

view\_frames Result

Recorded at time: 457.146

map

Broadcaster: /odom\_map\_broadcaster  
Average rate: 10.231 Hz  
Most recent transform: 457.195 ( -0.049 sec old)  
Buffer length: 4.105 sec

odom

Broadcaster: /gazebo  
Average rate: 10.244 Hz  
Most recent transform: 457.124 ( 0.022 sec old)  
Buffer length: 4.100 sec

robot\_footprint

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 457.146 sec old)  
Buffer length: 0.000 sec

chassis

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 457.146 sec old)  
Buffer length: 0.000 sec

camera

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 457.146 sec old)  
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot\_state\_publisher  
Average rate: 10.244 Hz  
Most recent transform: 457.067 ( 0.079 sec old)  
Buffer length: 4.100 sec

left\_wheel

Broadcaster: /robot\_state\_publisher  
Average rate: 10.244 Hz  
Most recent transform: 457.067 ( 0.079 sec old)  
Buffer length: 4.100 sec

right\_wheel