AV-Planning $_{CN}$

Binjian Xin July 30, 2024

```
epistemic vs aleatoric
  \mathbf{CVAE}
  Diffusion)
DAgger,
RLHF Bradley-Terry [ ] HF state
                                               action
  loss, DPO RL-> MLE
        KL
       ->
 RL
 {\bf Control Net}
     SOTA
                              ( )
    Score Function)
GAN
\mathbf{VAE}
        {f Z}
                              2
           tokens
```