

1.)

State Sequence	Observation Sequence	State, τ
x , y, z, x	b, c, a, b	{start, x, y, z, x, stop}
x, z, y	a, c, a	{start, x, z, y, stop}
z, y, x, z, y	b, c, c, b, c	{start, z, y, x, z, y, stop}
z, x, y	c, b, a	{start, z, x, y, stop}
z, x, y	c, c, c	{start, z, x, y, stop}

Ex:

$$a'_{1,y} = \frac{\text{Count}(1,y)}{\text{Count}(x)} = \frac{3}{6} = \frac{1}{2}$$

a'

n/v	start	x	y	z	stop
start		2/5	0	3/5	0
x		0	1/2	1/3	1/6
y		1/6	0	1/6	2/3
z		1/2	1/2	0	0

I use a' and b'
to differentiate from a, b
in observation (o)

Ex: ~~b~~

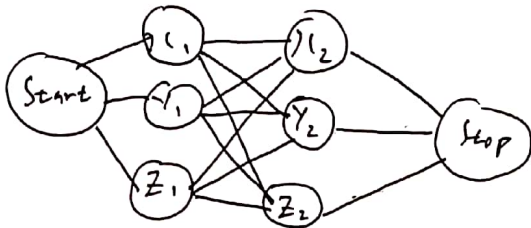
$$b'_1(o) = b'_1(a) = \frac{\text{Count}(x \rightarrow a)}{\text{Count } x} = \frac{2}{6} = \frac{1}{3}$$

$b'_1(o)$

	a	b	c
start x	1/6	1/2	1/3
y	1/3	0	2/3
z	1/6	1/3	1/2

2.) By ~~Bit~~ Viterbi Algorithm,

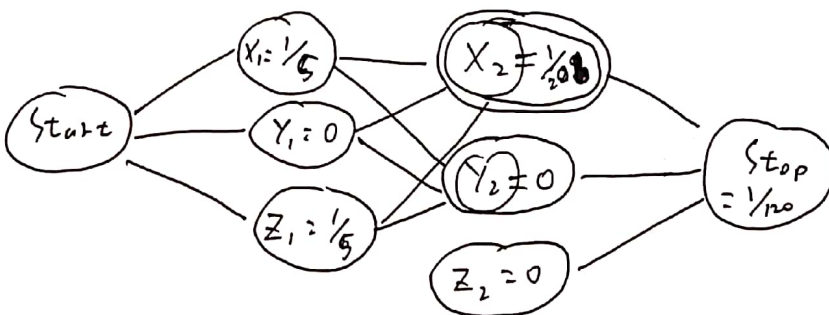
- 1.) We do forward pass to ~~get~~ populate the nodes
- 2.) We do a backward pass to get the highest prob



Step 1: Populating Nodes.

for $(b, 1)$ ~~Start~~ \rightarrow at Node $x_1, \Rightarrow a \in y_1, z_1 \Rightarrow$ substituting x_1 to y_1 or z_1 accordingly

$$Val = a'(start, x_1) \cdot b'_{x_1}(b) = \frac{2}{5} \times \frac{1}{2} = \frac{1}{5}$$



at Node $x_2, \Rightarrow y_2, z_2$, ~~substitute~~ substitute x_2 to y_2, z_2 .

at Stop Node

$$Val = \max \begin{bmatrix} x_1 \cdot a'(x_1, x_2) \cdot b'_{x_2}(b), \\ y_1 \cdot a'(y_1, x_2) \cdot b'_{x_2}(b), \\ z_1 \cdot a'(z_1, x_2) \cdot b'_{x_2}(b) \end{bmatrix}$$

$$\max \begin{bmatrix} x_2 \cdot a'(x_2, stop), \\ y_2 \cdot a'(y_2, stop), \\ z_2 \cdot a'(z_2, stop) \end{bmatrix}$$

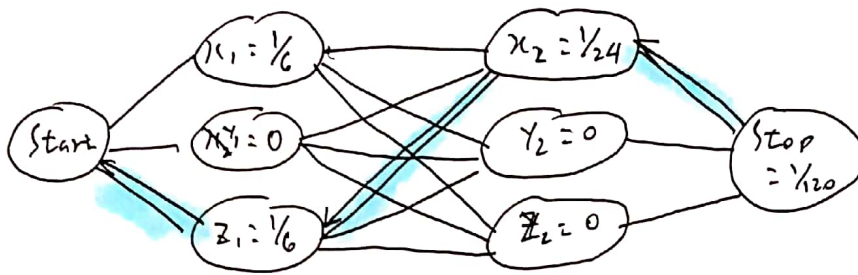
$$= \max \left[\frac{1}{20} \times \frac{1}{4}, 0, 0 \right]$$

$$= \max \left[0, \cancel{\frac{1}{20}}, \frac{1}{24} \right]$$

$$= \frac{1}{120} //$$

$$= \frac{1}{24}$$

Step 2: We do backward to find the path



\therefore Path = Start, z_1 , x_1 , Stop
 $= \{z, x\}$
~~##~~

$$3.) Y_1^*, \dots, Y_n^* = \arg \max_{Y_1, \dots, Y_n} P(x_1, \dots, x_n, Y_1, \dots, Y_n)$$

$l_i = \text{"the"}$

$Y_i = V$

$$Y_1^*, \dots, Y_{i-1}^*, Y_{i+1}^*, \dots, Y_n^* = \arg \max_{Y_1, \dots, Y_n} P(x_1, \dots, x_n, Y_1, \dots, Y_{i-1}, Y_{i+1}, \dots, Y_n | Y_i \neq V)$$

Algorithm:

1. Initialization

$$\pi(0, u) = \begin{cases} 1 & \text{if } u = \text{START} \\ 0 & \text{otherwise} \end{cases}$$

2.) ~~for $j = 0 \dots n-1$, for each $u \in T$~~

~~$$\pi(j+1, u) = \max_v \{ \pi(j, v) \times b_u(x_{j+1}) \times a_{v,u} \}$$~~

~~$$\pi(n+1, l_{\text{stop}}) = \max \{ \pi(n, v) \times a(v, l_{\text{stop}}) \}$$~~

2. for $j = 0 \dots n-1$, for each $u \in T$:

~~$\pi(j+1, u) = 0$~~ if $(j \neq i \ \& \ u = V)$:

$$\pi(j+1, u) = \max_v 0$$

else:

$$\pi(j+1, u) = \max_v \{ \pi(j, v) \times b_u(x_{j+1}) \times a_{v,u} \}$$

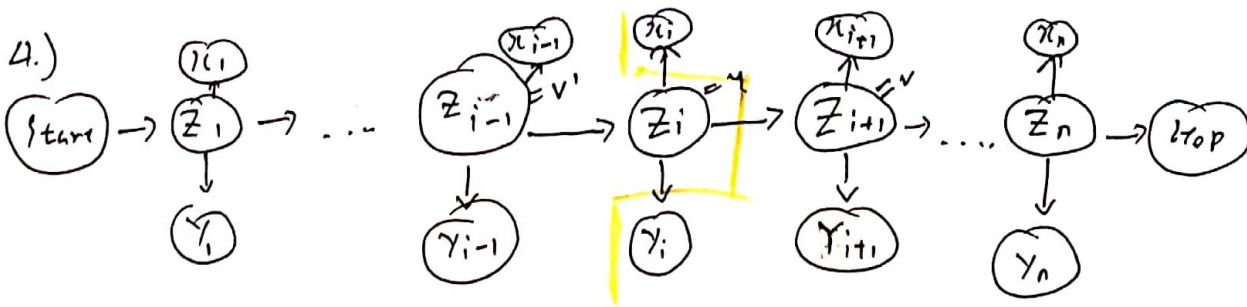
Final step:

$$\pi(n+1, \text{stop}) = \max_v \{ \pi(n, v) \times a_{v, \text{stop}} \}$$

Explanation:

I have added an additional conditional statements to check if the stage is i and the word is V , thus value of that node is 0. which will not be the max. (different w normal viterbi algo)

Ex: If $x(i) = \text{'the'}$, value of the node for label "verb"(V) will be zero and thus the max label will not be verb.



$$P = \frac{P(x_1, \dots, x_{i-1}, y_1, \dots, y_{i-1}, z_i = u, x_i, \dots, x_n, y_i, \dots, y_n; \theta)}{\sum_v P(x_1, \dots, x_{i-1}, y_1, \dots, y_{i-1}, z_i = v, x_i, \dots, x_n, y_i, \dots, y_n; \theta)}$$

$$P = \frac{\alpha_u(l_i) \beta_u(l_i)}{\sum_v \alpha_v(l_i) \beta_v(l_i)}$$

$$\alpha_u(l_i) = P(x_1, \dots, x_{i-1}, y_1, \dots, y_{i-1}, z_i = u)$$

Sum of all scores from start to node u at stage i.

Forward Pass,

$$\alpha_v(l_{i+1}) = \sum_u \alpha_u(l_i) \cdot a_{uv} \cdot b_u(x_i) \cdot b_v(y_i)$$

algorithm from left to right

$$\frac{\beta_{start}(u)}{\alpha_u(l_1)} = a_{start,u}$$

$$\beta_u(l_i) = P(x_i, \dots, x_n, y_i, \dots, y_n | z_i = u)$$

Sum of all scores from node u at stage i to stop

Backward Pass,

$$\beta_u(l_i) = \sum_v a_{uv} \cdot b_u(x_i) \cdot b_v(y_i) \beta_v(l_{i+1})$$

algorithm from right to left.

4.) Time Complexity :

No of states = N , $(0, \dots, N)$

No of nodes within a state = n nodes,
assuming there are n unique labels, $\{z_1, \dots, z_n\}$

In the forward pass, we need to calculate value for each node and then find the max.

Therefore, within one state, Time is $O(n^2)$

Since there are N states, Time is $O(Nn^2)$
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