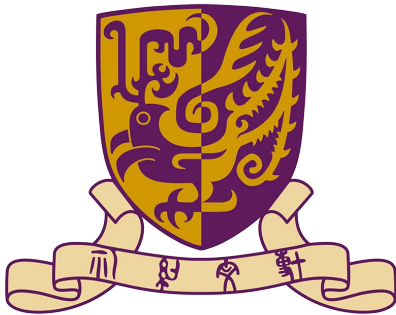


EIE4512 - Digital Image Processing

Geometric Operations



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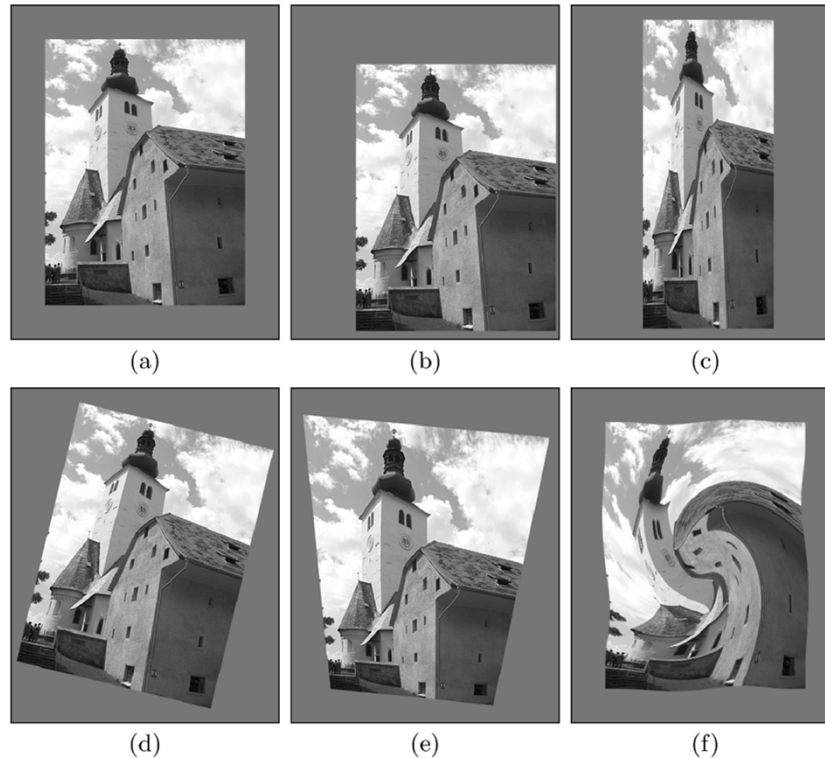
The Chinese University of Hong Kong, Shen Zhen

April 4, 2019

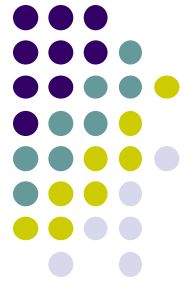


Geometric Operations

- Filters, point operations change intensity
- Pixel position (and geometry) unchanged
- Geometric operations: change image geometry
- **Examples:** translating, rotating, scaling an image



**Examples of
Geometric
operations**



Geometric Operations

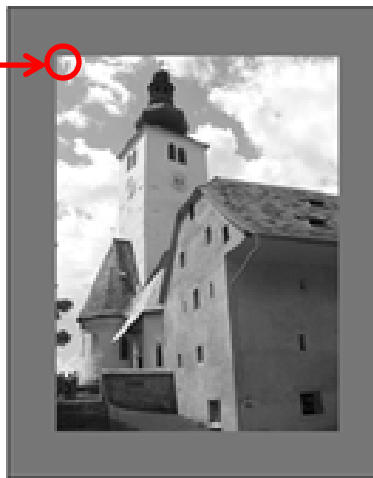
- Example applications of geometric operations:
 - Zooming images, windows to arbitrary size
 - Computer graphics: deform textures and map to arbitrary surfaces
- **Definition:** Geometric operation transforms image I to new image I' by modifying **coordinates of image pixels**

$$I(x, y) \rightarrow I'(x', y')$$

- Intensity value originally at (x, y) moved to new position (x', y')

Example: Translation
geometric operation
moves value at
 (x, y) to $(x + d_x, y + d_y)$

(x, y) →



← $(x + d_x, y + d_y)$





Geometric Operations

- Since image coordinates can only be discrete values, some transformations may yield (x', y') that's not discrete
- **Solution:** interpolate nearby values



Simple Mappings

- **Translation:** (shift) by a vector (d_x, d_y)

$$\begin{aligned} T_x : x' &= x + d_x \\ T_y : y' &= y + d_y \end{aligned} \quad \text{or} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} d_x \\ d_y \end{pmatrix}$$

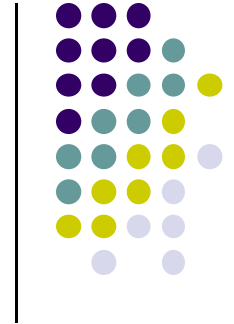


- **Scaling:** (contracting or stretching) along x or y axis by a factor s_x or s_y

$$\begin{aligned} T_x : x' &= s_x \cdot x \\ T_y : y' &= s_y \cdot y \end{aligned} \quad \text{or} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} s_x & 0 \\ 0 & s_y \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

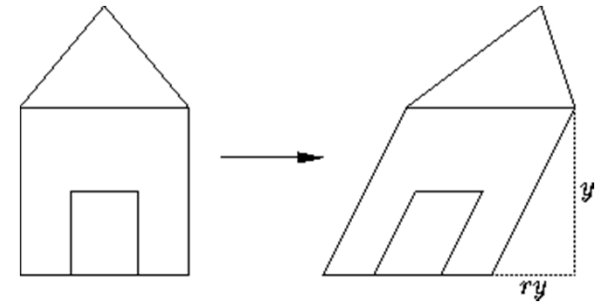


Simple Mappings



- **Shearing:** along x and y axis by factor b_x and b_y

$$\begin{aligned} T_x : x' &= x + b_x \cdot y \\ T_y : y' &= y + b_y \cdot x \end{aligned} \quad \text{or} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 1 & b_x \\ b_y & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$



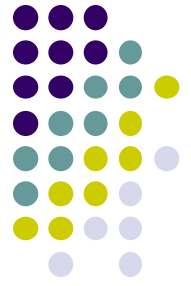
- **Rotation:** the image by an angle α

$$\begin{aligned} T_x : x' &= x \cdot \cos \alpha - y \cdot \sin \alpha \\ T_y : y' &= x \cdot \sin \alpha + y \cdot \cos \alpha \end{aligned}$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

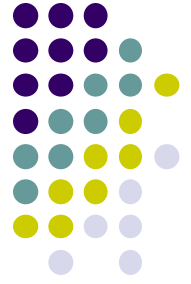


Image Flipping & Rotation by 90 degrees



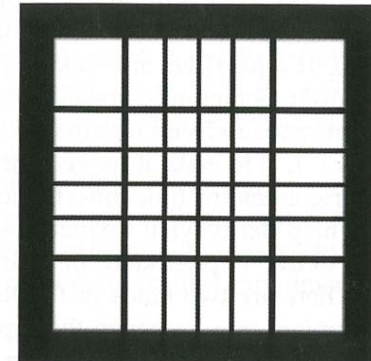
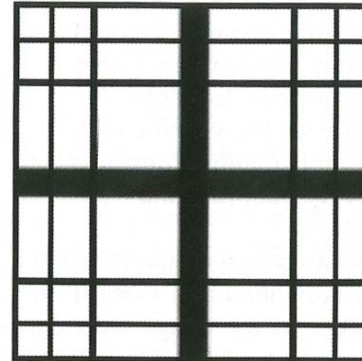
- We can achieve 90,180 degree rotation easily
- Basic idea: Look up a **transformed pixel address** instead of the current one
- To flip an image upside down:
 - At pixel location xy , look up the color at location $x(1 - y)$
- For horizontal flip:
 - At pixel location xy , look up $(1 - x)y$
- Rotating an image 90 degrees counterclockwise:
 - At pixel location xy , look up $(y, 1 - x)$

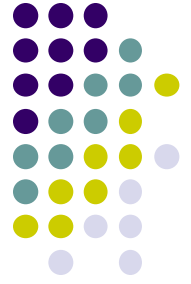
Image Flipping, Rotation and Warping



- **Image warping:** we can use a function to select which pixel somewhere else in the image to look up
- For example: apply function on both texel coordinates (x, y)

$$x = x + y * \sin(\pi * x)$$



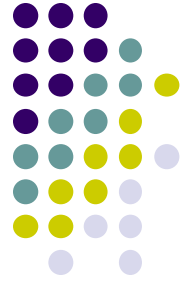


Homogeneous Coordinates

- Notation useful for converting scaling, translation, rotating into point-matrix multiplication
- To convert ordinary coordinates into homogeneous coordinates

$$\mathbf{x} = \begin{pmatrix} x \\ y \end{pmatrix} \quad \text{converts to} \quad \hat{\mathbf{x}} = \begin{pmatrix} \hat{x} \\ \hat{y} \\ h \end{pmatrix} = \begin{pmatrix} h x \\ h y \\ h \end{pmatrix}$$

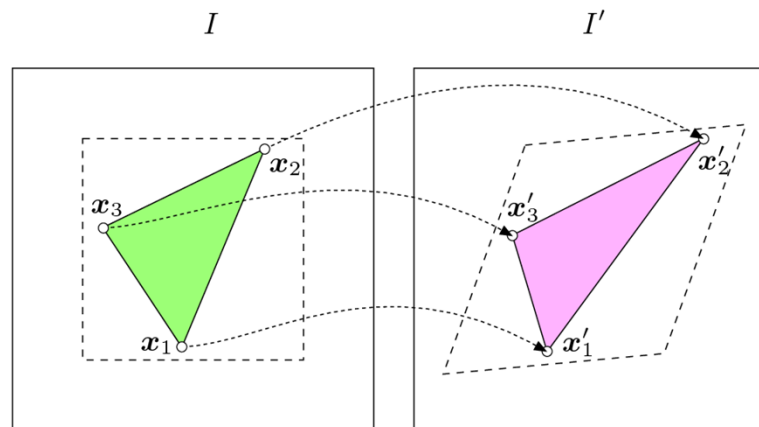
Affine (3-Point) Mapping



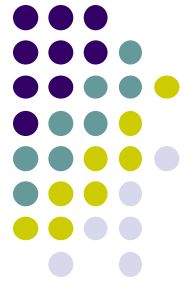
- Can use homogeneous coordinates to rewrite translation, rotation, scaling, etc as vector-matrix multiplication

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

- **Affine mapping:** Can then derive values of matrix that achieve desired transformation (or combination of transformations)

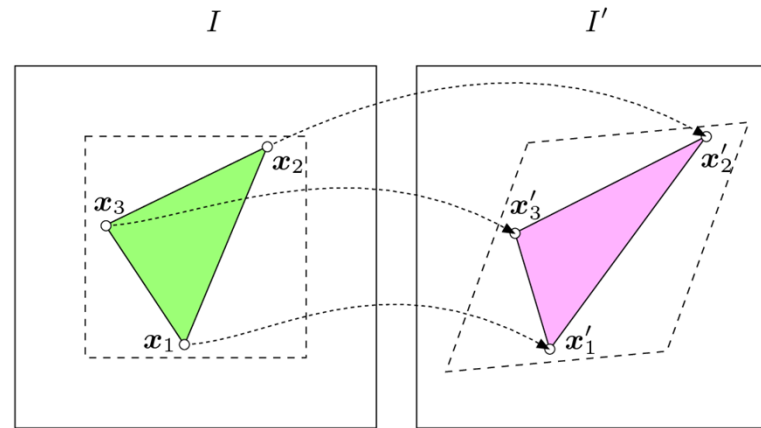


- Inverse of transform matrix is **inverse mapping**



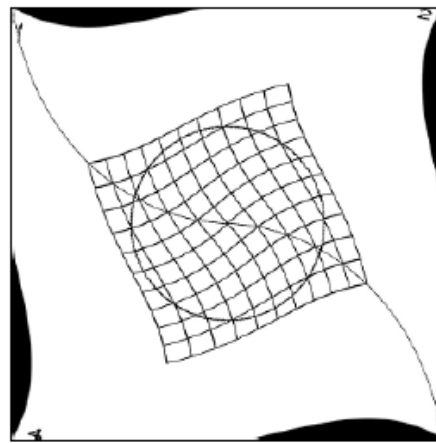
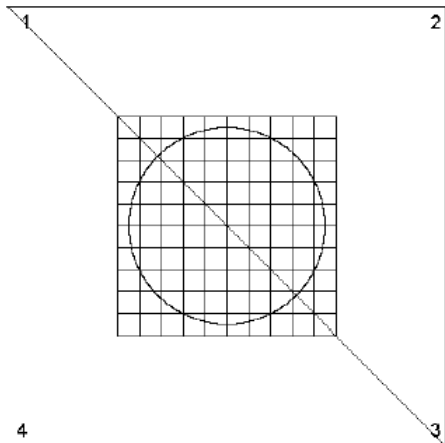
Affine (3-Point) Mapping

- What's so special about affine mapping?

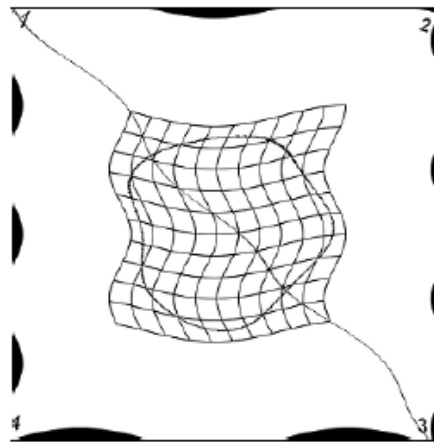


- Maps
 - straight lines \rightarrow straight lines,
 - triangles \rightarrow triangles
 - rectangles \rightarrow parallelograms
 - Parallel lines \rightarrow parallel lines
- Distance ratio on lines do not change

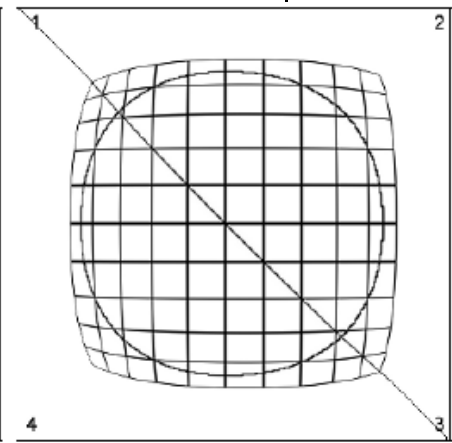
Non-Linear Image Warps



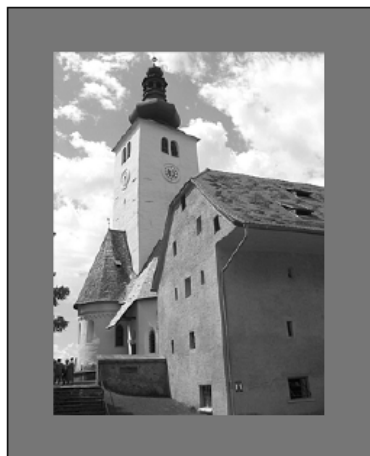
(a)



(b)



(c)



Original



(d)

Twirl



(e)

Ripple



(f)

Spherical

Twirl

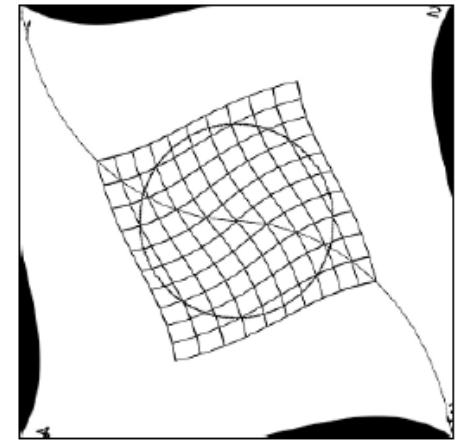
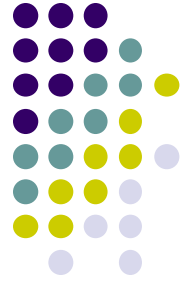
- **Notation:** Instead using texture colors at (x', y') , use texture colors at twirled (x, y) location
- Twirl?
 - Rotate image by angle α at center or anchor point (x_c, y_c)
 - Increasingly rotate image as radial distance r from center increases (up to r_{\max})
 - Image unchanged outside radial distance r_{\max}

$$T_x^{-1} : x = \begin{cases} x_c + r \cdot \cos(\beta) & \text{for } r \leq r_{\max} \\ x' & \text{for } r > r_{\max}, \end{cases}$$

$$T_y^{-1} : y = \begin{cases} y_c + r \cdot \sin(\beta) & \text{for } r \leq r_{\max} \\ y' & \text{for } r > r_{\max}, \end{cases}$$

with

$$\begin{aligned} d_x &= x' - x_c, & r &= \sqrt{d_x^2 + d_y^2}, \\ d_y &= y' - y_c, & \beta &= \text{Arctan}(d_y, d_x) + \alpha \cdot \left(\frac{r_{\max} - r}{r_{\max}} \right). \end{aligned}$$



(a)



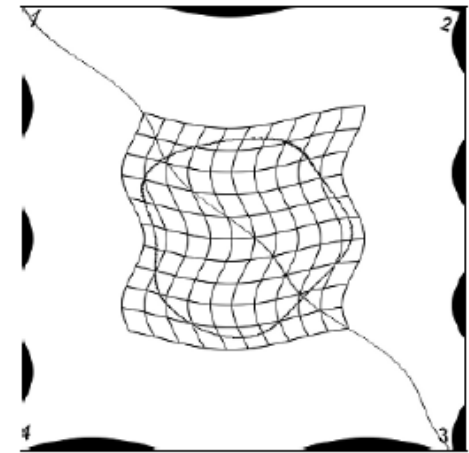
(d)

Ripple

- Ripple causes wavelike displacement of image along both the x and y directions

$$T_x^{-1} : x = x' + a_x \cdot \sin\left(\frac{2\pi \cdot y'}{\tau_x}\right),$$
$$T_y^{-1} : y = y' + a_y \cdot \sin\left(\frac{2\pi \cdot x'}{\tau_y}\right).$$

- Sample values for parameters (in pixels) are
 - $\tau_x = 120$
 - $\tau_y = 250$
 - $a_x = 10$
 - $a_y = 15$



(b)



(e)

Spherical Transformation

- Imitates viewing image through a lens placed over image
- Lens parameters: center (x_c, y_c) , lens radius r_{\max} and refraction index ρ
- Sample values $\rho = 1.8$ and $r_{\max} = \text{half image width}$

$$T_x^{-1} : \quad x = x' - \begin{cases} z \cdot \tan(\beta_x) & \text{for } r \leq r_{\max} \\ 0 & \text{for } r > r_{\max}, \end{cases}$$

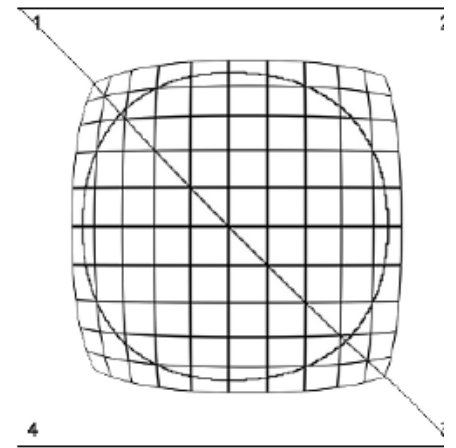
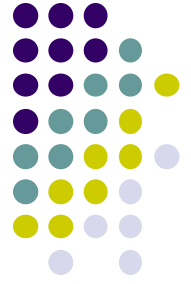
$$T_y^{-1} : \quad y = y' - \begin{cases} z \cdot \tan(\beta_y) & \text{for } r \leq r_{\max} \\ 0 & \text{for } r > r_{\max}, \end{cases}$$

$$d_x = x' - x_c, \quad r = \sqrt{d_x^2 + d_y^2},$$

$$d_y = y' - y_c, \quad z = \sqrt{r_{\max}^2 - r^2},$$

$$\beta_x = \left(1 - \frac{1}{\rho}\right) \cdot \sin^{-1}\left(\frac{d_x}{\sqrt{d_x^2 + z^2}}\right),$$

$$\beta_y = \left(1 - \frac{1}{\rho}\right) \cdot \sin^{-1}\left(\frac{d_y}{\sqrt{d_y^2 + z^2}}\right).$$



(c)



(f)

Image Warping

