )` [read]

6.14.2.4 `int32_t convertfloat ( struct ximage ** f1 )`

6.14.2.5 `int32_t convertgen ( struct ximage ** f1, struct ximage ** f2 )`

6.14.2.6 `int32_t convertlong ( struct ximage ** f1 )`

6.14.2.7 `int32_t copy2image ( struct ximage * dest, struct ximage * source )`

6.14.2.8 `struct ximage* copyimage ( struct ximage * f )` [read]

6.14.2.9 `int32_t equalimages ( struct ximage * im1, struct ximage * im2 )`

6.14.2.10 `void freadulong ( uint32_t * ptr, FILE * fd )`

6.14.2.11 `void freadushort ( uint16_t * ptr, FILE * fd )`

6.14.2.12 `void freeimage ( struct ximage * image )`

Frees an image object.

## Parameters

<i>image</i>	The pointer to the image
--------------	--------------------------

6.14.2.13 void fwriteulong ( uint32\_t *ul*, FILE \* *fd* )

6.14.2.14 void fwriteushort ( uint16\_t *us*, FILE \* *fd* )

6.14.2.15 double\* image2list ( struct ximage \* *image*, index\_t \* *n* )

6.14.2.16 void list2image ( struct ximage \* *image*, double \* *P*, index\_t *n* )

6.14.2.17 \_\_pink\_\_inline FILE\* pink\_fopen\_read ( char \* *filename* )

6.14.2.18 \_\_pink\_\_inline FILE\* pink\_fopen\_write ( char \* *filename* )

6.14.2.19 void printimage ( struct ximage \* *image* )

6.14.2.20 void razimage ( struct ximage \* *f* )

fills the image with zeros description Sets every pixel of the image to binary zero.

## Parameters

<i>f</i>	the input image
----------	-----------------

## Returns

no return value

6.14.2.21 int32\_t readbmp ( char \* *filename*, struct ximage \*\* *r*, struct ximage \*\* *g*, struct ximage \*\* *b* )

6.14.2.22 struct ximage\* readheader ( char \* *filename* ) [read]

6.14.2.23 struct ximage\* readimage ( const char \* *filename* ) [read]

Reads an image from a file.

## Parameters

<i>filename</i>	The name of the image file.
-----------------	-----------------------------

## Returns

A Pointer to a newly allocated image.

6.14.2.24 struct ximage\* readlongimage ( char \* *filename* ) [read]

6.14.2.25 int32\_t readrgb ( char \* *filename*, struct ximage \*\* *r*, struct ximage \*\* *g*, struct ximage \*\* *b* )

plus 404 bytes dummy padding to make header 512 bytes padding bytes

red bytes

green bytes

blue bytes



6.14.2.26 `int32_t readrgbimage ( char * filename, struct ximage ** r, struct ximage ** g, struct ximage ** b )`

6.14.2.27 `struct ximage* readse ( char * filename, index_t * x, index_t * y, index_t * z )` [read]

6.14.2.28 `int32_t showheader ( char * name )`

6.14.2.29 `void writeascimage ( struct ximage * image, char * filename )`

6.14.2.30 `void writebmp ( struct ximage * redimage, struct ximage * greenimage, struct ximage * blueimage, char * filename )`

6.14.2.31 `void writeimage ( struct ximage * image, char * filename )`

Writes an image to disk.

#### Parameters

<i>image</i>	The pointer to the image
<i>filename</i>	The file to write the image at.

6.14.2.32 `void writelist2 ( char * filename, int32_t * x, int32_t * y, int32_t npoints )`

6.14.2.33 `void writelist3 ( char * filename, int32_t * x, int32_t * y, int32_t * z, int32_t npoints )`

6.14.2.34 `void writelongimage ( struct ximage * image, char * filename )`

6.14.2.35 `void writerawimage ( struct ximage * image, char * filename )`

6.14.2.36 `void writergbascimage ( struct ximage * redimage, struct ximage * greenimage, struct ximage * blueimage, char * filename )`

6.14.2.37 `void writergbimage ( struct ximage * redimage, struct ximage * greenimage, struct ximage * blueimage, char * filename )`

6.14.2.38 `void writese ( struct ximage * image, char * filename, index_t x, index_t y, index_t z )`

## 6.15 /home/costa/Data/Code/C/apps/imported/pgm2itkvol/mcimage.h File Reference

This file holds the basic image allocation functions.

### Macros

- `#define __pink__inline`
- `#define HUGE_IMAGE_SIZE INT32_MAX`

### Typedefs

- `typedef unsigned char u_int8_t`
- `typedef unsigned int u_int32_t`
- `typedef unsigned char uint8_t`
- `typedef int int32_t`
- `typedef unsigned int uint32_t`
- `typedef int32_t index_t`

## Functions

- struct `xvimage` \* `allocimage` (char \*name, `index_t` rs, `index_t` cs, `index_t` ds, `int32_t` t)  
*Allocates an image object with the given size and type.*
- struct `xvimage` \* `allocmultimage` (char \*name, `index_t` rs, `index_t` cs, `index_t` ds, `index_t` ts, `index_t` nb, `int32_t` t)
- void `razimage` (struct `xvimage` \*f)  
*fills the image with zeros description Sets every pixel of the image to binary zero.*
- struct `xvimage` \* `allocheader` (char \*name, `index_t` rs, `index_t` cs, `index_t` d, `int32_t` t)
- `int32_t` `showheader` (char \*name)
- void `freeimage` (struct `xvimage` \*image)  
*Frees an image object.*
- struct `xvimage` \* `copyimage` (struct `xvimage` \*f)
- `int32_t` `copy2image` (struct `xvimage` \*dest, struct `xvimage` \*source)
- `int32_t` `equalimages` (struct `xvimage` \*im1, struct `xvimage` \*im2)
- void `list2image` (struct `xvimage` \*image, double \*P, `index_t` n)
- double \* `image2list` (struct `xvimage` \*image, `index_t` \*n)
- void `writeimage` (struct `xvimage` \*image, char \*filename)  
*Writes an image to disk.*
- void `writese` (struct `xvimage` \*image, char \*filename, `index_t` x, `index_t` y, `index_t` z)
- void `writelongimage` (struct `xvimage` \*image, char \*filename)
- void `writerawimage` (struct `xvimage` \*image, char \*filename)
- void `writeascimage` (struct `xvimage` \*image, char \*filename)
- void `printimage` (struct `xvimage` \*image)
- void `writergbimage` (struct `xvimage` \*redimage, struct `xvimage` \*greenimage, struct `xvimage` \*blueimage, char \*filename)
- void `writergbascimage` (struct `xvimage` \*redimage, struct `xvimage` \*greenimage, struct `xvimage` \*blueimage, char \*filename)
- struct `xvimage` \* `readimage` (const char \*filename)  
*Reads an image from a file.*
- struct `xvimage` \* `readheader` (char \*filename)
- struct `xvimage` \* `readse` (char \*filename, `index_t` \*x, `index_t` \*y, `index_t` \*z)
- struct `xvimage` \* `readlongimage` (char \*filename)
- `int32_t` `readrgbimage` (char \*filename, struct `xvimage` \*\*r, struct `xvimage` \*\*g, struct `xvimage` \*\*b)
- `int32_t` `readbmp` (char \*filename, struct `xvimage` \*\*r, struct `xvimage` \*\*g, struct `xvimage` \*\*b)
- void `writebmp` (struct `xvimage` \*redimage, struct `xvimage` \*greenimage, struct `xvimage` \*blueimage, char \*filename)
- `int32_t` `readrgb` (char \*filename, struct `xvimage` \*\*r, struct `xvimage` \*\*g, struct `xvimage` \*\*b)
- `int32_t` `convertgen` (struct `xvimage` \*\*f1, struct `xvimage` \*\*f2)
- `int32_t` `convertlong` (struct `xvimage` \*\*f1)
- `int32_t` `convertfloat` (struct `xvimage` \*\*f1)
- void `writelist2` (char \*filename, `int32_t` \*x, `int32_t` \*y, `int32_t` npoints)
- void `writelist3` (char \*filename, `int32_t` \*x, `int32_t` \*y, `int32_t` \*z, `int32_t` npoints)

### 6.15.1 Detailed Description

This file holds the basic image allocation functions. Pink

#### Author

Michel Couprie, 2009

## 6.15.2 Macro Definition Documentation

6.15.2.1 `#define __pink__inline`

6.15.2.2 `#define HUGE_IMAGE_SIZE INT32_MAX`

## 6.15.3 Typedef Documentation

6.15.3.1 `typedef int32_t index_t`

6.15.3.2 `typedef int int32_t`

6.15.3.3 `typedef unsigned int u_int32_t`

6.15.3.4 `typedef unsigned char u_int8_t`

6.15.3.5 `typedef unsigned int uint32_t`

6.15.3.6 `typedef unsigned char uint8_t`

## 6.15.4 Function Documentation

6.15.4.1 `struct xvimage* allocheader ( char * name, index_t rs, index_t cs, index_t d, int32_t t )` [read]

6.15.4.2 `struct xvimage* allocimage ( char * name, index_t rs, index_t cs, index_t ds, int32_t t )` [read]

Allocates an image object with the given size and type.

### Parameters

<i>name</i>	Not used
<i>rs</i>	x-size
<i>cs</i>	y-size
<i>ds</i>	z-size
<i>t</i>	t-size

### Returns

The pointer to the image.

6.15.4.3 `struct xvimage* allocmultimage ( char * name, index_t rs, index_t cs, index_t ds, index_t ts, index_t nb, int32_t t )` [read]

6.15.4.4 `int32_t convertfloat ( struct xvimage ** f1 )`

6.15.4.5 `int32_t convertgen ( struct xvimage ** f1, struct xvimage ** f2 )`

6.15.4.6 `int32_t convertlong ( struct xvimage ** f1 )`

6.15.4.7 `int32_t copy2image ( struct xvimage * dest, struct xvimage * source )`

6.15.4.8 `struct xvimage* copyimage ( struct xvimage * f )` [read]

6.15.4.9 `int32_t equalimages ( struct xvimage * im1, struct xvimage * im2 )`

6.15.4.10 void freeimage ( struct ximage \* *image* )

Frees an image object.

#### Parameters

<i>image</i>	The pointer to the image
--------------	--------------------------

6.15.4.11 double\* image2list ( struct ximage \* *image*, index\_t \* *n* )

6.15.4.12 void list2image ( struct ximage \* *image*, double \* *P*, index\_t *n* )

6.15.4.13 void printimage ( struct ximage \* *image* )

6.15.4.14 void razimage ( struct ximage \* *f* )

fills the image with zeros description Sets every pixel of the image to binary zero.

#### Parameters

<i>f</i>	the input image
----------	-----------------

#### Returns

no return value

6.15.4.15 int32\_t readbmp ( char \* *filename*, struct ximage \*\* *r*, struct ximage \*\* *g*, struct ximage \*\* *b* )

6.15.4.16 struct ximage\* readheader ( char \* *filename* ) [read]

6.15.4.17 struct ximage\* readimage ( const char \* *filename* ) [read]

Reads an image from a file.

#### Parameters

<i>filename</i>	The name of the image file.
-----------------	-----------------------------

#### Returns

A Pointer to a newly allocated image.

6.15.4.18 struct ximage\* readlongimage ( char \* *filename* ) [read]

6.15.4.19 int32\_t readrgb ( char \* *filename*, struct ximage \*\* *r*, struct ximage \*\* *g*, struct ximage \*\* *b* )

plus 404 bytes dummy padding to make header 512 bytes padding bytes

red bytes

green bytes

blue bytes

6.15.4.20 int32\_t readrgbimage ( char \* *filename*, struct ximage \*\* *r*, struct ximage \*\* *g*, struct ximage \*\* *b* )

6.15.4.21 `struct xvimage* readse ( char * filename, index_t * x, index_t * y, index_t * z ) [read]`

6.15.4.22 `int32_t showheader ( char * name )`

6.15.4.23 `void writeascimage ( struct xvimage * image, char * filename )`

6.15.4.24 `void writebmp ( struct xvimage * redimage, struct xvimage * greenimage, struct xvimage * blueimage, char * filename )`

6.15.4.25 `void writeimage ( struct xvimage * image, char * filename )`

Writes an image to disk.

#### Parameters

<i>image</i>	The pointer to the image
<i>filename</i>	The file to write the image at.

6.15.4.26 `void writelist2 ( char * filename, int32_t * x, int32_t * y, int32_t npoints )`

6.15.4.27 `void writelist3 ( char * filename, int32_t * x, int32_t * y, int32_t * z, int32_t npoints )`

6.15.4.28 `void writelongimage ( struct xvimage * image, char * filename )`

6.15.4.29 `void writerawimage ( struct xvimage * image, char * filename )`

6.15.4.30 `void writergbascimage ( struct xvimage * redimage, struct xvimage * greenimage, struct xvimage * blueimage, char * filename )`

6.15.4.31 `void writergbimage ( struct xvimage * redimage, struct xvimage * greenimage, struct xvimage * blueimage, char * filename )`

6.15.4.32 `void writese ( struct xvimage * image, char * filename, index_t x, index_t y, index_t z )`

## 6.16 /home/costa/Data/Code/C/apps/imported/pgm2itkvol/mcutil.h File Reference

### Macros

- `#define mcabs(X) ((X)>=0?(X):- (X))`
- `#define mcmmax(X, Y) ((X)>=(Y)?(X):(Y))`
- `#define mcmin(X, Y) ((X)<=(Y)?(X):(Y))`
- `#define mcodd(X) ((X)&1)`
- `#define mceven(X) (((X)&1)==0)`
- `#define arrondi(z) (((z)-(double)((int32_t)(z)))<=0.5?((int32_t)(z)):((int32_t)(z+1)))`
- `#define signe(z) (((z)>0.0)?1.0:-1.0)`
- `#define mcsqr(x) ((x)*(x))`
- `#define M_E 2.7182818284590452354 /* e */`
- `#define M_LOG2E 1.4426950408889634074 /* log_2 e */`
- `#define M_LOG10E 0.43429448190325182765 /* log_10 e */`
- `#define M_LN2 0.69314718055994530942 /* log_e 2 */`
- `#define M_LN10 2.30258509299404568402 /* log_e 10 */`
- `#define M_PI 3.14159265358979323846 /* pi */`
- `#define M_PI_2 1.57079632679489661923 /* pi/2 */`
- `#define M_PI_4 0.78539816339744830962 /* pi/4 */`

- `#define M_1_PI 0.31830988618379067154 /* 1/pi */`
- `#define M_2_PI 0.63661977236758134308 /* 2/pi */`
- `#define M_2_SQRTPI 1.12837916709551257390 /* 2/sqrt(pi) */`
- `#define M_SQRT2 1.41421356237309504880 /* sqrt(2) */`
- `#define M_SQRT1_2 0.70710678118654752440 /* 1/sqrt(2) */`

## 6.16.1 Macro Definition Documentation

6.16.1.1 `#define arrondi( z ) (((z)-(double)((int32_t)(z)))<=0.5?((int32_t)(z)):((int32_t)(z+1)))`

6.16.1.2 `#define M_1_PI 0.31830988618379067154 /* 1/pi */`

6.16.1.3 `#define M_2_PI 0.63661977236758134308 /* 2/pi */`

6.16.1.4 `#define M_2_SQRTPI 1.12837916709551257390 /* 2/sqrt(pi) */`

6.16.1.5 `#define M_E 2.7182818284590452354 /* e */`

6.16.1.6 `#define M_LN10 2.30258509299404568402 /* log_e 10 */`

6.16.1.7 `#define M_LN2 0.69314718055994530942 /* log_e 2 */`

6.16.1.8 `#define M_LOG10E 0.43429448190325182765 /* log_10 e */`

6.16.1.9 `#define M_LOG2E 1.4426950408889634074 /* log_2 e */`

6.16.1.10 `#define M_PI 3.14159265358979323846 /* pi */`

6.16.1.11 `#define M_PI_2 1.57079632679489661923 /* pi/2 */`

6.16.1.12 `#define M_PI_4 0.78539816339744830962 /* pi/4 */`

6.16.1.13 `#define M_SQRT1_2 0.70710678118654752440 /* 1/sqrt(2) */`

6.16.1.14 `#define M_SQRT2 1.41421356237309504880 /* sqrt(2) */`

6.16.1.15 `#define mcabs( X ) ((X)>=0?(X):- (X))`

6.16.1.16 `#define mceven( X ) (((X)&1)==0)`

6.16.1.17 `#define mcmax( X, Y ) ((X)>=(Y)?(X):(Y))`

6.16.1.18 `#define mcmin( X, Y ) ((X)<=(Y)?(X):(Y))`

6.16.1.19 `#define mcodd( X ) ((X)&1)`

6.16.1.20 `#define mcsqr( x ) ((x)*(x))`

6.16.1.21 `#define signe( z ) (((z)>0.0)?1.0:-1.0)`

## 6.17 /home/costa/Data/Code/C/apps/imported/pgm2itkvol/pgm2itkvol.cxx File Reference

```
#include <stdio.h>
#include <stdint.h>
#include <sys/types.h>
#include <stdlib.h>
#include <mcimage.h>
#include <mccodimage.h>
#include <itkImage.h>
#include <itkImageRegionIterator.h>
#include <itkImageFileWriter.h>
```

### Macros

- `#define VERBOSE`
- `#define UINTDATA unsigned int *`

### Functions

- `int main (int argc, char **argv)`

#### 6.17.1 Macro Definition Documentation

6.17.1.1 `#define UINTDATA unsigned int *`

6.17.1.2 `#define VERBOSE`

#### 6.17.2 Function Documentation

6.17.2.1 `int main ( int argc, char ** argv )`

## 6.18 /home/costa/Data/Code/C/apps/LabelBiventricularMesh.cpp File Reference

Generate labels for Rafa's biventricular mesh.

```
#include <vtkPolyData.h>
#include <vtkDataSet.h>
#include <vtkAppendPolyData.h>
#include <vtkSmartPointer.h>
#include "vtkTransform.h"
#include "vtkTransformPolyDataFilter.h"
#include "vtkPolyDataNormals.h"
#include "vtkPolyDataConnectivityFilter.h"
#include "vtkShortArray.h"
#include "vtkCellData.h"
#include "vtkCellLocator.h"
#include "vtkCell.h"
#include "vtkPointData.h"
#include "CommonTools.h"
#include "vnl/vnl_vector.h"
#include <stdlib.h>
#include <stdio.h>
#include <iostream>
```

## Functions

- void [SetScalars](#) (vtkPolyData \*mesh, int value, const char \*array)  
*add scalar array to the mesh. Don't remember why it is not in common tools*
- int [main](#) (int argc, char \*\*argv)

### 6.18.1 Detailed Description

Generate labels for Rafa's biventricular mesh.

### 6.18.2 Function Documentation

6.18.2.1 int main ( int argc, char \*\* argv )

6.18.2.2 void SetScalars ( vtkPolyData \* mesh, int value, const char \* array )

add scalar array to the mesh. Don't remember why it is not in common tools

## 6.19 /home/costa/Data/Code/C/apps/MakeBiventricularMesh.cpp File Reference

Make biventricular mesh for Rafa's model.

```
#include <vtkPolyData.h>
#include <vtkPolyDataToImageStencil.h>
#include <vtkImageStencil.h>
#include <vtkImageData.h>
#include <vtkDataSet.h>
#include <vtkDataSetReader.h>
#include <vtkDataSetWriter.h>
#include <vtkAppendPolyData.h>
#include <vtkSmartPointer.h>
#include "vtkTransform.h"
#include "vtkTransformPolyDataFilter.h"
#include "vtkPolyDataNormals.h"
#include "vtkImageWeightedSum.h"
#include "vtkImageOpenClose3D.h"
#include "vtkImageMarchingCubes.h"
#include "vtkImageContinuousErode3D.h"
#include "vtkImageGaussianSmooth.h"
#include "vtkSmoothPolyDataFilter.h"
#include "CommonTools.h"
#include <stdlib.h>
#include <stdio.h>
#include <iostream>
```

## Functions

- vtkImageData \* [CreateEmptyImage](#) (double \*bounds, double \*spacing, double padding, float value)  
*creates an empty image*
- vtkImageData \* [CreateMask](#) (vtkImageData \*image, vtkPolyData \*shape, float value)  
*creates a mask*
- vtkPolyData \* [DecimateMesh](#) (vtkPolyData \*mesh, int nFaces)



*decimates mesh*

- int `main` (int argc, char \*\*argv)

### 6.19.1 Detailed Description

Make biventricular mesh for Rafa's model.

### 6.19.2 Function Documentation

6.19.2.1 `vtkImageData * CreateEmptyImage ( double * bounds, double * spacing, double padding, float value )`

creates an empty image

6.19.2.2 `vtkImageData * CreateMask ( vtkImageData * image, vtkPolyData * shape, float value )`

creates a mask

6.19.2.3 `vtkPolyData * DecimateMesh ( vtkPolyData * mesh, int nFaces )`

decimates mesh

6.19.2.4 `int main ( int argc, char ** argv )`

## 6.20 /home/costa/Data/Code/C/apps/MeshHeart.cpp File Reference

Something to do with biventricular model generation.

```
#include <vtkPolyData.h>
#include <vtkPolyDataToImageStencil.h>
#include <vtkImageStencil.h>
#include <vtkImageData.h>
#include <vtkDataSet.h>
#include <vtkDataSetReader.h>
#include <vtkDataSetWriter.h>
#include <vtkCellArray.h>
#include <vtkSmartPointer.h>
#include "vtkTransform.h"
#include "vtkTransformPolyDataFilter.h"
#include "CommonTools.h"
#include <vtkDelaunay3D.h>
#include <vtkType.h>
#include <vtkUnstructuredGrid.h>
#include <vtkPointData.h>
#include <vtkShortArray.h>
#include <vtkThreshold.h>
#include <vtkDataSetSurfaceFilter.h>
#include <vtkCellData.h>
#include <stdlib.h>
#include <stdio.h>
#include <iostream>
```

## Functions

- `vtkPolyData * ExtractSurface (vtkUnstructuredGrid *volmesh, int id)`
- `int main (int argc, char **argv)`

### 6.20.1 Detailed Description

Something to do with biventricular model generation.

### 6.20.2 Function Documentation

6.20.2.1 `vtkPolyData * ExtractSurface ( vtkUnstructuredGrid * volmesh, int id )`

6.20.2.2 `int main ( int argc, char ** argv )`

## 6.21 /home/costa/Data/Code/C/apps/MeshSegmentationLaplace.cpp File Reference

Mesh segmentation using distance to skeleton along the gradiwent of the solution of the laplacian equation.

```
#include "CommonTools.h"
#include <vtkSmartPointer.h>
#include <vtkPolyData.h>
#include <vtkPointData.h>
#include <vtkFloatArray.h>
#include <vtkType.h>
#include <vtkImageGradient.h>
#include <vtkAssignAttribute.h>
#include <vtkStreamTracer.h>
#include <vtkImageContinuousDilate3D.h>
#include <iostream>
```

## Functions

- `int main (int argc, char *argv[])`

### 6.21.1 Detailed Description

Mesh segmentation using distance to skeleton along the gradiwent of the solution of the laplacian equation.

### 6.21.2 Function Documentation

6.21.2.1 `int main ( int argc, char * argv[] )`

## 6.22 /home/costa/Data/Code/C/apps/MRIRemesh.cpp File Reference

From shortaxis contours in MRI + reference point creates a smoother mesh using splines longitudinally.

```

#include <vtkPolyData.h>
#include <vtkCellArray.h>
#include <vtkSmartPointer.h>
#include "CommonTools.h"
#include <vtkPlane.h>
#include <vtkType.h>
#include <vtkPointData.h>
#include <vtkShortArray.h>
#include <vtkCellData.h>
#include <vtkCutter.h>
#include <vtkAppendPolyData.h>
#include <stdlib.h>
#include <stdio.h>
#include <iostream>
#include <math.h>
#include <vector>
#include <vnl/vnl_vector.h>
#include <vnl/vnl_matrix.h>
#include <vnl/vnl_cross.h>

```

## Classes

- struct [sorting\\_struct](#)

## Macros

- #define [CONTOUR\\_ENDO\\_APICAL](#) 0
- #define [CONTOUR\\_ENDO\\_BASAL](#) 2
- #define [CONTOUR\\_ENDO](#) 1
- #define [CONTOUR\\_EPI\\_APICAL](#) 5
- #define [CONTOUR\\_EPI\\_BASAL](#) 7
- #define [CONTOUR\\_EPI](#) 6
- #define [REF\\_POINT](#) 10

## Functions

- int [struct\\_cmp\\_by\\_value](#) (const void \*a, const void \*b)
- void [ComputeCentroid](#) (vtkPolyData \*shape, double \*centroid)  
*compute centroid of polydata*
- vnl\_vector< double > [ArbitraryRotate](#) (vnl\_vector< double > p, double theta, vnl\_vector< double > p1, vnl\_vector< double > p2)  
*Rotate a point p by angle theta around an arbitrary line segment p1-p2.*
- vtkPolyData \* [OrderPoints](#) (vtkPolyData \*pts, int apical\_id, int basal\_id)  
*Something about point order for this specific application.*
- int [main](#) (int argc, char \*\*argv)

### 6.22.1 Detailed Description

From shortaxis contours in MRI + reference point creates a smoother mesh using splines longitudinally.

## 6.22.2 Macro Definition Documentation

6.22.2.1 `#define CONTOUR_ENDO 1`

6.22.2.2 `#define CONTOUR_ENDO_APICAL 0`

6.22.2.3 `#define CONTOUR_ENDO_BASAL 2`

6.22.2.4 `#define CONTOUR_EPI 6`

6.22.2.5 `#define CONTOUR_EPI_APICAL 5`

6.22.2.6 `#define CONTOUR_EPI_BASAL 7`

6.22.2.7 `#define REF_POINT 10`

## 6.22.3 Function Documentation

6.22.3.1 `vnل_vector< double > ArbitraryRotate ( vnل_vector< double > p, double theta, vnل_vector< double > p1, vnل_vector< double > p2 )`

Rotate a point p by angle theta around an arbitrary line segment p1-p2.

Return the rotated point. Positive angles are anticlockwise looking down the axis towards the origin. Assume right hand coordinate system.

6.22.3.2 `void ComputeCentroid ( vtkPolyData * shape, double * centroid )`

compute centroid of polydata

6.22.3.3 `int main ( int argc, char ** argv )`

6.22.3.4 `vtkPolyData * OrderPoints ( vtkPolyData * pts, int apical_id, int basal_id )`

Something about point order for this specific application.

6.22.3.5 `int struct_cmp_by_value ( const void * a, const void * b )`

## 6.23 /home/costa/Data/Code/C/apps/PassScalars.cpp File Reference

copies scalars from one polydata to another

```
#include "vtkPolyDataReader.h"
#include "vtkMath.h"
#include "vtkPointData.h"
#include "vtkPointLocator.h"
#include "vtkPolyData.h"
#include "vtkPolyDataWriter.h"
#include "vtkShortArray.h"
#include "vtkType.h"
#include "vtkCellData.h"
#include "vtkCellLocator.h"
#include "vtkSmartPointer.h"
#include "vtkCell.h"
#include "CommonTools.h"
```

## Functions

- int [main](#) (int argc, char \*argv[])

### 6.23.1 Detailed Description

copies scalars from one polydata to another

### 6.23.2 Function Documentation

6.23.2.1 int main ( int *argc*, char \* *argv*[] )

## 6.24 /home/costa/Data/Code/C/apps/PassScalarsInterp.cpp File Reference

Copies scalars from one mesh to another. When the source is sparse, for every target point it finds a corresponding cell and interpolates the point scalars.

```
#include "vtkPolyDataReader.h"
#include "vtkMath.h"
#include "vtkPointData.h"
#include "vtkPointLocator.h"
#include "vtkPolyData.h"
#include "vtkPolyDataWriter.h"
#include "vtkShortArray.h"
#include "vtkType.h"
#include "vtkCellData.h"
#include "vtkCellLocator.h"
#include "vtkSmartPointer.h"
#include "vtkCell.h"
#include "CommonTools.h"
#include "vtkFloatArray.h"
```

## Functions

- void [PassScalarsFloat](#) (int argc, char \*argv[])
- int [main](#) (int argc, char \*argv[])

### 6.24.1 Detailed Description

Copies scalars from one mesh to another. When the source is sparse, for every target point it finds a corresponding cell and interpolates the point scalars.

### 6.24.2 Function Documentation

6.24.2.1 int main ( int *argc*, char \* *argv*[] )

6.24.2.2 void PassScalarsFloat ( int *argc*, char \* *argv*[] )

## 6.25 /home/costa/Data/Code/C/apps/PassScalarsReverse.cpp File Reference

Same as PassScalars, except that the search is done for every point/cell of target, not source!

```
#include "vtkPolyDataReader.h"
#include "vtkMath.h"
#include "vtkPointData.h"
#include "vtkPointLocator.h"
#include "vtkPolyData.h"
#include "vtkPolyDataWriter.h"
#include "vtkShortArray.h"
#include "vtkType.h"
#include "vtkCellData.h"
#include "vtkCellLocator.h"
#include "vtkSmartPointer.h"
#include "vtkCell.h"
#include "CommonTools.h"
#include "vtkFloatArray.h"
```

### Functions

- void [PassScalarsFloat](#) (int argc, char \*argv[])
- void [PassScalarsShort](#) (int argc, char \*argv[])
- int [main](#) (int argc, char \*argv[])

#### 6.25.1 Detailed Description

Same as PassScalars, except that the search is done for every point/cell of target, not source!

#### 6.25.2 Function Documentation

6.25.2.1 int main ( int *argc*, char \* *argv*[] )

6.25.2.2 void PassScalarsFloat ( int *argc*, char \* *argv*[] )

6.25.2.3 void PassScalarsShort ( int *argc*, char \* *argv*[] )

## 6.26 /home/costa/Data/Code/C/apps/ResampleImage.cpp File Reference

Resample image, smooth, reconstruct shape.

```

#include <vtkImageData.h>
#include <vtkSmartPointer.h>
#include <vtkImageResample.h>
#include <vtkImageMarchingCubes.h>
#include <vtkImageGaussianSmooth.h>
#include <vtkCleanPolyData.h>
#include <vtkDataSetSurfaceFilter.h>
#include <vtkPolyDataNormals.h>
#include <vtkImageCast.h>
#include <vtkImageConstantPad.h>
#include <vtkImageChangeInformation.h>
#include <vtkShortArray.h>
#include <vtkCellData.h>
#include "CommonTools.h"
#include <stdlib.h>
#include <stdio.h>
#include <iostream>

```

## Functions

- int [main](#) (int argc, char \*\*argv)

### 6.26.1 Detailed Description

Resample image, smooth, reconstruct shape.

### 6.26.2 Function Documentation

6.26.2.1 int [main](#) ( int *argc*, char \*\* *argv* )

## 6.27 /home/costa/Data/Code/C/apps/SetScalars.cpp File Reference

adds scalar array ro polydata and sets its value to a constant

```

#include <vtkPointData.h>
#include <vtkShortArray.h>
#include <vtkPolyData.h>
#include <vtkPolyDataWriter.h>
#include <vtkSTLWriter.h>
#include <vtkPolyDataReader.h>
#include <vtkSTLReader.h>
#include "vtkCellData.h"
#include "CommonTools.h"
#include "vtkSmartPointer.h"
#include <vtkDataArray.h>
#include <vtkFloatArray.h>

```

## Functions

- template<typename vtk\_array\_type >  
void [AddArray](#) (vtkPolyData \*shapePt, bool use\_points, double value, const char \*property\_name, vtk\_array\_type \*fakeparam)
- int [main](#) (int argc, char \*argv[])

### 6.27.1 Detailed Description

adds scalar array ro polydata and sets its value to a constant

### 6.27.2 Function Documentation

6.27.2.1 `template<typename vtk_array_type > void AddArray ( vtkPolyData * shapePt, bool use_points, double value, const char * property_name, vtk_array_type * fakeparam )`

6.27.2.2 `int main ( int argc, char * argv[] )`

## 6.28 /home/costa/Data/Code/C/apps/SmoothMeshTrhoughImage.cpp File Reference

Smooth mesh using image mask.

```
#include "vtkPolyData.h"
#include "vtkCleanPolyData.h"
#include "CommonTools.h"
#include <vtkPolyDataToImageStencil.h>
#include <vtkImageStencil.h>
#include <vtkImageMarchingCubes.h>
#include <vtkImageGaussianSmooth.h>
#include <vtkDataSetWriter.h>
#include <vtkSmartPointer.h>
#include <vtkPolyDataNormals.h>
#include <iostream>
#include <fstream>
#include <stdio.h>
#include "vtkDataSetSurfaceFilter.h"
```

### Functions

- int [main](#) (int argc, char \*argv[])

### 6.28.1 Detailed Description

Smooth mesh using image mask.

### 6.28.2 Function Documentation

6.28.2.1 `int main ( int argc, char * argv[] )`

## 6.29 /home/costa/Data/Code/C/apps/TransformPhilipsHeart.cpp File Reference

Transforms Philips mesh to suit EM simulations. Don't remember WTF is that.

```
#include "CommonTools.h"
#include <vtkSmartPointer.h>
#include <vtkPolyData.h>
#include <vtkBooleanOperationPolyDataFilter.h>
#include <vtkCleanPolyData.h>
```



## Functions

- int [main](#) (int argc, char \*argv[])

### 6.29.1 Detailed Description

Transforms Philips mesh to suit EM simulations. Don't remember WTF is that.

### 6.29.2 Function Documentation

6.29.2.1 int main ( int *argc*, char \* *argv*[] )

## 6.30 /home/costa/Data/Code/C/apps/VTKConvert.cpp File Reference

Convert vtk polydata between formats.

```
#include "CommonTools.h"  
#include <vtkSmartPointer.h>  
#include <vtkPolyData.h>
```

## Functions

- int [main](#) (int argc, char \*argv[])

### 6.30.1 Detailed Description

Convert vtk polydata between formats.

### 6.30.2 Function Documentation

6.30.2.1 int main ( int *argc*, char \* *argv*[] )

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