1. Introducing Physical Investment

(a)
$$r_t dt = q_{t+\Delta t} k_{t+\Delta t}^i - q_t k_t^i + \left[a(k_t^i) k_t^i - i_t^i k_t^i \right] \Delta t$$

$$dr_{t}^{\kappa}(\iota_{t}) = \frac{a^{i}(\ell_{t}^{i}) - \iota_{t}^{i}}{2\iota} + \frac{d^{i}(\ell_{t}^{i})}{2\iota_{t}^{i}}$$
Dividend

wield

$$\pi_{t} dt = d(9_{t} K_{t}^{i}) + \left[a^{i}(R_{t}^{i})K_{t}^{i} - l_{t}^{i}K_{t}^{i}\right] dt$$

$$\frac{\pi_{t}}{q_{t}k_{t}^{i}} dt = \frac{d(9_{t}K_{t}^{i})}{q_{t}k_{t}^{i}} + \frac{a^{i}(R_{t}^{i})K_{t}^{i} - l_{t}^{i}K_{t}^{i}}{q_{t}K_{t}^{i}} dt$$

$$= \frac{d(a_{t}K_{t}^{i})}{q_{t}K_{t}^{i}} + \left[\frac{a^{i}(\Gamma_{t}^{i})K_{t}^{i}}{q_{t}K_{t}^{i}} - \frac{l_{t}^{i}K_{t}^{i}}{q_{t}K_{t}^{i}}\right] dt$$

$$\frac{d}{q_{t}}(q_{t}K_{t}^{i}) + \left[\frac{a^{i}(\Gamma_{t}^{i})K_{t}^{i}}{q_{t}K_{t}^{i}} - \frac{l_{t}^{i}K_{t}^{i}}{q_{t}K_{t}^{i}}\right] dt$$

So,
$$\frac{\pi_{t}}{q_{t}k_{t}^{i}} = \frac{\frac{d}{dt}(q_{t}k_{t}^{i})}{q_{t}k_{t}^{i}} + \left[\frac{a(k_{t}^{i})}{q_{t}} - \frac{k_{t}^{i}}{q_{t}}\right]$$

So, $\frac{dv_{t}^{k}(l_{t})}{q_{t}k_{t}} = \frac{d(q_{t}k_{t})}{q_{t}k_{t}} + \frac{(a(n_{t}^{i}) - k_{t}^{i})}{q_{t}}dt$

Now,
$$\frac{dK_t}{K_l} = \left[\frac{\pi}{2} (\frac{1}{4}) - \delta \right] dt + \sigma dZ$$

(d)

Postwate
$$\frac{dq_t}{q_t} = M_t^a dt + \Gamma_t^q dZ$$
(By Ito's \Rightarrow

$$d(q, k_t) = \Gamma \delta(L) - \delta + M^2$$

So, By Ito's =
$$\frac{d(q_{t}k_{t})}{q_{t}k_{t}} = \left[\frac{2(q_{t}) - \delta + M_{t}^{2} + \sigma\sigma_{t}^{2}}{dt} + \left[\sigma + \sigma_{t}^{2}\right]dZ\right]$$
So,
$$dr^{k}(q_{t}) = \left[\frac{d(q_{t}k_{t}) - C_{t}^{i}}{q_{t}} + \frac{2}{2}(c_{t}^{i}) - \delta + M_{t}^{2} + \sigma\sigma_{t}^{2}\right]dt + (\sigma + \sigma_{t}^{2})dZ$$

2. Basak-Croco

1>(a) Goods market cleaning implies > aekt-GKt = eengtkt + ph(1- 1/4) 9/4/4

S.,
$$q(\eta) = \frac{1+\phi a^e}{1+\phi \hat{p}(\eta)}$$
 $(\eta) = \frac{\hat{a}-\hat{p}(\eta)}{1+\phi \hat{p}(\eta)}$

$$u_{\gamma} = \frac{\alpha - \hat{\rho}(\eta)}{1 + \hat{\phi}\hat{\rho}(\eta)}$$

Now,
$$q(\eta) = \frac{1+a^{e}\phi}{1+\phi\hat{\rho}(\eta)}$$

So, $q' = \frac{1+a^{e}\phi}{(1+\phi\hat{\rho}(\eta))^{2}}\phi(\rho^{e}-\rho^{h})$

and $q'' = 2\frac{(1+a^{e}\phi)(\phi(\rho^{e}-\rho^{h}))^{2}}{(1+\phi\hat{\rho}(\eta))^{2}}$

so, By Ito's
$$r^{2}(\eta) = -\frac{\phi(\rho^{e}-\rho^{h})}{(1+\phi\hat{\rho}(\eta))} \cdot \sigma^{n}(\eta)\eta$$

$$\partial_t^{K,e} = \frac{1}{h_t}$$

 $\mathcal{O}_{t}^{K,e} = \frac{1}{h_{t}}$ By Ito's using $N_{t} = N_{t}^{e}/N_{t} = N_{t}^{e}/q_{t}K_{t}$,

By Ito's wring
$$t_t = \frac{4v}{N_t} - \frac{4v}{N_t}$$
 $\frac{e^{-t}N_t}{q_t} - \frac{4v}{q_t} - \frac{e^{-t}}{q_t} - \frac{e^{-t}}$

$$\zeta_0, \quad \zeta_t^{h} = -\left[1 - \frac{1}{h}\right] \left(\sigma + \zeta_t^{h}\right)$$

-0

$$= \frac{1 - l_{\perp}}{\eta_{\perp}} (\tau + \sigma_{\perp}^{2}) \qquad -2$$
Cardinine () & (1-n) (1+4 \hat{\rho}(\eta))

 $\sigma_{t}^{q} = -(1-\eta) \cdot \frac{\phi(\rho^{e}-\rho^{h})}{1+\phi\rho^{e}}$

(C) So,
$$M_{t}^{n} = -\rho^{e_{+}}X_{t} + \theta_{t}^{x_{e}} + g_{t}^{e_{t}} (\sigma + \sigma_{t}^{2}) - X_{t} + \frac{a^{e_{-}}Y_{t}}{2t} - g_{t}^{e_{t}} (\sigma + \sigma_{t}^{2})^{2} (1 - \theta_{t}^{x_{e}})^{2} (1 - \theta_{t}^{x_{e}})^{2} (1 - \theta_{t}^{x_{e}})^{2} = -\rho^{e_{+}} + \hat{\rho} - (1 - \theta_{t}^{x_{e}}) G_{t} (\sigma + \sigma_{t}^{2}) + (1 - \theta_{t}^{x_{e}}) (\sigma + \sigma_{t}^{2})^{2} = -\rho^{e_{+}} + \hat{\rho} + (1 - \theta_{t}^{x_{e}}) (\sigma + \sigma_{t}^{2}) (G_{t} + \sigma_{t}^{2})^{2} = -\rho^{e_{+}} + \hat{\rho} + (1 - \theta_{t}^{x_{e}})^{2} (\sigma + \sigma_{t}^{2})^{2} (\sigma + \sigma_{t}^{2})^{2}$$

$$= -\rho^{e_{+}} + \hat{\rho} + (1 - \theta_{t}^{x_{e}})^{2} (\sigma + \sigma_{t}^{2})^{2} (\sigma + \sigma_{t}^{2})^{2$$

2. MATLAB Plof.

3.
$$\sigma + \sigma^{2} = \frac{1 + \phi \hat{p}(y)}{1 + \phi \hat{p}^{e}} \sigma$$

5., $\frac{\sigma + \sigma^{2}}{\sigma} = \frac{1 + \phi \hat{p}}{1 + \phi \hat{p}^{e}} \Rightarrow \hat{p} < \hat{p}^{e}$

5., if $\phi > 0$

$$\Rightarrow \frac{\sigma + \sigma^{2}}{\sigma} < | \qquad \Rightarrow \frac{1 + \phi \hat{p}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{1 + \phi \hat{p}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{1 + \phi \hat{p}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{\sigma} < | \qquad \Rightarrow \frac{1 + \phi \hat{p}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow \frac{\sigma + \sigma^{2}}{1 + \phi \hat{p}^{e}} < | \qquad \Rightarrow$$

- 4. When 1 -> 0 experts become good, in that situation drift becomes positive. Experts more productive which gives them advantage, thought more impatient. So, 1 pulses back up.
 - e when $\eta > 1$ experts dominate, but howeholds, patience make them save more, η pulse Θ back down.

· productivity advantage of Experts balances patience advantage of households, creating a stable interior steady state.