



AHB-Lite Timer

Datasheet

[HTTP://ROALOGIC.GITHUB.IO/PLIC](http://roalogic.github.io/plic)

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1. Introduction

The Roa Logic AHB-Lite Timer IP is a fully parameterized soft IP implementing a user-defined number of timers and functions as specified by the RISC-V Privileged 1.9.1 specification.

The IP features an AHB-Lite Slave interface, with all signals defined in the *AMBA 3 AHB-Lite v1.0* specifications fully supported, supporting a single AHB-Lite based host connection. Bus address & data widths as well as the number of timers supported are specified via parameters.

The timebase of the timers is derived from the AHB-Lite bus clock, scaled down by a programmable value.

The module features a single Interrupt output which is asserted whenever an enabled timer is triggered

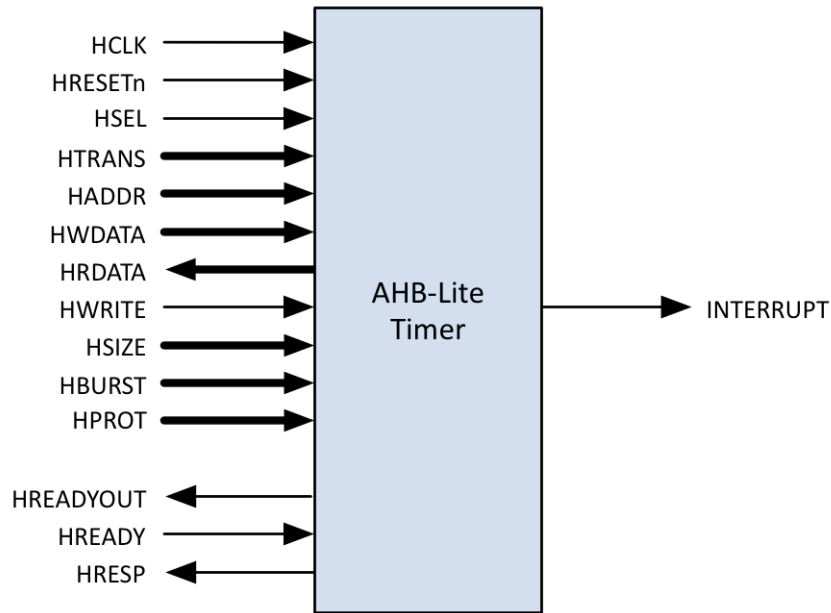


Figure 1.1: AHB-Lite Timer

1.1 Features

- AHB-Lite Interface with programmable address and data width
- User defined number of counters (Up to 32)
- Programmable time base derived from AHB-Lite bus clock

2. Specification

2.1 Functional Description

The AHB-Lite Timer IP is a fully parameterised Timer-tick core, featuring a single AHB-Lite Slave interface and a single multiplexed Interrupt output signal.

The Timer IP is intended to generate CPU interrupts at regular time intervals, for timed events such as time keeping, task/context switches, and sleep().

The number of timers and Address & Data width of the AHB-Lite interface are specified via parameters defined at compile time.

The time base of the timers is common to all timers and defined at runtime by writing to the `PRESCALER` register. Individual timer alarms may then set via the `TIMECMP[n]` registers. All timers are permanently enabled however a separate `IENABLE` register allows any triggered counter output to be masked.

The user may determine both the status of the `TIMERS` including which timer has generated an interrupt via a read operation to the AHB-Lite interface.

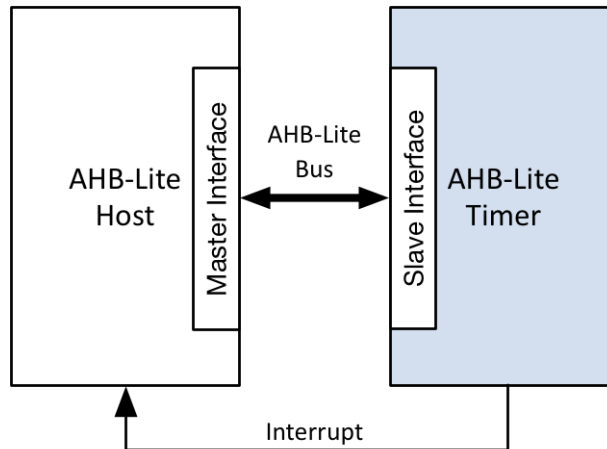


Figure 2.1: AHB-Lite Timer System Diagram

3. Configuration

3.1 Introduction

The size and implementation style of the timer module is defined via HDL parameters as specified below.

3.2 Core Parameters

Parameter	Type	Default	Description
TIMERS	Integer	3	Number of Timers
HADDR_SIZE	Integer	32	Width of AHB-Lite Address Bus
HDATA_SIZE	Integer	32	Width of AHB-Lite Data Buses

3.2.1 TIMERS

The parameter `TIMERS` defines the number of timers supported and thereby the number of `TIMECMP` registers implemented by the core. Values between 1 and 32 are supported, with the default defined as '3'.

3.2.2 HADDR_SIZE

The `HADDR_SIZE` parameter specifies the address bus size to connect to the AHB-Lite based host.

3.2.3 HDATA_SIZE

The `HDATA_SIZE` parameter specifies the data bus size to connect to the AHB-Lite based host. The maximum size supported is 64 bits.

3.3 Core Registers

Register	Address	Size	Access	Function
PRESCALER	Base + 0x00	32bits	Read/Write	Timebase
IPENDING	Base + 0x08	32bits	Read Only	Interrupt Pending
IENABLE	Base + 0x0C	32bits	Read/Write	Interrupt Enable
TIME	Base + 0x10	64bits	Read/Write	Timer Register
TIMECMP[n]	Base + 0x18+8n	64bits	Read/Write	Compare Value

Note: 'n' represents an integer for 0 to `TIMERS-1`.

3.3.1 PRESCALER

The Timer module operates synchronously with the AHB-Lite bus clock input HCLK. A 32 bit PRESCALER register enables the time base for the timers to be less than that of HCLK by dividing this clock frequency by the value of PRESCALER + 1.

For example: If PRESCALER=3, the timer will increment every PRESCALER+1=4 cycles of HCLK, setting the time base to HCLK/4 Hz.

The default value of PRESCALER=0, thereby setting the timer clock frequency equal to the bus (HCLK) frequency. The TIME counter starts incrementing once the register PRESCALER is written to for the first time.

Note: The value of PRESCALER value can only be defined once after the peripheral is released from reset.

3.3.2 IPENDING

IPENDING is a 32-bit read-only register that indicates if a timer interrupt is pending.

Each bit of the IPENDING register corresponds to one timer with the position of each bit indicating the associated timer. E.g. bit zero indicates the interrupt status of Timer[0]. IPENDING bits associated with unimplemented timers are tied low ('0')

An interrupt pending bit is set when the value of TIMECMP[n] equals the value of TIME. It is cleared by a write to the associated TIMECMP[n] register, as specified in the RISC-V privileged spec 1.9.1.

3.3.3 IENABLE

IENABLE is a 32-bit Read/Write register, where each bit of the register is a dedicated 'Interrupt Enable' bit for each time. The bit position indicates the associated timer. E.g. Interrupt Enable for Timer[0] is located at bit position 0.

Only TIMERS bits are implemented with the remaining MSBs always read as '0'. A write to the unused MSBs has no effect.

An interrupt is generated when a bit of IPENDING is set and its associated IENABLE bit is also set. This allows the core to be used in (1) pure POLL mode, where the CPU polls the status of the bits to determine if a timer event happened, (2) pure interrupt driven mode, where each timer can generate an interrupt, or (3) a combination of the above.

3.3.4 TIME

The TIME register is a common 64-bit high-resolution time-keeping counter used by all timers. It is the basis for the RDCYCLE instruction as specified in the RISC-V privileged spec 1.9.1 and may be written to also in accordance with the RISC-V specification.

The time base for the TIME register is derived from the AHB-Lite bus clock HCLK and is defined as:

$$\text{Freq}_{\text{TIME}} = \text{Freq}_{\text{HCLK}} / (\text{PRESCALER} + 1)$$

The counter starts incrementing once the register PRESCALER is written to for the first time.

3.3.5 TIMECMP[n]

For each timer (as defined by the parameter `TIMER`) there is a dedicated 64 bit Time Compare register which defines when the `IPENDING` bits are asserted

These registers are denoted as `TIMECMP[n]`, where 'n' is an index from 0 to `TIMERS-1`, and are located consecutively in the address space according to the formula:

Base Address of `TIMECMP[n]` = $0x18 + 8n$

For example, `TIMECMP[0]` is located at address `0x18`, `TIMECMP[1]` at `0x20`, `TIMECMP[5]` at `0x28` etc.

The `IPENDING` bit associated with the `TIMECMP` register is set when the `TIMECMP[n]` value equals the value of `TIME`.

`IPENDING[n] = (TIMECMP[n] == TIME)`

Writing the `TIMECMP[n]` register clears bit 'n' of the `IPENDING` register.

4. Interfaces

4.1 AHB-Lite Interface

The AHB-Lite interface is a regular AHB-Lite slave port. All signals are supported. See the [AMBA 3 AHB-Lite Specification](#) for a complete description of the signals.

Port	Size	Direction	Description
HRESETn	1	Input	Asynchronous active low reset
HCLK	1	Input	Clock Input
HSEL	1	Input	Bus Select
HTRANS	2	Input	Transfer Type
HADDR	HADDR_SIZE	Input	Address Bus
HWDATA	HDATA_SIZE	Input	Write Data Bus
HRDATA	HDATA_SIZE	Output	Read Data Bus
HWRITE	1	Input	Write Select
HSIZE	3	Input	Transfer Size
HBURST	3	Input	Transfer Burst Size
HPROT	4	Input	Transfer Protection Level
HREADYOUT	1	Output	Transfer Ready Output
HREADY	1	Input	Transfer Ready Input
HRESP	1	Output	Transfer Response

Table 4.1: PLIC Interface Signals

4.1.1 HRESETn

When the active low asynchronous HRESETn input is asserted ('0'), the interface is put into its initial reset state.

4.1.2 HCLK

HCLK is the interface system clock. All internal logic for the AHB-Lite interface operates at the rising edge of this system clock and AHB bus timings are related to the rising edge of HCLK.

4.1.3 HSEL

The AHB-Lite interface only responds to other signals on its bus – with the exception of the global asynchronous reset signal HRESETn – when HSEL is asserted ('1'). When HSEL is negated ('0') the interface considers the bus IDLE.

4.1.4 HTRANS

HTRANS indicates the type of the current transfer as shown in the table below:

HTRANS	Type	Description
00	IDLE	No transfer required
01	BUSY	Connected master is not ready to accept data, but intends to continue the current burst.
10	NONSEQ	First transfer of a burst or a single transfer
11	SEQ	Remaining transfers of a burst

Table 4.2: HTRANS Signal Types

4.1.5 HADDR

HADDR is the address bus. Its size is determined by the HADDR_SIZE parameter and is driven to the connected peripheral.

4.1.6 HWDATA

HWDATA is the write data bus. Its size is determined by the HDATA_SIZE parameter and is driven to the connected peripheral.

4.1.7 HRDATA

HRDATA is the read data bus. Its size is determined by the HDATA_SIZE parameter and is sourced by the connected peripheral.

4.1.8 HWRITE

HWRITE is the read/write signal. HWRITE asserted ('1') indicates a write transfer.

4.1.9 HSIZE

HSIZE indicates the size of the current transfer as shown in table 4.3:

HSIZE	Size	Description
000	8 bit	Byte
001	16 bit	Half Word
010	32 bit	Word
011	64 bits	Double Word
100	128 bit	
101	256 bit	
110	512 bit	
111	1024 bit	

Table 4.3: HSIZE Values

4.1.10 HBURST

HBURST indicates the transaction burst type – a single transfer or part of a burst.

HBURST	Type	Description
000	SINGLE	Single access
001	INCR	Continuous incremental burst
010	WRAP4	4-beat wrapping burst
011	INCR4	4-beat incrementing burst
100	WRAP8	8-beat wrapping burst
101	INCR8	8-beat incrementing burst
110	WRAP16	16-beat wrapping burst
111	INCR16	16-beat incrementing burst

Table 4.4: HBURST Types

4.1.11 HPROT

The HPROT signals provide additional information about the bus transfer and are intended to implement a level of protection.

Bit#	Value	Description
3	1	Cacheable region addressed
	0	Non-cacheable region addressed
2	1	Bufferable
	0	Non-bufferable
1	1	Privileged Access
	0	User Access
0	1	Data Access
	0	Opcode fetch

Table 4.5: HPROT Indicators

4.1.12 HREADYOUT

HREADYOUT indicates that the current transfer has finished. Note, for the AHB-Lite PLIC this signal is constantly asserted as the core is always ready for data access.

4.1.13 HREADY

HREADY indicates whether or not the addressed peripheral is ready to transfer data. When HREADY is negated ('0') the peripheral is not ready, forcing wait states. When HREADY is asserted ('1') the peripheral is ready and the transfer completed.

4.1.14 HRESP

HRESP is the instruction transfer response and indicates OKAY ('0') or ERROR ('1').

4.2 Timer Interface

4.2.1 `TIMER_INTERRUPT`

`TIMER_INTERRUPT` is a single output signal that is asserted the following conditions are both met:

1. Any bit of the `IPENDING` register is asserted
2. The corresponding bit of the `IENABLE` register is also asserted.

This may also be written as:

```
TIMER_INTERRUPT <= IPENDING & IENABLE
```

5. Resources

Below are some example implementations for various platforms. All implementations are push button, no effort has been undertaken to reduce area or improve performance.

Platform	DFF	Logic Cells	Memory	Performance (MHz)
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Table 5.1: Resource Utilization Examples

(This table will be updated in future revisions of the datasheet)

6. Revision History

Date	Rev.	Comments
13-Oct-2017	1.0	Initial Release

Table 6.1: Revision History