Physics I

Lecture 20

Recall that a 1-d problem is in principle solvable completely

$$E = \frac{1}{2} \mu \dot{r}^2 + \frac{1}{2} \frac{l^2}{\mu r^2} + U(r)$$

Using above to solve for i

$$\mathring{r} = \frac{dr}{dt} = \pm \sqrt{\frac{2}{\mu^2 r^2}} - \pm \sqrt{\frac{2}{\mu^2 r^2}} - \pm \sqrt{\frac{2}{\mu^2 r^2}}$$

$$\begin{array}{c|c}
l = mr^2 \mathring{0} \\
0 = \int \frac{l}{mr^2} dt \\
\text{substitutes } r(t)
\end{array}$$

$$\begin{array}{c|c}
t = t \\
t = t(r)
\end{array}$$

$$t = t \int \frac{dr}{\sqrt{2 (E-U)} - \frac{l^2}{\mu^2 r^2}}$$

$$t = t(r)$$
() invert to get $r(t)$

Our interest is to find the trajectory
$$r(0)$$

$$d\theta = \frac{d\theta}{dt} \frac{dt}{dr} = \frac{\dot{\theta}}{\dot{r}} dr \qquad \begin{cases} \dot{\theta} = \frac{l}{\mu r^2} \end{cases}$$

 $F(r) \propto r^n$ $(\frac{1}{\sqrt{82}})dr$ n = 1, -2, -3of sin, cos fig.

expressible in terms

$$L = \frac{1}{2} \mu \left(\dot{r}^2 + r^2 \dot{\theta}^2 \right) - U(r)$$

E-Legn.

$$\frac{\partial L}{\partial r} - \frac{d(\partial L)}{dt(\partial \dot{r})} = 0$$

$$\frac{\partial 0}{\partial r} - \frac{d(\partial L)}{dt(\partial \dot{r})} = 0$$

$$\frac{\partial V(\dot{r})}{\partial r} = F(r)$$

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Change variable to u = 1

$$\frac{du}{d\theta} = -\frac{1}{r^2} \frac{dr}{d\theta} = -\frac{1}{r^2} \frac{dr}{dt} \frac{dt}{d\theta} = -\frac{1}{r^2} \frac{\mathring{r}}{\mathring{\theta}} - \frac{2}{r^2}$$

from (1)
$$\dot{\theta} = \frac{l}{Mr^2} \longrightarrow \frac{du}{d\theta} = -\frac{l}{R} \frac{Mr^2 \dot{r}}{l} = -\frac{Mr^2 \dot{r}}{l} =$$

$$\frac{du}{d\theta} = -\frac{\mu}{2} \dot{r} - 3$$

$$\frac{d^2u}{d\theta^2} = -\mu \frac{d\dot{r}}{d\theta} = \frac{dt}{d\theta} \frac{d}{dt} \left(-\mu \dot{r}\right) = -\mu \dot{r}$$

again substitute for d'above

$$\left[\frac{d^2u}{d\theta^2} = -\frac{\mu}{l \cdot l} \frac{\mu r^2 \dot{r}}{r}\right] = -\frac{\mu^2}{l^2} r^2 \dot{r}$$

$$\theta = \frac{2}{y^{2}}$$

$$\theta = \frac{1}{y^{2}}$$

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E-L eqn in
$$r$$

$$\mu(\ddot{r} - r\dot{\theta}^2) = F(r)$$

from (5) we have
$$\dot{r} = -\frac{l^2}{\mu^2} \frac{u^2 d^2 u}{d\theta^2}$$
and $\dot{r} = \frac{l^2}{\mu^2} \frac{u^3}{d\theta^2}$.

Say

Substitute in
$$E-L$$
 legs.
$$-\frac{l^2}{\mu} u^2 \frac{d^2 u}{d\theta^2} - \frac{l^2}{\mu} u^2 = F(\frac{l}{u})$$

$$F(r) = \frac{k}{r^2}$$

$$\int \frac{d^2u}{d\theta^2} + u = -\frac{\mu}{L^2} \frac{1}{u^2} F(\frac{1}{u}) \xrightarrow{\text{path eqn.}}$$

Say
$$F(r) = k/r^{2}$$

$$F(\frac{1}{2}) = ku^{2}$$

$$R.H.S = -\frac{\mu k}{\ell^{2}}$$

$$\frac{d^{2}}{d\theta^{2}}\left(\frac{1}{r}\right) + \frac{1}{r} = -\frac{\mu r^{2}}{L^{2}}F(r)$$

Notice that l=0, eqn. blows up. But should we worry? $mr^2\dot{o}=0$ $\theta=const$, st line through origin

Qualitative analysis of motion

$$E = \frac{1}{2}\mu\dot{r}^2 + \frac{l^2}{2\mu r^2} + U(r)$$

$$\dot{r} = 0 \quad \text{gives turning pts.}$$

$$E = U(x) \quad \text{turning pts.}$$

$$E - U(r) - \frac{l^2}{2\mu r^2} = 0$$

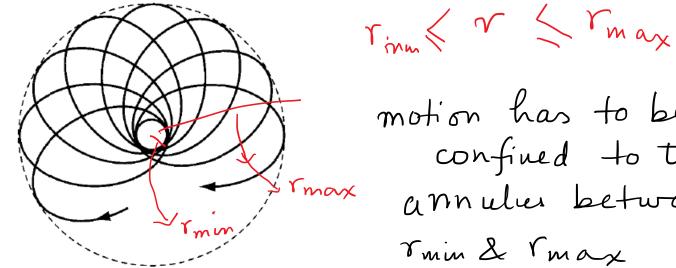
$$\text{Motion is bounded a periodic.}$$

$$\overline{E} - U(r) - \frac{\ell^2}{2\mu r^2} = 0$$

In general possesses two roots Timin, Timax.

rmin < r < rmox

L' Can it be bounded but not periodic?



motion has to be confined to the annulus between rnin & rmax

If the motion is periodic, then osbit is closed If the orbit does not close on itself after finite number of oscillations _s open

Recall O(r) × rn+1 closed, non $f\left(\frac{1}{2}\right)dr$ path can result only & for N = -2 or $+\frac{1}{2}$ $\Delta\theta = 2 \int_{r_{min}} \frac{l/r^2}{\sqrt{2\mu(E-U-l^2/2\mu r^2)}}$ motion is symmetric in time > path is closed if 10 is a rational fraction of $\triangle \Theta = 2 \pi \underline{m}$

, m, n are integers. -) after n periods r' made m complete revolutions.