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Lecture Support Vector Machines continued

PROF. LINDA SELLIE

SOME SLIDES FROM PROF. RANGAN

We can compare two hyperplanes by comparing their geometric margins.

Which hyperplane has a larger margin:

- Given the following data:

$$\mathbf{x}^{(1)} = \begin{bmatrix} 3.2 & 4.7 \end{bmatrix}$$

$$y^{(1)} = -1$$

$$\mathbf{x}^{(2)} = \begin{bmatrix} 3.5 & 1.4 \end{bmatrix}$$

$$y^{(2)} = 1$$

$$\mathbf{x}^{(3)} = \begin{bmatrix} 3. & 1.4 \end{bmatrix}$$

$$y^{(3)} = 1$$

- What is the geometric margin for:

$$w_0 = 1/2 \quad \mathbf{w} = \begin{bmatrix} 2/3 \\ -1 \end{bmatrix}$$

$$\overbrace{y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) / \|\mathbf{w}\|_2} = 1.7$$

$$(-1) \left(\begin{bmatrix} 2/3 & -1 \end{bmatrix} \begin{bmatrix} 3.2 \\ 4.7 \end{bmatrix} + 1/2 \right) / \sqrt{4/9 + 1}$$

$$(1) \left(\begin{bmatrix} 2/3 & -1 \end{bmatrix} \begin{bmatrix} 3.5 \\ 1.4 \end{bmatrix} + 1/2 \right) / \sqrt{4/9 + 1} = 1.2$$

$$(1) \left(\begin{bmatrix} 2/3 & -1 \end{bmatrix} \begin{bmatrix} 3 \\ 1.4 \end{bmatrix} + 1/2 \right) / \sqrt{4/9 + 1} = 0.9$$

$\gamma = 0.9$ ✓

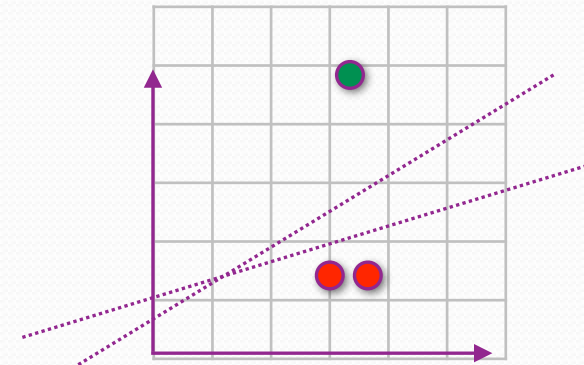
$$w_0 = 1 \quad \mathbf{w} = \begin{bmatrix} 1/3 \\ -1 \end{bmatrix}$$

$$(-1) \left(\begin{bmatrix} 1/3 & -1 \end{bmatrix} \begin{bmatrix} 3.2 \\ 4.7 \end{bmatrix} + 1 \right) / \sqrt{4/9 + 1} = 2.2$$

$$(1) \left(\begin{bmatrix} 1/3 & -1 \end{bmatrix} \begin{bmatrix} 3.5 \\ 1.4 \end{bmatrix} + 1 \right) / \sqrt{4/9 + 1} = 0.6$$

$$(1) \left(\begin{bmatrix} 1/3 & -1 \end{bmatrix} \begin{bmatrix} 3 \\ 1.4 \end{bmatrix} + 1 \right) / \sqrt{4/9 + 1} = 0.5$$

$\gamma = 0.5$



Goal is to find \mathbf{w}, w_0 that has the largest γ such that $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) / \|\mathbf{w}\|_2 \geq \gamma$

$$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) / \|\mathbf{w}\|_2 \geq 0.9$$

$$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) / \|\mathbf{w}\|_2 \geq 0.5$$

Objective function

Goal

$$\max_{w_0, \mathbf{w}} \gamma$$

subject to $y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq \gamma$ for all $i=1, \dots, N$

$$\|\mathbf{w}\|_2 = 1$$

Not yet the
form we need

Difficult to work with constraints that are not linear.

Let us write our objective function in a different way.

We want our constrained object function to return a unique \mathbf{W}, w_0

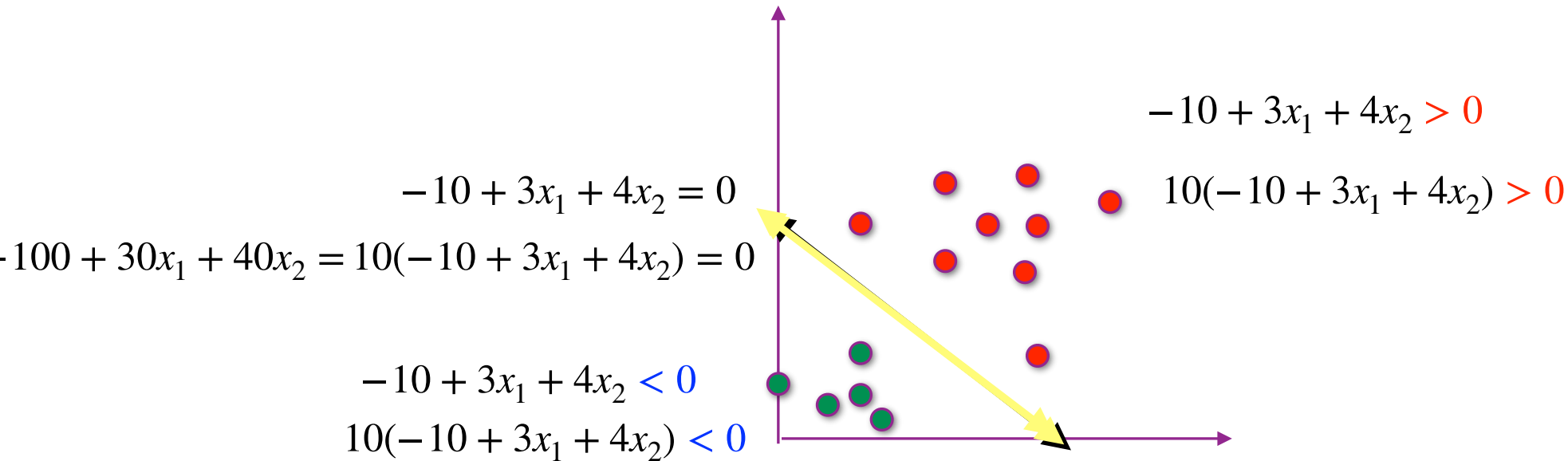
Crazy idea next!

Instead of requiring \mathbf{w} to be a unit vector (i.e. $\|\mathbf{w}\| = 1$),
We will define the idea of a “functional margin” and
require that to be 1.

Steps to understanding “functional margin”:

1. Simple observation: *rescaling* the parameters doesn't change the *decision boundary*.
2. How to rescale the parameters/weights, so the functional margin is 1. We call these weights/parameters *canonical weights*.

Step 1. We can write a hyperplane in many ways



Pair share: Do we change the classification if we multiply $-10 + 3x_1 + 4x_2 = 0$ by 10?

Step 1 conclusion

Rescaling the parameters doesn't change the line (decision boundary)!

$$\mathbf{w}^T \mathbf{x} + w_0 = 0 = c\mathbf{w}^T \mathbf{x} + cw_0$$

Step 2

What is another way to constrain the problem so that we get a unique solution?

$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) = 1$ for the closest point to the hyperplane

The functional margin of (\mathbf{w}, w_0) with respect to a point $\mathbf{x}^{(i)}$ is

$$\gamma^{(i)} = y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0)$$

The *Functional margin* of (\mathbf{w}, w_0) with respect to a set S is

$$\gamma = \min\{\gamma^{(1)}, \gamma^{(2)}, \dots, \gamma^{(N)}\}$$

Step 2

Canonical weights

$$\gamma^{(2)} = (1) \left(\frac{3}{3} \frac{4}{3} \begin{bmatrix} 3 \\ 1 \end{bmatrix} - \frac{10}{3} \right) \\ = (1) \frac{(3)}{3}$$

$$\gamma^{(1)} = (1) \left(\frac{3}{3} \frac{4}{3} \begin{bmatrix} 1 \\ 2.5 \end{bmatrix} - \frac{10}{3} \right) \\ = (1) \frac{(3)}{3}$$

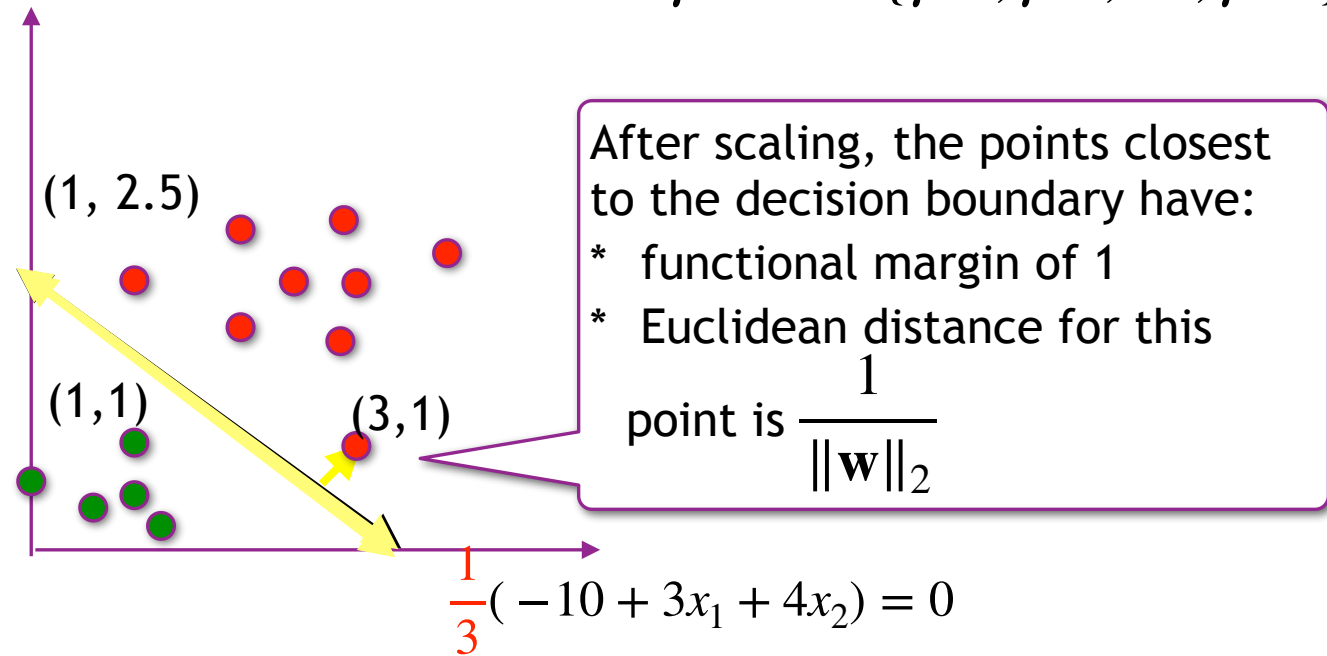
$$\gamma^{(N)} = (-1) \left(\frac{3}{3} \frac{4}{3} \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \frac{10}{3} \right) \\ = (-1) \frac{(-3)}{3}$$

Functional margin of (\mathbf{w}, w_0) with respect to a point $\mathbf{x}^{(i)}$ is

$$\gamma^{(i)} = y^{(i)} \left(\frac{\mathbf{w}^T \mathbf{x}^{(i)}}{3} + \frac{w_0}{3} \right)$$

Functional margin of (\mathbf{w}, w_0) with respect to a set S is

$$\gamma = \min \{ \gamma^{(1)}, \gamma^{(2)}, \dots, \gamma^{(N)} \}$$



$$-10 + 3x_1 + 4x_2 = 0 = -10/3 + 3/3x_1 + 4/3x_2$$

We can make $\gamma = 1$
The canonical weights

Step 2 conclusion

For any hyperplane that separates the data, we can make its functional margin any value we want.

Canonical weights are when the functional margin is 1 for the set of training examples

$$\min_i y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) = 1$$

Example: given a hyperplane $\mathbf{w} = (3,4)^T$, $w_0 = -10$ which has a functional margin of 3, rescale the parameters so the functional margin is 1

Next: Many equivalent versions of
our objective function

Hard-Margin SVM

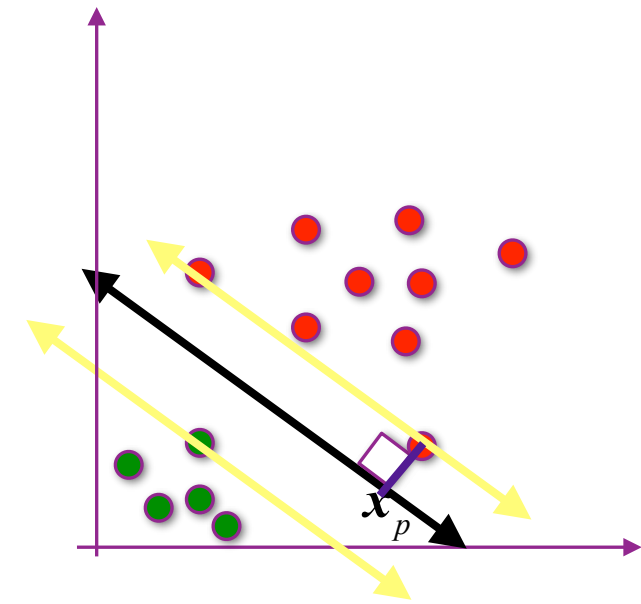
1)

Constrained optimization problem:

$$\max_{w_0, \mathbf{w}} \gamma$$

subject to $y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq \gamma$ for all $i=1, \dots, N$

$$\|\mathbf{w}\|_2 = 1$$



2)

Another formulation:

$$\max_{w_0, \mathbf{w}} \frac{\gamma}{\|\mathbf{w}\|_2} = r$$

subject to $y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq \gamma$ for all $i=1, \dots, N$

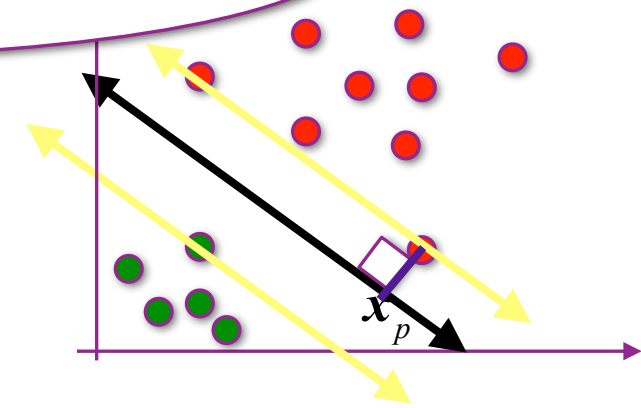
$$\frac{\gamma}{\|\mathbf{w}\|_2} = \text{Geometric margin}$$

Hard-Margin SVM

$$2) \max_{w_0, \mathbf{w}} \frac{\gamma}{\|\mathbf{w}\|_2} = r$$

subject to $y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq \gamma$ for all $i=1, \dots, N$

$$\frac{\gamma}{\|\mathbf{w}\|_2} = \text{Geometric margin}$$



Canonical weights!!!

Idea: we can rescale our margin to anything we want by rescaling our coefficients

notice that $\max \gamma / \|\mathbf{w}\|_2$ equals $\max(\gamma / \gamma) / \|\mathbf{w} / \gamma\|_2$

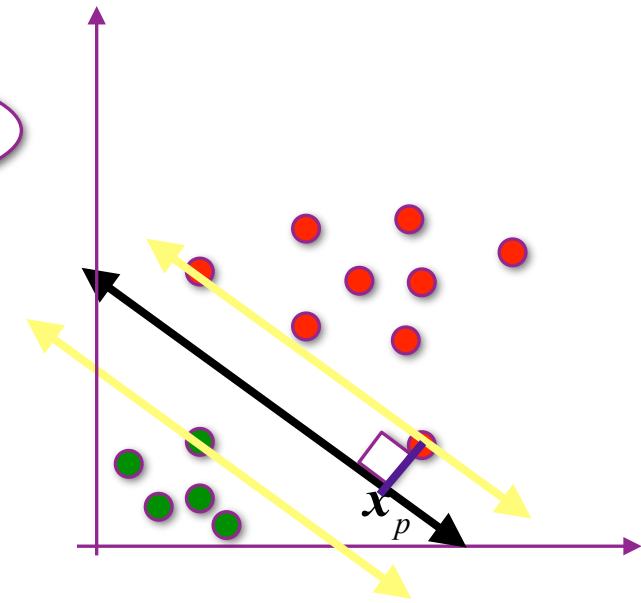
subject to $y^{(i)}(w_0 / \gamma + \mathbf{w}^T / \gamma \mathbf{x}^{(i)}) \geq \gamma / \gamma$ for all $i=1, \dots, N$

Hard-Margin SVM

Canonical weights!!!

$$\max \gamma / \|\mathbf{w}\|_2 \quad \max(\gamma / \gamma) / \|\mathbf{w} / \gamma\|_2$$

$$\text{subject to } y^{(i)}(w_0 / \gamma + \mathbf{w}^T / \gamma \mathbf{x}^{(i)}) \geq \gamma / \gamma \text{ for all } i=1, \dots, N$$



3) We set $w_0 := w_0 / \gamma$, and $\mathbf{w} := \mathbf{w} / \gamma$ Notice we now want to $\max 1 / \|\mathbf{w}\|_2$

Using this idea we rewrite the formula as

$$\max_{w_0, \mathbf{w}} 1 / \|\mathbf{w}\|_2 \quad \text{now } \gamma = 1$$

$$\frac{1}{\|\mathbf{w}\|_2} = \text{margin}$$

$$\text{Subject to } y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq 1 \text{ for all } i = 1, \dots, N$$

Hard-Margin SVM

3) Constrained optimization problem:

$$\max_{w_0, \mathbf{w}} 1/\|\mathbf{w}\|_2$$

Subject to $y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq 1$ for all $i = 1, \dots, N$

4) Notice $\max 1/\|\mathbf{w}\|_2$ is the same as $\min \|\mathbf{w}\|_2$

Notice $\min \|\mathbf{w}\|_2$ is the same as $\min \|\mathbf{w}\|_2^2$

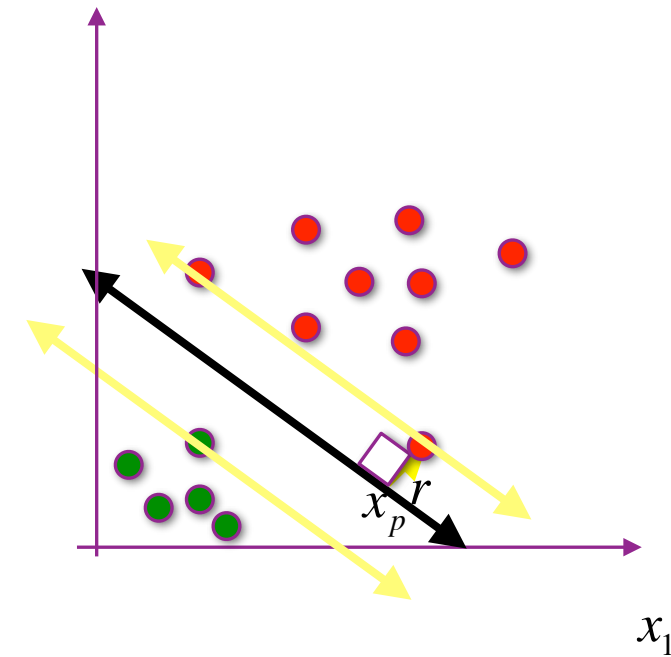
$$\min \|\mathbf{w}\|_2^2 = \min(w_1^2 + w_2^2 + \dots + w_d^2)$$

Subject to $y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq 1$ for all $i = 1, \dots, N$

Solvable in polynomial time!

Objective function is convex and points satisfying constraints are convex

A constrained quadratic optimization problem!



Example Hard-Margin SVM

(\mathbf{x}^T, y) : $((1, 2.5), 1), ((2, 2), 1), ((3, 1), 1), \dots, ((0, 0.75), -1), ((1, 1), -1)\}$

The constrained quadratic optimization function is:

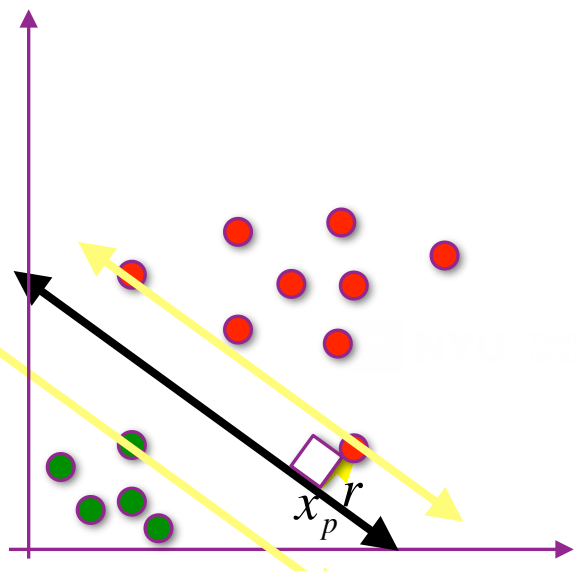
$$\min_{w_0, \mathbf{w}} \|\mathbf{w}\|_2^2 = w_1^2 + w_2^2$$

$$\text{subject to } (1) \left(w_0 + \mathbf{w}^T \begin{bmatrix} 1 \\ 2.5 \end{bmatrix} \right) \geq 1$$

$$(1) \left(w_0 + \mathbf{w}^T \begin{bmatrix} 2 \\ 2 \end{bmatrix} \right) \geq 1$$

$$\vdots$$

$$(-1) \left(w_0 + \mathbf{w}^T \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) \geq 1$$



Example Hard-Margin SVM

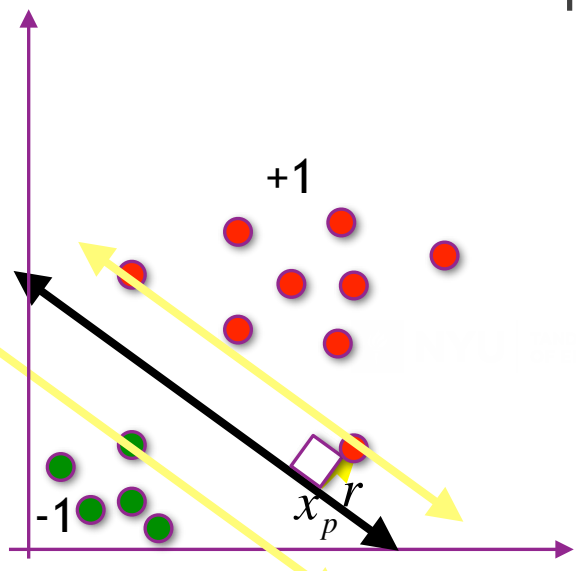
(\mathbf{x}^T, y) : $((1, 2.5), 1), ((2, 2), 1), ((3, 1), 1), \dots, ((0, 0.75), -1), ((1, 1), -1)\}$

The optimal hyperplane is: $\mathbf{w} = (1, 4/3)^T$, $w_0 = -10/3$

- $f(\mathbf{x}) = (1, 4/3)\mathbf{x} - 10/3$
- Predict +1 if $f(\mathbf{x}) > 0$
- Predict -1 if $f(\mathbf{x}) < 0$

Two types of training data:

- $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) = 1$. Points on the margin called **support vectors**
- $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) > 1$. If we remove these points, the solution doesn't change



Could it be possible for

$$y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) > 1 \text{ for all } i=1, \dots, N$$

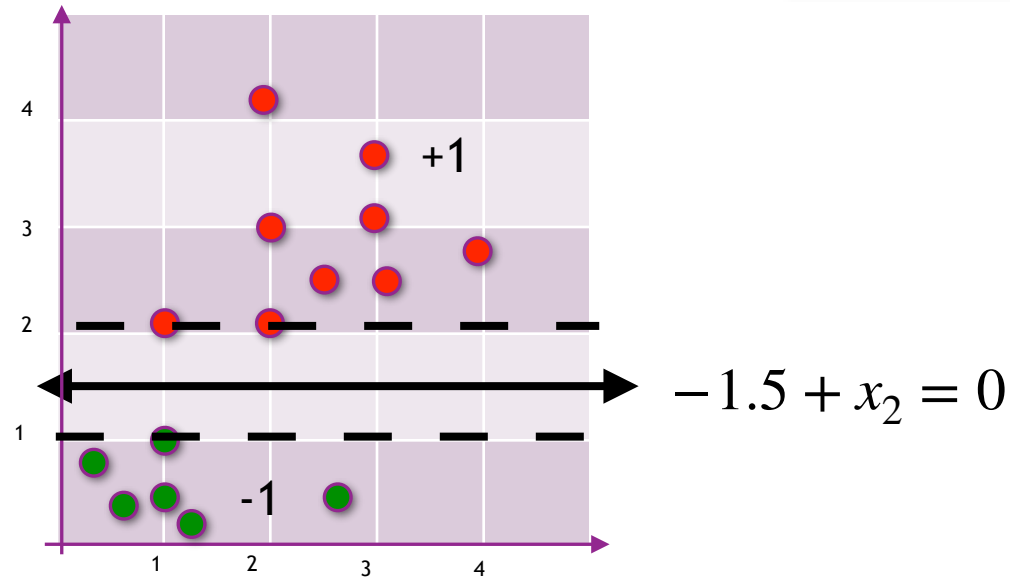
No!

We could scale w and w_0 to find
a smaller $\|\mathbf{w}\|_2^2$

So the functional margin
with respect to the set of
training examples will
be 1

Hard margin example

Pair share: How can modify our decision boundary to have a functional margin of 1?

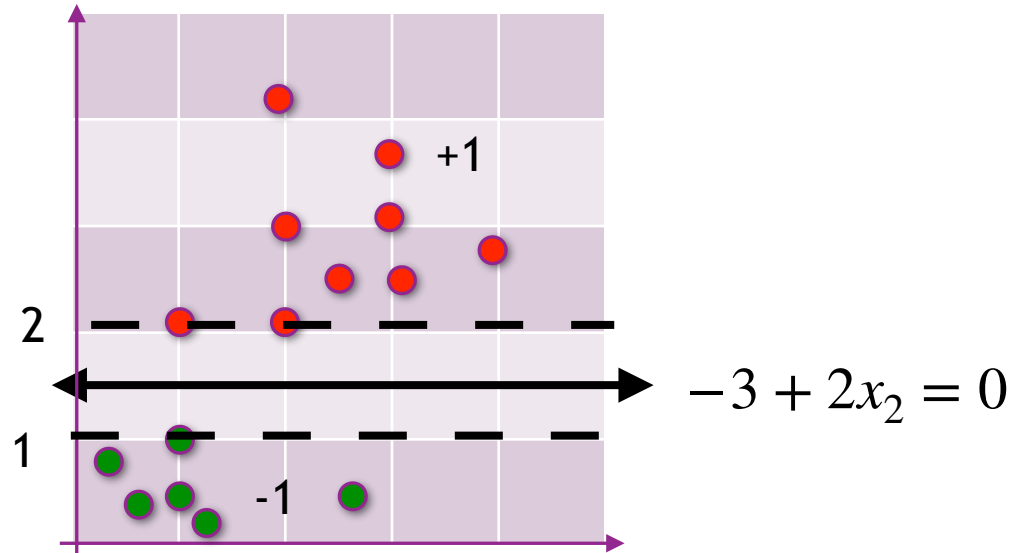


Decision boundary is $\mathbf{w} = [0, 1]^T$, $w_0 = -1.5$

Is this the form we wanted?

The support vectors are supposed to have a functional margin of 1: $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) = 1$

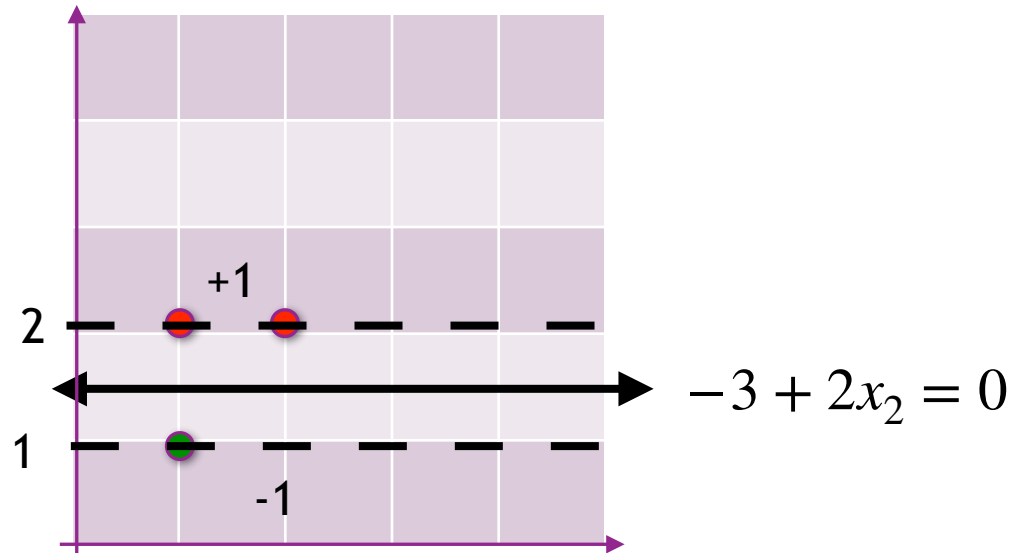
Example



Decision boundary is $\mathbf{w} = [0, 2]^T$, $w_0 = -3$

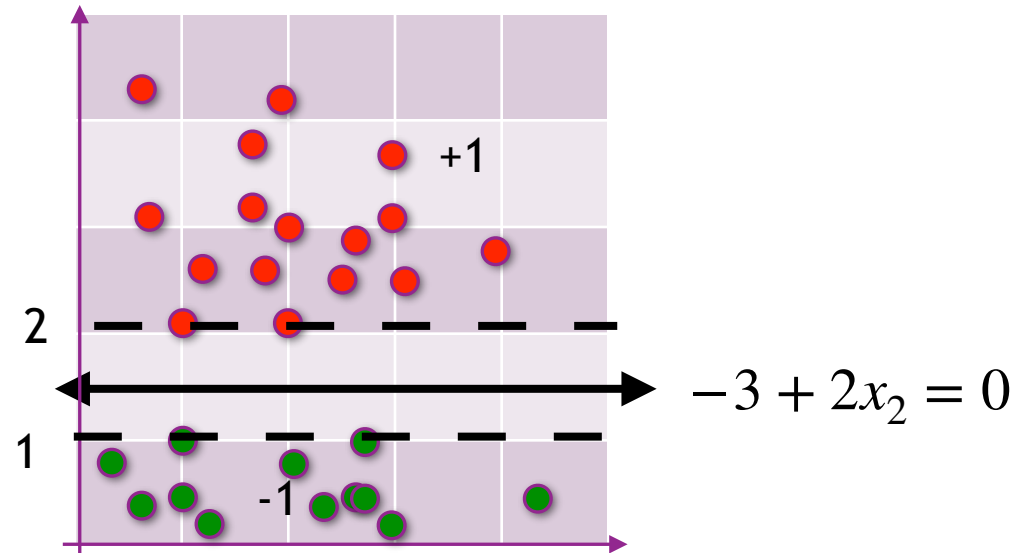
The support vectors have a functional margin of 1: $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) = 1$

Example



The boundary doesn't change if I remove points with a functional margin > 1

Example



The solution doesn't change if I add points whose functional margin is ≥ 1

Outline

- Notation change, intuition, and finding how to compare hyperplanes - **mathematically how do compare hyperplanes to find the one with the maximum margin. Can we turn this way of comparing hyperplanes into an objective function**

- Support vector machines

 - ★ hard margin - **find the constrained objective function when the data is linearly separable**



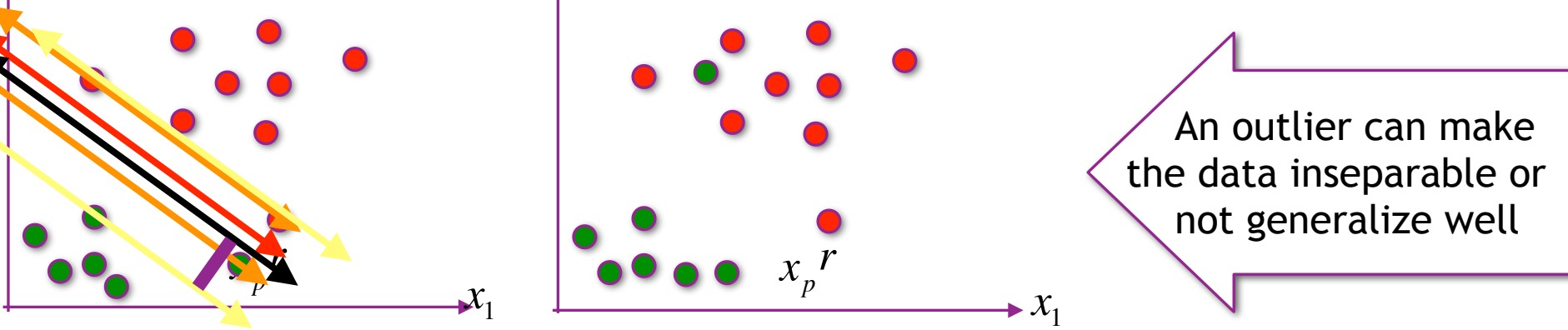
 - ★ Dealing with non-linear data - “Soft” margins for SVM - **New constrained objective function for the case where the data is not linearly separable**

 - ★ Pegasos algorithm. **Optimizer for soft margin SVM**

 - ★ Dealing with non-linear data - feature transformation with the kernel trick - **Show two popular feature maps**

Non-Linear Data

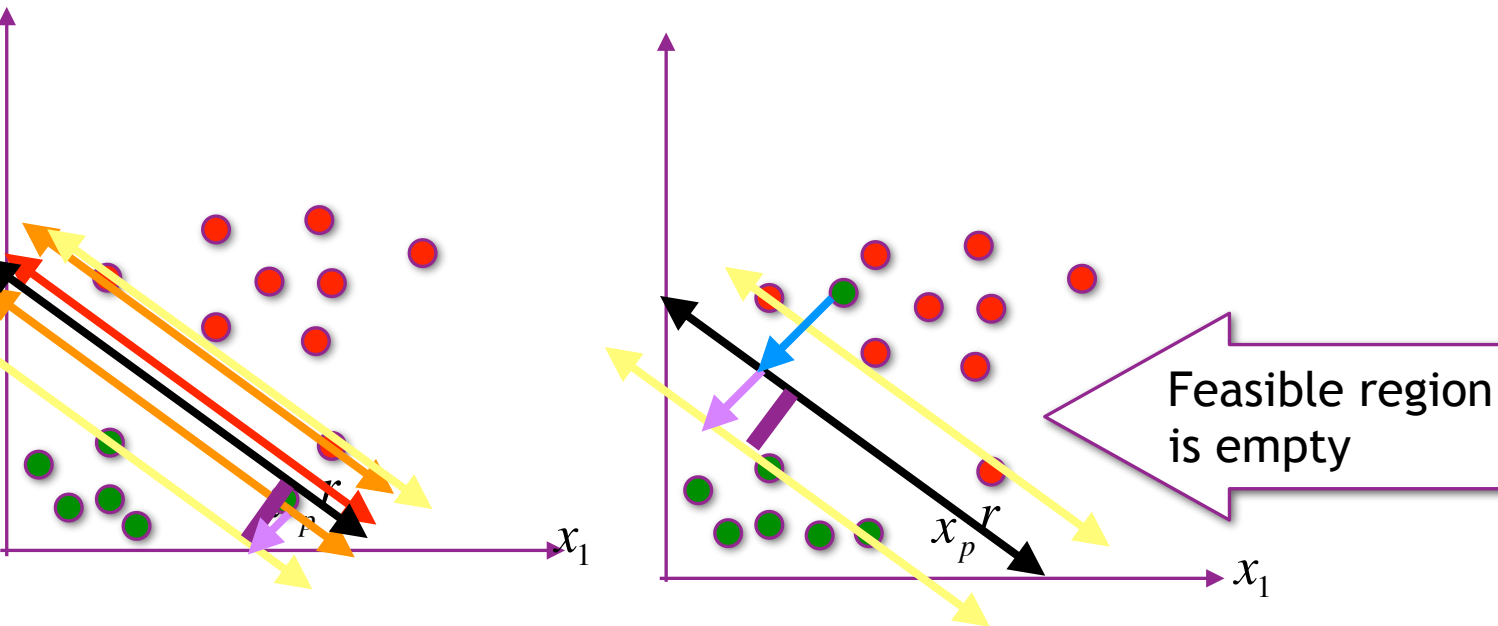
1. Soft margin
2. Transform features vector \mathbf{x} into a new feature space $\Phi(\mathbf{x})$



What if the data isn't linearly separable

WE CAN MAKE OUR MODEL MORE FLEXIBLE BY ADDING A COST FUNCTION FOR THE POINTS THAT ARE MISCLASSIFIED

Soft-Margin SVM



How can we still find the optimal hyperplane where we allow for a few points to either be misclassified or within the margin?

We could incur a cost $\xi^{(i)}$ for how far the $x^{(i)}$ is away from the margin.

We will create a slack variable $\xi^{(i)}$ for each training example $\mathbf{x}^{(i)}$

The hyperplane must satisfy

$$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) \geq 1 - \xi^{(i)}$$

$$\xi^{(i)} =$$

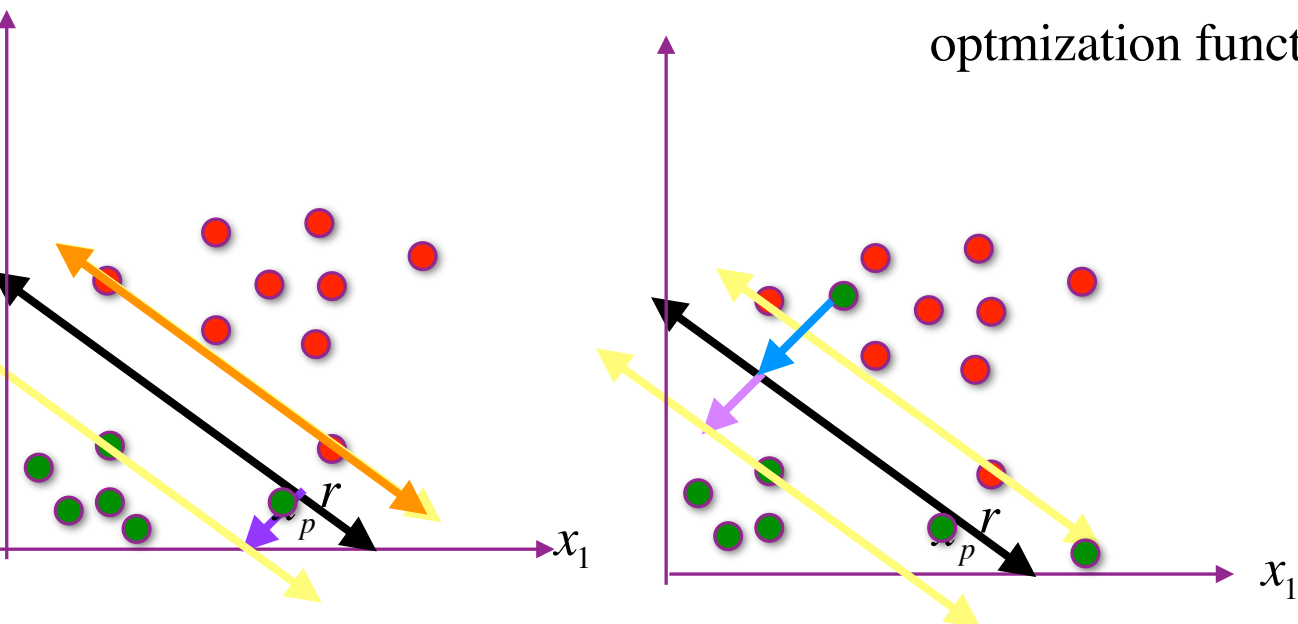
$$\xi^{(i)} =$$

What function should we use for

Which cost function?

SHOULD ALL THE POINTS BE CHARGED, OR ONLY THOSE THAT ARE INSIDE THE MARGIN OR INCORRECTLY CLASSIFIED?

Soft-Margin SVM



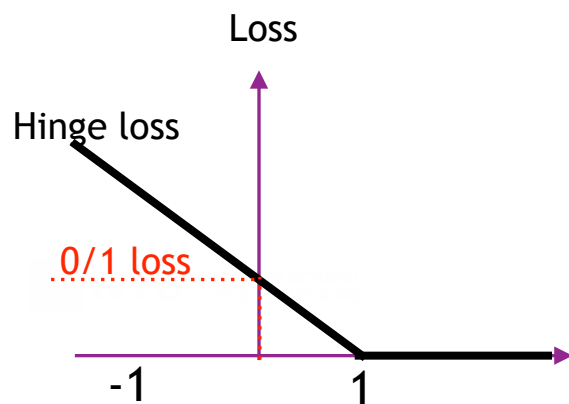
optimization function

$$\min_{w_0, \mathbf{w}, \{\xi^{(i)}\}_{i=1}^N} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N \xi^{(i)}$$

$$\text{subject to } y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq 1 - \xi^{(i)} \quad \text{for all } i=1, \dots, N$$

$$\xi^{(i)} \geq 0$$

C is a tunable parameter. Gives relative importance of the error term



$$\xi^{(i)} = \begin{cases} 0 & y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) \geq 1 \\ 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) & \text{otherwise} \end{cases}$$

Hinge Loss

Introduced one slack variable $\xi^{(i)}$ for each training example.



$$\xi^{(i)} = \begin{cases} 0 & y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) \geq 1 \\ 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) & \text{otherwise} \end{cases}$$

0-1 loss: No penalty if correctly classified. Cost of 1 for incorrectly classified points

Hinge loss: Penalty upper bounds 0/1 loss

- Penalizes correct predictions that are too close to the margin
- Penalty linearly increases for incorrect predictions (and close correct predictions)

No penalty on correct predictions that are far away from the margin

optimization function

$$\min_{w_0, \mathbf{w}, \{\xi^{(i)}\}_{i=1}^N} \|\mathbf{w}\|_2^2 + \sum_{i=1}^N \xi^{(i)}$$

$$\text{subject to } y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq 1 - \xi^{(i)}$$

$$\xi^{(i)} \geq 0$$

Pair share: What do you know about the functional margin for \mathbf{x} if:

1) $\xi \geq 1$

2) $0 < \xi < 1$

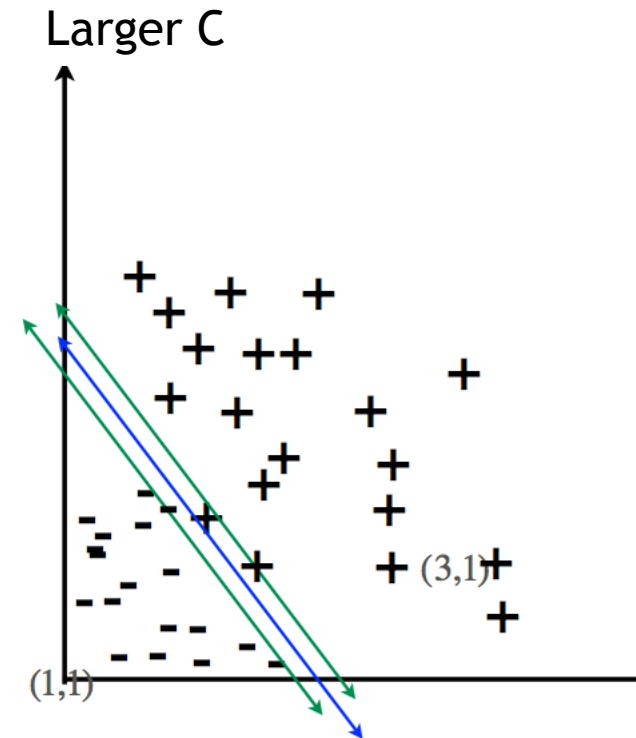
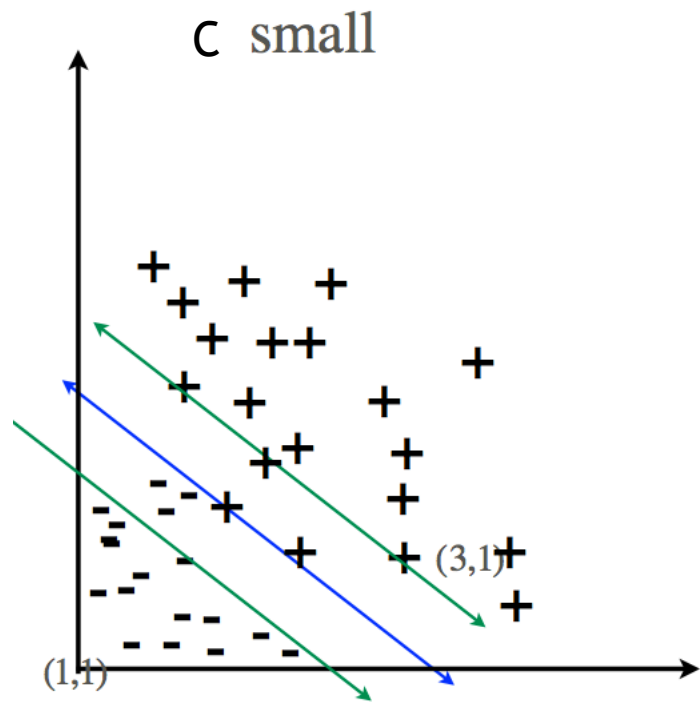
3) $\xi = 0$

Pair share: Do you think that $\sum_{i=1}^N \xi^{(i)}$ is an upper bound on the number of training errors (i.e. number of points misclassified incorrectly)?

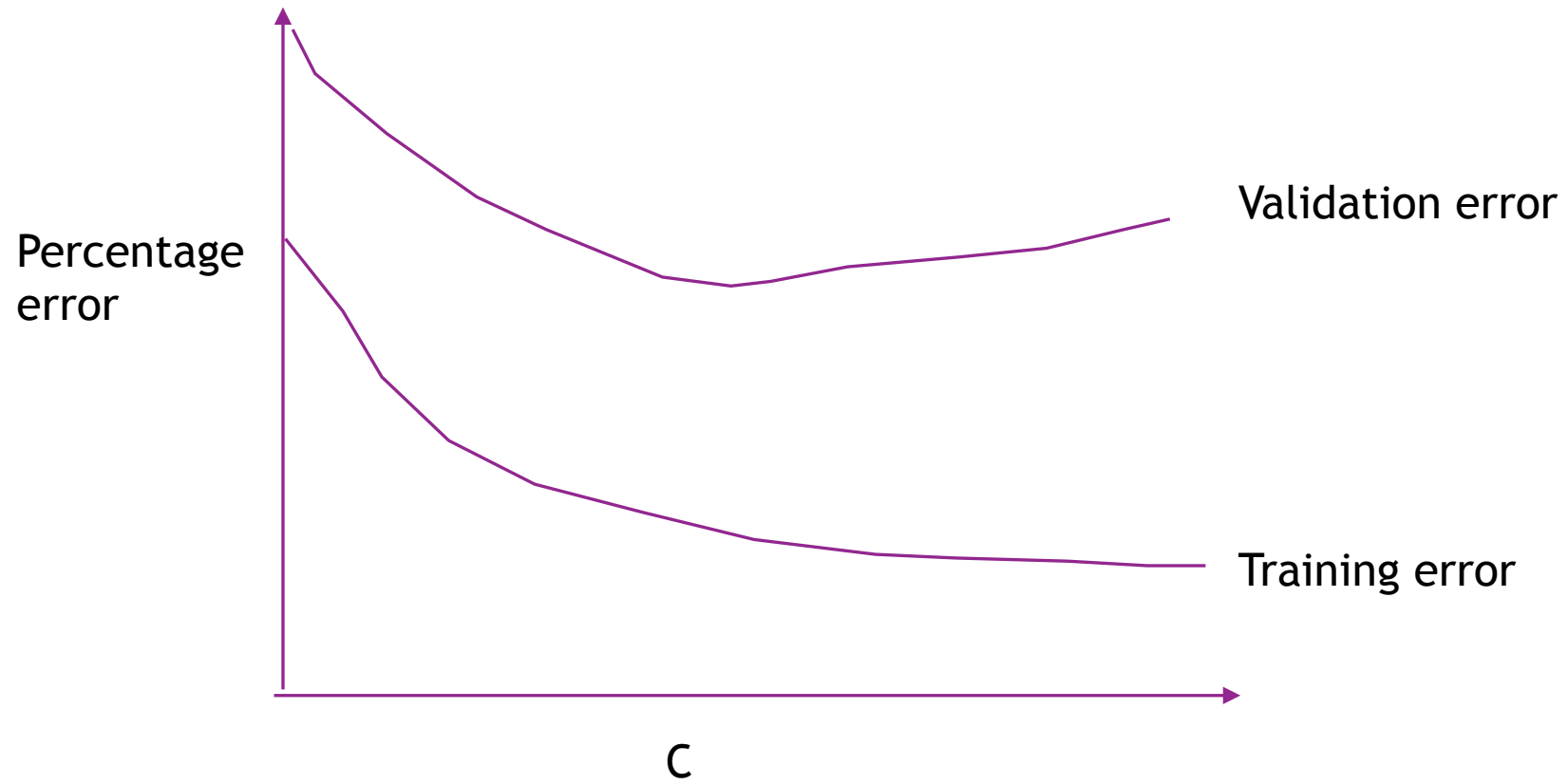
Pair share:

1) What happens to the margin if I make C large?

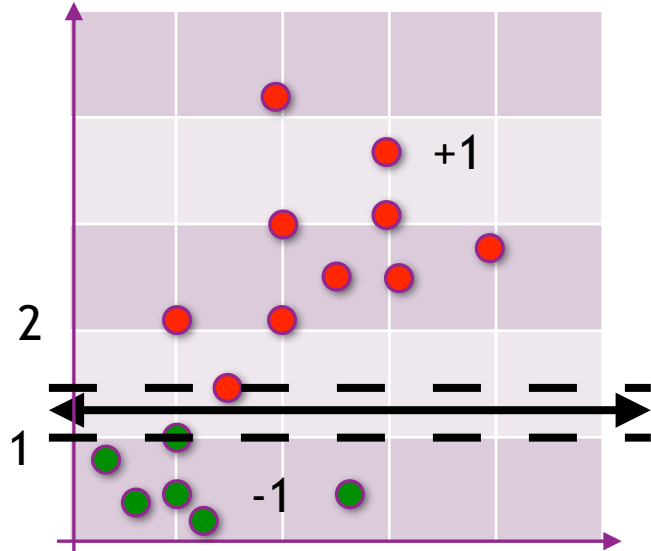
2) What happens to the margin if I make C small?



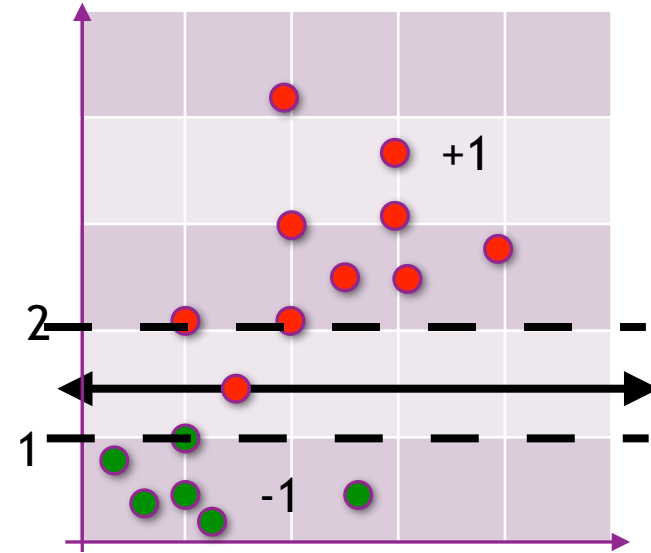
What if $C = \infty$?



Example




Our margin becomes smaller if we have an outlier



$$\min_{w_0, \mathbf{w}, \{\xi^{(i)}\}_{i=1}^N} \|\mathbf{w}\|_2^2 + \sum_{i=1}^N \xi^{(i)}$$

$$\text{subject to } y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq 1 - \xi^{(i)}$$

Outline

- ❑ Notation change, intuition, and finding how to compare hyperplanes - **mathematically how do compare hyperplanes to find the one with the maximum margin. Can we turn this way of comparing hyperplanes into an objective function**
- ❑ Support vector machines
 - ★ hard margin - **find the constrained objective function when the data is linearly separable**
 - ★ Dealing with non-linear data - “Soft” margins for SVM - **New constrained objective function for the case where the data is not linearly separable**
 -  ★ Pegasos algorithm. **Optimizer for soft margin SVM**
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Simplifying our objective
function

Rewriting our SVM objective function

$$\min_{w_0, \mathbf{w}, \{\xi^{(i)}\}_{i=1}^N} \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N \xi^{(i)}$$

$$\text{subject to } y^{(i)}(w_0 + \mathbf{w}^T \mathbf{x}^{(i)}) \geq 1 - \xi^{(i)} \\ \xi^{(i)} \geq 0$$

Same as: $\xi^{(i)} \geq 1 - y^{(i)} (\mathbf{w}^T \mathbf{x}^{(i)} + w_0)$

Our SVM objective function with hinge loss:

Setting $\lambda = 1/C$

$$\min_{\mathbf{w}, w_0} \underbrace{\frac{\lambda}{2} \|\mathbf{w}\|_2^2}_{\text{regularizer}} + \underbrace{C \sum_{i=1}^N \max(0, 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0))}_{\text{hinge Loss}}$$

Since $\xi^{(i)}$ is as small as possible

A balance between loss function and regularizer.

Our objective function is convex but not differentiable

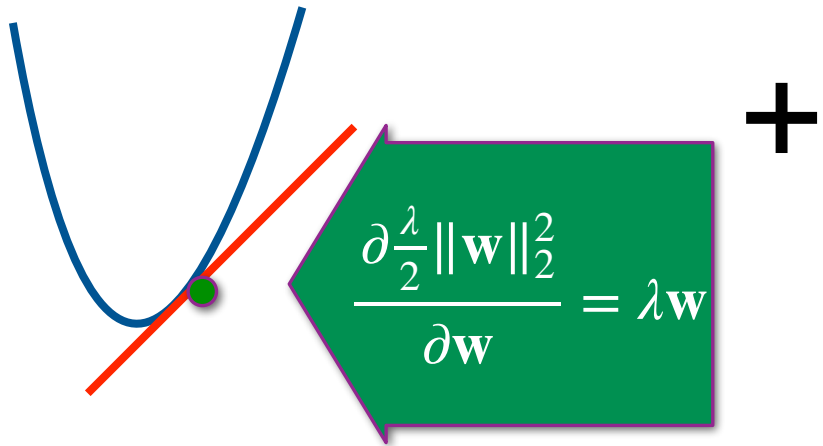
We can use a sub-gradient. Derivation is beyond the scope of course.

Derivative

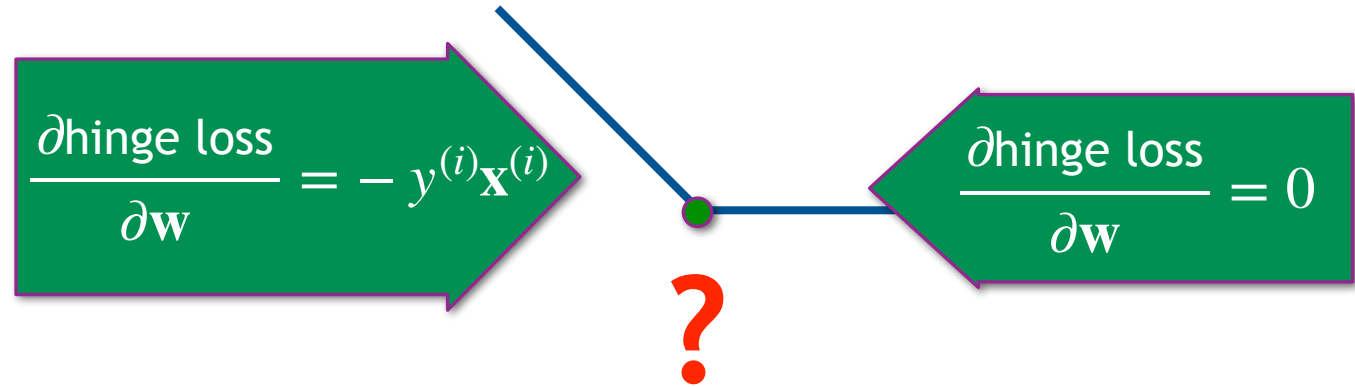
Sub-derivative of the hinge loss

$$\frac{\lambda}{2} \|\mathbf{w}\|_2^2$$

$$\text{hinge loss} = \max(0, 1 - y^{(i)} \mathbf{w}^T \mathbf{x})$$



+



$$J(\mathbf{w}) = \frac{\lambda}{2} \|\mathbf{w}\|_2^2 + \sum_{i=1}^N \max(0, 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0))$$

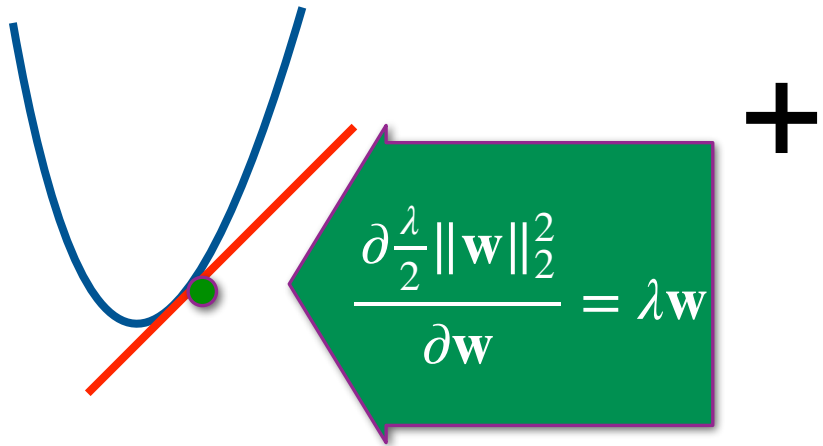
$$\nabla J(\mathbf{w}) = \lambda \mathbf{w} + \begin{cases} 0 & \text{if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) \geq 1 \\ -y^{(i)} \mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

Derivative

Sub-derivative of the hinge loss

$$\frac{\lambda}{2} \|\mathbf{w}\|_2^2$$

$$\text{hinge loss} = \max(0, 1 - y^{(i)} \mathbf{w}^T \mathbf{x})$$



$$\frac{\partial \frac{\lambda}{2} \|\mathbf{w}\|_2^2}{\partial \mathbf{w}} = \lambda \mathbf{w}$$

$$\frac{\partial \text{hinge loss}}{\partial \mathbf{w}} = -y^{(i)} \mathbf{x}^{(i)}$$

Sub-gradient: Linear global underestimate at this point

?

$$J(\mathbf{w}) = \frac{\lambda}{2} \|\mathbf{w}\|_2^2 + \sum_{i=1}^N \max(0, 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0))$$

$$\nabla J(\mathbf{w}) = \lambda \mathbf{w} + \begin{cases} 0 & \text{if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0) \geq 1 \\ -y^{(i)} \mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

$$J(\mathbf{w}) = \underbrace{\frac{\lambda}{2} \|\mathbf{w}\|_2^2}_{\text{regularizer}} + \sum_{i=1}^N \underbrace{\max(0, 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + w_0))}_{\text{hinge Loss}}$$

$$\text{subgradient}(\mathbf{w}) = \begin{cases} \lambda \mathbf{w} & \text{if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)}) \geq 1 \\ \lambda \mathbf{w} - y^{(i)} \mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

“We did not incorporate a bias term in any of our experiments. We found that including an un-regularized bias term does not significantly change the predictive performance for any of the data sets used. Furthermore, most methods we compare to, including [21, 24, 37, 18], do not incorporate a bias term either. Nonetheless, there are clearly learning problems where the incorporation of the bias term could be beneficial.” / <https://www.cs.huji.ac.il/w-shais/papers/ShalevSiSrCo10.pdf>

To keep it simple, we will not include a bias unit.

If N is large, batch gradient is slow

We will use stochastic sub-gradient descent
with an adaptive learning rate

Stochastic Gradient Descent

\mathbf{w} = random initialization

For $t = 1, 2, \dots, T$:

Pick a random training example $(\mathbf{x}^{(i)}, y^{(i)})$

$$\# \hat{J}(\mathbf{w}) = \frac{\lambda}{2} \|\mathbf{w}\|_2^2 + \max(0, 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)}))$$

Use only one training example in objective function, $N=1$

$$\mathbf{w} = \mathbf{w} - \alpha \nabla \hat{J}(\mathbf{w})$$

The Pegasos Algorithm

$$\text{subgradient}(\mathbf{w}) = \begin{cases} \lambda \mathbf{w} & \text{if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)}) \geq 1 \\ \lambda \mathbf{w} - y^{(i)} \mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

\mathbf{w} = random initialization

For $t = 1, 2, \dots, T$:

Pick a random training example $(\mathbf{x}^{(i)}, y^{(i)})$

Decrease the learning rate every iteration of the algorithm

Update the parameters by moving a small amount in the opposite direction of the sub gradient

Set
 $T = \tilde{O}\left(\frac{1}{\delta \lambda \epsilon}\right)$
err $\mathbf{w}^* < \mathbf{w} + \epsilon$
with probability
 $1 - \delta$

To keep it simple, we will not include a bias unit.

The Pegasos Algorithm

$$\text{subgradient}(\mathbf{w}) = \begin{cases} \lambda \mathbf{w} & \text{if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)}) \geq 1 \\ \lambda \mathbf{w} - y^{(i)} \mathbf{x}^{(i)} & \text{otherwise} \end{cases}$$

\mathbf{w} = random initialization

For $t = 1, 2, \dots, T$:

Pick a random training example $(\mathbf{x}^{(i)}, y^{(i)})$

$$\alpha = \frac{1}{\lambda \cdot t}$$

if $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)}) \geq 1$

$\mathbf{w} = \mathbf{w} - \alpha \lambda \mathbf{w}$ # weight decay

else

$$\mathbf{w} = \mathbf{w} - \alpha(\lambda \mathbf{w} - y^{(i)} \mathbf{x}^{(i)})$$

Set
 $T = \tilde{O}\left(\frac{1}{\delta \lambda \epsilon}\right)$
err $\mathbf{w}^* < \mathbf{w} + \epsilon$
with probability
 $1 - \delta$

Pair share: If α is small enough, will the function converge to a minimum value if enough iterations occur?

To keep it simple, we will not include a bias unit.

Modified Pegasos for Homework

$\mathbf{w} = 0, t = 0$

For iter = 1, 2, ..., num_iters:

For j = 1, 2, ..., N:

$t = t + 1$

$$\alpha = \frac{1}{\lambda \cdot t}$$

if $y^{(j)}(\mathbf{w}^T \mathbf{x}^{(j)}) \geq 1$

$\mathbf{w} = \mathbf{w} - \alpha \lambda \mathbf{w}$ # weight decay

else

$$\mathbf{w} = \mathbf{w} - \alpha(\lambda \mathbf{w} - y^{(j)} \mathbf{x}^{(j)})$$

To keep it simple, we will not include a bias unit.