

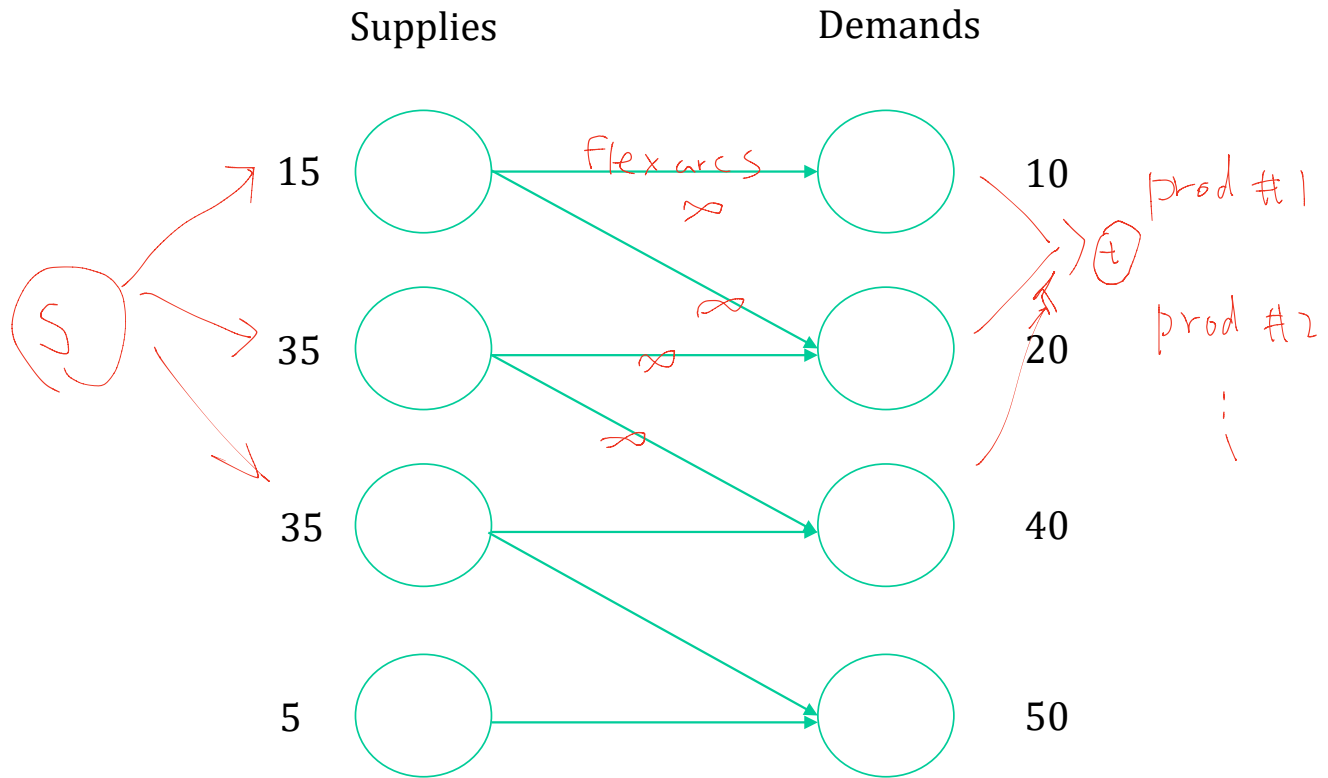
LEC011 Maximum Flow and Linear Program

VG441 SS2020

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Max Flow Applications

Cap. of Plant



Linear Programming

- Comparison to systems of linear equations

$$\begin{aligned}a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n &= b_1 \\a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n &= b_2 \\&\vdots \\a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n &= b_m\end{aligned}$$

Gaussian
elimination

能解決 80% 問題

Linear Programming

- Ingredients of a Linear Program

1. Decision variables $x_1, \dots, x_n \in \mathbb{R}$

$$X = (x_1, x_2, \dots, x_n)^T$$

2. Linear constraints, each of the form

linear $\sum_{j=1}^n a_{ij} x_j \quad (*) \quad b_i$ RHS

where $(*)$ could be \leq, \geq , or $=$

3. A linear objective function, of the form

$$\max \sum_{j=1}^n c_j x_j \quad \text{or} \quad \min \sum_{j=1}^n c_j x_j$$

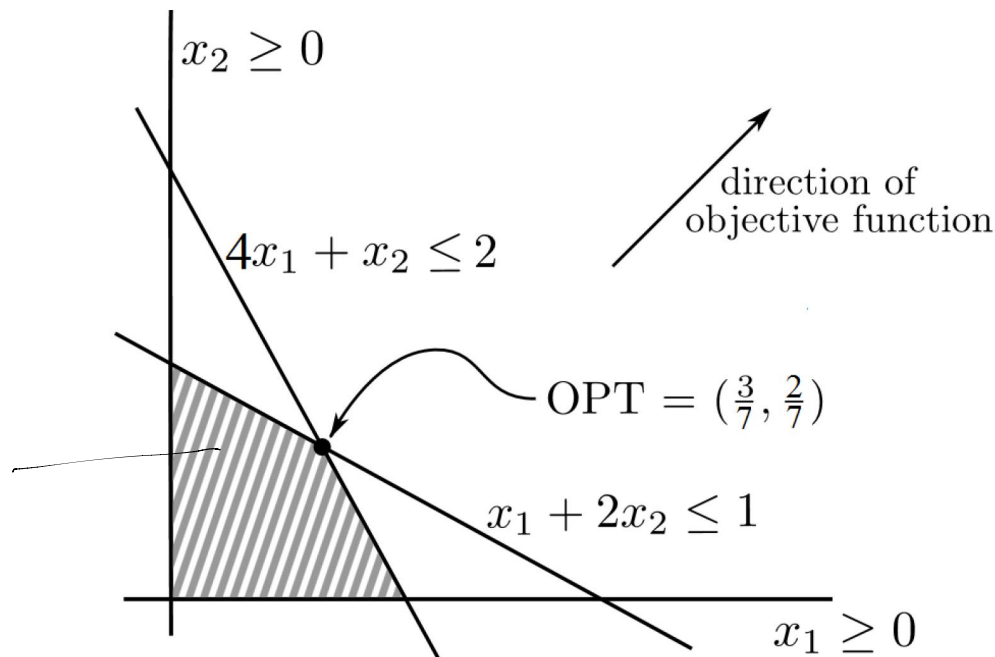
profit/reward cost/penalty.

A Simple Example

$$\begin{array}{ll}\max & x_1 + x_2 \\ \text{s.t.} & 4x_1 + x_2 \leq 2 \\ & x_1 + 2x_2 \leq 1 \\ & x_1, x_2 \geq 0\end{array}$$

2 维时
画图即可

feasible
region
"polyhedron"



Python + Gurobi Time!



GUROBI
OPTIMIZATION

安装 gurobi

加 licence

下面的例子是 numerical example

在后面的 slide 上

MaxFlow is a LP

- Decision variables

$$\{f_e\}_{e \in E}$$

↑ flow value
on each e .

- Constraints ($2m + n - 2$)

$$G(V, E)$$

$$\begin{matrix} \downarrow & \downarrow \\ n & m \end{matrix}$$

$$\underbrace{\sum_{e \in \delta^-(v)} f_e}_{\text{flow in}} - \underbrace{\sum_{e \in \delta^+(v)} f_e}_{\text{flow out}} = 0 \quad \forall v \in V \setminus \{s, t\}$$

$$m \text{ --- } f_e \leq u_e \quad \forall e$$

- Objectives

$$m \text{ --- } f_e \geq 0 \quad \forall e$$

$$\max \sum_{e \in \delta^+(s)} f_e$$

↑ flow value out of
source.

Gurobi
1/24/24

Generalization of MaxFlow

- Min-Cost MaxFlow

$$\min \sum_{e \in E} c_e f_e$$

- Easy to change the LP formulation!

for solving
Maxflow

~~LP~~ ~~model~~ ~~is~~ ~~not~~
model is not
ben dable

FF alg

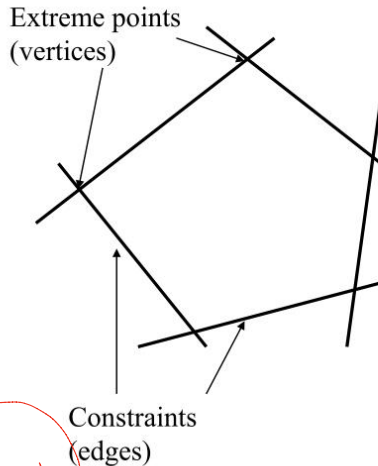
fastest alg: push & relabel

Solution Approaches

现实中两者接近

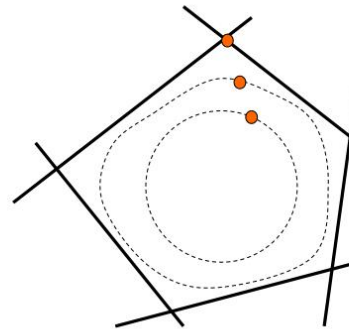
- Simplex methods
- Interior point methods

Interior point methods



Simplex: search from vertex to vertex along the edges

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Interior-point methods: go through the inside of the feasible space

Theoretical worst-case complexity

not in polynomial time

in polynomial time

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LP Duality

- Question: given a feasible solution, how can we know whether it is optimal or close to optimal?

$$\begin{array}{ll}\max & x_1 + x_2 \\ \text{s.t.} & 4x_1 + x_2 \leq 2 \\ & x_1 + 2x_2 \leq 1 \\ & x_1, x_2 \geq 0\end{array}$$

$$\underbrace{x_1 + x_2}_{\text{objective}} \leq 4x_1 + x_2 \leq \underbrace{2}_{\text{upper bound}}$$

$$\underbrace{x_1 + x_2}_{\text{objective}} \leq x_1 + 2x_2 \leq \underbrace{1}_{\text{upper bound}}$$

Can we get an even better upper bound?

$$x_1 + x_2 \leq \frac{1}{7} \underbrace{(4x_1 + x_2)}_{\leq 2 \text{ by (2)}} + \frac{3}{7} \underbrace{(x_1 + 2x_2)}_{\leq 1 \text{ by (3)}} \leq \frac{1}{7} \cdot 2 + \frac{3}{7} \cdot 1 = \frac{5}{7}$$

Deriving the Dual LP

Compact form

$$\begin{array}{ll} \max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{Ax} \leq \mathbf{b} \\ & \mathbf{x} \geq 0 \end{array}$$

$$\max \quad \sum_{j=1}^n c_j x_j$$

$$\text{s.t.} \quad \sum_{j=1}^n a_{1j} x_j \leq b_1$$

$$\sum_{j=1}^n a_{2j} x_j \leq b_2$$

$$\vdots \leq \vdots$$

$$\sum_{j=1}^n a_{mj} x_j \leq b_m$$

$$x_1, \dots, x_n \geq 0$$

dual variables

"Multipliers"

$$\longrightarrow y_1 \geq 0$$

$$\longrightarrow y_2 \geq 0$$

$$\longrightarrow y_m \geq 0$$

The idea is to "dominate the objective coefficients":

$$\sum_{i=1}^m y_i a_{ij} \geq c_j$$

More compactly,

Find $\mathbf{y} \geq 0$ such that $\mathbf{A}^T \mathbf{y} \geq \mathbf{c}$

Deriving the Dual LP

$$\begin{array}{ll}\max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{Ax} \leq \mathbf{b} \\ & \mathbf{x} \geq 0\end{array}$$

Find $\mathbf{y} \geq 0$ such that $\mathbf{A}^T \mathbf{y} \geq \mathbf{c}$

$$\begin{aligned}\underbrace{\sum_{j=1}^n c_j x_j}_{\text{x's obj fn}} &\leq \sum_{j=1}^n \left(\sum_{i=1}^m y_i a_{ij} \right) x_j \\ &= \sum_{i=1}^m y_i \cdot \left(\sum_{j=1}^n a_{ij} x_j \right) \\ &\leq \underbrace{\sum_{i=1}^m y_i b_i}_{\text{upper bound}}\end{aligned}$$

More compactly,

$$\mathbf{c}^T \mathbf{x} \leq (\mathbf{A}^T \mathbf{y})^T \mathbf{x} = \mathbf{y}^T (\mathbf{Ax}) \leq \mathbf{y}^T \mathbf{b}$$

matrix 转置

Deriving the Dual LP

$$\begin{array}{ll}\max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{Ax} \leq \mathbf{b} \\ & \mathbf{x} \geq 0\end{array}$$

Find $\mathbf{y} \geq 0$ such that $\mathbf{A}^T \mathbf{y} \geq \mathbf{c}$

$$\mathbf{c}^T \mathbf{x} \leq (\mathbf{A}^T \mathbf{y})^T \mathbf{x} = \mathbf{y}^T (\mathbf{Ax}) \leq \mathbf{y}^T \mathbf{b}$$

$$\begin{array}{ll}\min & \mathbf{b}^T \mathbf{y} \\ \text{s.t.} & \mathbf{A}^T \mathbf{y} \geq \mathbf{c} \\ & \mathbf{y} \geq 0\end{array}$$

A Simple Example

$$\begin{array}{ll}\max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{Ax} \leq \mathbf{b} \\ & \mathbf{x} \geq 0\end{array}$$

$$\begin{array}{ll}\min & \mathbf{b}^T \mathbf{y} \\ \text{s.t.} & \mathbf{A}^T \mathbf{y} \geq \mathbf{c} \\ & \mathbf{y} \geq 0\end{array}$$

$$\begin{array}{ll}\max & x_1 + x_2 \\ \text{s.t.} & 4x_1 + x_2 \leq 2 \\ & x_1 + 2x_2 \leq 1 \\ & x_1, x_2 \geq 0\end{array}$$

$$\begin{array}{ll}\min & 2y_1 + y_2 \\ \text{s.t.} & 4y_1 + y_2 \leq 1 \\ & y_1 + 2y_2 \leq 1 \\ & y_1, y_2 \geq 0\end{array}$$

$$x_1^* = 3/7, x_2^* = 2/7$$

$$y_1^* = 1/7, y_2^* = 3/7$$

Optimal objectives are the same!

Weak and Strong Duality

$$\begin{array}{ll}\max & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & \mathbf{Ax} \leq \mathbf{b} \\ & \mathbf{x} \geq 0\end{array}$$

$$\begin{array}{ll}\min & \mathbf{b}^T \mathbf{y} \\ \text{s.t.} & \mathbf{A}^T \mathbf{y} \geq \mathbf{c} \\ & \mathbf{y} \geq 0\end{array}$$

At optimality, we must have

- Weak Duality $\mathbf{c}^T \mathbf{x}^* \leq \mathbf{b}^T \mathbf{y}^*$



- Strong Duality $\mathbf{c}^T \mathbf{x}^* = \mathbf{b}^T \mathbf{y}^*$ "no gap"

Proof = Separating hyperplane theorem + Farkas's Lemma

不在491范围内, 参见 canvas

More General Form

Primal	Dual
variables x_1, \dots, x_n	n constraints
m constraints	variables y_1, \dots, y_m
objective function \mathbf{c}	right-hand side \mathbf{c}
right-hand side \mathbf{b}	objective function \mathbf{b}
$\max \mathbf{c}^T \mathbf{x}$	$\min \mathbf{b}^T \mathbf{y}$
constraint matrix \mathbf{A}	constraint matrix \mathbf{A}^T
i-th constraint is “ \leq ”	$y_i \geq 0$
i-th constraint is “ \geq ”	$y_i \leq 0$
i-th constraint is “ $=$ ”	$y_i \in \mathbb{R}$
$x_j \geq 0$	j-th constraint is “ \geq ”
$x_j \leq 0$	j-th constraint is “ \leq ”
$x_j \in \mathbb{R}$	j-th constraint is “ $=$ ”

Back to MaxFlow

- Let the decision variable be flow on an s-t path

$$\begin{array}{ll}\max & \sum_{P \in \mathcal{P}} f_P \quad \text{flow} \\ \text{s.t.} & \underbrace{\sum_{P \in \mathcal{P}: e \in P} f_P}_{\text{total flow on } e} \leq u_e \text{ for all } e \in E \\ & f_P \geq 0 \text{ for all } P \in \mathcal{P}\end{array}$$

Question: how to write its dual and what is its interpretation?

