Machine Learning Autoencoder Applied to Communication Channels

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ISAE-SUPAERO, 2019



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Outline

- Introduction
- Methodology
 - Reference Model
 - Design & Architecture
 - Training
 - Error Correction & Predictions
- Results & Discussions
 - DNN Decoders
 - DNN Autoencoders
 - Time Analysis
- 4 Conclusions
- 5 Future Work



Context

Communication system context in general - what field will I be treating

- My first point.
- My second point.



Context

Machine Learning applications - what could we do in communication system

- My first point.
- My second point.



Relevance & Challenges

Explain why the work is relevant and explain what are the challenges

- My first point.
- My second point.



Problem Statement

What exactly I will solve in this work

- My first point.
- My second point.



• First item.



- First item.
- Second item.



- First item.
- Second item.
- Third item.



- First item.
- Second item.
- Third item.
- Fourth item.



- First item.
- Second item.
- Third item.
- Fourth item.
- Fifth item.



- First item.
- Second item.
- Third item.
- Fourth item.
- Fifth item. Extra text in the fifth item.



Maximum a Posterior (MAP) Rule

Implementation of a MAP decoder for a linear block code through a BSC.

Algorithm 1 MAP rule for BSC and linear block code.

Input: received block $\mathbf{y}^n \in \{0,1\}^n$, code word set \mathcal{X} and generator matrix $G_{k \times n}$.

Output: message estimation $\hat{\mathbf{u}}^k \in \{0,1\}^k$.

procedure MAP DECODER (y, \mathcal{X}, G)

 $p \leftarrow$ channel crossover probability

for i in $range(2^k)$ do

 $distances[i] \leftarrow d_H(\mathbf{y}, word[i] \in \mathcal{X})$

 $\hat{\mathbf{x}} \leftarrow argmin(\text{distances})$

 $\hat{\mathbf{u}} \leftarrow \hat{\mathbf{x}} G^{-1}$ return $\hat{\mathbf{u}}$



Neural Network's Architecture I

Show the architecture used for each case and remarks some important parameters

Table: DNN array decoder architecture and parameters.

•		Dense: 128, activation: ReLU, input size: n		
	Decoder	Dense: 64, activation: ReLU Dense: 32, activation: ReLU		
•		Dense: 32, activation: ReLU		
		Dense: k , activation: Sigmoid		
Total parameters: 12776				

Table: DNN one-hot decoder architecture and parameters.

•	Decoder	Dense: 256, activation: Softmax, input size: <i>n</i>				
	Total parameters: 4352					



Neural Network's Architecture II

Show the architecture used for each case and remarks some important parameters

Table: DNN array autoencoder architecture and parameters.

•	Encoder	Dense: X, activation: ReLU, input size: k	
		Dense: X, activation: ReLU	
		Dense: n , activation: Sigmoid	
	Channel	Lambda: $Round(\mathbf{x})$, input size: n	
		Lambda: $\mathbf{x} \oplus \text{noise}$	
	Decoder	Dense: X, input size: n	
		Dense: X, activation: ReLU	
		Dense: k , activation: Sigmoid	
	Total parameters: XX		



Neural Network's Training

Show the best training parameters for each structure

Table: DNN array decoder training parameters.

Loss func.	Optimizer	N. Epochs	Batch Size
Binary cross-entropy	Adam	2^{16}	256

Table: DNN one-hot decoder training parameters.

Loss func.	Optimizer	N. Epochs	Batch Size
Binary cross-entropy	Adam	2^{14}	256

Table: DNN array autodecoder training parameters.

Loss func.	Optimizer	N. Epochs	Batch Size
Binary cross-entropy	Adam	2^{14}	256



Error Correction and Monte Carlo Simulations

Explain how we could use NN to predict the results with certain confidence.

- My first point.
- My second point.



Blocks

Block Title

You can also highlight sections of your presentation in a block, with it's own title

Theorem

There are separate environments for theorems, examples, definitions and proofs.

Example

Here is an example of an example block.



DNN Array Decoder

Show the results for the array decoder in terms of train p, Mep, Parameters, etc

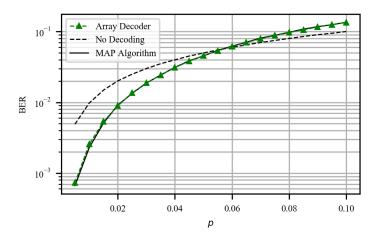


Figure: Array decoding BER performance. NN trained with a channel crossoverage probability error of $p_t = 0.07$.

DNN One-hot Decoder

Show the results for the one-hot decoder in terms of train p, Mep, Parameters, etc

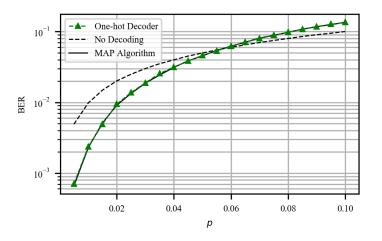


Figure: One hot decoding BER performance. NN decoder trained with a change crossover probability error of $p_t=0$.

DNN Autoencoder

Show the results for the autoencoder in terms of train p, Mep, Parameters, etc

- My first point.
- My second point.



Delay Time Analysis

Comparison of decoding time for each method.

Table: Decoding time comparison between the MAP algorithm and the DNN decoders and autoencoders. The data is normalized to the mean MAP algorithm decoding time.

MAP	A. Dec.	One-hot Dec.	A. Auto.	One-hot Auto.
1.00 ± 0.02	0.74 ± 0.03	0.76 ± 0.02	土	±



Conclusions

- My first point.
- My second point.



Future Work

- My first point.
- My second point.



Acknowledgment

- My first point.
- My second point.



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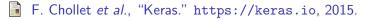


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