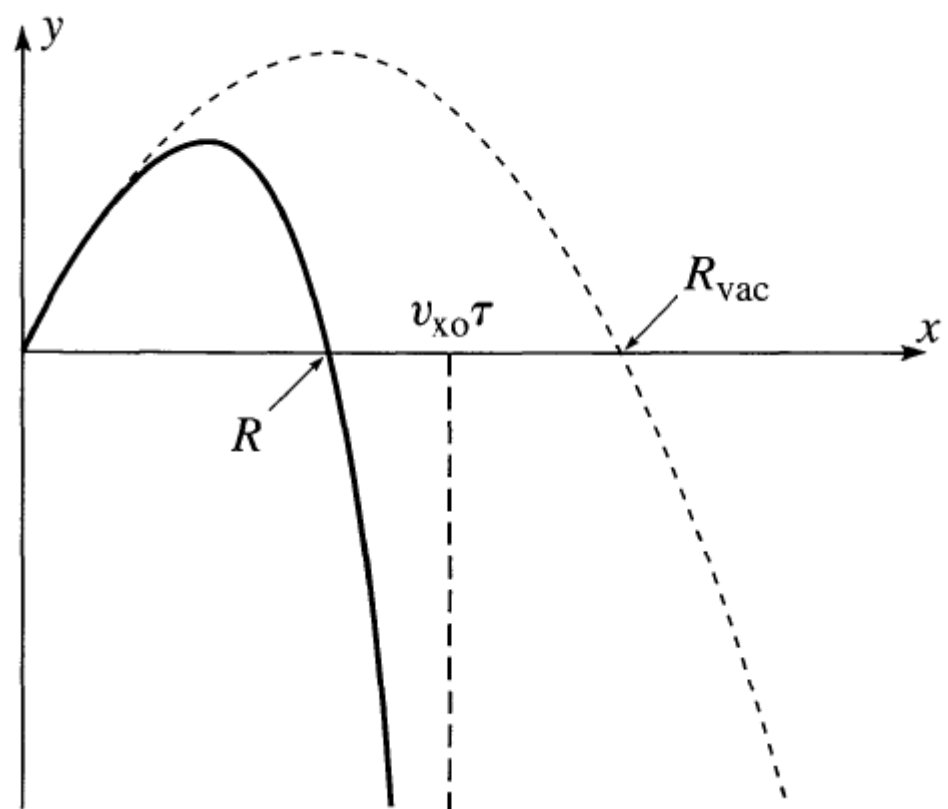


Physics I

Lecture 5



Trajectory and range in a linear medium

slight change \rightarrow will take upward y direction as +ve
 \hookrightarrow reverse the sign of v_{ter}

$$x(t) = v_{x_0} \tau (1 - e^{-t/\tau}) \quad \text{--- ①}$$

$$\tau = \frac{m}{b}$$

$$y(t) = (v_{y_0} + v_{ter}) \tau (1 - e^{-t/\tau}) - v_{ter} t \quad \text{--- ②}$$

eliminate t

$$\frac{x}{v_{x_0} \tau} = 1 - e^{-t/\tau}$$

$$t = -\tau \ln \left(1 - \frac{x}{v_{x_0} \tau} \right) \quad \text{--- ③}$$

Plug in (3) into (2)

$$y = \frac{(v_{y0} + v_{ter})x}{v_{x0}} + v_{ter}\tau \ln\left(1 - \frac{x}{v_{x0}\tau}\right) \rightarrow (4)$$

limit of small air resistance $\left\{\frac{1}{\tau} = \frac{b}{m}\right\}$ expand ln to lowest order
 $\tau = m/b$

$$y \approx -\frac{1}{2}g \frac{x^2}{v_{x0}^2}$$

vacuum case.

$v_{ter}, \tau \rightarrow \infty$, vacuum case.

$x \rightarrow v_{x0}\tau$, $y \rightarrow -\infty$ vertical asymptote

Horizontal Range

Recall $\boxed{R_{vac} = \frac{2 v_{x0} v_{y0}}{g}}$ case $b = 0$

Range: x for $y = 0$

$$y = \frac{(v_{y0} + v_{ter})x}{v_{x0}} + v_{ter}\tau \ln\left(1 - \frac{x}{v_{x0}\tau}\right)$$

$$0 = \frac{(v_{y0} + v_{ter})R}{v_{x0}} + v_{ter}\tau \ln\left(1 - \frac{R}{v_{x0}\tau}\right)$$

small for b small

$$\ln(1-\epsilon) = -\left(\epsilon + \frac{1}{2}\epsilon^2 + \frac{1}{3}\epsilon^3 + \dots\right)$$

large τ

$$\left(\frac{v_{y_0} + v_{ter}}{v_{x_0}}\right) R - v_{ter} \tau \left[\frac{R}{v_{x_0} \tau} + \frac{1}{2} \left(\frac{R}{v_{x_0} \tau} \right)^2 + \frac{1}{3} \left(\frac{R}{v_{x_0} \tau} \right)^3 + \dots \right] = 0$$

one trivial soln. $R=0$

$$\left(\frac{v_{y_0}}{v_{x_0}} - \frac{v_{ter} R}{2 v_{x_0}^2 \tau} - \frac{1}{3} \frac{R^2}{v_{x_0}^3 \tau^2} \right) = 0$$

$$\frac{v_{x0}}{v_{y0}} - \frac{v_{ter}}{2} \frac{R}{v_{x0}^2} \tau - \frac{1}{3} \frac{R^2}{v_{x0}^2} \tau^2 = 0$$

$$R \approx \frac{2v_{x0}v_{y0}}{g} - \frac{2}{3v_{x0}\tau} R^2$$

$$\boxed{\frac{v_{ter}}{\tau} = g}$$

→ small
R at best R_{vac} .

first approx

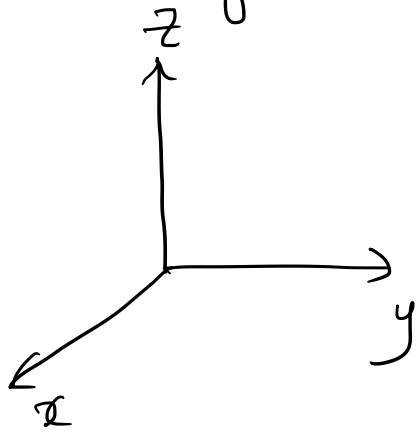
$$R \approx \frac{2v_{x0}v_{y0}}{g}$$

2nd approx

$$R \approx \frac{2v_{x0}v_{y0}}{g} - \frac{2}{3v_{x0}\tau} R_{vac}^2 \approx R_{vac} \left(1 - \frac{4}{3} \frac{v_{y0}}{v_{ter}} \right)$$

Another example of a velocity dependent force .

Charge in a uniform magnetic field .



$$\vec{B} = B_0 \hat{y}$$

$$\vec{F}_{\text{mag}} = q(\vec{v} \times \vec{B})$$

$$\vec{v} = \dot{x} \hat{x} + \dot{y} \hat{y} + \dot{z} \hat{z}$$

$$\vec{a} = \ddot{x} \hat{x} + \ddot{y} \hat{y} + \ddot{z} \hat{z}$$

Eqn. of motion $\vec{F} = m\vec{a}$

$$\left. \begin{aligned} m\ddot{x} &= (\vec{F}_{\text{mag}})_x = -qB_0\dot{z} \\ m\ddot{y} &= 0 \\ m\ddot{z} &= qB_0\dot{x} \end{aligned} \right\}$$

$$y = \dot{y}_0 t + y_0 \quad \text{--- (2)}$$

$$y_0 = y(t=0)$$

$$\dot{y}_0 = \dot{y}(t=0)$$

$$m \ddot{x} = -q B_0 \dot{z} \quad \left. \vphantom{\ddot{x}} \right\} \text{--- (1)}$$

$$m \ddot{z} = q B_0 \dot{x} \quad \left. \vphantom{\ddot{z}} \right\} \text{--- (3)}$$

$$\alpha = \frac{q B_0}{m}$$

$$\left. \begin{aligned} \dot{x} &= -\alpha \dot{z} \\ \dot{z} &= \alpha \dot{x} \end{aligned} \right\}$$

Take derivative

$$\left. \begin{aligned} \ddot{x} &= -\alpha \ddot{z} = -\alpha^2 \dot{x} \\ \ddot{z} &= +\alpha \ddot{x} = -\alpha^2 \dot{z} \end{aligned} \right\}$$

$$\dot{z} = u, \quad \dot{x} = v$$

$$\ddot{u} = -\alpha^2 u, \quad \ddot{v} = -\alpha^2 v$$

$$\ddot{u} + \alpha^2 u = 0$$

$$\ddot{v} + \alpha^2 v = 0$$

$$\rightarrow \dot{z} = u = \tilde{A} \sin \alpha t + \tilde{B} \cos \alpha t$$

Integrate once

$$z = -\frac{\tilde{A}}{\alpha} \cos \alpha t + \frac{\tilde{B}}{\alpha} \sin \alpha t$$

$$z(t) = A' \cos \alpha t + B' \sin \alpha t + z_0$$

Similarly

$$x = A \cos \alpha t + B \sin \alpha t + x_0$$

Are A, B, A', B'
all independent

$$\ddot{x} = -\alpha \dot{z}$$

$$\ddot{z} = \alpha \dot{x}$$

$$\rightarrow -\alpha^2 A \cos \alpha t - \alpha^2 B \sin \alpha t = -\alpha (-\alpha A' \sin \alpha t + \alpha B' \cos \alpha t)$$

valid for all t , $t = 0$, $t = \pi/2\alpha$.

$$-\alpha^2 A = -\alpha^2 B' \quad -\alpha^2 B = \alpha^2 A'$$

$$\boxed{A = B' \quad B = A'}$$

$$(x - x_0) = A \cos \alpha t + B \sin \alpha t$$

$$(y - y_0) = \dot{y}_0 t$$

$$(z - z_0) = -B \cos \alpha t + A \sin \alpha t$$

$$t=0 \quad \dot{z} = \dot{z}_0, \text{ and } x=0.$$

$$B=0, \quad \alpha A = \dot{z}_0$$

$$\left. \begin{aligned} x - x_0 &= \frac{\dot{z}_0}{\alpha} \cos \alpha t \\ (y - y_0) &= \dot{y}_0 t \\ (z - z_0) &= \frac{\dot{z}_0}{\alpha} \sin \alpha t \end{aligned} \right\}$$

what trajectory is this?

$$(x - x_0)^2 + (z - z_0)^2$$

$$= \left(\frac{\dot{z}_0^2 m^2}{q^2 B_0^2} \right)$$

right circular helix.