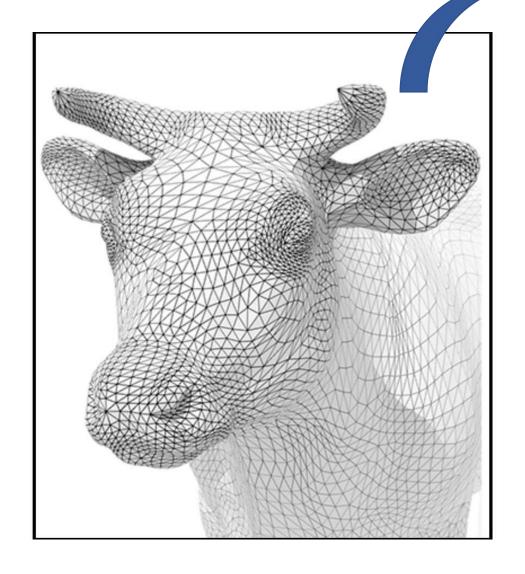
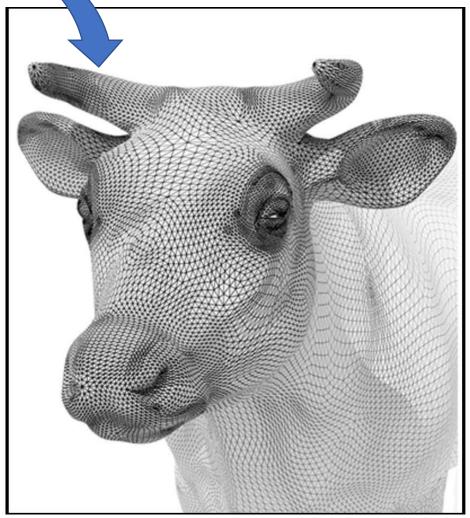
# Mesh Processing

## **Mesh Subdivision**



# **Mesh Subdivision**

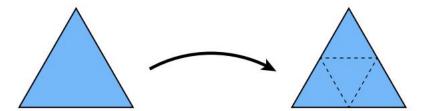


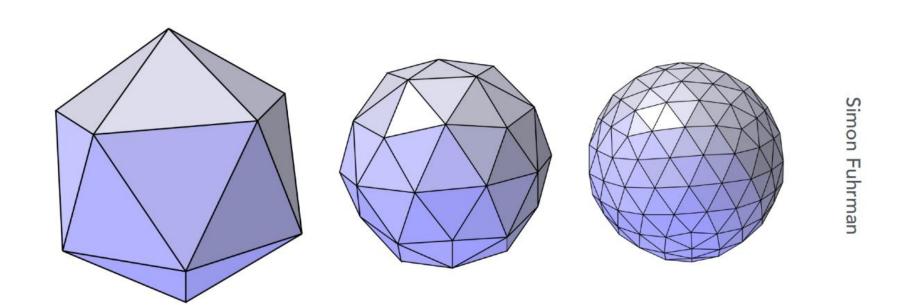


# **Loop Subdivision**

Triangular Mesh Subdivision

One-to-four split

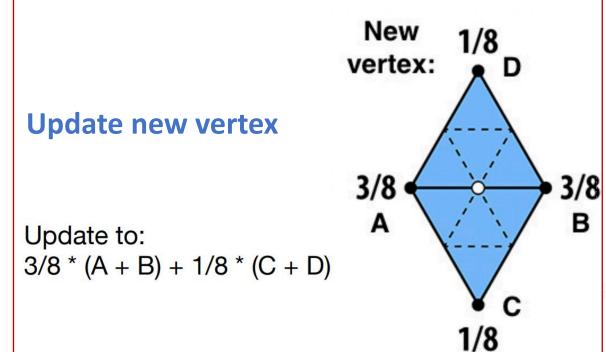


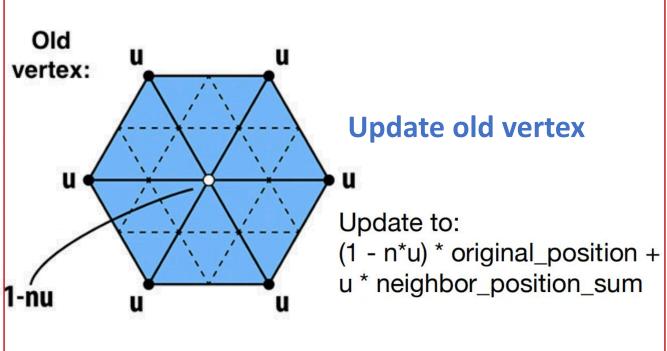


## **Loop Subdivision**

Triangular Mesh Subdivision

- One-to-four split
- Update vertex position

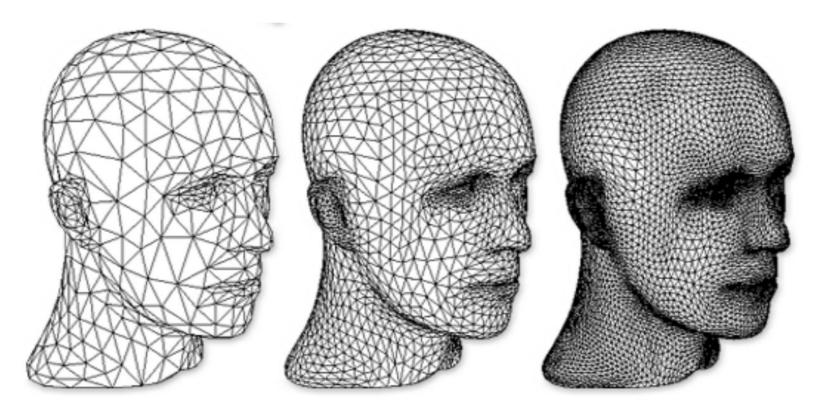




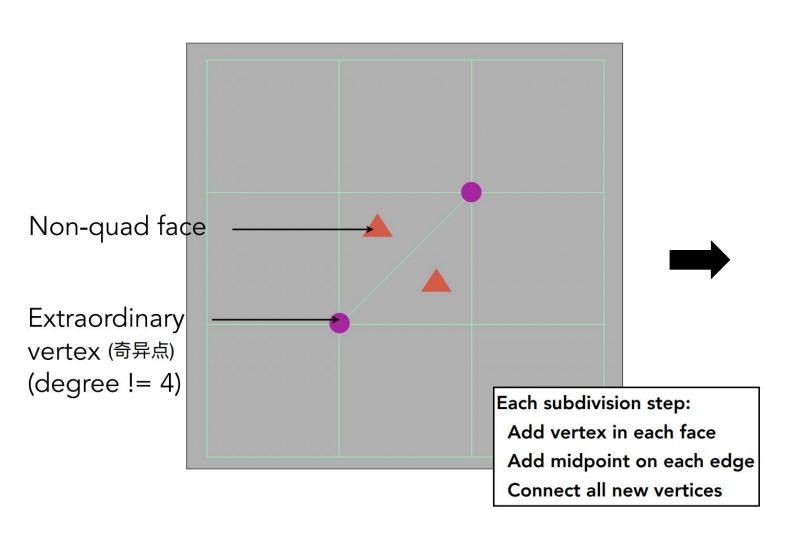
# **Loop Subdivision**

**Triangular Mesh Subdivision** 

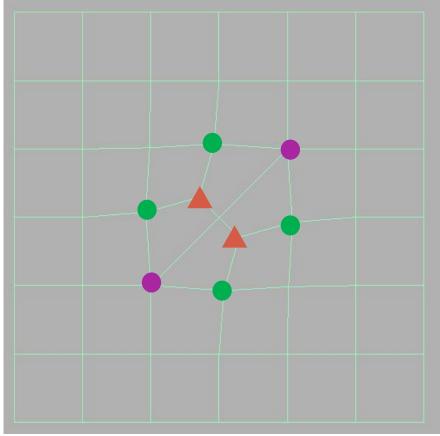
- One-to-four split
- Update vertex position



# **Catmull-Clark Subdivision (General Mesh)**

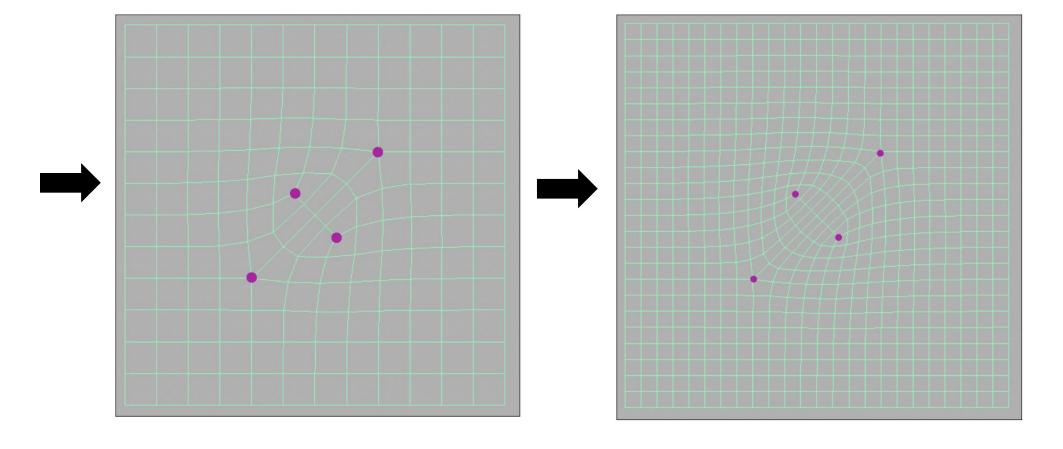


- New extraodinary vertices
- Old extraodinary vertices
- Regular vertices (degree=4)



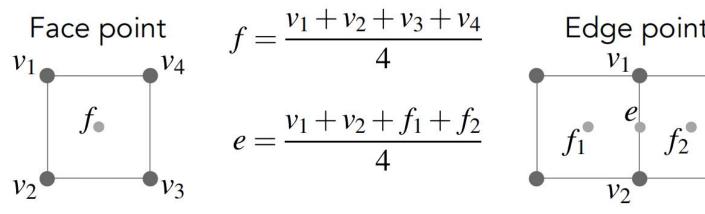
## **Catmull-Clark Subdivision (General Mesh)**

No more extraordinary vertices! All quad faces!



# Catmull-Clark Subdivision (General Mesh)

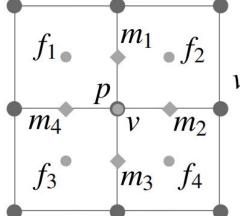
#### Three types of vertices



$$f = \frac{v_1 + v_2 + v_3 + v_4}{4}$$

$$e = \frac{v_1 + v_2 + f_1 + f_2}{4}$$

Edge point 
$$v_1$$
 $e$ 
 $f_1$ 
 $f_2$ 



Vertex point
$$v = \frac{f_1 + f_2 + f_3 + f_4 + 2(m_1 + m_2 + m_3 + m_4) + 4p}{16}$$

midpoint of edge old "vertex point"

### **Convergence: Overall Shape and Creases**

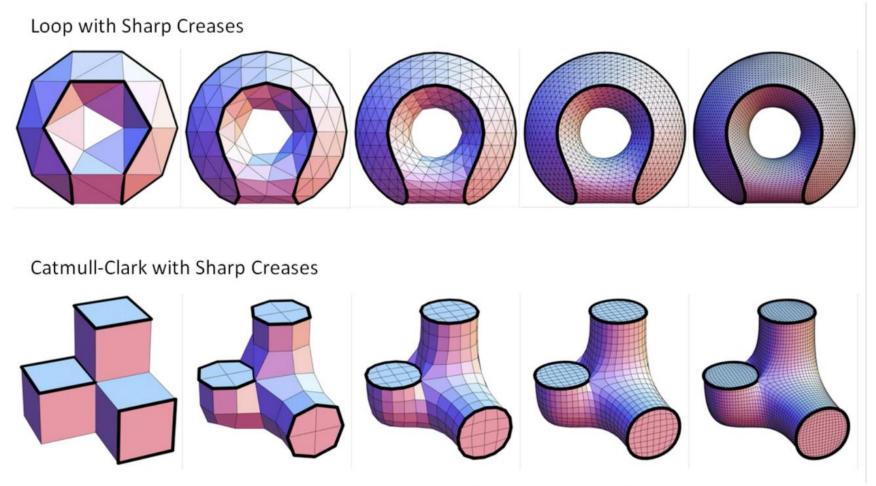


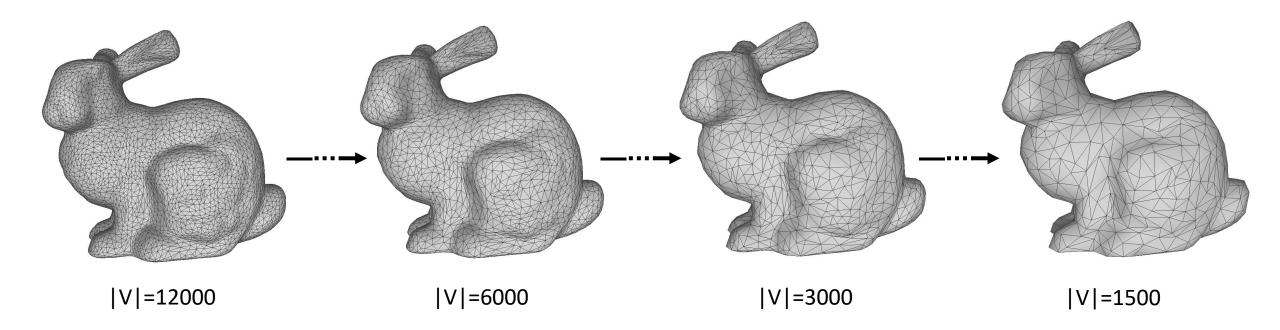
Figure from: Hakenberg et al. Volume Enclosed by Subdivision Surfaces with Sharp Creases

# **Mesh Simplification**



# **Mesh Simplification**

• Iteratively remove one vertex/edge per step



## **Mesh Simplification**

Initialization

• Repeat:

select a vertex/edge to remove

single-simplification step

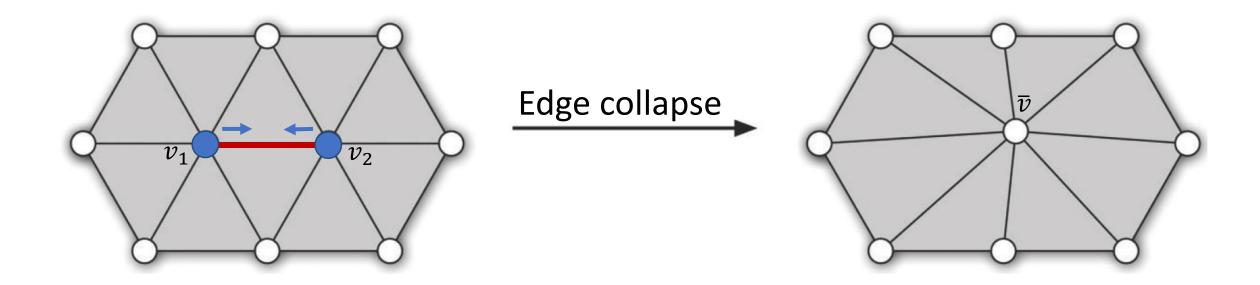
When to stop?

How to select?

How to simplify?

#### How to simplify?

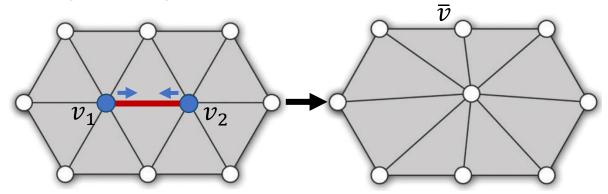
Edge Collapse: one edge contracted to one vertex



#### How to simplify?

Edge Collapse: one edge contracted to one vertex

Update position of new vertex: Quadric Error Metrics



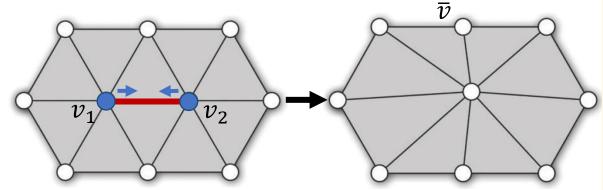
优化收缩点v的位置,使之尽可能接近原模型。 优化目标函数:

$$\overline{v} = \underset{v}{\operatorname{argmin}} \sum_{P \in plane(v_1) \cup plane(v_2)} distance(v, P)^2$$

plane(v)指顶点v邻接的三角面片集合

#### How to simplify?

Update position of new vertex: Quadraterror Metrics  $\overline{v}$   $\overline{v}$ 



优化收缩点 v的位置, 使之尽可能接近原模型。 优化目标函数:

$$\overline{v} = \underset{v}{\operatorname{argmin}} \sum_{P \in plane(v_1) \cup plane(v_2)} distance(v, P)^2$$

plane(v)指顶点v邻接的三角面片集合

dge Collapse: one edge contracted to 
$$choose p = [a,b,c,d]^T$$
,  $v = [x,y,z,1]^T$ ,

$$distance(v, P)^2 = (v^T p)^2 = v^T p p^T v = v^T K_p v$$

因此,设plane(v)为顶点v邻接的三角面片,收缩点的位置 可写为:

$$\overline{v} = \underset{v}{\operatorname{argmin}} v^{T} \left( \sum_{P \in plane(v_{1}) \cup plane(v_{2})} K_{p} \right) v$$

又因:

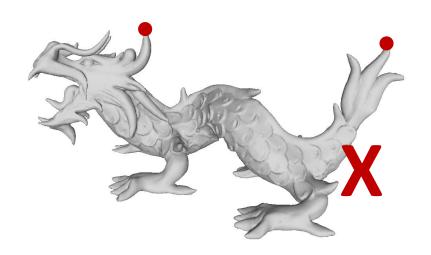
$$\overline{v} \approx \underset{v}{\operatorname{argmin}} v^{T} \left( \sum_{p \in plane(v_{1})} K_{p} + \sum_{p \in plane(v_{2})} K_{p} \right) v$$

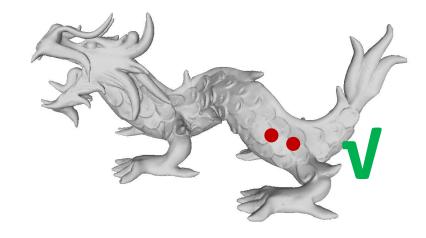
所以,最终可写成:

$$\overline{v} = \underset{v}{\operatorname{argmin}}$$
和  $O$  的 \$P\$ 通 计 算 得 到

#### How to select?

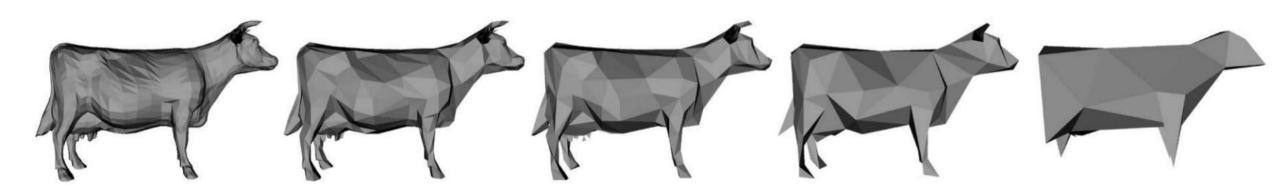
Select the connected nearby vertices





#### **QEM Algorithm Outline**

- 1. Compute the  $Q_v$  matrices for all the initial vertices.
- Select all valid vertex pairs.
- 3. Compute the optimal  $\overline{v}$  for each pair,  $\Delta(\overline{v})$  becomes the cost of contracting that pair.
- 4. Place all the pairs in a heap keyed on cost with the minimum cost pair at the top.
- 5. Iteratively remove the pair  $(v_1, v_2)$  of least cost from the heap, contract this pair, and update the costs of all valid pairs involving the new vertex  $\overline{v}$ .



# Thank you