

### PS3 Solutions

Thursday, November 11, 2021 4:47 PM

$$\underline{(Q1)} \quad a) \quad f(x, y, z) = x^2 + y^2 - z^2 - 2c_x x - 2c_y y + (c_x^2 + c_y^2 + r^2)$$

$$= [x \ y \ z \ 1] \begin{bmatrix} 1 & 0 & 0 & -c_x \\ 0 & 1 & 0 & -c_y \\ 0 & 0 & -1 & 0 \\ -c_x & -c_y & 0 & c_x^2 + c_y^2 + r^2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

$$b) \quad \nabla f(x, y, z) = \left( \frac{\partial f}{\partial x}(x, y, z), \frac{\partial f}{\partial y}(x, y, z), \frac{\partial f}{\partial z}(x, y, z) \right)$$

$$= (2(x - c_x), 2(y - c_y), -2z)$$

Normalize:

$$\|\nabla f\| = 2 \sqrt{(x - c_x)^2 + (y - c_y)^2 + z^2}$$

$$\frac{\nabla f}{\|\nabla f\|} = \frac{(x - c_x, y - c_y, -z)}{\sqrt{(x - c_x)^2 + (y - c_y)^2 + z^2}}$$

c) Consider fixed values of  $z \geq 0$ :

$$(x - c_x)^2 + (y - c_y)^2 = z^2 - r^2$$

Traces a circle of radius  $\sqrt{z^2 - r^2}$  with center  $(c_x, c_y, z)$

No solutions for  $z < r$ , so  $z_{\min} = r$ ,  $z_{\max} = +\infty$

kinda bleh  
notation  
I know

$$x(\theta, z) = c_x + \sqrt{z^2 - r^2} \cos(\theta)$$

$$y(\theta, z) = c_y + \sqrt{z^2 - r^2} \sin(\theta)$$

$$z(\theta, z) = z$$

$$d) \quad \text{normal} = \frac{\partial \vec{r}}{\partial \theta} \times \frac{\partial \vec{r}}{\partial z} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -\sqrt{z^2 - r^2} \sin(\theta) & \sqrt{z^2 - r^2} \cos(\theta) & 0 \\ \frac{z}{\sqrt{z^2 - r^2}} \cos(\theta) & \frac{z}{\sqrt{z^2 - r^2}} \sin(\theta) & 1 \end{vmatrix}$$

$$= (\sqrt{z^2 - r^2} \cos(\theta), \sqrt{z^2 - r^2} \sin(\theta), -z)$$

$$\|\text{normal}\|^2 = (z^2 - r^2) \cos^2 \theta + (z^2 - r^2) \sin^2 \theta + z^2$$

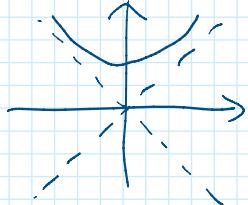
$$= 2z^2 - r^2$$

$$\text{unit normal} = \frac{1}{\sqrt{2z^2 - r^2}} (\sqrt{z^2 - r^2} \cos(\theta), \sqrt{z^2 - r^2} \sin(\theta), -z)$$

e) Recall that

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$$\begin{aligned} x &= \sinh \lambda \\ y &= \cosh \lambda \end{aligned} \quad \text{for } \lambda \in \mathbb{R} \quad \text{traces out top half of a hyperbola}$$



$$\text{and that } \cosh^2 \lambda - \sinh^2 \lambda = 1$$

This is the intersection with the two-sheeted hyperboloid along a plane. Thus, we may use a parameter  $\theta$  to denote the half-plane in question.

$$x(\theta, \lambda) = c_x + r \sinh(\lambda) \cos(\theta)$$

$$y(\theta, \lambda) = c_y + r \sinh(\lambda) \sin(\theta) \quad \text{for } \lambda \geq 0$$

$$z(\theta, \lambda) = r \cosh(\lambda)$$

$$\text{normal} = \frac{\partial \vec{r}}{\partial \theta} \times \frac{\partial \vec{r}}{\partial \lambda} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -r \sinh(\lambda) \sin(\theta) & r \sinh(\lambda) \cos(\theta) & 0 \\ r \cosh(\lambda) \cos(\theta) & r \cosh(\lambda) \sin(\theta) & r \sinh(\lambda) \end{vmatrix}$$

$$= (r^2 \sinh^2(\lambda) \cos(\theta), r^2 \sinh^2(\lambda) \sin(\theta), -r^2 \cosh(\lambda) \sinh(\lambda))$$

$$\|\text{normal}\|^2 = r^4 (\sinh^4(\lambda) + \cosh^2(\lambda) \sinh^2(\lambda)) = r^4 \sinh^2(\lambda) \cosh(2\lambda)$$

$$\text{unit normal} = \left( \frac{\sinh(\lambda) \cos \theta}{\sqrt{\cosh(2\lambda)}}, \frac{\sinh(\lambda) \sin \theta}{\sqrt{\cosh(2\lambda)}}, -\frac{\cosh(\lambda)}{\sqrt{\cosh(2\lambda)}} \right)$$

Q2 a)  $p(u) = p_0 + (p_1 - p_0)u$

$$= (2, 0, 0) + u(-2, 0, 6) = \begin{bmatrix} 2-2u \\ 0 \\ 6u \end{bmatrix}$$

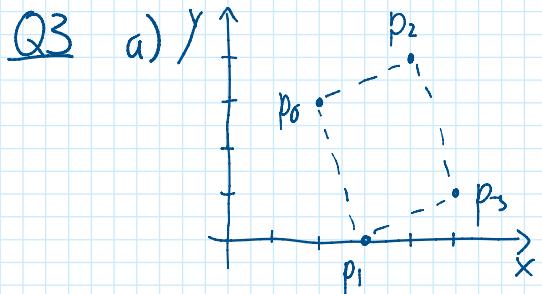
b)  $p(u)$  parametrizes the center point, while  $v$  parametrizes the elliptic cross-section

$$P(u, v) = p(u) + \begin{bmatrix} r_x \cos(2\pi v) \\ r_y \sin(2\pi v) \\ 0 \end{bmatrix} = \begin{bmatrix} 2-2u + r_x \cos(2\pi v) \\ r_y \sin(2\pi v) \\ 6u \end{bmatrix}$$

c)  $\text{normal} = \frac{\partial \vec{r}}{\partial v} \times \frac{\partial \vec{r}}{\partial u} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -2\pi r_x \sin(2\pi v) & 2\pi r_y \cos(2\pi v) & 0 \end{vmatrix}$

$$\text{c) normal} = \frac{\partial r}{\partial v} \times \frac{\partial r}{\partial u} = \begin{vmatrix} i & j & k \\ -2\pi r_x \sin(2\pi v) & 2\pi r_y \cos(2\pi v) & 0 \\ -2 & 0 & 6 \end{vmatrix}$$

$$= 2\pi(6r_y \cos(2\pi v), 6r_x \sin(2\pi v), 4r_y \cos(2\pi v))$$



b)  $p'(0) = 3(p_1 - p_0)$  (from lecture)  
 $= 3(1, -3) = (3, -9)$

c)  $C^0$  continuity? Yes, as  $(p_3 \text{ of second curve}) = (p_0 \text{ of first curve})$   
 Are first derivatives equal? For second curve:

$$p'(1) = 3(p_3 - p_2) = 3(2, -6) = (6, -18) \neq (3, -9)$$

NO

d) If we change  $p_2$  of second curve to  $(1, 6)$  we have:

$$3(p_3 - p_2) = 3(1, -3) = (3, -9)$$

Q4 a) Assuming  $P(u) = au^3 + bu^2 + cu + d$ , the constraints give us:

$$P(0) = d = p_k$$

$$P(1) = a + b + c + d = p_{k+1}$$

$$\begin{cases} P'(0) = c = -\frac{1}{2}(1+b)p_{k-1} + bp_k + \frac{1}{2}(1-b)p_{k+1} \\ P'(1) = 3a + 2b + c = -\frac{1}{2}(1+b)p_k + bp_{k+1} + \frac{1}{2}(1-b)p_{k+2} \end{cases}$$

This implies:

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 3 & 2 & 1 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} P(0) \\ P(1) \\ P'(0) \\ P'(1) \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\frac{1}{2}(1+b) & b & \frac{1}{2}(1-b) & 0 \\ 0 & -\frac{1}{2}(1+b) & b & \frac{1}{2}(1-b) \end{bmatrix} \begin{bmatrix} p_{k-1} \\ p_k \\ p_{k+1} \\ p_{k+2} \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} p_{k-1} \\ p_k \\ p_{k+1} \\ p_{k+2} \end{bmatrix}$$

denoted A

$$P(u) = [u^3 \ u^2 \ u \ 1] \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = [u^3 \ u^2 \ u \ 1] \begin{bmatrix} p_{k-1} \\ p_k \\ p_{k+1} \\ p_{k+2} \end{bmatrix}$$

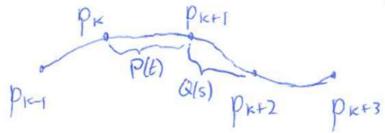
denoted B

$$b) M_c = \begin{bmatrix} -\frac{1}{2}(b+1) & \frac{1}{2}(b+3) & \frac{1}{2}(b-3) & \cancel{\frac{1}{2}(1-b)} \\ b+1 & -\frac{1}{2}(3b+5) & 2 & \frac{1}{2}(b-1) \\ -\frac{1}{2}(b+1) & b & \frac{1}{2}(1-b) & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

hole swap in term order

$$\begin{aligned} P(u) &= [-\frac{1}{2}(b+1)u^3 + (b+1)u^2 - \frac{1}{2}(b+1)u] p_{k-1} \\ &\quad + [\frac{1}{2}(b+3)u^3 - \frac{1}{2}(3b+5)u^2 + bu + 1] p_k \\ &\quad + [\frac{1}{2}(b-3)u^3 + 2u^2 + \frac{1}{2}(1-b)u] p_{k+1} \\ &\quad + [\frac{1}{2}(1-b)u^3 + \frac{1}{2}(b-1)u^2] p_{k+2} \end{aligned}$$

- c) A schematic (not an actual spline)



For two adjacent segments  $P(t)$  &  $Q(s)$ :

$C_0$  continuity? Yes,  $P(1) = Q(0) = p_{k+1}$  YES

$C_1$  continuity? Yes:

$$P'(1) = -\frac{1}{2}(1+b)p_k + bp_{k+1} + \frac{1}{2}(1-b)p_{k+2} = Q'(0)$$

(note the indices shift for  $Q$ )

- d) Changing  $b$  changes the linear combination of control points that define  $P'(0)$  &  $P'(1)$ , so the direction changes, as well as the magnitude.

See Fig. 19 in text for examples.