

## 原 编写字符设备驱动实现内核态与用户态通信

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本次主要实现的是通过编写字符设备，实现从用户态获得只有内核态才有权访问的进程段地址（比如代码段，其他同理）

初稿主要代码如下：

firstdriver.c

```
1  /* 字符注册模块实现如下*/
2  #include<linux/slab.h>
3  #include<linux/module.h>
4  #include<linux/init.h>
5  #include<linux/types.h>
6  #include<linux/errno.h>
7  #include<linux/fs.h>
8  #include<linux/mm.h>
9  #include<linux/cdev.h>
10 #include<asm/io.h>
11 #include<linux/sched.h>
12 #include<asm/uaccess.h>
13 #include<linux/kernel.h>
14 #include<linux/list.h>
15 #include<linux/sem.h>
16 #include<linux/pid.h>
17
18
19 #define MAJOR_NUM 260
20 #define MINOR_NUM 0
21 #define MINIOR_NUM 0
22 #define DEVICE_NUM 1
23
24
25 // 以下为驱动需要实现的四个函数的生命，注册之后，用户态程序即调用此对应函数
26 static int firstdriver_open(struct inode *, struct file *);
27 static int firstdriver_release(struct inode *,struct file *);
28 static ssize_t firstdriver_read(struct file *, char __user *,size_t, loff_t *);
29 static ssize_t firstdriver_write(struct file *,char __user *,size_t ,loff_t *);
30 struct ret_type //定义返回用户态的函数类型
31 {
32     unsigned long start_code;
33     unsigned long end_code;
34 };
35
36 static int firstdriver_major = MAJOR_NUM; //定义主设备号
37 static int firstdriver_minor = MINOR_NUM; //定义次设备号
38 struct file_operations firstdriver_fops =
39 {
40     .owner = THIS_MODULE,
41     .open = firstdriver_open,
42     .write = firstdriver_write,
43     .release = firstdriver_release,
44     .read = firstdriver_read,
45 };
46 struct cdev *cdev;
47 static pid_t pidno = 1;
48 static int __init firstdriver_init(void)
49 {
50     int ret = 0;
51     dev_t devno = MKDEV(MAJOR_NUM,MINOR_NUM);
52     cdev = cdev_alloc();//分配设备空间，这里为了简单，静态指定了设备号，最好动态申请
53     if(register_chrdev_region(devno,DEVICE_NUM,"firstdriver"))
54     {
55         printk(KERN_ALERT"register_chrdev_region fail\n");
56         return -1;
57     }
58     else
59     {
60         cdev_init(cdev,&firstdriver_fops);
61         cdev->owner = THIS_MODULE;
```

```
62         cdev->ops = &firstdriver_fops;
63         if((ret = cdev_add(cdev,devno,1)))
64             printk(KERN_ALERT"Error in adding firstdriver\n");
65     else
66         printk(KERN_ALERT"register success\n");
67     }
68     return ret;
69 }
70 static void __exit firstdriver_exit(void)
71 {
72     dev_t devno = MKDEV(MAJOR_NUM,0);
73     cdev_del(cdev);
74     unregister_chrdev_region(devno,1);
75     if(cdev)
76         kfree(cdev);
77     cdev = NULL;
78 }
79 static int firstdriver_open(struct inode * inode ,struct file * filp)
80 {
81     printk(KERN_ALERT"open succedd\n");
82     return 0;
83 }
84 static int firstdriver_release(struct inode* inode, struct file *filp)
85 {
86     printk(KERN_ALERT"release success\n");
87     return 0;
88 }
89 static ssize_t firstdriver_read(struct file *filp,char *buf,size_t len, loff_t * off)
90 {
91     printk("READING:\n");
92     struct task_struct *p = NULL;
93     struct ret_type *tmp;
94     struct pid *kpid = find_get_pid(pidno);
95     tmp = kmalloc(sizeof(*tmp),GFP_KERNEL);
96     if(tmp == NULL){
97         return -ENOMEM;
98     }
99     p = pid_task(kpid,PIDTYPE_PID);
100     if(p == NULL){
101         kfree(tmp);
102         printk(KERN_ALERT"find task failed\n");
103         return -1;
104     }
105     if(p->mm == NULL){
106         kfree(tmp);
107         printk(KERN_ALERT"mm = NULL error\n");
108         return -1;
109     } else {
110         tmp->start_code = p->mm->start_code;
111         tmp->end_code = p->mm->end_code;
112         printk(KERN_ALERT"start_code: %lu\n",tmp->start_code);
113         printk(KERN_ALERT"end_code: %li\n",tmp->end_code);
114     }
115     if(copy_to_user(buf,tmp,sizeof(*tmp)))
116         return -EFAULT;
117     return sizeof(*tmp);
118 }
119 static ssize_t firstdriver_write(struct file *filp,char * buf,size_t len,loff_t * off)
120 {
121     printk("writing:\n");
122     if(copy_from_user(&pidno,buf,sizeof(int)))
123         return -EFAULT;
124     return sizeof(int);
125 }
126 module_init(firstdriver_init);
127 module_exit(firstdriver_exit);
128
129 MODULE_LICENSE("GPL");
130 MODULE_AUTHOR("firstdriver");
131
```

test.c

```
1  #include<stdlib.h>
2  #include<unistd.h>
3  #include<stdio.h>
4  #include<fcntl.h>
5  #include<malloc.h>
6  struct ret_type
7  {
8      unsigned long start_code;
9      unsigned long end_code;
10 };
11 int main(int argc,char *argv[])
12 {
13     struct ret_type *tmp;
14     tmp = (struct ret_type *)malloc(sizeof(struct ret_type));
15     if(tmp == NULL)
16     {
17         printf("malloc error\n");
18         return -1;
19     }
20     int fd,num;
21     num = atoi(argv[1]);
22     printf("num is %d\n",num);
23
24     fd = open("/dev/firstdriver",O_RDWR,S_IRUSR|S_IWUSR);
25     if(fd != -1){
26         int n;
27         n = write(fd,&num,sizeof(int));
28         if(n != sizeof(int)){
29             printf("write error\n");
30             goto out;
31         }
32         n = read(fd,tmp,sizeof(*tmp));
33         if(n != sizeof(*tmp)){
34             printf("read error, n = %d\n",n);
35             goto out;
36         }
37         n = read(fd,tmp,sizeof(*tmp));
38         if(n != sizeof(*tmp)){
39             printf("read error, n = %d\n",n);
40             goto out;
41         }
42         printf("start_code is %lu \n",tmp->start_code);
43         printf("end_code is %lu \n",tmp->end_code);
44
45         close(fd);
46     }
47     else
48         printf("device open failed \n");
49
50     out:free(tmp);
51     return 0;
52 }
53
```

getchar.c

```
1  #include<stdio.h>
2  int main()
3  {
4      getchar();
5      return 0;
6  }
```

以超级用户身份执行以下事项:

1.make 生成模块文件,firstdriver.ko;

```
2.insmod firstdriver.ko;  
3.cd /dev, mknod firstdriver c 260 0  
4.gcc -o getchar getchar.c  
5. ./getchar &  
6.gcc -o test test.c  
7. ./test (5生成的后台运行的进程号)  
8.可看到结果如下:  
  
start_code: 4194304  
end_code: 4196284
```

参考:

- 1.[http://www.360doc.com/content/14/0123/19/14451193\\_347404829.shtml](http://www.360doc.com/content/14/0123/19/14451193_347404829.shtml)
- 2.<http://blog.chinaunix.net/uid-20662363-id-1904086.html>
- 3.<http://blog.csdn.net/rainbolide/article/details/7335888>
- 4.[http://www.360doc.com/content/10/1130/20/1378815\\_73825191.shtml](http://www.360doc.com/content/10/1130/20/1378815_73825191.shtml)
- 5.[http://www.360doc.com/content/12/0901/16/10588621\\_233591860.shtml](http://www.360doc.com/content/12/0901/16/10588621_233591860.shtml)



### 人工智能难学？也许能让你抓住未来的饭碗

人工智能技术向前发展，也必然会出现一些岗位被人工智能取代，但我们相信，随着人工智能的发展，会有更多的新的、属于未来的工作岗位出现，是社会发展的必然产物，我们能做的也许只能是与时俱进了