# Dynamic Programming Mini-Lecture: Asset Pricing

Thomas J. Sargent and John Stachurski

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# Pricing a single payoff

An asset pays a random amount  $G_{t+1}$  at time t+1 and nothing thereafter

One way to price this asset is risk-neutral pricing:

$$P_t = \beta \, \mathbb{E}_t G_{t+1}$$

#### Here

- $\beta$  is a constant discount factor
- $\mathbb{E}_t = \mathsf{expectation}$  at time t

Roughly speaking,

cost = expected benefit

This model fails empirically: same rate of return regardless of risk

Most investors demand higher rates of return for holding risky assets

Hence we modify to

$$P_t = \mathbb{E}_t M_{t+1} G_{t+1}$$

In this expression,  $M_{t+1}$ 

- replaces  $\beta$
- is called the stochastic discount factor (SDF) / pricing kernel

This model fits the data somewhat better when  ${\cal M}_{t+1}$  is suitably chosen

# Pricing a cash flow

Now let's try to price an asset like a share

• delivers a cash flow  $D_t, D_{t+1}, \dots$ 

We will call these payoffs dividends

Ex-dividend contract: buy share, hold for one period sell it again yields payoff

$$G_{t+1} = D_{t+1} + P_{t+1}$$

Inserting into the previous equation gives

$$P_t = \mathbb{E}_t M_{t+1} [D_{t+1} + P_{t+1}]$$

## Growing prices

We could try to solve the last equation

$$P_t = \mathbb{E}_t M_{t+1} [D_{t+1} + P_{t+1}]$$

But prices grow over time, which complicates analysis

Easier to solve for the **price-dividend ratio**  $V_t := P_t/D_t$ 

Inserting this into the last equation and rearranging gives

$$V_t = \mathbb{E}_t \left[ M_{t+1} \frac{D_{t+1}}{D_t} (1 + V_{t+1}) \right]$$

We can also write this as

$$V_t = \mathbb{E}_t \left[ M_{t+1} \exp(G_{t+1}^d) (1 + V_{t+1}) \right]$$

where

$$G_{t+1}^d = \ln \frac{D_{t+1}}{D_t} = \text{ growth rate of dividends}$$

To solve for  $V_t$  we need to specify

- 1. the stochastic discount factor  $M_{t+1}$  and
- 2. the growth rate of dividends  $G_{t+1}^{d}$

# Choosing the SDF

For simplicity we adopt the Lucas SDF

$$M_{t+1} = \beta \frac{u'(C_{t+1})}{u'(C_t)}$$

where

- u = utility
- $C_t$  is time t consumption (representative consumer)

We assume CRRA utility:

$$u(c) = \frac{c^{1-\gamma}}{1-\gamma} \implies u'(c) = c^{-\gamma}$$

With

$$G_{t+1}^c := \ln \frac{C_{t+1}}{C_t}$$

the Lucas SDF becomes

$$M_{t+1} = \beta \frac{u'(C_{t+1})}{u'(C_t)} = \beta \left(\frac{C_{t+1}}{C_t}\right)^{-\gamma}$$
$$= \beta \exp(G_{t+1}^c)^{-\gamma} = \beta \exp(-\gamma G_{t+1}^c)$$

# Solving for the price-dividend ratio

Recall that our aim is to solve

$$V_t = \mathbb{E}_t \left[ M_{t+1} \exp(G_{t+1}^d)(1 + V_{t+1}) \right]$$

Substituting in the last expression gives

$$V_t = \beta \mathbb{E}_t \left[ \exp(G_{t+1}^d - \gamma G_{t+1}^c)(1 + V_{t+1}) \right]$$

We assume that  $(G_t^d, G_t^c)$  are driven by state process  $(X_t)$ 

- P-Markov chain on finite state  $X = \{x_1, \dots, x_N\}$
- aggregate shock

#### More specifically, we assume

$$G_{t+1}^{c} = \mu_c + X_t + \sigma_c \varepsilon_{t+1}^{c}$$
  
$$G_{t+1}^{d} = \mu_d + X_t + \sigma_d \varepsilon_{t+1}^{d}$$

#### Here

- $(\varepsilon_t^c) \stackrel{\text{\tiny IID}}{\sim} N(0,1)$
- $(\varepsilon_t^d) \stackrel{\text{\tiny IID}}{\sim} N(0,1)$
- independent of each other

Recall that

$$V_t = \beta \mathbb{E}_t \left[ \exp(G_{t+1}^d - \gamma G_{t+1}^c)(1 + V_{t+1}) \right]$$

Guess:  $V_t = v(X_t)$  for some unknown  $v \in \mathbb{R}^X$ 

With  $a:=\mu_d-\gamma\mu_c$  this means

$$v(X_t) =$$

$$\beta \mathbb{E}_t \left\{ \exp[a + (1 - \gamma)X_t + \sigma_d \varepsilon_{t+1}^d - \gamma \sigma_c \varepsilon_{t+1}^c] (1 + v(X_{t+1})) \right\}$$

Shocks  $\varepsilon_{t+1}^c$  and  $\varepsilon_{t+1}^d$  are IID so we integrate them out

 $Y = \exp(c\varepsilon)$  for  $c \in \mathbb{R}, \ \varepsilon \sim N(0,1)$  implies  $\mathbb{E}Y = \exp(c^2/2)$ 

This yields

$$v(X_t) = \beta \mathbb{E}_t \left\{ \exp \left[ a + (1 - \gamma)X_t + \frac{\sigma_d^2 + \gamma^2 \sigma_c^2}{2} \right] (1 + v(X_{t+1})) \right\}$$

Conditioning on  $X_t = x$ , we can write this as

$$v(x) = \beta \sum_{u \in \mathsf{X}} \exp\left[a + (1 - \gamma)x + \frac{\sigma_d^2 + \gamma^2 \sigma_c^2}{2}\right] (1 + v(y)) P(x, y)$$

## Considering $\boldsymbol{v}, \boldsymbol{x}$ as arrays we get

$$v[i] = \beta \sum_{i=1}^{N} \exp \left[ a + (1 - \gamma)x[i] + \frac{\sigma_d^2 + \gamma^2 \sigma_c^2}{2} \right] (1 + v[j])P[i, j]$$

Equivalently,

$$v[i] = \sum_{j=1}^{N} K[i, j](1 + v[j])$$

where

$$K[i,j] := \beta \exp \left[ a + (1-\gamma)x[i] + \frac{\sigma_d^2 + \gamma^2 \sigma_c^2}{2} \right] P[i,j]$$

Thus we have

$$v = K(\mathbb{1} + v) = K\mathbb{1} + Kv$$

where

$$K[i,j] = \beta \exp\left[a + (1-\gamma)x[i] + \frac{\sigma_d^2 + \gamma^2 \sigma_c^2}{2}\right] P[i,j]$$

- When does this equation have a unique solution?
- How can we compute it?

Suppose r(K) := spectral radius < 1

Then I - K is invertible and

$$v = (I - K)^{-1} K \mathbb{1}$$

Once we specify P, state space X and all the parameters, we can

- 1. obtain K
- 2. verify r(K) < 1
- 3. compute the solution

To specify P and the state space X we assume

$$X_{t+1} = \rho X_t + \sigma \eta_{t+1}$$

#### where

- $\rho, \sigma$  are parameters
- ullet  $(\eta_t)$  is IID and standard normal

#### Now discretize

• Eg., use QuantEcon.py's tauchen function

# An Extended Example

One problem: volatility is not constant over time

To accommodate this, we now suppose that

$$G_{t+1}^i = \mu_i + Z_t + \bar{\sigma} \exp(H_t^i) \varepsilon_{t+1}^i \qquad i \in \{c, d\}$$

- $(Z_t)$  is R-Markov on Z
- ullet  $(H_t^c)$  and  $(H_t^d)$  are volatility processes.

In particular,

$$H_{t+1}^i = \rho_i H_t^i + \sigma_i \eta_{t+1}^i \qquad i \in \{c, d\}$$

Here  $(\eta_t^c)$  and  $(\eta_t^d)$  are IID standard normal

We set  $X := (H^c, H^d, Z)$  and consider again

$$V_t = \beta \mathbb{E}_t \left[ \exp(G_{t+1}^d - \gamma G_{t+1}^c)(1 + V_{t+1}) \right]$$

Guessing  $V_t = v(X_t)$  for some  $v \in \mathbb{R}^X$  yields

$$v(x) = \beta \mathbb{E}_x \exp[a + (1 - \gamma)z + \bar{\sigma}e^{h_d}\varepsilon_{t+1}^d - \gamma \bar{\sigma}e^{h_c}\varepsilon_{t+1}^c](1 + v(X_{t+1}))$$

As before, we integrate out the independent shocks and use the rules for expectations of lognormals to obtain

$$v(x) = \beta \mathbb{E}_x \exp \left[ a + (1 - \gamma)z + \bar{\sigma}^2 \frac{e^{2h_d} + \gamma^2 e^{2h_c}}{2} \right] (1 + v(X_{t+1}))$$

## Setting

$$A(h_c, h_d, z, h'_c, h'_d, z') =$$

$$\beta \exp \left[ a + (1 - \gamma)z + \bar{\sigma}^2 \frac{\exp(2h_d) + \gamma^2 \exp(2h_c)}{2} \right]$$

$$P(h_c, h'_c)Q(h_d, h'_d)R(z, z')$$

we can rewrite the equation as

$$v(h_c, h_d, z) = \sum_{h'_c, h'_d, z'} (1 + v(h'_c, h'_d, z')) A(h_c, h_d, z, h'_c, h'_d, z')$$

Using indices (i, j, k) for  $(h_c, h_d, z)$ , we can express as

$$v[i, j, k] = \sum_{i', j', k'} A[i, j, k, i', j', k'] (1 + v[i', j', k'])$$

where

$$A[i, j, k, i', j', k'] = \beta \exp \left[ a + (1 - \gamma)z[k] + \bar{\sigma}^2 \frac{\exp(2h_d[j]) + \gamma^2 \exp(2h_c[i])}{2} \right]$$
$$P[i, i']Q[j, j']R[k, k']$$

## One option to solve

$$v[i, j, k] = \sum_{i', j', k'} A[i, j, k, i', j', k'] (1 + v[i', j', k'])$$

#### Reshape

- v into an N-vector, where  $N = I \times J \times K$
- A into an  $N \times N$  matrix

Then we write as

$$v = A(1 + v)$$

Provided that r(A) < 1, the solution is given by

$$v = (I - A)^{-1} A \mathbb{1}_{0 + 1}$$

## See https://jax.quantecon.org/markov\_asset.html

- NumPy code
- JAX code
- JAX code with linear operators

The code assumes that  $(Z_t)$  is a discretization of

$$Z_{t+1} = \rho_z Z_t + \sigma_z \xi_{t+1}$$