# TDDE09 Project Presentation Group 03

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### Outline

- Baseline System and Feature engineering
- Perceptron based
  - Non-projective trees
  - Beam search
- Neural network based
  - POS tagger
  - Syntactic parser



## Baseline system

- 64.60% (65.18%) accuracy on English dataset
- 59.60% (62.13%) accuracy on Swedish dataset
- 74.88% (71.46%) accuracy on French dataset

## After feature engineering

- 76.11% (76.79%) accuracy on English dataset
- 71.98% (75.28%) accuracy on Swedish dataset
- 81.22% (78.43%) accuracy on French dataset



## Non-projective trees

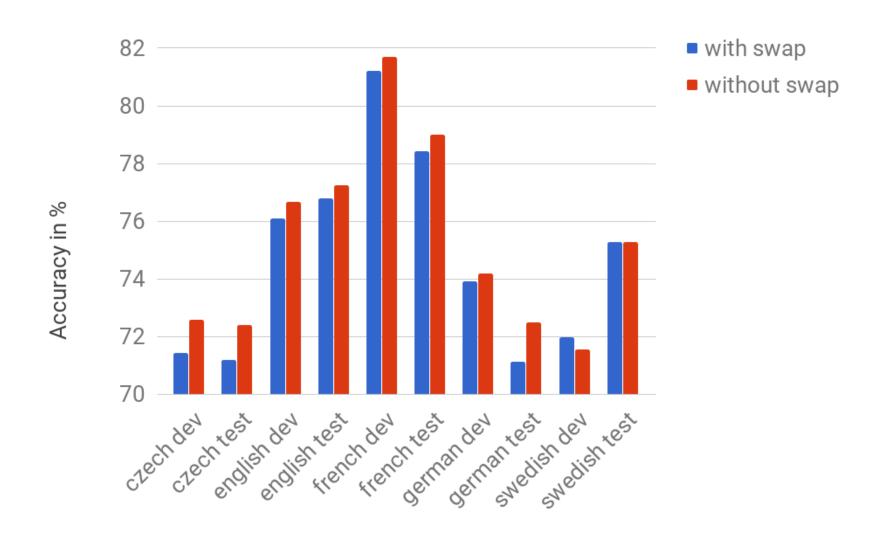
- Non-projective trees exist in reality
- Possible improvement in accuracy
- Introduce "swap"-operation

Research article:

Non-Projective Dependency Parsing in Expected Linear Time



## Non-projective trees - Results





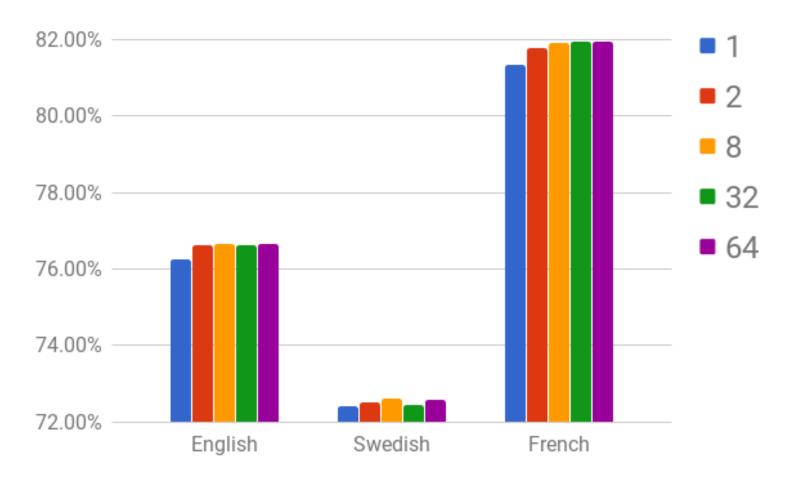
#### **Beam Search**

- During the transition-based parsing
- At each step, apply all possible moves, not only the predicted one
- Always consider multiple partial dependency trees at the same time
- Reduces error propagation
- Similar to a Breadth-first search
- Can be implemented for both training and parsing
- Research article: <u>A Tale of Two Parsers</u>



### Beam Search - Results

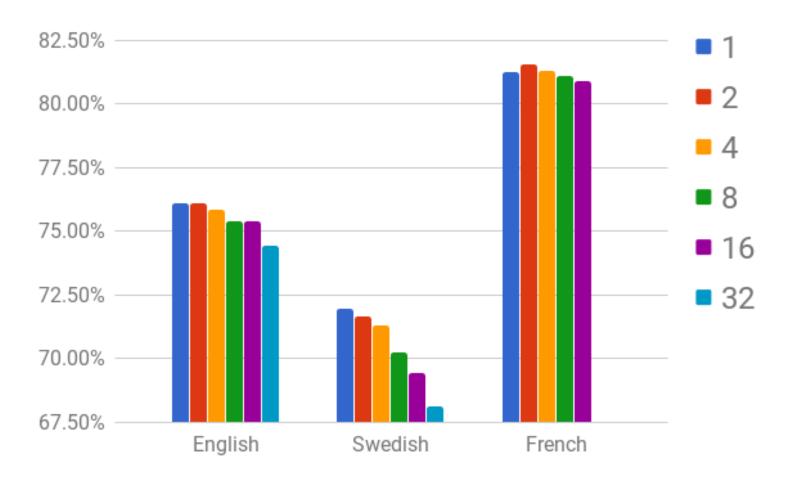
Beam search for parsing only





#### Beam Search - Results

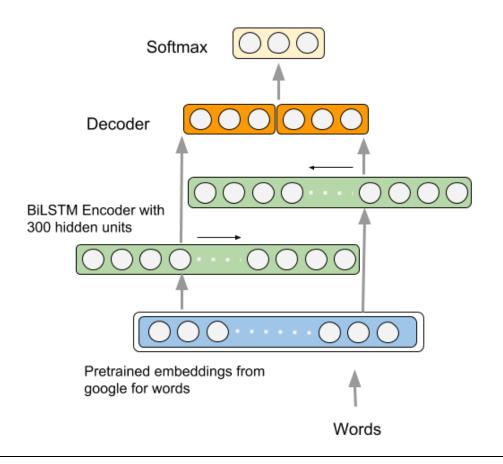
Beam search for training and parsing





## NN - POS Tagger

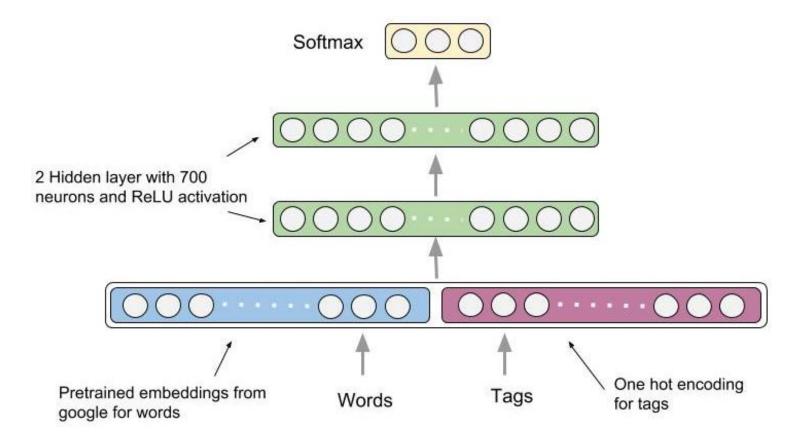
 Based on: POS Tagging with Bidirectional LSTM RNN <a href="https://arxiv.org/pdf/1510.06168.pdf">https://arxiv.org/pdf/1510.06168.pdf</a>





## NN - Dependency Parser

 Based on A <u>Fast and Accurate Dependency Parser</u> <u>using Neural Networks</u> by Chen and Manning





#### NN - Results

#### Score on the test data

	Tagging Accuracy	UAS	Exact matches
LSTM	88.97	79.81	47.47
Neural Net	92.91	79.77	48.94
Perceptron	92.94	80.45	48.67

- Observation: Word embeddings help generalize to unseen words.
  - ~2 % improvement when using pretrained word embeddings for unseen word, as opposed to using a random embedding
- Note: Due to random initialization of the weights, the results can vary between different runs. The values provided are average over 3 runs



#### Conclusion and Outlook

- Reimplemented 4 topics
  - features, "swap", beam-search, neural networks
- Largest improvement by feature engineering (~10%)
- Less improvement compared to the papers
- Many more possibilities:
  - Pretrain word embeddings
  - Larger training data sets
  - Combine approaches:
    - e.g. Beam search with Neural Network
    - Conditional Random Field to predict a Viterbisequence

