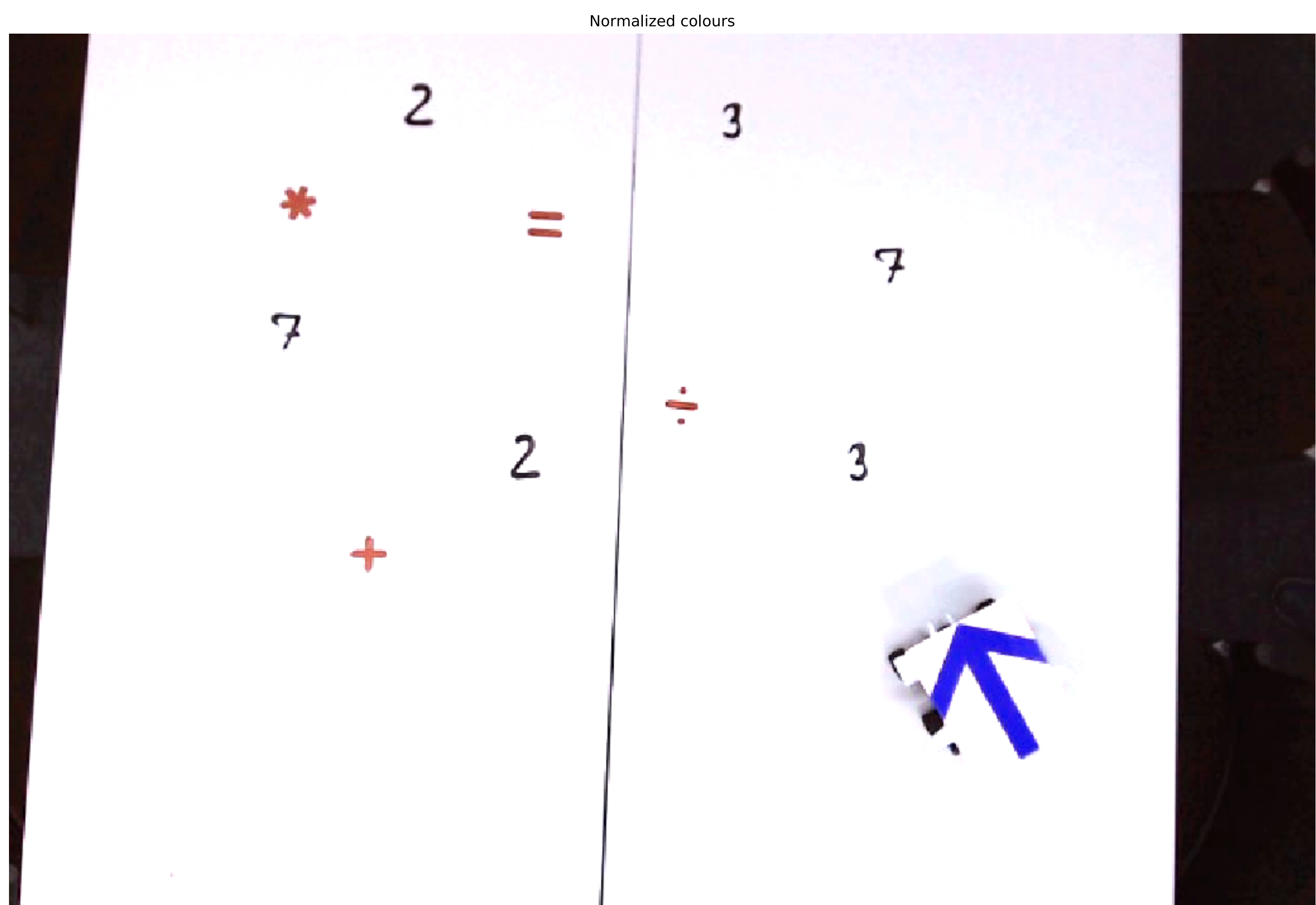


Blue arrow with center of gravity



Black (and red) threshold

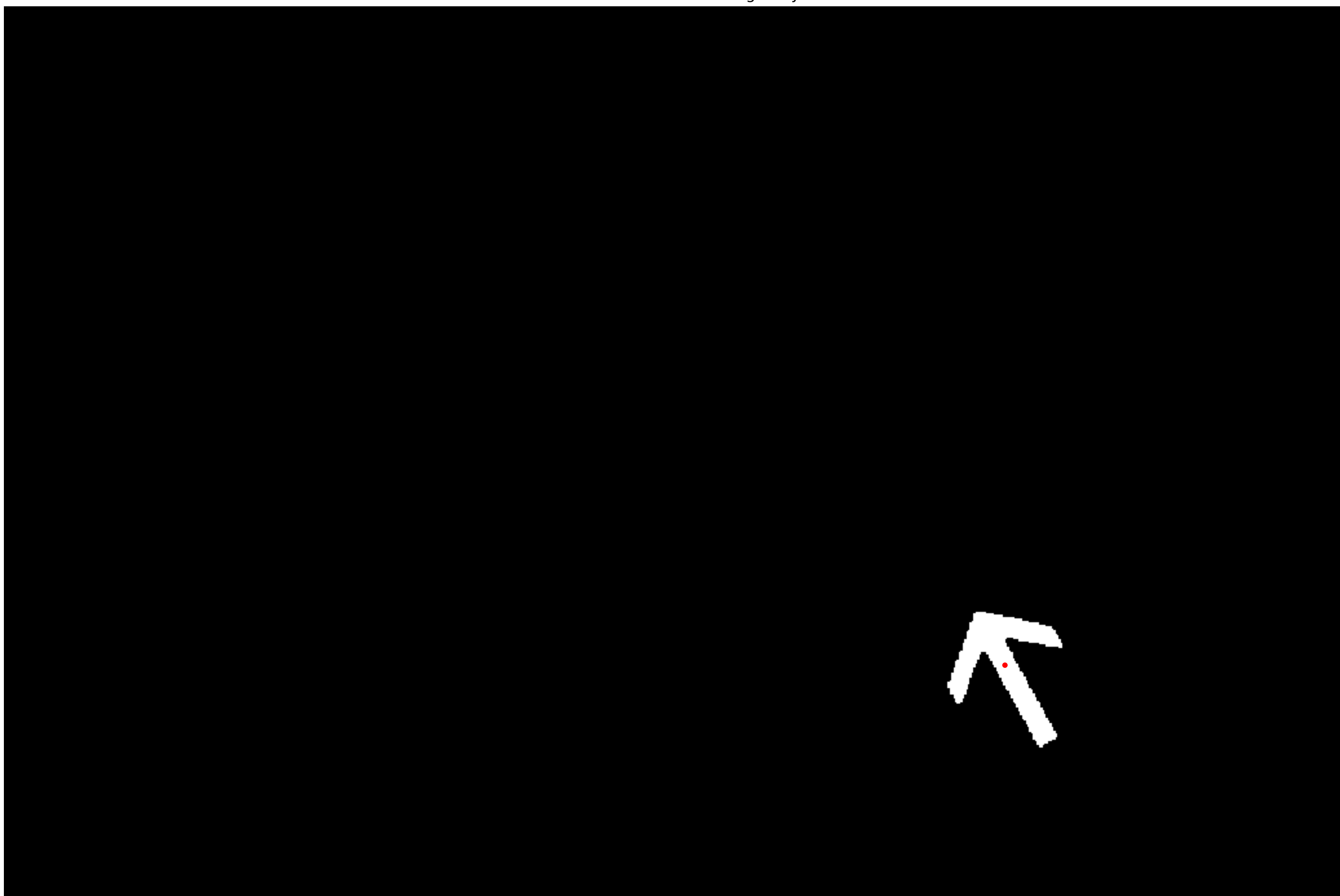
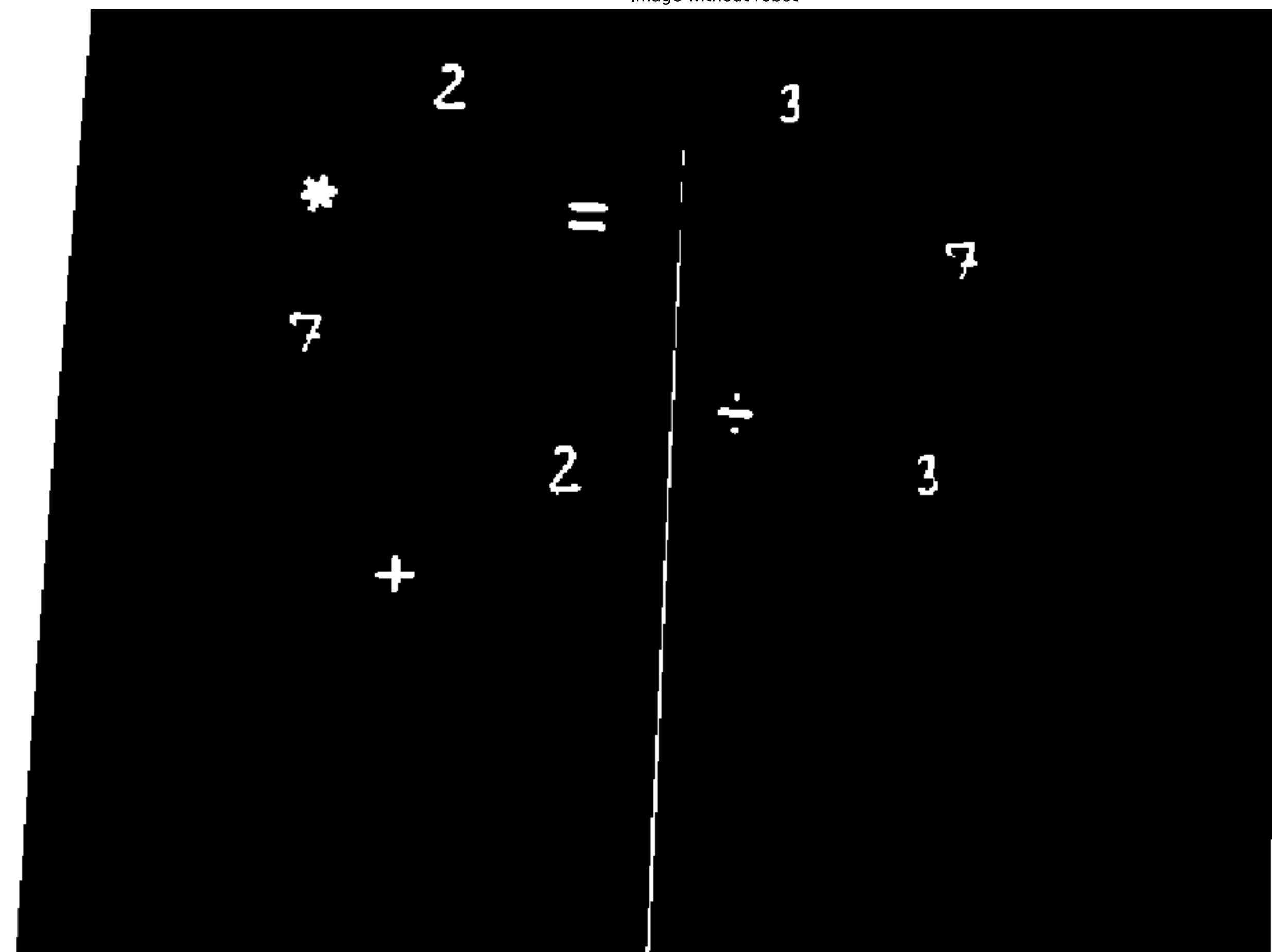
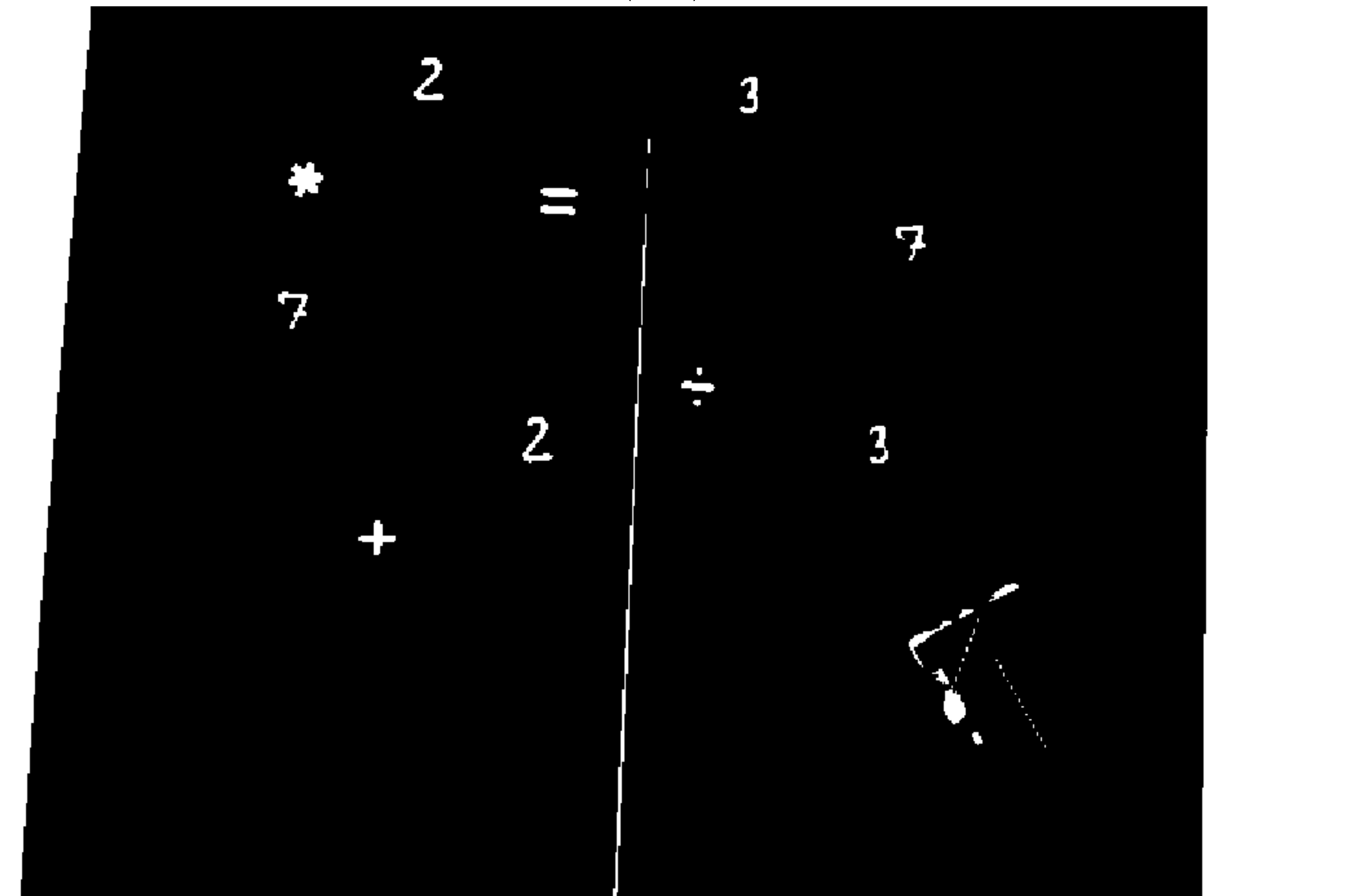
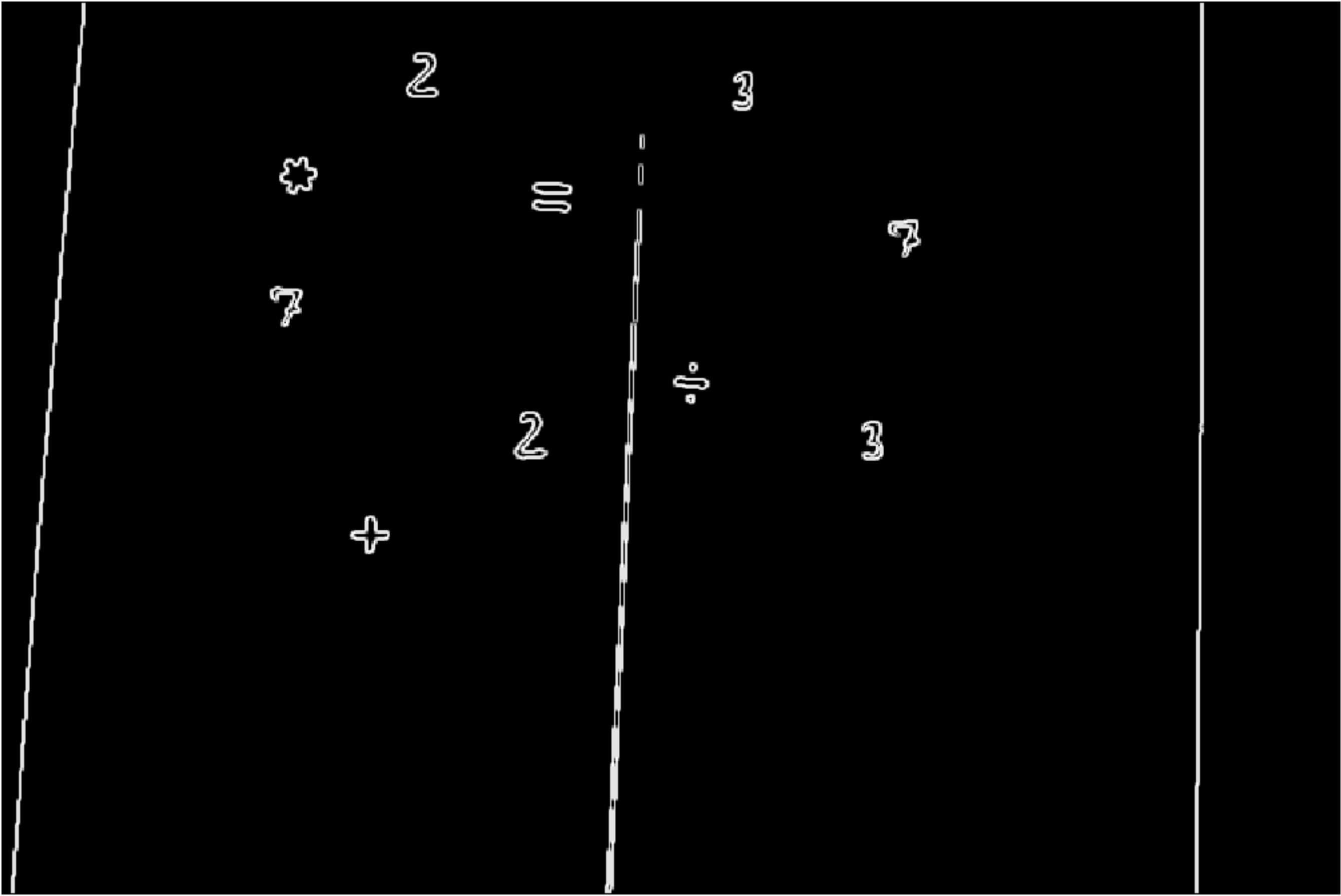


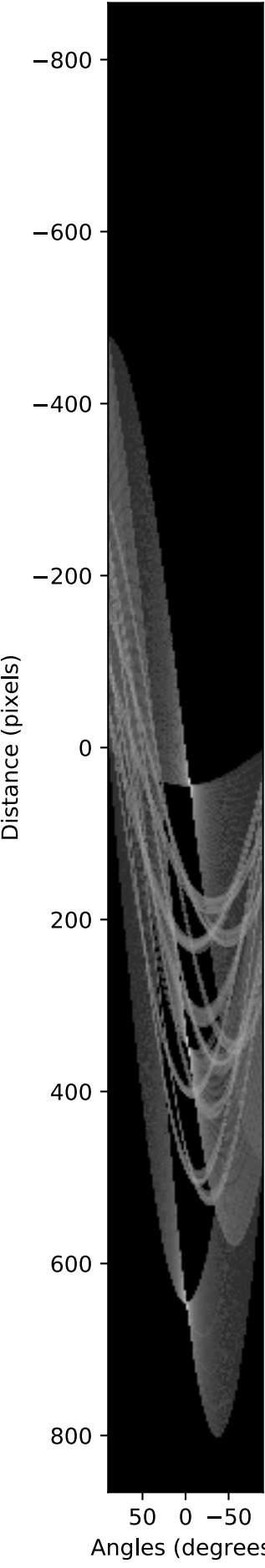
Image without robot



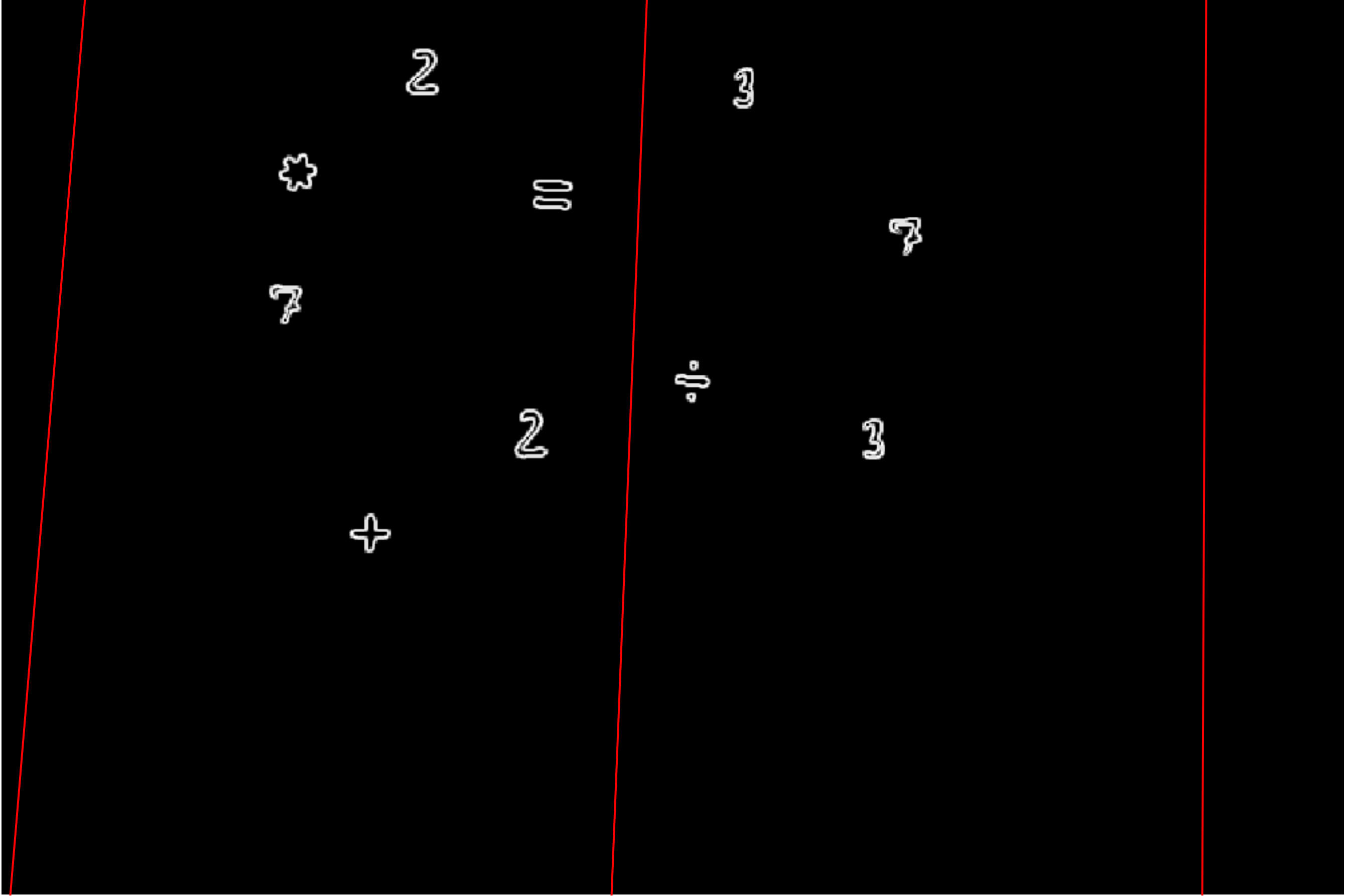
Input image



Hough transform



Detected lines



Polygon covering lines

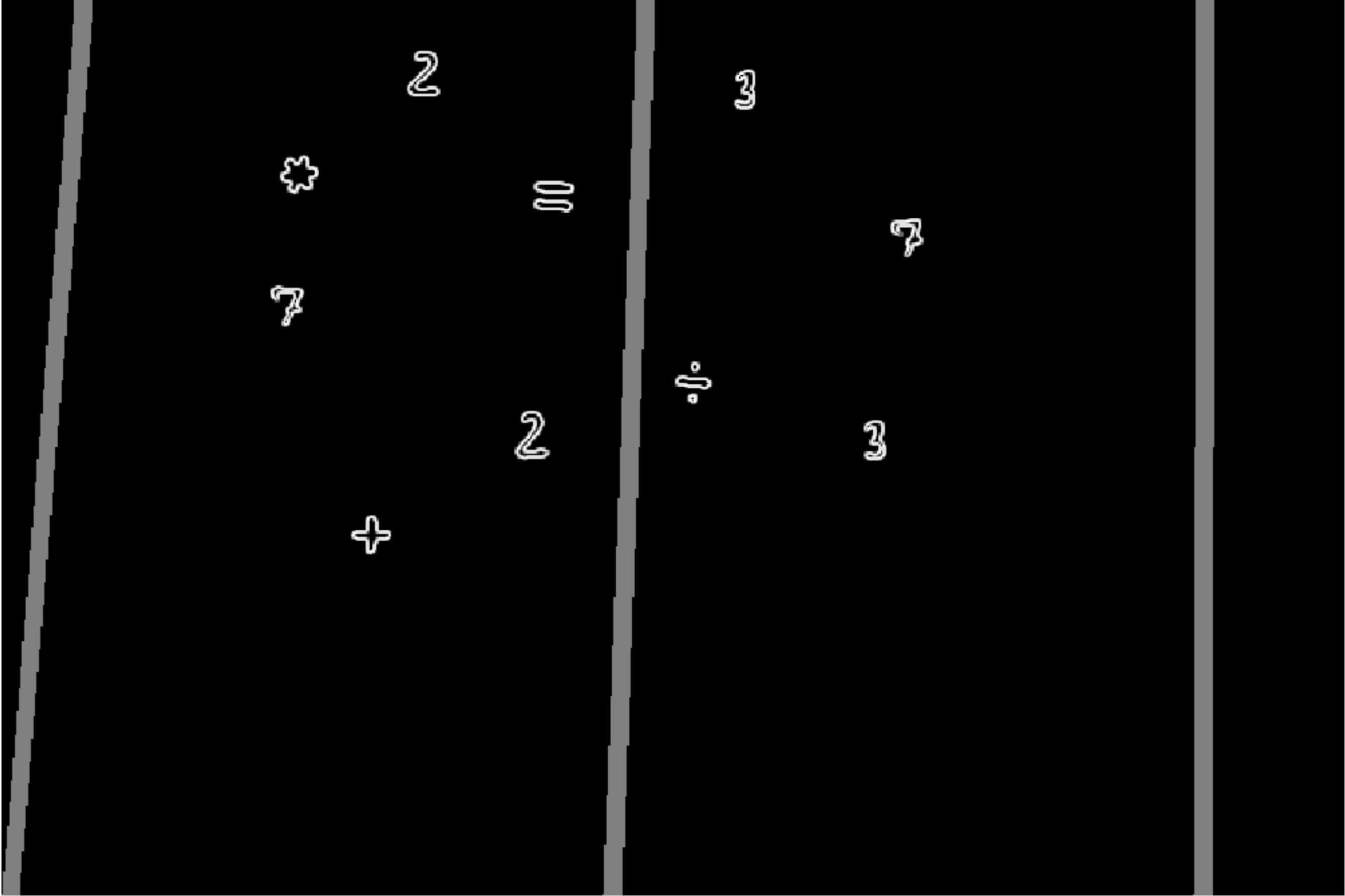


Image without lines

