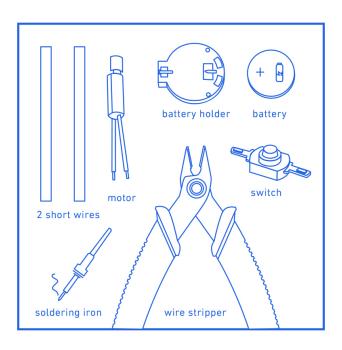
Shitty Robots



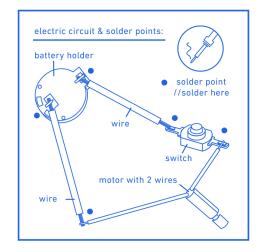
Quantity	Name	Description
1	Vibration motor	3 V 12 mA
1	CR2032 3 V Battery	
1	Battery holder	
1	Switch button	2 pins
2	Wires	5-10cm long

Difficulty: ●○○○ Build-Time: 20–40 Minutes

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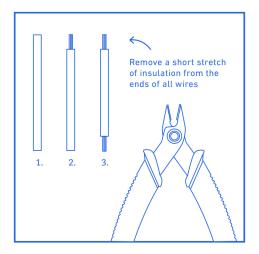
Step 1

a) This is the complete curcuit.



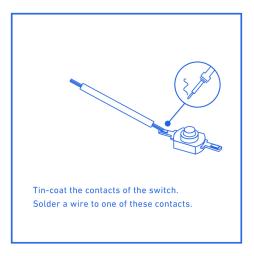
Step 2

a) Remove a short stretch of insulation from the end of all wires.



Step 3

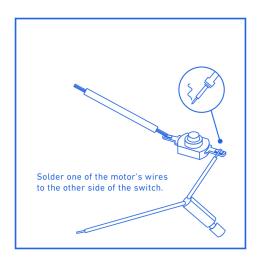
- a) Tin-coat the contacts of the switch.
- b) Solder a wire to one of these contacts.





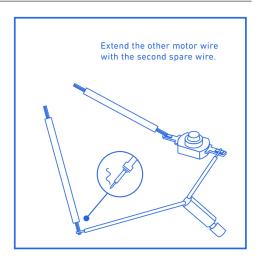
Step 4

a) Solder one of the motor's wires to the other side of the switch.



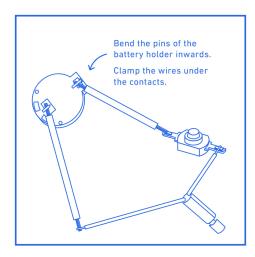
Step 5

a) Extend the other motor wire with the second spare wire.



Step 6

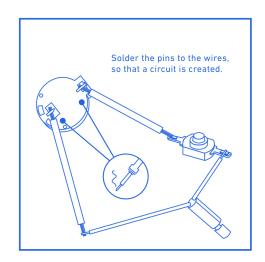
- a) Bend the pins of the battery holder inwards
- b) Clamp the wires under the contacts.





Step 7

a) Solder the pins to the wires, so a curcuit is created.



Step 8

- a) Turn over the battery holder and insert the battery with + upwards
- b) Test it!

