

Autocorrect & Hidden Markov Models

POS Tagging & Sequence Labeling

Learning Objectives



Understand Autocorrect Systems

Learn how spelling correction works using edit distance and language models



Minimum Edit Distance Algorithm

Implement dynamic programming solution for string similarity measurement



Part-of-Speech Tagging

Understand grammatical categories and their importance in NLP applications



Hidden Markov Models

HMM-based POS tagger with transition and emission probabilities



Viterbi Algorithm

Find optimal tag sequences using dynamic programming decoding

Today's Agenda

Autocorrect Systems

Spelling correction fundamentals

Minimum Edit Distance

Levenshtein distance & DP

Part-of-Speech Tagging

Grammatical categories & tagsets

Hidden Markov Models

Probabilistic sequence modeling

Viterbi Algorithm

Optimal sequence decoding

Lab: Autocorrect System

Hands-on implementation

Quick Recap: Session 04

Machine Translation

Transformation matrices for word vectors

$X \cdot R \approx Y$ mapping between languages

Frobenius norm for loss optimization

K-Nearest Neighbors for translation

Document Search

TF-IDF vector representations

Cosine similarity for matching

Approximate nearest neighbors

Efficiency vs accuracy trade-offs

Locality Sensitive Hashing

Hash functions for similar vectors

Random hyperplanes partitioning

Multi-table approach for accuracy

$O(1)$ lookup for large datasets

PART 1

Autocorrect Systems

Spelling Error Types & Detection

Edit Distance Fundamentals

Minimum Edit Distance Algorithm

Candidate Generation & Scoring

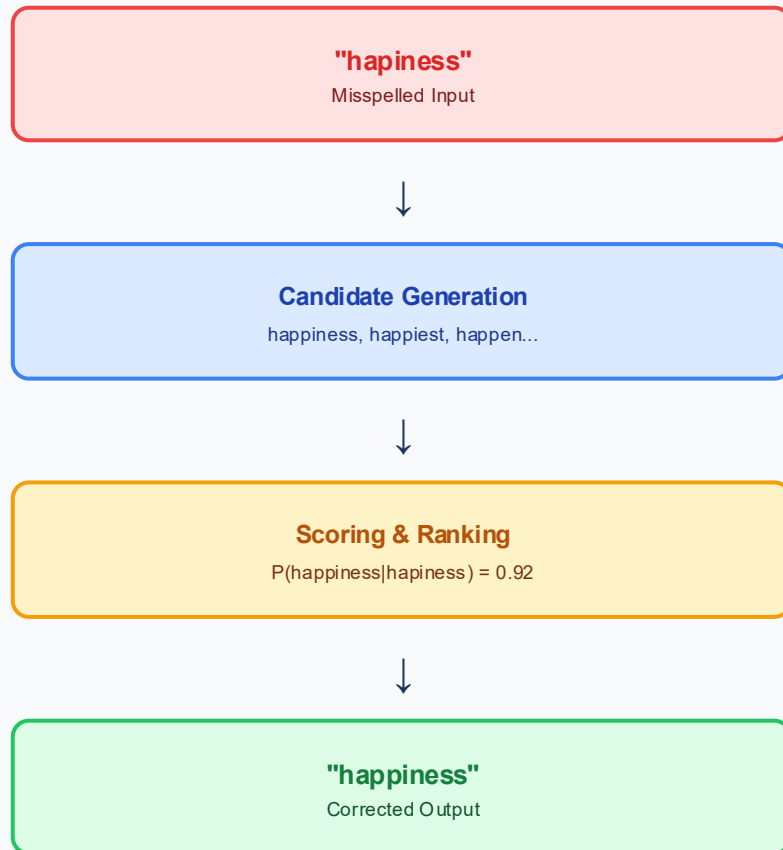
What is Autocorrect?

Definition

Autocorrect is a feature that automatically detects and corrects misspelled words, typos, and grammatical errors as you type.

Core Components

- **Error Detection:** Identify misspelled words
- **Candidate Generation:** Find possible corrections
- **Candidate Scoring:** Rank by probability
- **Correction:** Apply the best candidate



Types of Spelling Errors

Non-word Errors

Result in invalid words

Insertion: "thhe" → "the"

Deletion: "acros" → "across"

Substitution: "graffe" → "giraffe"

Transposition: "teh" → "the"

Detection: Easy - word not in dictionary

Real-word Errors

Valid but wrong words

Typos: "there" → "three"

Cognitive: "their" → "there"

Homophones: "piece" → "peace"

Grammar: "affect" → "effect"

Detection: Hard - requires context analysis

80%

of errors are within
edit distance 1

25%

of spelling errors
are real words

97%

covered by
edit distance ≤ 2

Edit Distance (Levenshtein Distance)

Definition

The **minimum edit distance** between two strings is the minimum number of editing operations (insert, delete, substitute) needed to transform one string into another.

Example: "intention" → "execution"

I	N	T	E	N	T	I	O	N
E	X	E	C	U	T	I	O	N

Edit Operations

I

Add a character: "at" → "cat"

D

Remove a character: "heat" → "hat"

S

Replace a character: "hat" → "hot"

Named after: Vladimir Levenshtein (1965)

Edit Distance = 5

3 substitutions + 1 insertion + 1 deletion

Minimum Edit Distance Algorithm

Dynamic Programming Approach

Build a matrix $D[i,j]$ where $D[i,j]$ represents the minimum edit distance between the first i characters of source string and first j characters of target string.

Recurrence Relation

```
D[i,j] = min {  
    D[i-1,j] + 1 // delete  
    D[i,j-1] + 1 // insert  
    D[i-1,j-1] + cost // sub  
}
```

where $\text{cost} = 0$ if $\text{source}[i] = \text{target}[j]$, else $\text{cost} = 1$ (or 2 for Levenshtein)

Base Cases:

$D[i,0] = i$ (delete all i characters)

$D[0,j] = j$ (insert all j characters)

Complexity Analysis

$O(mn)$

Time

$O(mn)$

Space

$m = |\text{source}|, n = |\text{target}|$

Distance Variants

Levenshtein: sub cost = 1

LCS Distance: sub cost = 2

Damerau: includes transposition

Weighted: keyboard-aware costs

Edit Distance Matrix Example

D matrix for "CAT" → "CUT"

		C	U	T
	0	1	2	3
C	1	0	1	2
A	2	1	1	2
T	3	2	2	1

Result: $D[3,3] = 1$ (one substitution: A → U)

Cell Calculation

For $D[2,2]$ (comparing "CA" with "CU"):

$$\begin{aligned} & \min\{D[1,2]+1, D[2,1]+1, D[1,1]+1\} \\ &= \min\{1+1, 1+1, 0+1\} = 1 \end{aligned}$$

Color Legend

- Base cases (initialization)
- Match (cost = 0)
- Substitution path
- Final answer

Backtrace: Finding the Alignment

Backtrace: "INTENTION" → "EXECUTION"

	ε	E	X	E	C	U	T
ε	0	1	2	3	4	5	6
I	1	1	2	2	3	4	5
N	2	2	2	3	3	4	5
T	3	3	3	3	4	4	4
E	4	3	4	3	4	5	5
N	5	4	4	4	4	5	5

Backtrace path shown in green

Note: depend on selecting adjacent cells but total cost is 5

Backtrace Rules

↖ **Diagonal:** Match or Substitute

← **Left:** Insert into target

↑ **Up:** Delete from source

Resulting Alignment

I	N	T	E	N	T	I	O	N
E	X	E	C	U	T	I	O	N

Operations:

5 substitutions

Total: **5**

Weighted Edit Distance

Keyboard-Aware Costs

Adjacent keys on keyboard are more likely to be confused than distant keys. Weighted edit distance assigns lower costs to more probable errors.

QWERTY Keyboard Layout



E↔R substitution: cost 0.5 (adjacent) | E↔Z substitution: cost 2.0 (distant)

Cost Matrix Examples

Operation	Pair	Cost
sub(adjacent)	e → r	0.5
sub(same row)	e → t	1.0
sub(distant)	e → z	2.0
delete	any	1.0
insert	any	1.0

Confusion Matrices

del[x,y]: P(xy typed as x)

ins[x,y]: P(x typed as xy)

sub[x,y]: P(x typed as y)

Candidate Generation

Edit Distance 1 Operations

For misspelled word "helo":

Deletion: elo, hlo, heo, hel

Insertion: ahelo, bhelo, ... zhelo, haelo, ...

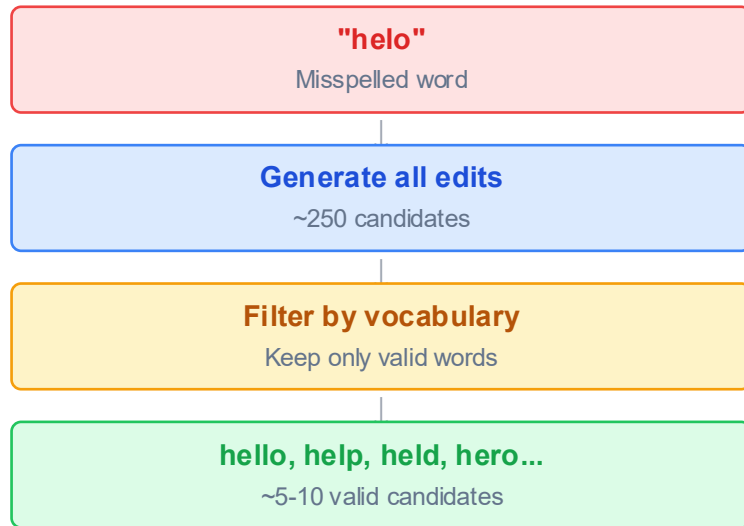
Substitution: aelo, belo, ... zelo, halo, ...

Transposition: ehlo, hleo, heol

Number of Candidates

Operation	Formula	n=4
Deletion	n	4
Insertion	$26 \times (n+1)$	130
Substitution	$26 \times n$	104
Transposition	$n - 1$	3
Total	$54n + 25$	~241

Filtering Pipeline



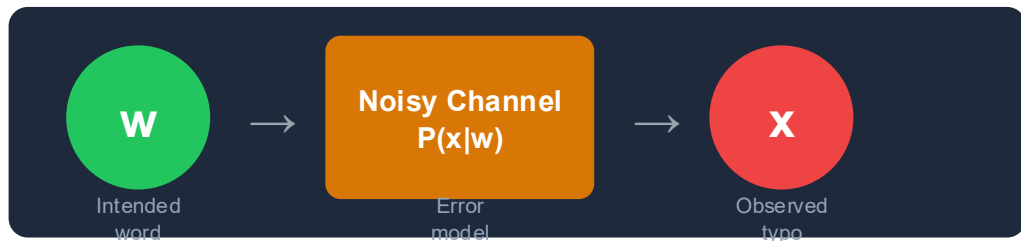
Edit Distance 2

Apply edits to edit-1 candidates: ~40K → ~50 valid

Noisy Channel Model

The Core Idea

The writer intended to type word w , but the "noisy channel" (keyboard + human errors) produced the observed misspelling x . Find the most likely original word.



Bayes' Rule for Spelling Correction

$$\hat{w} = \operatorname{argmax} P(w|x) = \operatorname{argmax} P(x|w) \cdot P(w)$$

$P(x|w)$ - Channel Model
Probability of error x given w

$P(w)$ - Language Model
Prior probability of word w

Example: "acress"

Candidate	$P(x w)$	$P(w)$	Score
actress	0.037	0.0002	7.4e-6
cress	0.012	0.0001	1.2e-6
caress	0.008	0.00005	4.0e-7
access	0.017	0.0003	5.1e-6
across	0.019	0.0004	7.6e-6

Language Model $P(w)$

Unigram: word frequency

Bigram: $P(w|w_{-1})$

N-gram: context-aware

Channel Model $P(x|w)$

Based on confusion matrices from spelling error corpora

PART 2

Part-of-Speech Tagging

What is POS Tagging?

Tag Sets: Penn Treebank & Universal

Ambiguity & Challenges

Applications in NLP

What is Part-of-Speech Tagging?

Definition

Part-of-Speech (POS) tagging is the process of assigning a grammatical category (noun, verb, adjective, etc.) to each word in a sentence based on its definition and context.

Example Tagging

DET

ADJ

NOUN

VERB

ADP

DET

ADJ

NOUN

Also known as: POS tagging, grammatical tagging, word-class tagging

Why is POS Tagging Important?



Parsing: Syntactic analysis



NER: Named entity recognition



MT: Machine translation



QA: Question answering

Sequence Labeling Task

Input: sequence of words

Output: sequence of tags

One tag per word

Challenge: Same word can have different tags depending on context!

"I **book** a flight" (VERB)

"Read this **book**" (NOUN)

Penn Treebank Tag Set

Core Tags (45 total)

Tag	Description	Example
NN	Noun, singular	<i>cat, dog</i>
NNS	Noun, plural	<i>cats, dogs</i>
NNP	Proper noun, singular	<i>John, London</i>
NNPS	Proper noun, plural	<i>Americans</i>
VB	Verb, base form	<i>run, eat</i>
VBD	Verb, past tense	<i>ran, ate</i>
VBG	Verb, gerund	<i>running</i>
VBN	Verb, past participle	<i>eaten</i>
VBP	Verb, non-3rd sg pres	<i>run, eat</i>
VBZ	Verb, 3rd sg present	<i>runs, eats</i>
JJ	Adjective	<i>big, fast</i>
JJR	Adjective, comparative	<i>bigger</i>
JJS	Adjective, superlative	<i>biggest</i>
RB	Adverb	<i>quickly</i>
RBR	Adverb, comparative	<i>faster</i>
RBS	Adverb, superlative	<i>fastest</i>

Function Words & Others

Tag	Description	Example
DT	Determiner	<i>the, a, an</i>
PRP	Personal pronoun	<i>I, you, he</i>
PRP\$	Possessive pronoun	<i>my, your</i>
WDT	Wh-determiner	<i>which, that</i>
WP	Wh-pronoun	<i>who, what</i>
WP\$	Possessive wh-	<i>whose</i>
IN	Preposition/subord conj	<i>in, of, that</i>
CC	Coordinating conj	<i>and, but, or</i>
TO	"to"	<i>to</i>
MD	Modal	<i>can, will</i>
CD	Cardinal number	<i>one, 2, 100</i>
EX	Existential there	<i>there is</i>
FW	Foreign word	<i>bonjour</i>
UH	Interjection	<i>oh, wow</i>
.	Sentence-final punct	<i>. ! ?</i>

Note: Penn Treebank is the most widely used tag set for English NLP

Universal Dependencies Tag Set

Why Universal Tags?

Penn Treebank has **45 tags** – very details but only apply to Eng. Universal Dependencies (UD) provide tags.

17 Universal POS Tags

Tag	Description	Tag	Description
ADJ	Adjective	NOUN	Noun
ADP	Adposition	NUM	Numeral
ADV	Adverb	PART	Particle
AUX	Auxiliary	PRON	Pronoun
CCONJ	Coord. Conjunction	PROPN	Proper Noun
DET	Determiner	PUNCT	Punctuation
INTJ	Interjection	SCONJ	Subord. Conjunction
VERB	Verb	SYM	Symbol
		X	Other

So sánh Tag Sets

Penn Treebank

NN, NNS, NNP, NNPS

4 noun tags

Universal

NOUN, PROPN

2 noun tags



Cross-lingual Example

English: The cat sleeps

DET NOUN VERB

Vietnamese: Con mèo ngủ

NOUN NOUN VERB

UD Project: 200+ treebanks cho 100+ ngôn ngữ

<https://universaldependencies.org>

POS Ambiguity - Challenges

Ambiguity statistics:

40%

word types have multi tags

55%

word tokens ambiguous

Example

"book"

NOUN

"I read a book"

VERB

"Please book a flight"

"back"

NOUN

"My back hurts"

VERB

"Back the car up"

ADV

"Go back home"

ADJ

"The back door"

Disambiguation Approaches

1. Context-based

words before/after help to determine tags

2. Statistical

$P(\text{tag}|\text{word}, \text{previous_tags})$

3. Neural Networks

Bi-LSTM + CRF models

Most Frequent Tag Baseline

If assign popular tag to each word:

Accuracy: **~90%**

~10% disambiguate!

Challenge: OOV - Out of Vocabulary account for 5-10% tokens in the new text

POS Tagging Approaches

Rule-based

Use dictionary + rule base provided by experts

Ví dụ quy tắc:

IF word ends "-ing"
AND prev_tag = "be"
THEN tag = VBG

✓ Explainable, precise

✗ Labor-intensive, inflexible

Statistical (HMM)

Learn from labeled data (supervised learning)

Hidden Markov Model:

$$P(\text{tag} | \text{prev_tag}) \times P(\text{word} | \text{tag})$$

✓ Data-driven, ~97% acc

✗ Needs labeled data

Neural Networks

Deep learning with word embeddings and sequence models

Modern approach:

BiLSTM + CRF
BERT + Fine-tuning
Transformer models

✓ State-of-the-art, ~98% acc

✗ Compute-intensive

03

Hidden Markov Models

HMM for Sequence Labeling

States &
Transitions

Emission
Probabilities

Decoding
Algorithm

What is a Hidden Markov Model?

Definition

Hidden Markov Model (HMM) is a probabilistic model in which the system is modeled as a Markov process with hidden states.

Assumptions

1 Markov Assumption

Probability of current state depending on previous state:

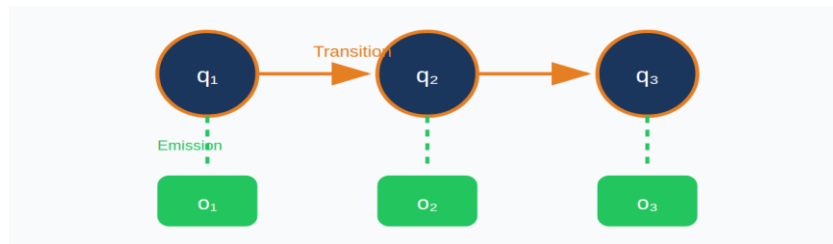
$$P(q_i | q_1 \dots q_{i-1}) = P(q_i | q_{i-1})$$

2 Output Independence

Observation only depending on its state:

$$P(o_i | q_1 \dots q_n, o_1 \dots o_n) = P(o_i | q_i)$$

HMM Structure



HMM	POS Tagging	Examples
Hidden States	POS Tags	NOUN, VERB, DET, ADJ...
Observations	Words in sentence	the, cat, runs, fast...
Transitions	Prob of tag \rightarrow tag	$P(\text{NOUN} \text{DET}) = 0.8$
Emissions	Prob of tag \rightarrow word	$P(\text{'cat'} \text{NOUN}) = 0.02$

"Hidden" means we can not observe – only see outputs! We just see the words

HMM Components ($\lambda = A, B, \pi$)

Q - States

Collection of N states has:

$$Q = \{q_1, q_2, \dots, q_n\}$$

POS: {NOUN, VERB, ADJ, DET, ...}

V - Observations

Vocabulary - symbol observations:

$$V = \{v_1, v_2, \dots, v_m\}$$

POS: {the, cat, run, quickly, ...}

A - Transitions

Transition matrix of states:

$$a_{ij} = P(q_j | q_i)$$

$\forall i \ d\mu: P(\text{NOUN}|\text{DET}) = 0.8$

B - Emissions

Emission matrix of observation from states:

$$b_i(v_k) = P(v_k | q_i)$$

$\forall i \ d\mu: P(\text{"cat"}|\text{NOUN}) = 0.02$

π - Initial Probs

Initial probability:

$$\pi_i = P(q_1 = q_i)$$

$\forall i \ d\mu: P(\text{start}=\text{DET}) = 0.4$

Summary

HMM is defined by:

$$\lambda = (A, B, \pi)$$

$N \times N + N \times M + N$ parameters

Transition Probabilities (A Matrix)

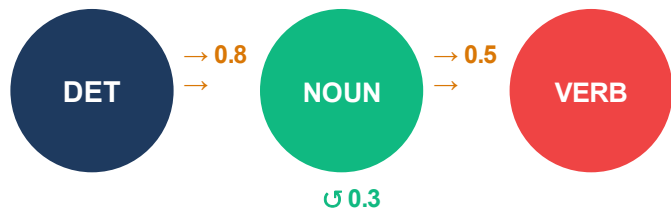
Definition

$$a_{ij} = P(t_j | t_i) = C(t_i, t_j) / C(t_i)$$

Transition Matrix Example

A	<s>	DET	NOUN	VERB	ADJ	</s>
<s>	0	0.40	0.25	0.20	0.10	0.05
DET	0	0.02	0.80	0.01	0.15	0.02
NOUN	0	0.05	0.10	0.50	0.05	0.30
VERB	0	0.25	0.35	0.10	0.15	0.15
ADJ	0	0.05	0.70	0.05	0.10	0.10

State Transition Diagram



Constraints: sum of each row = 1: $\sum_j a_{ij} = 1$

Insight: $P(\text{NOUN}|\text{DET}) = 0.80$ high because articles usually is come along with nouns ("the cat", "a book")

Emission Probabilities (Matrix B)

Definition

$$b_i(w) = P(w \mid t_i) = C(t_i, w) / C(t_i)$$

Emission Matrix Example

B	the	a	cat	dog	runs	big
DET	0.65	0.30	0	0	0	0
NOUN	0	0	0.05	0.03	0	0
VERB	0	0	0	0	0.08	0
ADJ	0	0	0	0	0	0.12

Emission Visualization

NOUN

↓ 0.05

cat

↓ 0.03

dog

↓ 0.02

book

Sparsity Problem

$|V| = 50,000$ words and $|T| = 45$ tags

→ Matrix B has 2.25M entries, almost = 0. needs smoothing!

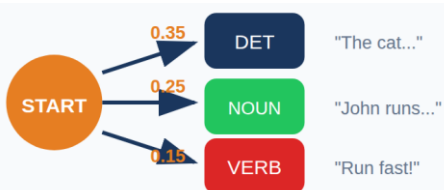
Constraints: with each tag t_i : $\sum_w b_i(w) = 1$ (sum of probabilities emit from all words = 1)

Initial Probabilities (Vector π)

Definition

$$\pi = P(t = t) = C(t \text{ is a tag at beginning of sent}) / N$$

Start Distribution



Example of Vector π

$\pi(\text{DET})$

0.35

$\pi(\text{NOUN})$

0.25

$\pi(\text{VERB})$

0.15

$\pi(\text{PRON})$

0.20

$\pi(\text{other})$

0.05

Constraints: $\sum_i \pi_i = 1$

HMM Complete Definition

$\lambda = (A, B, \pi)$

A: Transition matrix ($N \times N$)

B: Emission matrix ($N \times |V|$)

π : Initial distribution ($N \times 1$)

N = no of tags, **|V|** = vocabulary size

Training HMM from Corpus

Supervised Training (with labeled corpus)

Tagged Corpus Example:

The/DET cat/NOUN sat/VERB on/ADP the/DET mat/NOUN ./PUNCT
A/DET dog/NOUN runs/VERB fast/ADV ./PUNCT

Count-Based Estimation

STEP 1: Transition Counts

$$a_{ij} = C(t_i \rightarrow t_j) / C(t_i)$$

STEP 2: Emission Counts

$$b_i(w) = C(t_i, w) / C(t_i)$$

STEP 3: Initial Counts

$$\pi_i = C(t_i \text{ starts sentence}) / N$$

Zero Probability Problem

if a bigram tag is not in training $\rightarrow P = 0 \rightarrow$ all the sequence = 0!

Solution: Add-k Smoothing

$$a_{ij} = (C(t_i, t_j) + k) / (C(t_i) + k \cdot N)$$

$k = 0.001$ or 1 (Laplace smoothing)

Corpus: Penn Treebank, Brown, Universal Dependencies



Viterbi Algorithm

PART 4: VITERBI ALGORITHM

The Decoding Problem

Goal

$$\hat{t} = \operatorname{argmax}_{t_1 \dots t_n} P(t_1 \dots t_n \mid w_1 \dots w_n)$$

Find the best tags sequence for a given words

Example

Input:

"The bear can run"

Output:

DET NOUN VERB VERB

Solution: Dynamic Programming

Viterbi algorithm uses DP to find optimal path with $O(N^2T)$ instead of $O(NT)$

Insight

Optimal Substructure: Best path to state j at time t depends on best paths at time $t-1$



Complexity Comparison

Brute Force

$O(NT)$

Viterbi

$O(N^2T)$

Brute Force Problem

with N tags and T words $\rightarrow N^T$ possible sequences!

$N=45, T=20 \rightarrow 45^{20} \approx 10^{33} \rightarrow$ impossible mission (:P)

Viterbi Recurrence

STEP 1: Initialization (t = 1)

$$v_1(j) = \pi_j \cdot b_j(w_1)$$

Probability of state j × probability emitting at the beginning

STEP 2: Recursion (t = 2...T)

$$v_t(j) = \max_i [v_{t-1}(i) \cdot a_{ij}] \cdot b_j(w_t)$$

$v_t(i)$: best score to state i at time t-1

a: transition prob from i → j

b(w): emission prob of w from j

STEP 2b: Store Backpointer

$$bp_t(j) = \operatorname{argmax}_i [v_{t-1}(i) \cdot a_{ij}]$$

Save the best state to j → used to trace back

STEP 3: Termination

$$\begin{aligned} \text{best_score} &= \max_j v_T(j) \\ \text{best_last_tag} &= \operatorname{argmax}_j v_T(j) \end{aligned}$$

Numerical Underflow

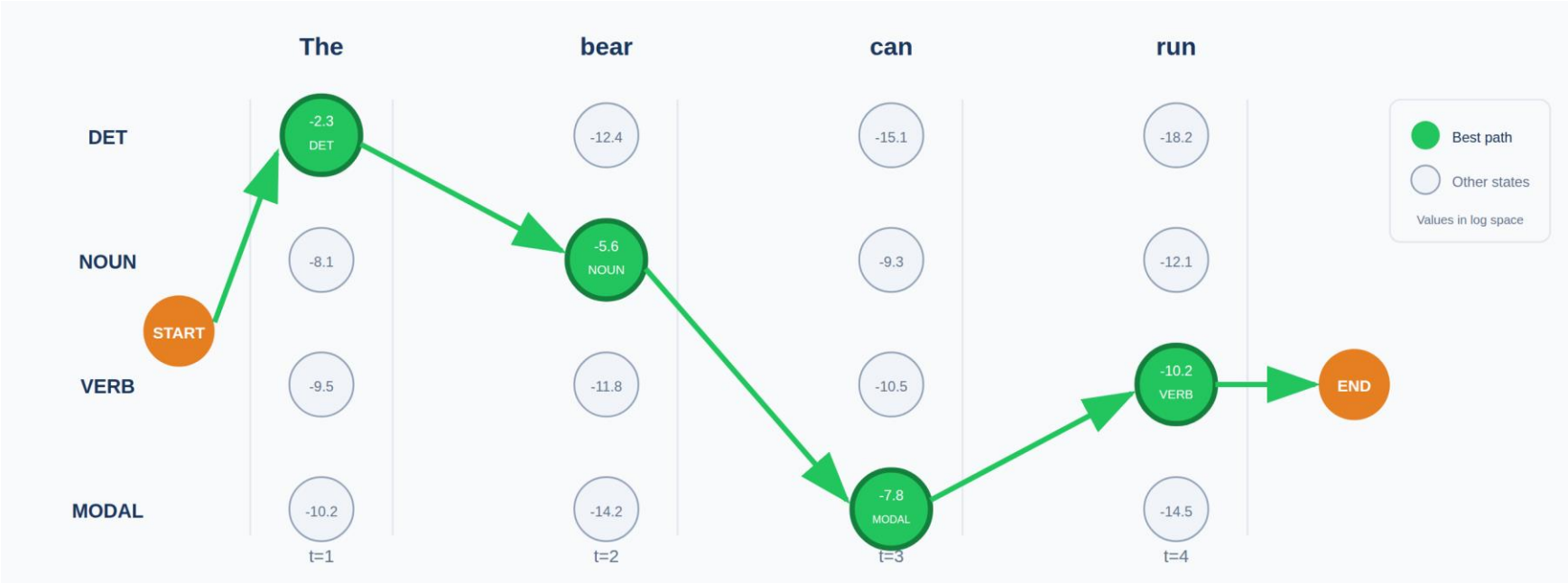
Product of small prob → underflow (≈ 0)

Solution: Log Space

$$\log v_t(j) = \max_i [\log v_{t-1}(i) + \log a_{ij}] + \log b_j(w_t)$$

Viterbi Trellis Diagram

Input: "The bear can run" → Output: DET NOUN MODAL VERB



Example: Step by step

1 Initialization: $t=1$, word="The"

$$v_1(\text{DET}) = \pi(\text{DET}) \times b_{\text{DET}}(\text{"The"})$$
$$= 0.35 \times 0.50 = 0.175$$

DET: 0.175 ✓ NOUN: 0.001

2 Recursion: $t=2$, word="bear"

$$v_2(\text{NOUN}) = \max[v_1(i) \times a_{i,\text{NOUN}}] \times b_{\text{NOUN}}(\text{"bear"})$$
$$= 0.14 \times 0.05 = 0.007$$

$bp_2(\text{NOUN}) = \text{DET}$

NOUN: 0.007 ✓ DET: 0.0001

3 Continue: $t=3,4$

$t=3$: "can"
Best: MODAL, bp=NOUN

$t=4$: "run"
Best: VERB, bp=MODAL

Backpointer Table

t	1	2	3	4
Tag	DET	NOUN	MODAL	VERB
bp	START	DET	NOUN	MODAL

Backtrace: Reconstruct Path

VERB ← MODAL ← NOUN ← DET

Result: The/DET bear/NOUN can/MODAL run/VERB



Lab & Practice

Autocorrect System

HMM POS Tagger

Lab 1: Autocorrect System

Implementation Pipeline

Step 1: Build Vocabulary

Load corpus, count word frequencies

Step 2: Implement Edit Distance

DP algorithm with backtrace

Step 3: Generate Candidates

Edit dist 1 and 2, filter by vocab

Step 4: Rank Candidates

Noisy channel model scoring

 **Dataset:** Shakespeare corpus hoặc Wikipedia text dump

✓ **Expected:** "speling" → "spelling", "correc" → "correct"

Lab 2: HMM POS Tagger

Implementation Steps

Step 1: Load & Preprocess Data

NLTK Brown corpus với POS tags

Step 2: Estimate Probabilities

Build A, B, π matrices từ counts

Step 3: Apply Smoothing

Add-k smoothing for unknown transitions

Step 4: Implement Viterbi

DP decoding with backpointers

Step 5: Evaluate

Accuracy trên test set

Summary

1. Autocorrect Systems

Minimum Edit Distance (Levenshtein), Dynamic Programming với backtrace, Noisy Channel Model

2. POS Tagging

Sequence labeling task, Penn Treebank (45 tags) và Universal (17 tags), Word ambiguity challenge

3. Hidden Markov Models

$\lambda = (A, B, \pi)$ definition, Transition và Emission probabilities, Supervised training từ corpus

4. Viterbi Algorithm

DP decoding $O(N^2T)$, Log space computation, Backpointer for path reconstruction

Edit Distance

$$D[i,j] = \min\{D[i-1,j]+1, D[i,j-1]+1, D[i-1,j-1]+\text{cost}\}$$

Viterbi Recursion

$$V[i,j] = \max_k \{V[i-1,k] + a_{kj}\}$$

Ồ NẾU CẢM NHẬN ĐƯỢC