

Time Series Analysis.

Model: • discrete time: $t=1, 2, \dots, T$

• continuous time: $t \in [0, T]$, e.g. Stock Price.

Observe X_t , the realized value of some r.v. X_t

$\{X_t : t \in T_0\}$: data set. It is a realization of $\{X_t : t \in T_0\}$, which comes from $\{X_t : t \in T_1\}$, $T_0 \subset T_1$.
 → Use Kolmogorov's theorem to guarantee that X_t exists.

• Stationarity: past & future.

Def: The t.s. $\{X_t\}$ is strictly stationary if $\forall k \in \mathbb{N}$, t_1, t_2, \dots, t_k , the joint dist. of $(X_{t_1}, X_{t_2}, \dots, X_{t_k})$ and $(X_{t_1+h}, X_{t_2+h}, \dots, X_{t_k+h})$ are the same.

Intuition: shift time by $h \rightarrow$ statistical properties of the observed data are similar.

Problem: cannot test str. stat. ($\text{infinite set of } t_1 < t_2 < \dots < t_k \text{ we have}$)

$k=1: \cdot X_1, X_2, \dots, X_T \text{ has the same dist.}$

$k=2: \cdot (X_1, X_2), (X_2, X_3), \dots, (X_T, X_T)$

$\cdot (X_1, X_2), (X_2, X_3), \dots, (X_{T-2}, X_T)$

$k=3: \cdot (X_1, X_2, X_3), (X_2, X_3, X_4) \dots$

Def Let $\text{Var}(X_t) < \infty, \forall t$. The autocovariance $\gamma_X(r, s)$ of X_t is $\gamma_X(r, s) = \text{cov}(X_r, X_s) = \mathbb{E}[(X_r - \mathbb{E}[X_r])(X_s - \mathbb{E}[X_s])]$
 $(\{X_t : t \in T\})$ $\forall r, s \in T$.

Def The t.s. $\{X_t\}$ is weakly stationary (covariance stationary) if

(i) $\mathbb{E}[|X_t|^2] < \infty, \forall t$

(ii) $\mathbb{E}[X_t] = \mu, \forall t$

(iii) $\gamma_X(r, s) = \gamma_X(r+t, s+t), \forall r, s, t$

Remark: If X_t is weakly stat., then $\gamma_X(r, s) = \gamma_X(r-s, 0)$

Let $\gamma_X(h) = \gamma_X(h, 0) = \text{cov}(X_{t+h}, X_t) \quad \forall t$, then $\gamma_X(\cdot)$ is the autocovariance of X_t .

f-n: function.

$$\gamma(0) = \text{cov}(X_t, X_t) = \text{Var}(X_t)$$

Def Auto-correlation f-n of weakly stat. t.s. $\{X_t\}$ is $\rho_X(h) = \frac{\gamma(h)}{\gamma(0)} = \text{corr}(X_{t+h}, X_t), \forall t, h$

Other notations: $\gamma_h = \gamma_X(h)$

$$\rho_h \equiv \gamma_X(h)/\gamma_X(0)$$

• Relationship btw. weak & strong stationarity:

1) $X_t \sim i.i.d$ Cauchy: $f(x; \mu, \gamma) = \frac{1}{\pi \gamma [1 + (\frac{x-\mu}{\gamma})^2]}$ heavy-tailed

$\Rightarrow \{X_t\}$ is str. stat.

$\{X_t\}$ is not weak stat since $\mathbb{E}[|X_t|^2] = \infty$

2) X_t str. stat $\nabla \mathbb{E}[|X_t|^p] < \infty$

$\Rightarrow X_t$ weak stat.

$\mathbb{E}[|X_t|^2] < \infty \Rightarrow \mathbb{E}[|X_t|^2] < \infty \quad \forall t$

$\mathbb{E}[X_t] < \infty \Rightarrow \mathbb{E}[X_t] < \infty \quad \forall t$

str. stat. with $k=2$: $\gamma_X(t+h, s+h) = \gamma_X(t, s)$

3) $X_t \sim$ independent.

$X_t \sim \begin{cases} N(1, 1) & t - \text{even} \\ \exp(1) & t - \text{odd} \end{cases}$

exponential: $f(x; \lambda) = \lambda e^{-\lambda x} \quad x > 0$

$$\Rightarrow \mathbb{E}[X_t] = 1 \quad \forall t, \quad \mathbb{E}[|X_t|^p] < \infty, \quad \forall t$$

$$\gamma_X(h) = \begin{cases} 1 & \text{if } h=0 \\ 0 & \text{if } h \neq 0 \end{cases}$$

$\Rightarrow X_t$ is weakly stat. $\Rightarrow X_t$ is not str. stat. (X_1 is exponential, X_2 is normal)

e.g. 1. $Z_t \sim \text{iid}(0, \sigma^2)$

$$X_t = Z_t + \theta Z_{t-1}, \quad \theta \in \mathbb{R}$$

$$\text{Then: } \mathbb{E}[X_t] = 0$$

$$\begin{aligned} \text{cov}(X_{t+h}, X_t) &= \text{cov}(Z_{t+h} + \theta Z_{t+h-1}, Z_t + \theta Z_{t-1}) \\ &= \begin{cases} \sigma^2 + \theta^2 \sigma^2 & \text{if } h=0 \\ \theta \sigma^2 & \text{if } |h|=1 \\ 0 & \text{if } |h|>1. \end{cases} \end{aligned}$$

$\Rightarrow X_t$ is weakly stat. In fact also strictly stat.

e.g. 2. Y_t = weakly stat.

$$X_t = \begin{cases} Y_t & t-\text{even} \\ Y_t+1 & t-\text{odd} \end{cases}$$

$$\text{Then, } \text{cov}(X_{t+h}, X_t) = \text{cov}(Y_{t+h}, Y_t) = \gamma_Y(h)$$

$$\text{However, } \mathbb{E}[X_t] \neq \text{constant}. \quad \mathbb{E}[X_1] = \mathbb{E}[Y_1] + 1 \neq \mathbb{E}[X_2] = \mathbb{E}[Y_2]$$

X_t is not weakly stat.

e.g. 3. (Random Walk)

$$X_t \sim \text{iid}(0, \sigma^2)$$

$$S_t = X_1 + \dots + X_t$$

$$\text{Then: } \mathbb{E}[S_t] = 0, \quad \forall t$$

$$\begin{aligned} \text{cov}(S_{t+h}, S_t) &= \text{cov}(X_1 + X_2 + \dots + X_{t+h}, X_1 + X_2 + \dots + X_t) \\ &= \text{cov}(X_1 + X_2 + \dots + X_t, X_1 + X_2 + \dots + X_t) \\ &= \sigma^2 + \dots + \sigma^2 \\ &= t\sigma^2 \quad \Rightarrow S_t \text{ is not weakly stat.} \end{aligned}$$

• Proposition: If $\gamma(\cdot)$ is the autocovariance fn of weakly stat. X_t , $\rho(\cdot)$ is its autocorrelation fn.

$$i) \gamma(0) > 0, \quad \rho(0) = 1$$

$$ii) |\gamma(h)| \leq \gamma(0), \quad |\rho(h)| \leq 1, \quad \forall h$$

$$iii) \gamma(h) = \gamma(-h), \quad \rho(h) = \rho(-h)$$

$$\text{proof: i). } \gamma(0) = \text{cov}(X_t, X_t) = \text{var}(X_t) \geq 0$$

$$\rho(0) = \frac{\gamma(0)}{\gamma(0)} = 1$$

$$iii) \gamma(h) = \text{cov}(X_{t+h}, X_t) = \text{cov}(X_t, X_{t-h}) = \text{cov}(X_{t-h}, X_t) = \gamma(-h)$$

$$\rho(h) = \frac{\gamma(h)}{\gamma(0)} = \frac{\gamma(-h)}{\gamma(0)} = \rho(-h)$$

$$ii) |\text{cov}(X_{t+h}, X_t)| \leq \sqrt{\text{var}(X_{t+h})} \sqrt{\text{var}(X_t)} \quad (\text{Cauchy-Bunyakovsky-Schwarz ineq.})$$

$$\text{proof: } X, Y \text{ r.v. } \text{var}(\lambda X + Y) \geq 0 \quad \forall \lambda \in \mathbb{R}$$

$$\lambda^2 \text{var}(X) + 2\lambda \text{cov}(X, Y) + \text{var}(Y) \geq 0 \quad \forall \lambda \in \mathbb{R}.$$

$$\therefore 4\text{cov}(X, Y)^2 - 4\text{var}(X)\text{var}(Y) \leq 0$$

$$|\text{cov}(X, Y)| \leq \sqrt{\text{var}(X)} \sqrt{\text{var}(Y)}.$$

$$\cos(\alpha) \cos(\beta) = \frac{1}{2} \cos(\alpha + \beta) + \frac{1}{2} \cos(\alpha - \beta). \quad \cos(\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta.$$

• Ergodicity - LLN and CLT for time series • Long-run variance, NAC

Sample Setting:

$\{x_1, \dots, x_T\}$ observed

x_{T+1}, x_{T+2}, \dots out of sample
 x_0, x_{-1}, \dots pre-sample

estimate $\hat{\gamma}(h), \hat{\rho}_{X(h)}$

Def. The sample autocovar fun of $\{x_1, \dots, x_T\}$ is

$$\begin{cases} \hat{\gamma}(h) := \frac{1}{T} \sum_{j=1}^{T-h} (x_{j+h} - \bar{x})(x_j - \bar{x}), & 0 \leq h < T \\ \hat{\gamma}(h) := \hat{\gamma}(-h), & -T < h < 0 \end{cases}$$

$$\text{where } \bar{x} = \frac{1}{T} \sum_{t=1}^T x_t$$

The sample autocorr. is $\hat{\rho}(h) := \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}, |h| < T$

When do sample moments converge to the true moments?

In cross-sectional, usually $x_t \sim \text{iid}$, so LLN implies sample \rightarrow true

e.g. $\varepsilon_t \sim \text{iid } N(0, \sigma^2)$

$$\mu \sim N(0, \lambda^2), \quad \varepsilon_t \perp \mu$$

$$Y_t = \mu + \varepsilon_t, \quad t=1, 2, 3, \dots$$

$$\rightarrow \mathbb{E}[Y_t] = \mathbb{E}[\mu] + \mathbb{E}[\varepsilon_t] = 0$$

$$\frac{1}{T} \sum_{t=1}^T Y_t = \frac{1}{T} \sum_{t=1}^T (\mu + \varepsilon_t) = \mu + \frac{1}{T} \sum_{t=1}^T \varepsilon_t \xrightarrow{P} \mu \neq \mathbb{E}[Y_t]$$

$$\text{cov}(Y_{t+h}, Y_t) = \begin{cases} \sigma^2 + \lambda^2, & h=0 \\ \lambda^2, & h \neq 0 \end{cases} = \mathbb{E}[(\mu + \varepsilon_{t+h})(\mu + \varepsilon_t)]$$

$\therefore Y_t$ is weakly stat., but $\frac{1}{T} \sum_{t=1}^T Y_t \not\rightarrow \mathbb{E}[Y_t]$

Def. A weakly stat. t.s. $\{x_t\}$ is ergodic for the mean if

$$\frac{1}{T} \sum_{t=1}^T x_t \xrightarrow{P} \mathbb{E}[x_t].$$

Intuition: i) Many Universes

ii) Observe one univ. with $\{y_1, \dots, y_T\}$

iii) Other universes have

$$\{y_1^{(i)}, y_2^{(i)}, \dots, y_T^{(i)}\}, \quad i=1, 2, \dots$$

$$\mathbb{E}[y_t] = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{j=1}^N y_j^{(i)}$$

Ergodicity: temporal avg = spatial avg.

Lack of memory across t. i.e. can use LLN

Stationarity: similarity across t

Lemma: If $\{x_t\}$ is weakly stationary and $\sum_{j=-\infty}^{\infty} |\gamma(j)| < \infty$. then $\frac{1}{T} \sum_{t=1}^T x_t \xrightarrow{P} \mathbb{E}[x_t]$, ergodic for the mean.

Proof: WTS $\mathbb{P}(|\frac{1}{T} \sum_{t=1}^T x_t - \mathbb{E}[x_t]| > \varepsilon) \rightarrow 0 \quad \forall \varepsilon$.

First, we show the Markov Inequality $\mathbb{P}(Y > c) \leq \frac{\mathbb{E}[Y]}{c}$, $Y \geq 0$ r.v.
 $\mathbb{E}[Y] = \int y d(F(y)) \geq \int_c^{\infty} y d(F(y)) \geq \int_c^{\infty} c d(F(y)) = c \mathbb{P}(Y > c)$

$$\begin{aligned} \text{Apply it. } \mathbb{P}\left(|\frac{1}{T} \sum_{t=1}^T x_t - \mathbb{E}[x_t]| > \varepsilon\right) &\leq \frac{1}{\varepsilon^2} \mathbb{E}\left[\left(\frac{1}{T} \sum_{t=1}^T x_t - \mathbb{E}[x_t]\right)^2\right] \\ &= \frac{1}{\varepsilon^2} \text{Var}\left(\frac{1}{T} \sum_{t=1}^T x_t\right) \\ &= \frac{1}{\varepsilon^2} \frac{1}{T^2} \sum_{i=1}^T \sum_{j=1}^T \text{cov}(x_i, x_j) \\ &\quad \text{(1,2),(2,1), ..., (1,3),(3,1), ..., (1,T),(T,1)} \\ &= \frac{1}{\varepsilon^2} \frac{1}{T} (\gamma(0) + 2 \sum_{i=1}^{T-1} \gamma(i) 2 \underline{\gamma(T-i)} + \gamma(2) \underline{\gamma(T-2)} + \dots + \gamma(T-1) \underline{\gamma(1)}) \\ &= \frac{1}{\varepsilon^2} \frac{1}{T} (\gamma(0) + 2 \sum_{i=1}^{T-1} \gamma(i) (1 - \frac{i}{T})) \\ &\leq \frac{1}{\varepsilon^2} \frac{1}{T} \sum_{i=0}^{\infty} |\gamma(i)| \quad \text{since } \gamma(h) = \gamma(-h) \\ &\quad \underbrace{< \infty}_{\longrightarrow 0 \quad \text{as } T \rightarrow \infty} \\ &\therefore \frac{1}{T} \sum_{t=1}^T x_t \xrightarrow{P} \mu \quad \text{as } T \rightarrow \infty. \end{aligned}$$

Corollary. Variance in CLT changes. with what?

If $x_t \sim \text{iid } (\mu, \sigma^2)$, then $\text{var}\left(\frac{1}{T} \sum_{t=1}^T x_t\right) = \frac{1}{T^2} \cdot T \sigma^2 = \frac{\sigma^2}{T}$

Now: $\text{var}\left(\frac{1}{T} \sum_{t=1}^T x_t\right) = \frac{1}{T} (\gamma(0) + 2 \sum_{i=1}^{T-1} \gamma(i) (1 - \frac{i}{T}))$

$\gamma(0) + 2 \sum_{i=1}^{T-1} \gamma(i) (1 - \frac{i}{T}) \xrightarrow[T \rightarrow \infty]{\text{correlation across time}} \sum_{i=0}^{\infty} \gamma(i) = \gamma(0) + 2 \sum_{i=1}^{\infty} \gamma(i) = \text{long-run variance}$

? Why not $\frac{1}{T}$.

CLT

Theorem: Let $x_t = \mu + \sum_{j=0}^{\infty} c_j \varepsilon_{t-j}$, $\varepsilon_t \sim \text{indep}(0, \sigma^2)$, $\sum_{j=0}^{\infty} |c_j| < \infty$.

Then: $\sqrt{T} \left(\frac{1}{T} \sum_{t=1}^T x_t - \mu \right) \xrightarrow{D} N(0, J)$, $J = \sum_{h=-\infty}^{\infty} \gamma(h)$

Proof?

Remark: $J < \infty$ because:

$$\begin{aligned} h \geq 0: \gamma(h) &= \text{cov}(x_{t+h}, x_t) = \text{cov}(\mu + \sum_{j=0}^{\infty} c_j \varepsilon_{t+h-j}, \mu + \sum_{j=0}^{\infty} c_j \varepsilon_{t-j}) \\ &= \text{cov}(\mu + \sum_{j=h}^{\infty} c_{j+h} \varepsilon_{t-j}, \mu + \sum_{j=0}^{\infty} c_j \varepsilon_{t-j}) \\ &= \sum_{j=0}^{\infty} c_{j+h} c_j \sigma^2 \end{aligned}$$

$$\begin{aligned} J &= \sum_{h=-\infty}^{\infty} \gamma(h) \\ &= \gamma(0) + 2 \sum_{h=1}^{\infty} \gamma(h) \quad \text{by } \gamma(h) = \gamma(-h) \\ &= \sum_{i=0}^{\infty} c_i^2 \sigma^2 + 2 \sum_{h=1}^{\infty} \sum_{j=0}^{\infty} (c_{j+h} c_j \sigma^2) \\ &= \sigma^2 \left(\sum_{i=0}^{\infty} c_i^2 + 2 \sum_{h=1}^{\infty} \sum_{j=0}^{\infty} c_{j+h} c_j \right) \\ &= \sigma^2 \left(2 \sum_{h=0}^{\infty} \sum_{j=0}^{\infty} c_{j+h} c_j - \sum_{i=0}^{\infty} c_i^2 \right) \\ &\quad \left(c_0^2 + c_1^2 + \dots \right) + 2(c_1 c_0 + c_2 c_1 + c_3 c_0 + \dots) \\ &\geq 2(c_0^2 + c_1 c_0 + c_1^2 + c_2 c_1 + c_2 c_0 + c_3^2 + \dots) \end{aligned}$$

From $\sum_{j=0}^{\infty} |c_j| < \infty$:

$$\begin{aligned} \left| \sum_{h=0}^{\infty} \sum_{j=0}^{\infty} c_{j+h} c_j \right| &\leq \sum_{h=0}^{\infty} \left| \sum_{j=0}^{\infty} c_{j+h} c_j \right| \leq \sum_{h=0}^{\infty} \sum_{j=0}^{\infty} |c_{j+h}| |c_j| \\ &\leq \left(\sum_{i=0}^{\infty} |c_i| \right)^2 < \infty \end{aligned}$$

$$\therefore J = \sigma^2 \left(\sum_{i=0}^{\infty} c_i^2 + 2 \sum_{h=1}^{\infty} \sum_{j=0}^{\infty} c_{j+h} c_j \right) < \infty$$

Alternatively, via iterative back-substitution:

$$\begin{aligned}
 Y_t &= \alpha + \beta Y_{t-1} + \varepsilon_t \\
 &= \alpha + \beta(\alpha + \beta Y_{t-2} + \varepsilon_{t-1}) + \varepsilon_t \\
 &= \alpha(1+\beta) + \beta^2 Y_{t-2} + \beta \varepsilon_{t-1} + \varepsilon_t \\
 &= \alpha(1+\beta) + \beta^2(\alpha + \beta Y_{t-3} + \varepsilon_{t-2}) + \varepsilon_t + \beta \varepsilon_{t-1} \\
 &= \alpha(1+\beta+\beta^2) + \beta^3 Y_{t-3} + \varepsilon_t + \beta \varepsilon_{t-1} + \beta^2 \varepsilon_{t-2} \\
 &= \alpha(1+\beta+\dots+\beta^{h-1}) + \beta^h Y_{t-h} + \varepsilon_t + \beta \varepsilon_{t-1} + \dots + \beta^{h-1} \varepsilon_{t-h+1} \\
 &\xrightarrow{h \rightarrow \infty} \alpha \frac{1}{1-\beta} + \sum_{i=0}^{\infty} \beta^i \varepsilon_{t-i}
 \end{aligned}$$

With MA(∞) representation:

$$\begin{aligned}
 \mathbb{E}[Y_t] &= \mathbb{E}\left[\frac{\alpha}{1-\beta} + \sum_{i=0}^{\infty} \beta^i \varepsilon_{t-i}\right] = \frac{\alpha}{1-\beta} \\
 h > 0, \quad \text{cov}(Y_t, Y_{t+h}) &= \text{cov}\left(\sum_{i=0}^{\infty} \beta^i \varepsilon_{t-i}, \sum_{i=0}^{\infty} \beta^{i+h} \varepsilon_{t+h-i}\right) \\
 &= \sigma^2 \sum_{i=0}^{\infty} \beta^{2i} \beta^{ih} = \sigma^2 \beta^h \frac{1}{1-\beta^2}
 \end{aligned}$$

In particular: $\text{var}(Y_t) = \sigma^2 \frac{1}{1-\beta^2}$. (R)

Notice: • if $|\beta| > 1$, then $1-\beta^2 < 0$, (R) doesn't make sense.

• if $|\beta| = 0$, then $\frac{1}{1-\beta^2} = \infty$, infinite variance.

∴ Same with invertible lag operator, $|\beta| < 1$.

Another way to calculate moments:

$\mathbb{E}[Y_t] = ?$ Assume Y_t weakly stat.

$$\begin{aligned}
 \mathbb{E}[Y_t] &= \mathbb{E}[\alpha + \beta Y_{t-1} + \varepsilon_t] = \alpha + \beta \mathbb{E}[Y_{t-1}] + \mathbb{E}[\varepsilon_t] = \alpha + \beta \mathbb{E}[Y_t] + \mathbb{E}[\varepsilon_t] \\
 &= \alpha + \beta \mathbb{E}[Y_t]
 \end{aligned}$$

$$\Rightarrow \mathbb{E}[Y_t] = \frac{\alpha}{1-\beta}.$$

$\text{var}(Y_t) = ?$ Assume Y_t is weakly stat.

$$\begin{aligned}
 \text{var}(Y_t) &= \text{var}(\alpha + \beta Y_{t-1} + \varepsilon_t) = \beta^2 \text{var}(Y_{t-1}) + \text{var}(\varepsilon_t) + 2\beta \text{cov}(Y_{t-1}, \varepsilon_t) \\
 &= \beta^2 \text{var}(Y_t) + \sigma^2 + 0
 \end{aligned}$$

$$\Rightarrow \text{var}(Y_t) = \frac{\sigma^2}{1-\beta^2}$$

$h > 0$

$$\gamma(h) = \text{cov}(Y_{t+h}, Y_t) = \text{cov}(Y_t, Y_{t+h}) = \text{cov}(\alpha + \beta Y_{t-1} + \varepsilon_t, Y_{t+h})$$

$$= \beta \text{cov}(Y_{t-1}, Y_{t+h}) + \text{cov}(\varepsilon_t, Y_{t+h}) = \beta \gamma(h-1) + 0$$

$$\therefore \text{Yule-Walker Equation: } \gamma(h) = \beta \gamma(h-1) = \beta^2 \gamma(h-2) = \beta^h \gamma(0) = \beta^h \frac{\sigma^2}{1-\beta^2}$$

$$\text{Autocorrelation: } \rho(h) = \frac{\gamma(h)}{\gamma(0)} = \beta^h \quad (\text{geometrically decay}).$$

Impulse Response Function (IRF)

$$\text{IRF}_h := \frac{\partial Y_{t+h}}{\partial \varepsilon_t} \quad \text{effect of } \varepsilon_t \text{ on } Y_{t+h}, \text{ assuming } \varepsilon_{t+1}, \dots, \varepsilon_{t+h} \text{ do not change.}$$

$$\begin{aligned}
 Y_{t+h} &= \alpha + \beta Y_{t+h-1} + \varepsilon_{t+h} = \alpha + \beta(\alpha + \beta Y_{t+h-2} + \varepsilon_{t+h-1}) + \varepsilon_{t+h} \\
 &= \sum_{i=0}^h \alpha \beta^i + \sum_{i=0}^h \beta^i \varepsilon_{t+h-i} + \beta^{h+1} Y_{t-1} \\
 &= \beta^h \varepsilon_t + \sum_{i=0}^{h-1} \beta^i \varepsilon_{t+h-i} + \alpha \sum_{i=0}^h \beta^i + \beta^{h+1} Y_{t-1}
 \end{aligned}$$

$$\Rightarrow \text{IRF}_h = \beta^h \quad \text{If } |\beta| < 1, \text{ then } \beta^h \rightarrow 0 \text{ as } h \rightarrow 0 \\ \text{no long-run effect.}$$

• $\beta = 1$: unit-root random walk

$$1 - \beta L = 0 \Leftrightarrow L = \frac{1}{\beta} \quad \text{if } \beta = 1, \rightarrow \text{root } \equiv 1.$$

$$\begin{aligned}
 Y_t &= \alpha + Y_{t-1} + \varepsilon_t = 2\alpha + Y_{t-2} + \varepsilon_t + \varepsilon_{t-1} \\
 &= \alpha t + Y_0 + \sum_{i=1}^t \varepsilon_i
 \end{aligned}$$

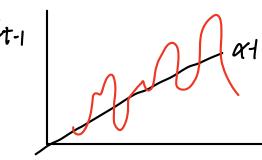
linear time trend if $\alpha \neq 0$

Let Y_0 be constant. Then:

$$\mathbb{E}[Y_t] = \mathbb{E}[xt + Y_0 + \sum_{i=1}^t \varepsilon_i] = xt + Y_0$$

$$\text{var}(Y_t) = \text{var}(xt + Y_0 + \sum_{i=1}^t \varepsilon_i) = \text{var}\left(\sum_{i=1}^t \varepsilon_i\right) = \sigma^2 t \xrightarrow{t \rightarrow \infty}$$

shocks ε_i do not disappear as $t \rightarrow \infty$.



Autoregression

$$\text{AR}(k): Y_t = \alpha + \beta_1 Y_{t-1} + \dots + \beta_k Y_{t-k} + \varepsilon_t, \quad \varepsilon_t \sim WN(0, \sigma^2)$$

$$(1 - \beta_1 L - \dots - \beta_k L^k) Y_t = \alpha + \varepsilon_t, \quad (1 - \beta_1 L - \dots - \beta_k L^k)^{-1} = (1 - \lambda_1 L)^{-1} \cdots (1 - \lambda_k L)^{-1} \quad \text{Need } |\lambda_i| < 1 \quad \forall i = 1, \dots, k$$

then: Y_t is MA(∞). $Y_t = (1 - \beta_1 L - \dots - \beta_k L^k)^{-1} (\alpha + \varepsilon_t)$

$\Rightarrow Y_t$ is covar. stat. MA(∞) is always cov. stat.

If Y_t is covariance stat, then $\mathbb{E}[Y_t] = M$, $V[Y_t]$:

$$M = \mathbb{E}[Y_t] = \mathbb{E}[\alpha + \beta_1 Y_{t-1} + \dots + \beta_k Y_{t-k} + \varepsilon_t]$$

$$= \alpha + (\beta_1 + \dots + \beta_k) M + 0$$

$$\Rightarrow M = \frac{\alpha}{1 - (\beta_1 + \dots + \beta_k)}$$

$$\alpha = M - \mu(\beta_1 + \dots + \beta_k) \quad \text{plug in:}$$

$$\Rightarrow Y_t - M = (Y_{t-1} - \mu)\beta_1 + \dots + (Y_{t-k} - \mu)\beta_k + \varepsilon_t$$

"deviations from the mean" form.

Another useful way to work with AR(k):

$$\begin{pmatrix} Y_t \\ Y_{t-1} \\ \vdots \\ Y_{t-k+1} \end{pmatrix} = \underbrace{\begin{pmatrix} \beta_1 & \beta_2 & \dots & \beta_{k-1} & \beta_k \\ 1 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{pmatrix}}_{k \times k} \begin{pmatrix} Y_{t-1} \\ Y_{t-2} \\ \vdots \\ Y_{t-k} \end{pmatrix} + \begin{pmatrix} \alpha \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \begin{pmatrix} \varepsilon_t \\ 0 \\ \vdots \\ 0 \end{pmatrix} \\
 F = \underbrace{\begin{pmatrix} \beta_1 & \beta_2 & \dots & \beta_{k-1} & \beta_k \\ 1 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{pmatrix}}_{k \times k}$$

$$Z_t = (Y_t, Y_{t-1}, \dots, Y_{t-k+1})'$$

$$\bar{\alpha} = (\alpha, 0, \dots, 0)'$$

$$\Rightarrow Z_t = \bar{\alpha} + F Z_{t-1} + (W_t \quad \text{AR}(k)).$$

Roots $1 - \beta_1 L - \dots - \beta_k L^k = 0$ are $|1| > 1$ is equivalent to

eigenvalues of F are $|1| < 1 \Rightarrow$ cov. stat.

$$\text{e.g. } k=2: F = \begin{pmatrix} \beta_1 & \beta_2 \\ 1 & 0 \end{pmatrix} \quad \det(F - \lambda I) = 0 \Leftrightarrow \begin{vmatrix} \beta_1 - \lambda & \beta_2 \\ 1 & -\lambda \end{vmatrix} = 0$$

$$\lambda(\lambda - \beta_1) - \beta_2 = 0 \quad \lambda^2(1 - \frac{1}{\lambda}\beta_1 - \frac{1}{\lambda}\beta_2) = 0 \quad \text{solutions: } L^* = \frac{1}{\lambda}$$

General k :

$$\begin{aligned}
 \det(F - \lambda I) &= \begin{vmatrix} \beta_1 - \lambda & \beta_2 & \beta_3 & \dots & \beta_{k-1} & \beta_k \\ 1 & -\lambda & 0 & \dots & 0 & 0 \\ 0 & 1 & -\lambda & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 & -\lambda \end{vmatrix} \\
 &= (\beta_1 - 1)(-1)^{k-1} \lambda^{k-1} - \beta_2 (-1)^{k-2} \lambda^{k-2} + \beta_3 (-1)^{k-3} \lambda^{k-3} - \beta_4 (-1)^{k-4} \lambda^{k-4} \\
 &\quad + \dots + (-1)^{k+1} \beta_{k-1} \lambda^{k-1} \lambda^{k-1} \\
 &= (-1)^k \lambda^k (\lambda - \beta_1) + (-1)^{k+1} \beta_2 (-1)^{k-2} \lambda^{k-2} + (-1)^{k+2} \beta_3 (-1)^{k-3} \lambda^{k-3} + (-1)^{k+3} \beta_4 (-1)^{k-4} \lambda^{k-4} \\
 &\quad + \dots + (-1)^{k+1} \beta_{k-1} (-1)^k \lambda^k
 \end{aligned}$$

$$= (-1)^k \lambda^k (\lambda - \beta_1) - (-1)^k \beta_2 \lambda^{k-1} - (-1)^k \beta_3 \lambda^{k-2} - \dots - (-1)^k \beta_k \lambda^{k-1}$$

$$= (-1)^k \lambda^k \left(1 - \frac{1}{\lambda} \beta_1 - \frac{1}{\lambda} \beta_2 - \dots - \frac{1}{\lambda} \beta_k\right)$$

$$1 - \frac{1}{\lambda} \beta_1 - \frac{1}{\lambda^2} \beta_2 - \cdots - \frac{1}{\lambda^k} \beta_k = 0$$

$$1 - \beta_1 L - \beta_2 L^2 - \cdots - \beta_k L^k = 0$$

In deviation from the mean form.

$$\begin{pmatrix} Y_t - \mu \\ Y_{t-1} - \mu \\ \vdots \\ Y_{t+k-1} - \mu \end{pmatrix} = \underbrace{\begin{pmatrix} \beta_1 & \beta_2 & \cdots & \beta_{k-1} & \beta_k \\ 1 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \end{pmatrix}}_F \begin{pmatrix} Y_{t-1} - \mu \\ Y_{t-2} - \mu \\ \vdots \\ Y_{t-k+1} - \mu \end{pmatrix} + \begin{pmatrix} \epsilon_t \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$\eta_t := (Y_t - \mu, Y_{t-1} - \mu, \dots, Y_{t+k-1} - \mu)'$ $k \times 1$ **Deviation from the mean**

$$\mathbb{E}[\eta_t] = (0, \dots, 0)', \quad W_t = (\epsilon_t, 0, \dots, 0)'$$

$$\eta_t = F \eta_{t-1} + W_t \quad \text{AR(L) without intercept.} \quad Q$$

$$W_t \sim WN(\vec{0}, \begin{pmatrix} \sigma^2 & 0 & \cdots & 0 \\ 0 & \sigma^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma^2 \end{pmatrix})$$

$$\Sigma_0 := \text{Var}(\eta_t) = \mathbb{E}[\eta_t \eta_t'] = \mathbb{E}\begin{pmatrix} (Y_t - \mu)^2 & \cdots & (Y_{t+k-1} - \mu)(Y_{t-k} - \mu) \\ (Y_t - \mu)(Y_{t-1} - \mu) & \cdots & (Y_{t+k-1} - \mu)(Y_{t-k-1} - \mu) \\ \vdots & \ddots & \vdots \\ (Y_t - \mu)(Y_{t+k-1} - \mu) & \cdots & (Y_{t+k-1} - \mu)^2 \end{pmatrix}$$

Matrix of first
k-1 autocov $r(0), \dots, r(k-1)$

$$= \begin{pmatrix} r(0) & r(1) & \cdots & r(k-1) \\ r(1) & r(0) & \cdots & r(k-2) \\ \vdots & \vdots & \ddots & \vdots \\ r(k-1) & r(k-2) & \cdots & r(0) \end{pmatrix}$$

and var $r(0)$.

Or: $\Sigma_0 = \text{Var}(\eta_t) = \text{Var}(F \eta_{t-1} + W_t)$

Var(η_{t-1}, w) F' ?

$$= F \text{Var}(\eta_{t-1}) F' + \text{Var}(W_t) + F \mathbb{E}[\eta_{t-1} W_t'] + \mathbb{E}[W_t \eta_{t-1}']$$

$$= F \Sigma_0 F' + Q, \text{ where } Q = \text{Var}(W_t) = 0$$

Since η_{t-1} only contains s_1, s_2, \dots

$$W_t = (\epsilon_t, 0, \dots, 0)'$$

$\Sigma_0 = F \Sigma_0 F' + Q$ system of lin. eqns on $r(0), r(1), \dots, r(k-1)$

k unknowns ($r(0), r(1), \dots, r(k-1)$) . k eqns. Σ_0 solvable. Why? Because:

$$F = \begin{pmatrix} \beta_1 & \beta_2 & \cdots & \beta_k \\ I_{k-1} & 0_{k \times 1} \end{pmatrix} \quad A: 1 \times k-1 \quad B: 1 \times 1$$

$$\Sigma_0 = \begin{pmatrix} D & E \\ \sum_{i=1}^k (I_{k-1}, 1:k-1) & E \end{pmatrix} \quad D: k-1 \times k-1 \quad E: k-1 \times 1$$

since Σ_0 symmetric

$$F \Sigma_0 F' = (A \quad B)(D \quad E)(A' \quad I_{k-1}) \quad \text{all the dimensions agree!}$$

$$= ((AD + BE')A' + (AE' + BD')B' \quad AD + BE') \quad B \text{ & } D \text{ are symmetric,}$$

$$= (DA' + EB' \quad D) \quad \text{so } AD + BE' = (DA' + EB')$$

$$= \left(\begin{array}{c|cc} \cdot & \cdots & \cdot \\ \hline \cdot & \sum_{i=1}^k (I_{k-1}, 1:k-1) & \end{array} \right) = \Sigma_0 - Q$$

$$\therefore \Sigma_0 (1:k-1, 1:k-1) = \Sigma_0 (2:k, 2:k)$$

$$\text{cov}(Y_{t-i}, Y_{t-j}) = \text{cov}(Y_{t-1-i}, Y_{t-1-j})$$

$$\therefore \Sigma_0 = F \Sigma_0 F' + Q$$

$$\begin{pmatrix} r(0) & r(1) & \cdots & r(k-1) \\ r(1) & \sum_{i=1}^k (I_{k-1}, 1:k-1) & & \\ \vdots & & \ddots & \\ r(k-1) & & & \sum_{i=1}^k (I_{k-1}, 1:k-1) \end{pmatrix} = \begin{pmatrix} (AD + BE')A' + (AE' + BG')B' + \sigma^2 & AD + BE' \\ DA' + EB' & \sum_{i=1}^k (I_{k-1}, 1:k-1) \end{pmatrix}$$

∴ Only 1st row and column gives non-trivial equation. And they are the same. The rest: $\Sigma_0 (1:k-1, 1:k-1) = \Sigma_0 (1:k-1, 1:k-1)$. **k eqns.**

$$\Sigma_j := \text{cov}(\eta_t, \eta_{t-j}) \quad \forall j \geq 1 \quad k \times k \text{ matrix}$$

$$\Sigma_j = \begin{pmatrix} \mathbb{E}[Y_t Y_{t-j}] & \mathbb{E}[Y_t Y_{t-j-1}] & \cdots \\ \mathbb{E}[Y_{t-1} Y_{t-j}] & \mathbb{E}[Y_{t-1} Y_{t-j-1}] & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix} \text{ ignoring } \mu$$

$$= \begin{pmatrix} r(j) & r(j+1) & \cdots & r(j+k-1) \\ r(j-1) & r(j) & \cdots & r(j+k-2) \\ \vdots & \vdots & \ddots & \vdots \\ r(j-k+1) & r(j-k+2) & \cdots & r(j) \end{pmatrix} \quad k \times k \text{ matrix, not symmetric}$$

$$\Sigma_j = \mathbb{E}[\eta_t \eta_{t-j}'] = \mathbb{E}[(F \eta_{t-1} + W_t) \eta_{t-j}']$$

$$= F \mathbb{E}[\eta_{t-1} \eta_{t-j}'] + \mathbb{E}[W_t \eta_{t-j}'] \quad W_t = (s_1, 0, \dots, 0)$$

$$= F \Sigma_{j-1} \quad \eta_{t-1} \text{ only has } s_{t,j}, s_{t+1,j}, \dots, t \geq t+j$$

$$\Sigma_j = F \Sigma_{j-1} = F^2 \Sigma_{j-2} = \cdots = F^j \Sigma_0. \quad \text{AR(L): geometric.}$$

1) solve for Σ_0 , easier. 2). get all Σ_j .

• Autoregressive Moving Average

$$\text{ARMA}(k, q) \quad Y_t = \alpha + \beta_1 Y_{t-1} + \cdots + \beta_k Y_{t-k} + \epsilon_t + \theta_1 \epsilon_{t-1} + \cdots + \theta_q \epsilon_{t-q}$$

$$(1 - \beta_1 L - \cdots - \beta_k L^k) Y_t = \alpha + (1 + \theta_1 L + \cdots + \theta_q L^q) \epsilon_t$$

$\beta(L) \quad \theta(L)$

$$\beta(L) Y_t = \alpha + \theta(L) \epsilon_t$$

ARMA representation is not unique!

- $Y_t = \beta Y_{t-1} + \epsilon_t = \sum_{i=0}^{\infty} \beta^i \epsilon_{t-i}$ if $|\beta| < 1$
- If $\beta(L) Y_t = \theta(L) \epsilon_t$
then $\alpha(L) \beta(L) Y_t = \alpha(L) \theta(L) \epsilon_t$
- e.g. $Y_t = \epsilon_t \Rightarrow (1 - \beta L) Y_t = (1 - \beta L) \epsilon_t$

$$Y_t = \beta Y_{t-1} + \epsilon_t - \beta \epsilon_{t-1}.$$

• Introduction to Forecast

Y : random var. \hat{Y} : point forecast of Y (non-random)
 $e := Y - \hat{Y}$ forecast error.

Loss function: $L(Y, \hat{Y})$ Special case: $L(Y - \hat{Y}) \equiv L(e)$

e.g. $L(e) = e^2$ quadratic loss $L(e) = |e|$ absolute loss

$$L(e) = \begin{cases} ae^2, & e \geq 0 \\ be^2, & e < 0 \end{cases} \quad a, b \geq 0 \quad \text{asymmetric}$$

e.g. Monopolist sells a product at price p.

Demand is linear $Q = 2a - p$

$$\max \pi(p) \rightarrow p^* = a \quad \pi(p^*) = a^2$$

a is unobserved → forecast $\hat{a} \rightarrow$ set $p = \hat{a}$

$$\pi(\hat{a}) = \hat{a}(2a - \hat{a})$$

$$\text{profit loss} = \pi(a) - \pi(\hat{a}) = a^2 - \hat{a}(2a - \hat{a}) = (\hat{a} - a)^2 \quad \text{quadratic loss.}$$

$$\cdot \text{Risk } R(\hat{Y}) = \mathbb{E}[L(Y, \hat{Y})] \quad \text{risk of a forecast}$$

$$\text{general case: } R(\hat{Y}) = \mathbb{E}[L(Y, \hat{Y})]$$

Def. The optimal (best) point forecast solves $\underset{Y}{\operatorname{argmin}} R(Y)$

$$\cdot L(e) = e^2$$

$$R(\hat{Y}) = \mathbb{E}[(Y - \hat{Y})^2] = \mathbb{E}[Y^2 - 2\hat{Y}Y + \hat{Y}^2] \\ = \mathbb{E}[Y^2] - 2\hat{Y}\mathbb{E}[Y] + \hat{Y}^2$$

min $\rightarrow \hat{Y}^* = \mathbb{E}[Y] \therefore$ optimal forecast under quadratic loss is mean.

$$\cdot L(e) = |e|$$

$$R(\hat{Y}) = \mathbb{E}[|Y - \hat{Y}|] = \int_{-\infty}^{\bar{Y}} (\bar{Y} - y) f_Y(y) dy + \int_{\bar{Y}}^{\infty} (y - \bar{Y}) f_Y(y) dy$$

$$\text{Since } \frac{\partial}{\partial x} \int_{-\infty}^x g(y, x) dy = g(x, x) + \int_{-\infty}^x \frac{\partial}{\partial x} g(y, x) dy$$

$$\frac{\partial}{\partial \bar{Y}} \mathbb{E}[|Y - \hat{Y}|] = \int_{-\infty}^{\bar{Y}} f_Y(y) dy - \int_{\bar{Y}}^{\infty} f_Y(y) dy = F(\bar{Y}) - (1 - F(\bar{Y}))$$

$$\text{F.O.C.: } 0 = F(\bar{Y}) - (1 - F(\bar{Y})) \Rightarrow F(\bar{Y}) = \frac{1}{2} \quad \bar{Y}^* = \text{median}(Y)$$

\therefore optimal forecast under absolute loss is the median.

If we have extra info: $\mathbb{E}[\cdot] \rightarrow \mathbb{E}[\cdot | X]$ $\underset{\hat{Y}}{\operatorname{argmin}} \mathbb{E}[L(Y - \hat{Y}) | X]$

Different loss function \rightarrow different choice of point optimal forecast.

Forecasting Time Series

$$\text{AR(1): } Y_t = \alpha + \beta Y_{t-1} + \varepsilon_t, |\beta| < 1, \varepsilon_t \sim WN(0, \sigma^2)$$

$$\text{Assume: } \mathbb{E}[\varepsilon_t | \varepsilon_{t+1}, \varepsilon_{t+2}, \dots] = 0 \quad \varepsilon_t \text{ is unforecastable}$$

$$\mathbb{E}[\varepsilon_t | \dots] = \mathbb{E}[\varepsilon_t] = 0$$

$$\mathbb{E}[Y_{t+h} | Y_t, Y_{t+1}, \dots] = \mathbb{E}[\alpha + \beta Y_t + \varepsilon_{t+1} | Y_t, \dots] \\ = \alpha + \beta Y_t + \mathbb{E}[\varepsilon_{t+1} | Y_t, \dots] \quad \text{same information.} \\ = \alpha + \beta Y_t + \mathbb{E}[\varepsilon_{t+1} | \varepsilon_t, \dots] \quad \text{since } Y_t \text{ inv. stat.,} \\ = \alpha + \beta Y_t \quad Y_t = (I - \beta L)^{-1}(\alpha + \varepsilon_t)$$

$$\mathbb{E}[Y_{T+h} | Y_T, \dots] = \mathbb{E}[\alpha + \beta Y_{T+h-1} + \varepsilon_{T+h} | Y_T, \dots] \\ = \alpha(I + \beta + \dots + \beta^{h-1}) + \beta^h Y_T + \mathbb{E}[\varepsilon_{T+h} + \beta \varepsilon_{T+h-1} + \dots] \\ = \alpha \frac{1 - \beta^h}{1 - \beta} + \beta^h Y_T + \beta^{h-1} \varepsilon_{T+1} | Y_T \dots]$$

$$\cdot \text{ Forecast error: } Y_{T+h} - \mathbb{E}[Y_{T+h} | Y_T] \\ = Y_{T+h} - \mathbb{E}[\alpha + \beta Y_{T+h-1} + \varepsilon_{T+h} | Y_T] \\ = \varepsilon_{T+h} + \beta \varepsilon_{T+h-1} + \dots + \beta^{h-1} \varepsilon_{T+1}$$

$$\cdot \text{ AR}(k): Y_t = \alpha + \beta_1 Y_{t-1} + \dots + \beta_k Y_{t-k} + \varepsilon_t. \text{ stat. } \varepsilon_t \sim WN(0, \sigma^2)$$

$$\mathbb{E}[\varepsilon_t | \varepsilon_{t+1}, \dots] = 0$$

$$\mathbb{E}[Y_{T+h} | Y_T, Y_{T+1}, \dots] = \alpha + \beta_1 Y_T + \beta_2 Y_{T+1} + \dots + \beta_k Y_{T-k+1} + \mathbb{E}[\varepsilon_{T+h} | Y_T \dots] \\ = \alpha + \beta_1 Y_T + \beta_2 Y_{T+1} + \dots + \beta_k Y_{T-k+1}$$

$$\mathbb{E}[Y_{T+2} | Y_T, Y_{T+1}, \dots] = \alpha + \beta_1 \mathbb{E}[Y_{T+1} | Y_T \dots] + \beta_2 Y_T + \dots + \beta_k Y_{T-k+2} \\ = \alpha + \beta_1(\alpha + \beta_1 Y_T + \dots + \beta_k Y_{T-k+1}) + \beta_2 Y_T + \dots + \beta_k Y_{T-k+2}.$$

For generalized horizon h : either iterate h times (very messy)
or work with vector AR(1) $\eta_t = F\eta_{t-1} + \omega_t$.

$$\text{MA(1): } Y_t = \alpha + \varepsilon_t + \theta \varepsilon_{t-1} \quad \varepsilon_t \sim WN(0, \sigma^2) \quad \mathbb{E}[\varepsilon_t | \varepsilon_{t+1}, \dots] = 0$$

$$|\theta| < 1: \text{ guarantees } \varepsilon_t = (I + \theta L)^{-1}(-\alpha + Y_t) = \sum_{j=0}^{\infty} (-\theta)^j (Y_{t-j} - \alpha)$$

$$\mathbb{E}[Y_{T+h} | Y_T \dots] = \alpha + \mathbb{E}[\varepsilon_{T+h} + \theta \varepsilon_{T+h-1} | Y_T, \dots]$$

$$= \alpha + \mathbb{E}[\varepsilon_{T+h} + \theta \varepsilon_{T+h-1} | \varepsilon_T, \dots]$$

$$= \begin{cases} \alpha + \theta \varepsilon_T & \text{if } h=1 \\ \alpha & \text{if } h>1 \end{cases}$$

$$= \begin{cases} \alpha + \theta \sum_{i=0}^{\infty} (-\theta)^i (Y_{T-i} - \alpha) & , h=1 \\ \alpha & , h>1 \end{cases}$$

$$\text{MA}(q): Y_t = \alpha + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q} \quad \varepsilon_t \sim WN(0, \sigma^2)$$

$$\mathbb{E}[\varepsilon_t | \varepsilon_{t-1}, \dots] = 0 \quad + \text{ invertibility:}$$

$$(I + \theta_1 L + \dots + \theta_q L^q)^{-1} \text{ exists.}$$

$$\mathbb{E}[Y_{T+h} | Y_T, \dots] = \alpha + \mathbb{E}[\varepsilon_{T+h} + \theta_1 \varepsilon_{T+h-1} + \dots + \theta_q \varepsilon_{T+h-q} | \varepsilon_T, \dots] \\ = (\alpha + \theta_1 \varepsilon_T + \dots + \theta_q \varepsilon_{T+q-1}), \quad h \leq q$$

$$h=1: = \alpha + \theta_1 \varepsilon_T + \dots + \theta_q \varepsilon_{T+q-1}$$

$$h=2: = \alpha + \theta_2 \varepsilon_T + \dots + \theta_q \varepsilon_{T+q-2}$$

Moving Average Difference Sequence (MDS)

$$\mathbb{E}[\varepsilon_t | \varepsilon_{t-1}, \varepsilon_{t-2}, \dots] = 0$$

(Generally, $\mathbb{E}[\varepsilon_t | f_{t+1}] = 0$, f_{t+1} : iteration)

MDS \Rightarrow WN, since:

$$1) \mathbb{E}[\varepsilon_t] = \mathbb{E}[\mathbb{E}[\varepsilon_t | \varepsilon_{t-1}, \dots]] = \mathbb{E}[0] = 0$$

$$2) \gamma(h) = \mathbb{E}[\varepsilon_t \varepsilon_{t+h}] = \mathbb{E}[\mathbb{E}[\varepsilon_t \varepsilon_{t+h} | \varepsilon_{t+h-1}, \varepsilon_{t+h-2}, \dots]] \\ h>0 = \mathbb{E}[\varepsilon_t \mathbb{E}[\varepsilon_{t+h} | \varepsilon_{t+h-1}, \varepsilon_{t+h-2}, \dots]] \\ = \mathbb{E}[\varepsilon_t \cdot 0] = 0$$

$$\hookrightarrow \gamma(h) = 0, \forall h \neq 0.$$

Model Selection

(I) Testing.

$$H_0: \text{AR}(k-1) \quad \text{vs.} \quad H_1: \text{AR}(k) \quad \text{i.e. } \beta_k \neq 0 \text{ in } Y_t = \alpha + \beta_1 Y_{t-1} + \dots + \beta_{k-1} Y_{t-k} + \varepsilon_t$$

Reject \rightarrow AR(k). Not Reject \rightarrow AR(k-1)

$$\rightarrow H_0: \text{AR}(k-2) \text{ v.s. } H_1: \text{AR}(k-1) \quad \text{i.e. } \beta_{k-1} \neq 0 \text{ in } Y_t = \alpha + \beta_1 Y_{t-1} + \dots + \beta_{k-1} Y_{t-k+1} + \varepsilon_t$$

Reject \rightarrow AR(k-1). Not Reject \rightarrow AR(k-2)

\rightarrow Repeat, Get AR(k*)

• Multiple Testing: hard to control size.

• Inconsistent: e.g. true AR(1). Test AR(1) vs AR(2)

$H_0: \beta_2 = 0$ vs $H_1: \beta_2 \neq 0$ on 5% level. \rightarrow In 5% cases we reject and choose AR(2).

(II) Information Criteria. Idea: evaluate the fit of AR(k)

and penalize for larger k.

1) Estimate AR(k), get residuals

$$\hat{\varepsilon}_t(k) := Y_t - \hat{\alpha}(k) - \hat{\beta}_1(k) Y_{t-1} - \dots - \hat{\beta}_k(k) Y_{t-k}$$

$$\hat{\varepsilon}^2(k) := \frac{1}{T} \sum_t \hat{\varepsilon}_t^2(k) \quad \text{sum of squared residuals.}$$

2) Choose

$$\hat{k} = \underset{k \in \bar{k}}{\operatorname{argmin}} \left(\ln \hat{\varepsilon}^2(k) + \underbrace{(1+k)}_{\text{penalty}} \underbrace{\ln(T)}_{\text{# parameters in AR(k)}} \right)$$

$\bar{k} < \infty$: upper limit on (known) order of AR

$$\cdot g(T) = \begin{cases} \frac{2}{T} AIC & (\text{Akaike Information Criterion}) \\ \frac{\ln T}{T} BIC & (\text{Bayes / Schwarz Inf. Crit.}) \end{cases}$$

$$\frac{2}{T} < \frac{\ln T}{T} \Rightarrow AIC \text{ chooses (weakly) longer model than BIC}$$

BIC: Bayes Rule. Good: find true model. (Unreliable if true model is outside the considered class).

AIC: min forecast error. Goal: find the best forecast model.

- Def. \hat{k} is (weakly) consistent if $\overline{P}(\hat{k} = k_0) \xrightarrow{T \rightarrow \infty} 1$. i.e. true order.
- BIC is consistent. AIC: $\overline{P}(\hat{k} \geq k_0) \rightarrow 1$ as $T \rightarrow \infty$. can choose larger model.
- Lemma: If $g(T) \rightarrow 0$, then $\overline{P}(\hat{k} \geq k_0) \xrightarrow{T \rightarrow \infty} 1$.

Pf. $S_j := (\ln \hat{\sigma}^2(j)) + (4+j)g(T)$

$$\overline{P}(\hat{k} \geq k_0) = \overline{P}(\min(S_{k_0}, S_{k_0+1}, \dots, S_k) < \min(S_0, S_1, \dots, S_{k_0-1})) ?$$

$$\geq \overline{P}(S_{k_0} < \min(S_0, S_1, \dots, S_{k_0-1}))$$

$$= \overline{P}((\ln \hat{\sigma}^2(k_0) + (4+k_0)g(T)) < (\ln \hat{\sigma}^2(j) + (4+j)g(T)), \forall j=0, \dots, k_0-1)$$

$$= 1 - \overline{P}((\ln \hat{\sigma}^2(k_0) + (4+k_0)g(T)) \geq (\ln \hat{\sigma}^2(j) + (4+j)g(T)), \text{for some } j \in \{0, \dots, k_0-1\})$$

$$\geq 1 - \sum_{j=0}^{k_0-1} \overline{P}((\ln \hat{\sigma}^2(k_0) + (4+k_0)g(T)) \geq (\ln \hat{\sigma}^2(j) + (4+j)g(T)))$$

$$= 1 - \sum_{j=0}^{k_0-1} \overline{P}\left(\ln \frac{\hat{\sigma}^2(j)}{\hat{\sigma}^2(k_0)} - (k_0-j)g(T) \leq 0\right)$$

$$\hat{\sigma}^2(j) = \frac{1}{T} \sum_t (Y_t - \hat{\alpha} Y_{t-1} - \hat{\beta}_1 Y_{t-2} - \dots - \hat{\beta}_{j-1} Y_{t-j})^2$$

$$\hat{\sigma}^2(j) \xrightarrow{T \rightarrow \infty} \mathbb{E}[(Y_t - \hat{\alpha} Y_{t-1} - \hat{\beta}_1 Y_{t-2} - \dots - \hat{\beta}_{j-1} Y_{t-j})^2]$$

$$\text{where } \{\hat{\alpha}, \hat{\beta}_1, \hat{\beta}_2, \dots, \hat{\beta}_{k_0-1}\} = \underset{\{\alpha, \beta_1, \beta_2, \dots, \beta_{k_0-1}\}}{\operatorname{argmin}} \mathbb{E}[(Y_t - \alpha - \beta_1 Y_{t-1} - \dots - \beta_{k_0-1} Y_{t-k_0})^2]$$

True model $k_0 > j$ since $j \in \{0, \dots, k_0-1\}$, then:

$$\underset{\{\alpha, \beta_1, \dots, \beta_{k_0-1}\}}{\operatorname{argmin}} \mathbb{E}[(Y_t - \alpha - \beta_1 Y_{t-1} - \dots - \beta_{k_0-1} Y_{t-k_0})^2]$$

$$\Rightarrow \alpha = \hat{\alpha}, \beta_1 = \hat{\beta}_1, \dots, \beta_{k_0-1} = \hat{\beta}_{k_0-1}$$

$$\rightarrow \mathbb{E}[S_j] = 0$$

$\hat{\sigma}^2(k_0) \xrightarrow{T \rightarrow \infty} 0^2 < \hat{\sigma}^2(j)$ (since True model has k_0 lags, we cannot fit as good as it with only j lags)

$$\therefore \ln \frac{\hat{\sigma}^2(j)}{\hat{\sigma}^2(k_0)} \rightarrow \ln \frac{\hat{\sigma}^2(j)}{0^2} > 0, (k_0-j)g(T) \rightarrow 0 \text{ as } T \rightarrow \infty$$

$$\therefore \overline{P}(\ln \frac{\hat{\sigma}^2(j)}{\hat{\sigma}^2(k_0)} - (k_0-j)g(T) \leq 0) \rightarrow 0 \text{ as } T \rightarrow \infty$$

$$\therefore \overline{P}(\hat{k} \geq k_0) \rightarrow 1 \text{ as } T \rightarrow \infty \text{ if } g(T) \rightarrow 0 \text{ as } T \rightarrow \infty$$

• Lemma: If $Tg(T) \xrightarrow{T \rightarrow \infty} \infty$, then $\overline{P}(\hat{k} \leq k_0) \rightarrow 1$ as $T \rightarrow \infty$.

similar proof ideas with some modifications.

Verification: AIC: $g(T) = \frac{2}{T} \rightarrow 0$, $Tg(T) = 2 \rightarrow \infty$, so $\overline{P}(\hat{k} \geq k_0) \rightarrow 1$

BIC: $g(T) = \frac{\ln T}{T} \rightarrow 0$, $Tg(T) = \ln T \rightarrow \infty$, so $\overline{P}(\hat{k} = k_0) \rightarrow 1$ (consistent)

• Implementation: AR(1) $\hat{\epsilon}_1 = Y_1 - \hat{\alpha} Y_0$ unobservable
then $\hat{\epsilon}_1$ cannot calculate.

AR(2) $\hat{\epsilon}_2 = Y_2 - \hat{\alpha}_1 Y_1 - \hat{\beta}_1 Y_0$ unobservable

\rightarrow start with $t = \hat{k} + 1$ T = restricted sample

(so all models have the same set of residuals).

• Vector Autoregression (VAR)

$$Y_t = X + \varphi_1 Y_{t-1} + \dots + \varphi_k Y_{t-k} + \varepsilon_t \quad \text{VAR}(k)$$

$$Y_t = \begin{pmatrix} Y_{t1} \\ Y_{t2} \\ \vdots \\ Y_{tn} \end{pmatrix} \quad \text{purposes: } \begin{array}{l} \textcircled{1} \text{ Forecast econ time series.} \\ \textcircled{2} \text{ Design and evaluate econ. models} \end{array}$$

$\textcircled{3} \text{ Evaluate the consequences of alternative policy actions.}$

$$\mathbb{E}[S_t] = \bar{0} \quad \& \quad \mathbb{E}[S_t S_t'] = \begin{cases} \bar{0}, t+s \text{ nxn matrix of } D_s \\ (\Omega = \bar{0}) \quad \bar{0}, t=s \text{ symmetric, p.d.} \end{cases}$$

$$\Leftrightarrow \varepsilon_t \sim WN(0, \bar{0})$$

• Can also write eqns for each coordinate of ε_t :

$$\begin{aligned} Y_{it} &= \alpha_i + \varphi_1^{ii} Y_{i,t-1} + \dots + \varphi_p^{ii} Y_{i,t-p} & k \text{ lags of each coordinate} \\ &\quad + \varphi_2^{ii} Y_{i,t-2} + \dots + \varphi_p^{in} Y_{i,t-p} \\ &\quad + \dots \\ &\quad + \varphi_k^{ii} Y_{i,t-k} + \dots + \varphi_k^{in} Y_{i,t-k} + \varepsilon_{it} \\ \varphi_p^{ij} &= \varphi_p[i, j] \end{aligned}$$

In lag Operator Notation:

$$(I - \varphi_1 L - \dots - \varphi_k L^k) Y_t = \alpha + \varepsilon_t$$

$$= \varphi(L) Y_t = \alpha + \varepsilon_t \quad \varphi(L): \text{lag operator nxn matrix}$$

$$\varphi(L)[i, j] = S_{ij} - \varphi_1^{ij} L - \dots - \varphi_k^{ij} L^k$$

$$S_{ij} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

Find $\mathbb{E}[Y_t]$: If Y_t is covar. stat, then

$$M := \mathbb{E}[Y_t] = \mathbb{E}[\alpha + \varphi_1 Y_{t-1} + \dots + \varphi_k Y_{t-k} + \varepsilon_t]$$

$$= \alpha + \varphi_1 M + \dots + \varphi_k M + 0$$

$$\alpha = (I - \varphi_1 - \dots - \varphi_k) M$$

plug back α : $Y_{t-M} = \varphi_1(Y_{t-1} - M) + \dots + \varphi_k(Y_{t-k} - M) + \varepsilon_t$.

"deviations from the mean" form:

$$Z_t := \begin{pmatrix} Y_{t-M} \\ Y_{t-1} - M \\ \vdots \\ Y_{t-k+1} - M \end{pmatrix}_{nk \times 1} \quad Z_t = F Z_{t-1} + V_t \quad F = \begin{pmatrix} I_n & & & \\ & I_{n(k-1)} & & \\ & & \ddots & \\ & & & I_{n(k-1)} \end{pmatrix}_{nk \times nk} \quad V_t = \begin{pmatrix} \varepsilon_t \\ 0 \\ \vdots \\ 0 \end{pmatrix}_{nk \times 1}$$

$$nk \times 1$$

$$E[V_t] = 0 \quad E[V_t V_t'] = 0_{nk \times nk}$$

$$E[V_t V_t'] = \begin{pmatrix} 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{pmatrix}_{nk \times nk}$$

Need all the eigenvalues to be $| \cdot | < 1$ for stationarity.

i.e. need $F^t \rightarrow \infty$ as $t \rightarrow \infty$)

$$|F - \lambda I| = \begin{vmatrix} \varphi_1 - \lambda I_n & \varphi_2 & \dots & \varphi_k & \varphi_k \\ I_n & -\lambda I_n & \dots & 0_{nxn} & 0_{nxn} \end{vmatrix}$$

add last n-dim column

$$0_{nxn} \quad I_n \quad \dots \quad 0_{nxn} \quad 0_{nxn}$$

$\frac{1}{\lambda}$ to the previous n-dim column

$$\dots \quad \dots \quad \dots \quad \dots \quad \dots$$

$$0_{nxn} \quad 0_{nxn} \quad I_n - \lambda I_n$$

$$= \begin{vmatrix} \varphi_1 - \lambda I_n & \varphi_2 & \dots & \varphi_k + \frac{1}{\lambda} \varphi_k & \varphi_k \\ I_n & -\lambda I_n & \dots & 0 & 0 \\ 0 & I_n & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 0 \end{vmatrix}$$

keep on doing this

$$\dots \quad \dots \quad \dots \quad \dots \quad \dots$$

$$0 \quad 0 \quad \dots \quad 0 \quad 0$$

$$\downarrow \quad 0 \quad 0 \quad \dots \quad 0 \quad -\lambda I_n$$

turn it to a up-right triangle matrix.

$$= \begin{vmatrix} \varphi_1 - \lambda I_n + \frac{1}{\lambda} \varphi_2 + \frac{1}{\lambda^2} \varphi_3 + \cdots + \frac{1}{\lambda^{k-1}} \varphi_k & \varphi_1 \varphi_2 & \cdots & \cdots & \varphi_k \\ 0 & -\lambda I_n & \cdots & \cdots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \cdots & \cdots & -\lambda I_n \end{vmatrix}$$

$$=(-\lambda)^{n(k-1)} \left| (\varphi_1 - \lambda I_n + \frac{1}{\lambda} \varphi_2 + \frac{1}{\lambda^2} \varphi_3 + \cdots + \frac{1}{\lambda^{k-1}} \varphi_k) \right|$$

$$=(-\lambda)^{n(k-1)} (-\lambda)^n \left| I_n - \frac{1}{\lambda} \varphi_1 - \frac{1}{\lambda^2} \varphi_2 - \cdots - \frac{1}{\lambda^{k-1}} \varphi_k \right| \xrightarrow[n \times n]{\text{pull out } -\lambda \text{ from an } (n-1) \times (n-1)}$$

$$= 0 \cdot \leftarrow \det(F - \lambda I) = 0$$

Eigenvalues of F solves $|I_n - \frac{1}{\lambda} \varphi_1 - \cdots - \frac{1}{\lambda^{k-1}} \varphi_k| = 0$
or $|I_n - z \varphi_1 - \cdots - z^{k-1} \varphi_k| = 0, z = \frac{1}{\lambda}$.

Need: $|\lambda| < 1 \Leftrightarrow |z| > 1$.

• Vector MA(∞) Representation:

$$z_t = F z_{t-1} + v_t$$

$$(I - FL) z_t = v_t$$

$$\begin{aligned} z_t &= (I - FL)^{-1} v_t \\ &= \sum_{j=0}^{\infty} F^j v_{t-j}, F^j = F \cdot F \cdots F \end{aligned}$$

Another Way to get VMA(∞): iterated back-substitution.

$$\begin{aligned} z_t &= F z_{t-1} + v_t = F(F z_{t-2} + v_{t-1}) + v_t \\ &= F^2 z_{t-2} + v_t + F v_{t-1} = \cdots = \underbrace{F^t z_{t-t}}_{\rightarrow 0 \text{ as } t \rightarrow \infty} + v_t + F v_{t-1} + \cdots + F^{t-1} v_{t-1} \\ &= \sum_{j=0}^{\infty} F^j v_{t-j} \end{aligned}$$

Back to y_t . $S := (I_n, 0_{n \times (n-k)})$

$$S z_t = y_t - \mu$$

$$S' S z_t = \varepsilon_t$$

$$S' S z_t = \begin{pmatrix} I_n \\ 0_{(n-k) \times n} \end{pmatrix} \varepsilon_t = \begin{pmatrix} \varepsilon_t \\ 0 \\ \vdots \\ 0 \end{pmatrix} = v_t$$

$$\begin{aligned} y_t - \mu = S z_t &= S \sum_{j=0}^{\infty} F^j v_{t-j} = S \sum_{j=0}^{\infty} F^j S' S z_{t-j} = \sum_{j=0}^{\infty} S F^j S' S z_{t-j} \\ &= \sum_{j=0}^{\infty} \psi_j \varepsilon_{t-j} \quad \text{where } \psi_j = S F^j S' \end{aligned}$$

$\psi = S F^j S' = n \times n \text{ corner of } F^j$ (upper-left block)

$$\psi_0 = S S'$$

• VMA(∞) is not unique.

Let $H = n \times n$ nonsingular matrix. $u_t = H \varepsilon_t$

Then: $E[u_t] = H E[\varepsilon_t] = 0$.

$$E[u_t u_t'] = H E[\varepsilon_t \varepsilon_t'] H' = \begin{cases} 0, & t \neq s \\ H \Omega H', & t = s \end{cases} \Rightarrow u_t \sim WN(0, H \Omega H')$$

$$y_t - \mu = \sum_{j=0}^{\infty} \psi_j \varepsilon_{t-j} = \sum_{j=0}^{\infty} \psi_j H H' H \varepsilon_{t-j} = \sum_{j=0}^{\infty} \psi_j H' \underbrace{H \varepsilon_{t-j}}_{\tilde{\varepsilon}_j} = \sum_{j=0}^{\infty} \tilde{\psi}_j \tilde{\varepsilon}_j \quad (\star)$$

Another VMA(∞) representation.

Cholesky Decomposition:

$\Omega = L L'$, L = lower triangle matrix

$$H = L^T, u_t = H \varepsilon_t, \text{Var}(u_t) = H \Omega H' = L^T (L L') L^T = I_n$$

Impulse Response Functions

$$y_t = \alpha + \varphi_1 y_{t-1} + \cdots + \varphi_k y_{t-k} + \varepsilon_t, \varepsilon_t \sim WN(0, \Omega)$$

Estimate: OLS (eqn by eqn)

y_t on constants $y_{t-1}, \dots, y_{t-k}, y_{t-1}, \dots, y_{t-k}, \dots, y_{t-1}, \dots, y_{t-k}$.

If $\varepsilon_t \sim N(0, \Omega)$, then MLE \Leftrightarrow OLS

$$\hat{\Omega} = \frac{1}{T} \sum_t \hat{\varepsilon}_t \hat{\varepsilon}_t'$$

OLS: consistent, asymptotically normal (assuming stationarity)

But, hard to interpret $n \times n$ matrices of coefficients.

⇒ Impulse Response Functions.

$$\text{IRFs: } \left\{ \frac{\partial y_{t+s}}{\partial \varepsilon_{jt}} \right\}_{s=0,1,\dots, n^2 \text{ IRFs. } i \in \{1, \dots, n\}, j \in \{1, \dots, n\}}$$

• VMA(∞) representation: $y_t = \mu + \sum_{i=0}^{\infty} \psi_i \varepsilon_{t-i}$

$$y_{t+s} = \mu + \sum_{i=0}^{\infty} \psi_i \varepsilon_{t+s-i} \quad \therefore \frac{\partial y_{t+s}}{\partial \varepsilon_{jt}} = \psi_s(i, j) \quad (\star)$$

Problem: 1) VMA(∞) not unique

⇒ ε_{jt} and ε_{jt}' can be correlated: if ε_{jt} changes, then ε_{jt}' can also change. But in (\star) , we do not allow for such change.

Solution: Orthogonalize shocks.

Let $u_t = H \varepsilon_t$ s.t. $\text{Var}(u_t) = H \Omega H' = I_n$

e.g. Cholesky decomposition: $u_t = L^t$ where $L L' = \Omega$.
→ then, u_{jt} and u_{jt}' are uncorrelated.

$$(\star) \Rightarrow \frac{\partial y_{t+s}}{\partial u_{jt}} = \sum_{i=1}^{\infty} \psi_s(i, j) L^i(j, j)$$

$$\text{Since } y_t = \mu + \sum_{i=0}^{\infty} \psi_i \varepsilon_{t-i} = \mu + \sum_{i=0}^{\infty} \psi_i L^i u_{t-i}.$$

Work with $\left\{ \frac{\partial y_{t+s}}{\partial u_{jt}} \right\}$ (n^2 plots).

How to estimate IRFs:

1) Estimate VAR by OLS

$$\rightarrow \left\{ \begin{array}{c} \hat{\varphi}_1, 1=1,2,\dots,k \\ \hat{\Omega} \end{array} \right.$$

2) Invert to get VMA(∞) $\rightarrow \hat{\psi}_s, s=0,1,2,\dots$

3) Find H s.t. $H \hat{\Omega} H' = I_n$. e.g. Cholesky decomposition

$$H = L^T, L L' = \hat{\Omega}$$

$$4) \text{IRFs: } \hat{\psi}_s L$$

Standard Errors:

i). Delta Method: $\hat{\psi}_s, \hat{\Omega} - \text{asymptotically normal.}$

$$y_t = \alpha + \varphi_1 y_{t-1} + \cdots + \varphi_k y_{t-k} + \varepsilon_t$$

$$= \alpha + \varphi_1 (\alpha + \varphi_1 y_{t-2} + \cdots + \varphi_k y_{t-k-1} + \varepsilon_{t-1}) + \varphi_2 y_{t-2} + \cdots + \varphi_k y_{t-k} + \varepsilon_t$$

$$= \varepsilon_t + \varphi_1 \varepsilon_{t-1} + (\varphi_1^2 + \varphi_2) \varepsilon_{t-2} + \cdots$$

$$\Rightarrow \hat{\psi}_0 = I_n \quad L \text{ is a function of } \hat{\Omega}.$$

$$\hat{\psi}_1 = \varphi_1$$

→ use delta-method again.

$$\hat{\psi}_2 = \varphi_1^2 + \varphi_2$$

Many non-linear Transformation:

→ imprecise estimation of $\hat{\phi}_1, \hat{\phi}_2$ are exacerbated.

→ Bootstrap.

II). Bootstrap:

(1). Estimate VAR by OLS → $\hat{\alpha}, \hat{\phi}_1, \dots, \hat{\phi}_k, \hat{\sigma}$

→ residuals: $\hat{\epsilon}_t := Y_t - \hat{\alpha} - \hat{\phi}_1 Y_{t-1} - \dots - \hat{\phi}_k Y_{t-k}, t=k+1, \dots, T$

(2). Invert to get VMA(∞), IRFs.

(3). For $b=1, \dots, B$:

(a) Form $Y_t^b = \hat{\alpha} + \hat{\phi}_1 Y_{t-1}^b + \dots + \hat{\phi}_k Y_{t-k}^b + \hat{\epsilon}_t^b$.

$\hat{\epsilon}_t^b$ is randomly sampled (with replacement) from $\{\hat{\epsilon}_t\}_{t=k+1}^T$

(b) Estimate $\beta(\gamma)$ by OLS → $\hat{\alpha}^b, \hat{\phi}_1^b, \dots, \hat{\phi}_k^b, \hat{\sigma}^b$.

(c). Invert to get VMA(∞), IRFs.

(4). For each i, j, s . Sort $IRF^{(i,j,s)}$ in ascending order.

$IRF^{(i,j,s)} \leq \dots \leq IRF^{(i,j,s)}$.

(5). Form a confidence interval.

$[IRF^{(\lfloor B\alpha/2 \rfloor)}(i,j,s), IRF^{(\lceil B(1-\alpha/2) \rceil)}(i,j,s)]$ (Efron's Interval)
 $\frac{\alpha}{2}$ and $1 - \frac{\alpha}{2}$

Structural VAR

$B_0 Y_t = C + B_1 Y_{t-1} + \dots + B_k Y_{t-k} + V_t, V_t \sim WN(0, D)$

$B_0 = \begin{pmatrix} 1 & -a_{12} & \dots & -a_{1n} \\ -a_{21} & 1 & \dots & -a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -a_{n1} & -a_{n2} & \dots & 1 \end{pmatrix}$ is on the main diagonal.
 B_0 describes contemporaneous equilibrium relationships.

e.g. supply & demand.

$$S_t = C_1 + a_{12} d_t + \dots + V_t$$

$$d_t = C_2 + a_{21} S_t + \dots + V_{2t}$$

parameters: $n + kn^2 + n(n-1) + \frac{1}{2}n(n+1)$
 $C \quad B_1, \dots, B_k \quad B_0 \quad D$

However, in VAR: $Y_t = \alpha + \phi_1 Y_{t-1} + \dots + \phi_k Y_{t-k} + \epsilon_t$

parameters: $n + kn^2 + \frac{1}{2}n(n+1)$
 $\alpha \quad \phi_1, \dots, \phi_k \quad 0$

⇒ SVAR has more parameter than VAR.

⇒ Cannot, in general, identify SVAR from VAR.

Solution: impose extra restriction on SVAR:

1). B_0 is lower triangular

$$B_0 = \begin{pmatrix} 1 & 0 & \dots & 0 \\ -a_{12} & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ -a_{n1} & -a_{n2} & \dots & 0 \end{pmatrix} \frac{1}{2}n(n-1)$$

Idea: order by the speed of reaction. e.g.

Y_{it} = GDP (slowest to react). Y_{st} = inflation (modest to react)

Y_{rt} = interest rate (fastest to react)

2) $E[V_t V_t'] = D$ is diagonal. $\textcolor{red}{\checkmark}$

Idea: correlation is already captured by B_0 , via simultaneous equations).

parameters: $n + kn^2 + \frac{1}{2}n(n+1)$ Some in VAR and SVAR with restrictions 1), 2).

$D = LL' = A G A'$ \nwarrow LDL decomposition, $L = AG^{-1}$

Cholesky decomposition.

G-diag, A-lower triag with 1 on the main diag.

→ $D = (\text{diag}(L))^2, B_0^{-1} = L(\text{diag}(L))^{-1}$

Brownian Motion

Let $U_t \sim \text{iid } (0, \sigma^2), t=1, \dots, T$

$$S(\gamma) = \frac{1}{\sqrt{T}} \sum_{i=1}^{\lfloor T\gamma \rfloor} U_i \quad \gamma \in [0, 1]$$

e.g. $T=101, \gamma=\frac{1}{2}, [\frac{T}{2}] = 50$

$$[T\gamma] = \max \{n \in \mathbb{Z} \text{ s.t. } n \leq \gamma\} \quad S(\gamma) = \frac{1}{\sqrt{101}} \sum_{i=1}^{50} U_i$$

$$[T\gamma] \in [T\gamma-1, T\gamma] \quad \frac{[T\gamma]}{T} \in [\gamma - \frac{1}{T}, \gamma] \rightarrow \gamma \text{ as } T \rightarrow \infty$$

$$S(\gamma) = \frac{\sqrt{[T\gamma]}}{\sqrt{T}} \cdot \frac{1}{\sqrt{[T\gamma]}} \sum_{i=1}^{[T\gamma]} U_i \xrightarrow[T \rightarrow \infty]{d} N(0, \sigma^2)$$

$$S(\gamma) \xrightarrow{d} \tilde{P} N(0, \sigma^2) = N(0, \gamma\sigma^2)$$

LT_{Tγ} common errors

$$\bullet \gamma_1 \leq \gamma_2 \quad \begin{pmatrix} S(\gamma_1) \\ S(\gamma_2) \end{pmatrix} = \begin{pmatrix} \frac{[T\gamma_1]}{\sqrt{T}} \cdot \frac{1}{\sqrt{[T\gamma_1]}} \sum_{i=1}^{[T\gamma_1]} U_i \\ \frac{[T\gamma_2]}{\sqrt{T}} \cdot \frac{1}{\sqrt{[T\gamma_2]}} \sum_{i=1}^{[T\gamma_2]} U_i \end{pmatrix} \xrightarrow[T \rightarrow \infty]{d} N \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} \gamma_1 \sigma^2 & \gamma_1 \sigma^2 \\ \gamma_2 \sigma^2 & \gamma_2 \sigma^2 \end{pmatrix} \right)$$

Generalize:

$$\begin{pmatrix} S(\gamma_1) \\ S(\gamma_2) \\ \vdots \\ S(\gamma_k) \end{pmatrix} \xrightarrow{d} N \left(\begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \begin{pmatrix} \sigma^2 \gamma_1 & \sigma^2 \min\{\gamma_1, \gamma_2\} & \dots & : \\ \sigma^2 \min\{\gamma_1, \gamma_2\} & \sigma^2 \gamma_2 & \dots & : \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma^2 \gamma_k \end{pmatrix} \right)$$

However: our goal is to find something similar for all $\gamma \in [0, 1]$
(infinite, uncountable set of points γ)

Functional CLT

• Def. The Brownian motion or Wiener process is a stochastic process $W(t)$ s.t:

1) $W(0) = 0 \Rightarrow$ For $0 \leq t_1 \leq t_2 \leq \dots \leq t_k$, increments $W(t_{i+1}) - W(t_i), W(t_2) - W(t_1), \dots, W(t_k) - W(t_1)$ are independent.

2) Increments are Gaussian, $W(t) - W(s) \sim N(0, t-s)$ for $t > s$

3) $W(t)$ is almost surely continuous i.e. W has continuous paths $\text{for } t \geq 0$

• Properties of $W(t)$:

$$1) W(t) = W(t) - W(0) \sim N(0, t-0) = N(0, t)$$

$$\mathbb{E}[W(t)] = 0, \mathbb{E}[W^2(t)] = \text{Var}(W(t)) = t$$

$$\text{density } f_{W(t)}(x) = \frac{1}{\sqrt{2\pi t}} \exp(-\frac{x^2}{2t})$$

$$2) \text{cov}(W(s), W(t)) = \min\{t, s\}.$$

proof: Let $t > s$. then:

$$\text{cov}(W(s), W(t)) = \mathbb{E}[(W(s)W(t))] = \mathbb{E}[(W(t) - W(s) + W(s))W(t)]$$

$$= \mathbb{E}[(W(t) - W(s))W(t)] + \mathbb{E}[W^2(t)] = \mathbb{E}[W(t) - W(s)] \mathbb{E}[W(s)] + s = s = 0$$

$$3) \text{Let } t \geq s. \quad \overbrace{0}^s \overbrace{s}^t \overbrace{t} \rightarrow$$

$$\mathbb{E}[W(s)|W(t), t \geq s] = \mathbb{E}[W(t) - W(s) + W(s)|W(t), t \geq s]$$

$$= \mathbb{E}[W(t) - W(s)] + W(s) = W(s). W(t) \text{ is a martingale}$$

• Wiener Process as a limit of random walk.

Let $X_1, X_2, \dots, \sim \text{iid } N(0, 1)$. $\gamma \in [0, 1]$

$$S_T(\gamma) = \frac{1}{\sqrt{T}} \sum_{i=1}^{\lfloor T\gamma \rfloor} X_i \quad \text{where } l(x) = \max \{z \in \mathbb{Z} \text{ s.t. } n \leq x\}$$

$$\bullet S_T(\gamma) \stackrel{d}{\sim} N(0, \frac{\lfloor T\gamma \rfloor}{T}) \approx N(0, \gamma) \quad \text{as } \frac{\lfloor T\gamma \rfloor}{T} \in [\gamma - \frac{1}{T}, \gamma]$$

$$\bullet S_T(\gamma) - S_T(s) = \frac{1}{\sqrt{T}} \sum_{i=\lfloor Ts \rfloor + 1}^{\lfloor T\gamma \rfloor} X_i \stackrel{d}{\sim} N(0, \frac{\lfloor T\gamma \rfloor - \lfloor Ts \rfloor}{T}) \approx N(0, \gamma - s)$$

• Increments $0 \leq t_1 \leq t_2 \leq \dots \leq t_k : S_{t_1} - S_{t_0}, S_{t_2} - S_{t_1}, \dots \dots$

$S_{t_{k+1}} - S_{t_{k+2}}$ are independent. They do not share common X_i 's.

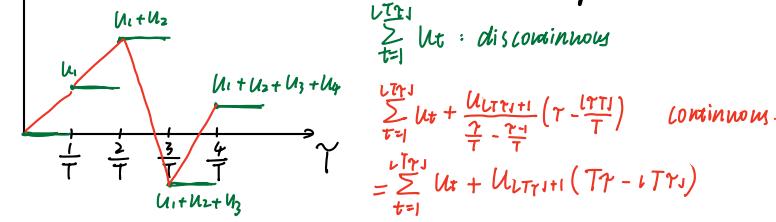
As $T \rightarrow \infty$, $S_T(\cdot)$ approaches $W(\cdot)$.

Theorem: (Functional CLT / Donsker's theorem)

Let $u_i \sim \text{iid } (0, \sigma^2)$. Then: $\frac{1}{\sqrt{T}} \sum_{i=1}^{\lfloor T\gamma \rfloor} u_i \xrightarrow{T \rightarrow \infty} \sigma W(\gamma), \gamma \in [0, 1]$

↳ For r.v., we say $Y_n \xrightarrow{d} Y$ as $n \rightarrow \infty$ if \forall cont. & bounded f.n $f: \mathbb{R} \rightarrow \mathbb{R}$, s.t. $\mathbb{E}[f(Y_n)] \rightarrow \mathbb{E}[f(Y)]$ as $n \rightarrow \infty$

Work with continuous functions!



• Def. Functional $F: C[0, 1] \rightarrow \mathbb{R}$

$$\text{Sup-norm } d_\infty(g_1, g_2) = \sup_{\gamma \in [0, 1]} |g_1(\gamma) - g_2(\gamma)|$$

Benefit of d_∞ : If $g_n \rightarrow g$ in d_∞ and $g_n \in C[0, 1]$, then $g \in C[0, 1]$.

• Continuity: F is continuous if $\forall \epsilon > 0, \exists \delta > 0$, s.t. if $g_1, g_2 \in C[0, 1]$ and $d_\infty(g_1, g_2) < \delta$, then $|F(g_1) - F(g_2)| < \epsilon$

• Boundedness: F is bounded if $\exists M > 0$, s.t. $\forall g \in C[0, 1]$,

$$|F(g)| \leq M \|g\|_\infty \equiv M \sup_{\gamma \in [0, 1]} |g(\gamma)|.$$

e.g. 1) $F(g) = g(x^*)$, $x^* = \text{fixed}$ 2) $F(g) = \int_A g(x) dx$, A, B fixed

• Unit Root Asymptotics

$$\begin{cases} Y_t = \beta Y_{t-1} + \varepsilon_t, |\beta| < 1 \text{ stat. AR(1)} & \text{v.s.} \\ Y_t = Y_{t-1} + \varepsilon_t, (\text{i.e. } \beta = 1) \text{ unit root.} & \varepsilon_t \sim \text{iid } (0, \sigma^2) \end{cases}$$

They have very different asymptotic behavior.

• $|\beta| < 1$: $Y_t = \beta Y_{t-1} + \varepsilon_t = \sum_{i=0}^{\infty} \beta^i \varepsilon_{t-i}$ MA(∞) representation.

$$1) \frac{1}{\sqrt{T}} Y_{\lfloor T\gamma \rfloor} = \frac{1}{\sqrt{T}} \sum_{i=0}^{\infty} \beta^i \varepsilon_{\lfloor T\gamma \rfloor - i} \xrightarrow{T \rightarrow \infty} 0 \quad \text{as } T \rightarrow \infty$$

$$\bullet \mathbb{E} \left[\frac{1}{\sqrt{T}} \sum_{i=0}^{\infty} \beta^i \varepsilon_{\lfloor T\gamma \rfloor - i} \right] = 0$$

$$\bullet \text{Var} \left[\frac{1}{\sqrt{T}} \sum_{i=0}^{\infty} \beta^i \varepsilon_{\lfloor T\gamma \rfloor - i} \right] = \frac{1}{T} \text{Var}(Y_T) = \frac{1}{T} \frac{\sigma^2}{1-\beta^2} \rightarrow 0 \quad \text{as } T \rightarrow \infty$$

$$2) \bar{Y} := \frac{1}{T} \sum_{t=1}^T Y_t \xrightarrow{T \rightarrow \infty} \mathbb{E}[Y_T] = 0$$

$$3) \text{OLS Estimate: } \hat{\beta} = \frac{\frac{1}{T} \sum_{t=1}^T Y_t Y_{t-1}}{\frac{1}{T} \sum_{t=1}^T Y_{t-1}^2} = \beta + \frac{\frac{1}{T} \sum_{t=1}^T \varepsilon_t Y_{t-1}}{\frac{1}{T} \sum_{t=1}^T Y_{t-1}^2}$$

$$\therefore \bar{Y}(\hat{\beta} - \beta) = \frac{\frac{1}{T} \sum_{t=1}^T \varepsilon_t Y_{t-1}}{\frac{1}{T} \sum_{t=1}^T Y_{t-1}^2} \xrightarrow{d} N(0, \frac{\sigma^4}{1-\beta^2})$$

Since: $\mathbb{E}[\varepsilon_t Y_{t-1}] = 0$

$$\mathbb{E}[\varepsilon_t^2 Y_{t-1}^2] = \mathbb{E}[\varepsilon_t^2] \mathbb{E}[Y_{t-1}^2] = \sigma^2 \cdot \frac{\sigma^2}{1-\beta^2} \quad \text{since independent} \rightarrow \mathbb{E}[\varepsilon_t Y_{t-1} Y_{t-1}] = \mathbb{E}[\varepsilon_t] \mathbb{E}[Y_{t-1} Y_{t-1}] = 0.$$

Therefore, $\bar{Y}(\hat{\beta} - \beta) \xrightarrow{d} N(0, 1 - \beta^2)$

$$4) t\text{-stat: } (\hat{\beta} - \beta) / \text{sd}(\hat{\beta}) \xrightarrow{d} N(0, 1)$$

• $\beta = 1$: $Y_t = Y_{t-1} + \varepsilon_t = Y_0 + \sum_{s=1}^t \varepsilon_s$ Results are the same if Assume $Y_0 = 0$, then $Y_t = \sum_{s=1}^t \varepsilon_s$ $Y_0 = \text{const. or } Y_0 = \bar{\varepsilon}_0(\bar{Y}_T)$ i.e.

$$1) \frac{1}{\sqrt{T}} Y_{\lfloor T\gamma \rfloor} = \frac{1}{\sqrt{T}} \sum_{s=1}^{\lfloor T\gamma \rfloor} \varepsilon_s \xrightarrow{T \rightarrow \infty} \sigma W(\gamma) \text{ by FCLT} \quad \frac{Y_T}{\sqrt{T}} \xrightarrow{T \rightarrow \infty} 0$$

$$2) \frac{1}{\sqrt{T}} \bar{Y} := \frac{1}{\sqrt{T}} \frac{1}{T} \sum_{t=1}^T Y_t = \frac{1}{\sqrt{T}} \sum_{t=1}^T \frac{1}{T} \sum_{s=1}^t \varepsilon_s = \frac{1}{\sqrt{T}} \sum_{t=1}^T S_T(\frac{t}{T})$$

$$\uparrow S_T(\gamma) \quad \gamma = \frac{t}{T}, S_T(\gamma) = \frac{1}{\sqrt{T}} \sum_{s=1}^{\lfloor T\gamma \rfloor} \varepsilon_s \quad \frac{Y_T}{\sqrt{T}} = \int S_T(\gamma) d\gamma + \frac{1}{T} S_T(1)$$

$$\downarrow \varepsilon_1/\sqrt{T} \quad \varepsilon_1 + \varepsilon_2/\sqrt{T} \quad \varepsilon_1 + \varepsilon_2 + \varepsilon_3/\sqrt{T} \quad \varepsilon_1 + \dots + \varepsilon_T/\sqrt{T}$$

$$\downarrow \varepsilon_1 + \dots + \varepsilon_T/\sqrt{T} \quad \downarrow \varepsilon_1 + \dots + \varepsilon_T$$

$$\frac{1}{\sqrt{T}} \sum_{t=1}^T S_T(\frac{t}{T}) \xrightarrow{T \rightarrow \infty} \int S_T(\gamma) d\gamma \xrightarrow{d} \sigma \int W(\gamma) d\gamma$$

$$\frac{1}{\sqrt{T}} S_T(1) \xrightarrow{T \rightarrow \infty} 0$$

$$\downarrow \sigma W(1) \text{ by FCLT}$$

$$\text{Therefore } \frac{1}{\sqrt{T}} \bar{Y} \xrightarrow{d} \int W(\gamma) d\gamma \quad \text{as } T \rightarrow \infty$$

$$\text{Similarly, } \frac{1}{T^{1/2}} \sum_{t=1}^T Y_t^k = \frac{1}{T} \sum_{t=1}^T \left(\frac{Y_t}{\sqrt{T}} \right)^k = \frac{1}{T} \sum_{t=1}^T \left(S_T \left(\frac{t}{T} \right) \right)^k$$

$\xrightarrow{d} \sigma \int W(\gamma) d\gamma$ width area, i.e. integral.

$$3) \hat{\beta} = \frac{\sum_{t=1}^T Y_t Y_{t-1}}{\sum_{t=1}^T Y_{t-1}^2} = 1 + \frac{\sum_{t=1}^T \varepsilon_t Y_{t-1}}{\sum_{t=1}^T Y_{t-1}^2}$$

$$T(\hat{\beta} - 1) = \frac{\frac{1}{T} \sum_{t=1}^T \varepsilon_t Y_{t-1}}{\frac{1}{T} \sum_{t=1}^T Y_{t-1}^2} \xrightarrow{d} \sigma \int W^2(\gamma) d\gamma \quad \text{as above}$$

$$\frac{1}{T} \sum_{t=1}^T \varepsilon_t Y_{t-1} = \frac{1}{T} \sum_{t=1}^T \varepsilon_t \sum_{s=1}^{t-1} \varepsilon_s = \frac{1}{T} \sum_{t=1}^T S_t \varepsilon_s = (x)$$

$$Y_t^2 = \left(\sum_{s=1}^T \varepsilon_s \right)^2 = \sum_{s=1}^T \varepsilon_s^2 + 2 \sum_{t>s} \varepsilon_t \varepsilon_s$$

$$\Rightarrow \sum_{t>s} \varepsilon_t \varepsilon_s = \frac{1}{2} (Y_T^2 - \sum_{s=1}^T \varepsilon_s^2)$$

$$(x) = \frac{1}{T} (Y_T^2 - \sum_{s=1}^T \varepsilon_s^2) = \frac{1}{2} \left(\frac{Y_T}{\sqrt{T}} \right)^2 - \frac{1}{2} \frac{1}{T} \sum_{s=1}^T \varepsilon_s^2$$

$$= \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \varepsilon_t \right)^2 \xrightarrow{d} \sigma^2 (LLN)$$

by FCLT

$$\beta = 1$$

$$\xrightarrow{d} \frac{\sigma^2}{2} (\bar{W}(1) - 1)$$

$$\therefore T(\hat{\beta} - 1) \xrightarrow{d} \frac{\frac{1}{2} (\bar{W}^2(1) - 1)}{\frac{\sigma^2}{2} \int_0^1 W^2(\gamma) d\gamma} = \frac{W^2(1) - 1}{2 \int_0^1 W^2(\gamma) d\gamma}$$

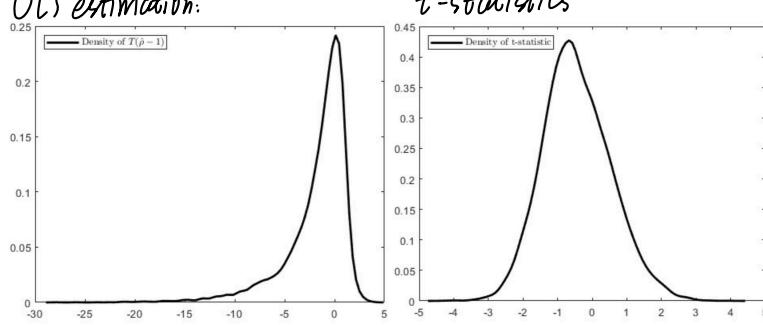
$$4) t\text{-statistics} = \frac{\hat{\beta} - 1}{\hat{\sigma}} \sqrt{\frac{1}{T} \sum_{t=1}^T Y_{t-1}^2} = \frac{T(\hat{\beta} - 1)}{\hat{\sigma}} \sqrt{\frac{1}{T} \sum_{t=1}^T Y_{t-1}^2}$$

$$\hat{\sigma}^2 = \frac{1}{T} \sum_{t=1}^T (Y_t - \hat{\beta} Y_{t-1})^2 \xrightarrow{\text{in P.S.}} \frac{1}{T} \sum_{t=1}^T \varepsilon_t^2 \xrightarrow{d} \frac{W^2(1) - 1}{2 \int_0^1 W^2(\gamma) d\gamma}$$

$$= \frac{W^2(1) - 1}{2 \int_0^1 W^2(\gamma) d\gamma}$$

Summary: very different asymptotic distribution and convergence rates (\bar{T} vs T)

OLS estimation:



$$\begin{aligned} \text{ARCH}(q) &\text{ is weakly stationary iff } \sum_{i=1}^q \alpha_i < 1 . \\ \text{If model is stat., then, } \mathbb{E}[U_t^2] &= \sigma^2 \text{ b.t.} \\ \text{Thus, } \sigma^2 &= \mathbb{E}[U_t^2] = \mathbb{E}[\mathbb{E}_{t-1}[U_t^2]] = \mathbb{E}[U_{t-1}^2] \\ &= \mathbb{E}[X_0 + \sum_{i=1}^q \alpha_i U_{t-i}^2] = \alpha_0 + \sum_{i=1}^q \alpha_i \mathbb{E}[U_{t-i}^2] \\ &= \alpha_0 + \sigma^2 \sum_{i=1}^q \alpha_i \stackrel{\text{= } \sigma^2 \text{ by stat.}}{=} \\ \Rightarrow \sigma^2 &= \frac{\alpha_0}{1 - \sum_{i=1}^q \alpha_i} \quad \alpha_0 = \sigma^2 \left(1 - \sum_{i=1}^q \alpha_i\right) \\ \sum_{i=1}^q \alpha_i < 1 &\text{ guarantees that } \sigma^2 > 0 . \\ \rightarrow \sigma_t^2 - \sigma^2 &= \sigma^2 \left(1 - \sum_{i=1}^q \alpha_i\right) + \sum_{i=1}^q \alpha_i U_{t-i}^2 - \sigma^2 \\ &= \sum_{i=1}^q \alpha_i (U_{t-i}^2 - \sigma^2) \text{ deviation from the mean form.} \end{aligned}$$

Spurious Regression:

$$Y_t = Y_{t-1} + \varepsilon_t, \varepsilon_t \sim \text{iid}(0, \sigma^2), X_t = X_{t-1} + U_t, U_t \sim \text{iid}(0, \lambda^2)$$

$\varepsilon_t \perp U_t, \forall t, s$.

Run a regression $Y_t = \beta X_t + V_t$, true $\beta = 0$.

However, $\hat{\beta} \gg 0$:

$$\begin{aligned} \hat{\beta} &= \frac{\sum Y_t X_t}{\sum X_t^2} = \frac{\frac{1}{T} \sum Y_t X_t}{\frac{1}{T} \sum X_t^2} \xrightarrow{d} \sigma \lambda \int W_x(\gamma) W_y(\gamma) d\gamma \\ &\quad \text{since } \frac{1}{T} \sum \frac{Y_t}{\sqrt{T}} \frac{X_t}{\sqrt{T}} \xrightarrow{d} \sigma \lambda \int W_y(\gamma) W_x(\gamma) d\gamma \\ &\quad \frac{d}{T \rightarrow \infty} \frac{\sigma}{\lambda} \frac{\int W_x(\gamma) W_y(\gamma) d\gamma}{\int W_x^2(\gamma) d\gamma} \end{aligned}$$

non standard random variable

$$t = \frac{\hat{\beta}}{\sigma} \sqrt{\sum X_t^2} = \sqrt{T} \text{ (random variable)} \rightarrow \infty.$$

$$\hat{\beta}^2 = \frac{1}{T} \sum_{t=1}^T (Y_t - \hat{\beta} X_t)^2 = \frac{1}{T} \sigma^2 \rightarrow \text{random variable.}$$

$H_0: \beta = 0$ is rejected as $|t| \nearrow \infty$

However, if $\begin{cases} Y_t = \beta X_t + \varepsilon_t, \beta \neq 0, \text{ then } T(\hat{\beta} - \beta) \xrightarrow{d} (\text{non-standard}) \\ X_t = X_{t-1} + U_t \quad \text{i.e. } \hat{\beta} \xrightarrow{T \rightarrow \infty} \beta \end{cases}$

Cointegration: X_t, Y_t are unit roots, but $X_t - \theta Y_t$ is stationary for e.g. $X_t, Y_t = \% \text{ rates of maturities}, X_t - \theta Y_t = \text{spread}$ some $\theta \in \mathbb{R}$

Autoregressive Conditional Heteroskedasticity

Time-varying Volatility.

AR, MA: about $\mathbb{E}[Y_t | \text{past}]$. e.g. in AR(1): $Y_t = \alpha + \beta Y_{t-1} + \varepsilon_t$,

$$\mathbb{E}[Y_t | Y_{t-1}, \dots] = \alpha + \beta Y_{t-1}$$

Nothing about $\text{var}(Y_t | \text{past})$, $\mathbb{E}[\varepsilon_t^2 | \text{past}] = \sigma^2$, not depend on t .

Now: replace σ^2 with σ_t^2

$Y_t = X_t \beta + U_t$. (X_t may include lags of Y_t , baseline: $X_t = 1, Y_t = \beta + U_t$)

$$\{ \mathbb{E}_{t-1}[U_t] := \mathbb{E}[U_t | U_{t-1}, \dots] = 0 \quad (\text{MDS}) \}$$

$$\mathbb{E}_{t-1}[U_t^2] := \mathbb{E}[U_t^2 | U_{t-1}, \dots] = \sigma_t^2, \quad U_t \sim WN(0, \sigma_t^2)$$

$$\Rightarrow \sigma_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i U_{t-i}^2, \quad \alpha_0 > 0, \quad \alpha_1, \dots, \alpha_q > 0 \quad \text{ARCH}(q).$$

$$\mathbb{E}_{t-1}[U_t] = 0, \quad \mathbb{E}_{t-1}[U_{t-1}^2] = \sigma_{t-1}^2,$$

$$\text{so 1) } \mathbb{E}[U_t] = \mathbb{E}[\mathbb{E}_{t-1}[U_t]] = 0$$

$$\text{2) } h > 0: \mathbb{E}[U_t U_{t+h}] = \mathbb{E}[\mathbb{E}_{t+h-1}[U_t U_{t+h}]] = \mathbb{E}[U_t \mathbb{E}_{t+h-1}[U_{t+h}]] = 0$$

$$\text{3) to let } \mathbb{E}[U_t^2] = \sigma^2, \text{ also need } \sum_{i=1}^q \alpha_i < 1$$

AR(1)(q) is weakly stationary iff $\sum_{i=1}^q \alpha_i < 1$.

If model is stat., then, $\mathbb{E}[U_t^2] = \sigma^2$ b.t.

$$\text{Thus, } \sigma^2 = \mathbb{E}[U_t^2] = \mathbb{E}[\mathbb{E}_{t-1}[U_t^2]] = \mathbb{E}[U_{t-1}^2]$$

$$= \mathbb{E}[X_0 + \sum_{i=1}^q \alpha_i U_{t-i}^2] = \alpha_0 + \sum_{i=1}^q \alpha_i \mathbb{E}[U_{t-i}^2]$$

$$= \alpha_0 + \sigma^2 \sum_{i=1}^q \alpha_i$$

$$\Rightarrow \sigma^2 = \frac{\alpha_0}{1 - \sum_{i=1}^q \alpha_i} \quad \alpha_0 = \sigma^2 \left(1 - \sum_{i=1}^q \alpha_i\right)$$

$$\sum_{i=1}^q \alpha_i < 1 \text{ guarantees that } \sigma^2 > 0 .$$

$$\rightarrow \sigma_t^2 - \sigma^2 = \sigma^2 \left(1 - \sum_{i=1}^q \alpha_i\right) + \sum_{i=1}^q \alpha_i U_{t-i}^2 - \sigma^2$$

$$= \sum_{i=1}^q \alpha_i (U_{t-i}^2 - \sigma^2) \text{ deviation from the mean form.}$$

Why Autoregressive conditional heteroskedasticity?

$$\text{Let } V_t := U_t^2 - \sigma_t^2 = U_t^2 - \mathbb{E}_{t-1}[U_t^2]$$

$$\rightarrow \mathbb{E}_{t-1}[V_t] := \mathbb{E}[V_t | U_{t-1}, \dots] = \mathbb{E}_{t-1}[U_t^2] - \mathbb{E}_{t-1}[\mathbb{E}_{t-1}[U_t^2]] \equiv 0$$

$$\rightarrow \forall h > 0: \mathbb{E}[V_t V_{t+h}] = \mathbb{E}[\mathbb{E}_{t+h-1}[V_t V_{t+h}]]$$

$$= \mathbb{E}[V_t \mathbb{E}_{t+h-1}[V_{t+h}]] = 0$$

so $V_t \sim WN$ with 0 mean.

$$\sigma_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i U_{t-i}^2$$

$$U_{t-1}^2 - V_t$$

$$\Rightarrow U_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i U_{t-i}^2 + V_t, \quad \text{AR}(q) \text{ for } U_t^2$$

$\sum_{i=1}^q \alpha_i < 1, \alpha_i > 0 \forall i = 1, \dots, q$ implies stat. for this AR(q). i.e. $\mathbb{E}[U_t^2] = \text{constant}$.

- The errors U_t are leptokurtic.

$$\text{kurtosis: } \text{kurt}(X) = \frac{\mathbb{E}[(X - \mathbb{E}[X])^4]}{(\mathbb{E}[(X - \mathbb{E}[X])^2])^2}$$

If $X \sim N(\mu, \sigma^2)$, then $(\mathbb{E}[(X - \mathbb{E}[X])^3])^2 = (\sigma^2)^3 = \sigma^4$

$$\mathbb{E}[(X - \mathbb{E}[X])^4] = 3\sigma^4.$$

$$\Rightarrow \text{kurt}(X) = \frac{3\sigma^4}{\sigma^4} = 3$$

leptokurtic: $\text{kurt} > 3$: fatter tails than N

platykurtic: $\text{kurt} < 3$: thinner tails than N

$$\bullet \text{ Let } U_0 / U_{t-1}, \dots \sim N(0, \sigma_t^2)$$

$$\text{Let } \varepsilon_t := \frac{U_t}{\sigma_t} \sim N(0, 1)$$

$$\mathbb{E}_{t-1}[\varepsilon_t] = \mathbb{E}_{t-1}\left[\frac{U_t}{\sigma_t}\right] = \frac{1}{\sigma_t} \mathbb{E}_{t-1}[U_t] = 0 \quad \boxed{\text{Known at } t-1}$$

$$\mathbb{E}_{t-1}[U_t^2] = \mathbb{E}_{t-1}\left[\frac{U_t^2}{\sigma_t^2}\right] = \frac{1}{\sigma_t^2} \mathbb{E}_{t-1}[U_t^2] = \frac{\sigma_t^2}{\sigma_t^2} = 1$$

$$\text{kurt}(U_t) = \frac{\mathbb{E}[U_t^4]}{\mathbb{E}[U_t^2]^2} = \frac{\mathbb{E}[(\sigma_t \varepsilon_t)^4]}{(\sigma_t^2)^2}$$

$$= \frac{\mathbb{E}[\mathbb{E}_{t-1}[\sigma_t^4 \varepsilon_t^4]]}{\sigma_t^4} = \frac{\mathbb{E}[\sigma_t^4 \mathbb{E}_{t-1}[\varepsilon_t^4]]}{\sigma_t^4}$$

$$= \frac{3 \mathbb{E}[\sigma_t^4]}{\sigma_t^4} \quad \text{since } \varepsilon_t | U_{t-1}, \dots \sim N(0, 1)$$

By Jensen's Ineq: $\mathbb{E}[(\sigma_t^2)^3] \geq (\mathbb{E}[\sigma_t^2])^3 = (\sigma^2)^3 = \sigma^4$

strict unless $\sigma_t^2 = \text{const.}$ i.e. if $\sigma_t^2 \neq \text{const.}$, $\text{kurt}(U_t) > 3$.

For more than N tails \rightarrow some moments may not exist.

Generalized Autoregressive Conditional Heteroskedasticity.

GARCH

$$\sigma_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i u_{t-i}^2 + \sum_{j=1}^p \beta_j \sigma_{t-j}^2 \quad (\text{GARCH}(p, q))$$

$$\begin{cases} \alpha_0 > 0, \quad \alpha_i > 0 \quad \forall i = 1, \dots, q \\ \beta_j \geq 0 \quad \forall j = 1, \dots, p \\ \sum_{i=1}^q \alpha_i + \sum_{j=1}^p \beta_j < 1 \end{cases}$$

$$\sigma^2 = \mathbb{E}[\sigma_t^2] = \alpha_0 + \sum_{i=1}^q \alpha_i \sigma^2 + \sum_{j=1}^p \beta_j \sigma^2$$

$$\Rightarrow \sigma^2 = \frac{\alpha_0}{1 - \sum_{i=1}^q \alpha_i - \sum_{j=1}^p \beta_j}$$

$$V_t := u_t^2 - \mathbb{E}_{\sigma^2}[u_t^2] = u_t^2 - \sigma^2$$

$$\sigma_t^2 = u_t^2 - V_t = \alpha_0 + \sum_{i=1}^q \alpha_i u_{t-i}^2 + \sum_{j=1}^p \beta_j (u_{t-j}^2 - V_{t-j})$$

$$u_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i u_{t-i}^2 + \sum_{j=1}^p \beta_j u_{t-j}^2 + V_t - \sum_{j=1}^p \beta_j V_{t-j}$$

ARMA($\max\{p, q\}$, p) for u_t^2