Revisiting Auxiliary Variables

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Specifications of State Machines

- Standard way of describing algorithms
 - ▶ initial condition, next-state relation express what may happen
 - fairness / liveness conditions assert what must happen

- Part of the state may be hidden
 - do not expose implementation details
 - delimit observable behavior that should be implemented

• Concrete syntax: TLA^+ $\exists x : Init \land \Box [Next]_{vars} \land L$

Refinement of State Machines

- From high-level specification to concrete implementation
 - executions of lower-level state machine coherent with specification
 - formally: inclusion of set of (observable) state sequences

$$(\exists y: Impl) \Rightarrow (\exists x: Spec)$$

Refinement of State Machines

- From high-level specification to concrete implementation
 - executions of lower-level state machine coherent with specification
 - formally: inclusion of set of (observable) state sequences

$$(\exists y : Impl) \Rightarrow (\exists x : Spec)$$

- Standard proof technique: refinement mapping
 - reconstruct high-level internal state from low-level state

$$Impl \Rightarrow Spec \{f/x\}$$

pointwise computation of internal state components



Example: Compute the Maximum Input Value

• First specification: store the set of all inputs

```
\begin{array}{ll} \operatorname{Init}_1 \stackrel{\triangle}{=} \operatorname{inp} = \{\} \wedge \operatorname{lastinp} = -\infty \wedge \operatorname{max} = -\infty \\ \operatorname{Input}_1(x) \stackrel{\triangle}{=} \operatorname{inp'} = \operatorname{inp} \cup \{x\} \wedge \operatorname{lastinp'} = x \wedge \operatorname{max'} = \operatorname{Max}(\operatorname{inp'}) \\ \operatorname{Next}_1 \stackrel{\triangle}{=} \exists x \in \operatorname{Int} : \operatorname{Input}_1(x) \\ \operatorname{Spec}_1 \stackrel{\triangle}{=} \exists \operatorname{inp}, \operatorname{lastinp} : \operatorname{Init}_1 \wedge \square[\operatorname{Next}_1]_{\langle \operatorname{inp}, \operatorname{lastinp}, \operatorname{max} \rangle} \end{array}
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Second specification: store just the maximum value

```
Init<sub>2</sub> \triangleq lastinp = -\infty \land max = -\infty

Input<sub>2</sub>(x) \triangleq lastinp' = x \land max' = IF x > max THEN x ELSE max

Next<sub>2</sub> \triangleq \exists x \in Int : Input<sub>2</sub>(x)

Spec<sub>2</sub> \triangleq \exists lastinp : Init<sub>2</sub> <math>\land \Box [Next_2]_{\langle lastinp, max \rangle}
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Spec_2 \triangleq \exists lastinp : Init_2 \land \Box [Next_2]_{\langle lastinp, max \rangle}
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What is the formal relationship between the two specifications?

- The two specifications are equivalent
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Refinement mappings alone are incomplete

Auxiliary Variables

Augment implementation, then construct refinement mapping

• specific rules justifying auxiliary variables: $Impl \equiv \exists a : Impl^a$

② augmented specification refines high-level: $Impl^a \Rightarrow \exists x : Spec$

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- Two particular kinds of auxiliary variables
 - history variables: record information about previous states
 - prophecy variables: predict information about future states

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- Two particular kinds of auxiliary variables
 - history variables: record information about previous states
 - prophecy variables: predict information about future states
- Classic reference

M. Abadi, L. Lamport. The Existence of Refinement Mappings. TCS (1991).

- introduces history and prophecy variables
- proves completeness under certain conditions
- closely related: forward / backward simulations



Outline

- Refinement Mappings
- 2 History Variables
- 3 Simple Prophecy Variables
- 4 Arrays of Auxiliary Variables
- 5 Stuttering Variables
- 6 Establishing Completeness

Record Information About Past States

Update history variable at every transition

$$Spec \equiv \exists h : Spec \land h = h_0 \land \Box [vars' \neq vars \land h' = f(h)]_{\langle vars, h \rangle}$$

- variable h does not occur in *Spec*, vars or h_0
- term f(h) does not contain h'
- \blacktriangleright h_0 is the initial value of the history variable
- lacksquare f represents the update function applied at every observable step

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- Example: step counter

$$Spec \equiv \exists h : Spec \land h = 0 \land \Box [vars' \neq vars \land h' = h + 1]_{\langle vars, h \rangle}$$

▶ similar: record the input values during executions of *Spec*₂



Parameterized Refinement Mappings

- Idea: many refinement mappings are better than one
 - 1 introduce parameterized specification equivalent to low-level spec

$$Impl \equiv \exists \beta \in S : PImpl(\beta)$$

define separate refinement mappings per parameter value

$$\forall \beta \in S : PImpl(\beta) \Rightarrow Spec \{ f(\beta)/x \}$$

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• Example: introduce a downward counter

$$Impl \stackrel{\triangle}{=} n = 0 \land \Box [n' = n+1]_{\langle n \rangle} \land \Diamond \Box [n' = n]_{\langle n \rangle}$$

$$Spec \stackrel{\triangle}{=} n = 0 \land k \in \mathbb{N} \land \Box [k > 0 \land n' = n+1 \land k' = k-1]_{\langle k,n \rangle}$$

$$Prove Impl \Rightarrow \exists k : Spec$$

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- observe
- $Impl \equiv \exists m \in \mathbb{N} : Impl \wedge \Box (n \leq m)$
- prove
- $\forall m \in \mathbb{N} : Impl \wedge \square(n \leq m) \Rightarrow Spec \{ m n/k \}$

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- β : sequence of states that "predicts" actual execution
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Related to Hesselink's eternity variables

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Abadi-Lamport Prophecy Variables

• Similar to history variables, with "time running backwards"

$$\frac{S \neq \{\} \quad IsFiniteSet(S) \quad Spec \Rightarrow \Box(\forall y \in S : f(y) \in S)}{Spec \equiv \exists p : Spec \land \Box(p \in S) \land \Box[vars' \neq vars \land p = f(p')]_{\langle vars, p \rangle}}$$

- ▶ variable *p* does not occur in *Spec*, *vars* or *S*
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- f(y) does not contain p
- Differences to rule for history variables
 - invariant "type condition" replaces initialization
 - ▶ finiteness of *S* required for soundness (König's lemma)
- Rule found to be difficult to apply in practice



Prophesize Next Occurrence of an Action

Consider a system that repeatedly produces integer values

```
Init \triangleq val = \{\}
Prod(n) \triangleq n \notin val \land val' = val \cup \{n\}
Spec \triangleq Init \land \Box [\exists n \in \mathbb{N} : Prod(n)]_{\langle val \rangle}
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Now predict the next value to be produced

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- Note: one need not be able to construct a prophecy variable
 - prophecy variables are used in proofs
 - the augmented specification need not be implementable

Simple Prophecy Variables: Introduction Rule

Predict the parameter of next occurrence of given action

$$S \neq \{\} \qquad Spec \Rightarrow \Box [\forall x : A(x) \Rightarrow x \in S]_{\langle vars \rangle}$$

$$Spec \equiv \exists p : \land Spec \land p \in S$$

$$\land \Box [\land vars' \neq vars$$

$$\land \text{ if } \exists x : A(x) \text{ THEN } A(p) \land p' \in S \text{ ELSE } p' = p]_{\langle vars, p \rangle}$$

- \blacktriangleright A(x) an action without occurrences of p
- p predicts for which value A will occur next
- other actions leave p unchanged
- variant: predict which action will be performed next

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- p predicts for which value A will occur next
- ▶ other actions leave *p* unchanged
- variant: predict which action will be performed next
- Simple soundness proof
 - suitable value for p determined at next occurrence of A
 - ▶ if *A* doesn't occur anymore, the value of *p* doesn't matter

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Auxiliary Functions

Aggregate auxiliary variables in an array

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\frac{S \neq \{\} \qquad \forall x \in S : Spec \equiv \exists y : \Box(y \in T) \land \Box[v \neq v]_{\langle y \rangle} \land ASpec(x, y)}{Spec \equiv \exists f : \Box(f \in [S \to T]) \land \Box[v \neq v]_{\langle f \rangle} \land \forall x \in S : ASpec(x, f[x])}
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- y, f do not occur in v
- similar to introducing a Skolem function in predicate logic
- premise will be established by previous rules

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- similar to introducing a Skolem function in predicate logic
- premise will be established by previous rules
- Generic principle for combining auxiliary variables
 - natural application: parameterized verification problems
 - can be used to justify original rule for prophecy variables



Example

Extend the producer system by an explicit output action

```
Init \triangleq val = \{\} \land out = none
Prod(n) \triangleq n \notin val \land val' = val \cup \{n\} \land out' = out
Out \triangleq out' \in val \land val' = val \setminus \{out'\}
Next \triangleq (\exists n \in \mathbb{N} : Prod(n)) \lor Out
Spec \triangleq Init \land \Box[Next]_{\langle val, out \rangle}
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Now add the possibility of "undoing" production

```
Undo(n) \stackrel{\triangle}{=} val' = val \setminus \{n\} \wedge out' = out

NextU \stackrel{\triangle}{=} Next \vee \exists n \in \mathbb{N} : Undo(n)

SpecU \stackrel{\triangle}{=} Init \wedge \square[NextU]_{\langle val, out \rangle}
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```

• Prove equivalence of $\exists val : SpecU$ and $\exists val : Spec$

Proving $SpecU \Rightarrow \exists val : Spec$

• For every $k \in \mathbb{N}$, predict if it will be output or not

```
\begin{array}{ll} \mathit{Init}^p \; \stackrel{\triangle}{=} \; \mathit{Init} \land p \in \{\text{``out", ``undo"}\} \\ \mathit{Prod}^p(n) \; \stackrel{\triangle}{=} \; \mathit{Prod}(n) \land \mathit{IF} \; n = k \; \mathit{THEN} \; p' \in \{\text{``out", ``undo"}\} \; \mathit{ELSE} \; p' = p \\ \mathit{Out}^p \; \stackrel{\triangle}{=} \; \mathit{Out} \land (\mathit{out'} = k \Rightarrow p = \text{``out"}) \land p' = p \\ \mathit{Undo}^p(n) \; \stackrel{\triangle}{=} \; \mathit{Undo} \land (n = k \Rightarrow p = \text{``undo"}) \land p' = p \\ \mathit{Next} U^p \; \stackrel{\triangle}{=} \; \mathit{Out}^p \lor (\exists n \in \mathbb{N} : \mathit{Prod}^p(n) \lor \mathit{Undo}^p(n)) \\ \mathit{Spec} U^p \; \stackrel{\triangle}{=} \; \mathit{Init}^p \land \Box [\mathit{Next} U^p]_{\langle \mathit{val,out,p} \rangle} \end{array}
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▶ use simple prophecy rule to prove $\forall k \in \mathbb{N} : SpecU \equiv \exists p : SpecU^p$

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- ▶ use simple prophecy rule to prove $\forall k \in \mathbb{N} : SpecU \equiv \exists p : SpecU^p$
- Use array rule to combine these predictions

```
SpecU \equiv \exists f: \Box (f \in [\mathbb{N} \to \{\text{``out", ``undo"}\}]) \land \ldots
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Proving $SpecU \Rightarrow \exists val : Spec$

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Init^p \stackrel{\triangle}{=} Init \land p \in \{\text{"out", "undo"}\}\
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Out^p \stackrel{\Delta}{=} Out \land (out' = k \Rightarrow p = \text{``out"}) \land p' = p
Undo^p(n) \stackrel{\Delta}{=} Undo \land (n = k \Rightarrow p = \text{``undo''}) \land p' = p
NextU^p \stackrel{\Delta}{=} Out^p \lor (\exists n \in \mathbb{N} : Prod^p(n) \lor Undo^p(n))
SpecU^p \stackrel{\triangle}{=} Init^p \wedge \square [NextU^p]_{(val,out,p)}
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- ▶ use simple prophecy rule to prove $\forall k \in \mathbb{N} : SpecU \equiv \exists p : SpecU^p$
- Use array rule to combine these predictions

$$SpecU \equiv \exists f : \Box (f \in [\mathbb{N} \to \{\text{``out"}, \text{``undo"}\}]) \land \ldots$$

• Finally, define suitable refinement mapping

$$SpecU^f \Rightarrow Spec \{ (val \setminus \{k \in \mathbb{N} : f[k] = \text{``undo"}\}) / val \}$$

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Stuttering Steps and Refinement

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Stuttering Steps and Refinement

- Adjust for different granularity of atomic actions
 - typically, refinement introduces lower-level detail
 - low-level transitions are invisible at higher level
 - ► TLA⁺ bakes stuttering invariance into the language
- Occasionally, the high-level specification may take more steps
 - toy example: clock specified with invisible seconds display
 - more realistic: thread completes operation on behalf of another
- Introduce explicit stuttering for defining refinement mapping
 - Abadi-Lamport: stuttering combined with prophecy variables
 - here: separate category of stuttering variables

Proof Rule

Add stuttering steps in between visible transitions

$$\frac{s_0 \in Nat \qquad \bigwedge_{i \in I} Spec \Rightarrow \Box(st_i \in \mathbb{N})}{Spec \equiv \exists s : Init^s \land \Box [Dec \lor \bigvee_{i \in I} A_i^s]_{\langle v, s \rangle} \land L}$$

original specification

$$Spec \equiv Init \wedge \Box [\bigvee_{i \in I} A_i]_{\langle v \rangle} \wedge L$$

initial stuttering

$$Init^s \stackrel{\Delta}{=} Init \wedge s = s_0$$

▶ stuttering after transition
$$A_i^s \triangleq A_i \land s = 0 \land s' = st_i$$

decrement variable s

$$Dec \stackrel{\Delta}{=} s > 0 \land s' = s - 1 \land v' = v$$

Proof Rule

Add stuttering steps in between visible transitions

$$\frac{s_0 \in Nat \qquad \bigwedge_{i \in I} Spec \Rightarrow \Box(st_i \in \mathbb{N})}{Spec \equiv \exists s : Init^s \land \Box \big[Dec \lor \bigvee_{i \in I} A_i^s \big]_{\langle v, s \rangle} \land L}$$

original specification

$$Spec \equiv Init \wedge \Box \big[\bigvee_{i \in I} A_i \big]_{\langle v \rangle} \wedge L$$

initial stuttering

$$Init^s \stackrel{\Delta}{=} Init \wedge s = s_0$$

• stuttering after transition $A_i^s \stackrel{\Delta}{=} A_i \wedge s = 0 \wedge s' = st_i$

$$A_i^s \stackrel{\Delta}{=} A_i \wedge s = 0 \wedge s' = st_i$$

decrement variable s

$$Dec \stackrel{\triangle}{=} s > 0 \land s' = s - 1 \land v' = v$$

- Obvious generalizations
 - allow for jumps instead of just counting down
 - variable taking values in set with well-founded ordering

Outline

- Refinement Mappings
- 2 History Variables
- Simple Prophecy Variables
- 4 Arrays of Auxiliary Variables
- 5 Stuttering Variables
- 6 Establishing Completeness

Two Completeness Proofs

Predict low-level execution

- add a step counter to low-level specification
- ▶ use simple prophecy variables to predict *n*-th state
- combine these into function predicting low-level behavior
- choose high-level behavior and define refinement mapping

Predict high-level behavior

- use history variable to record finite prefixes of low-level behavior
- predict prefixes of high-level behavior compatible with all low-level prefixes, then define refinement mapping

Remarks

- second approach: reasoning about finite prefixes suffices ...
- ... but "internal continuity" is necessary
- ▶ cf. AL'91: no machine closure or finite internal non-determinism

Wrapping Up

- New look at an old problem
 - refinement mappings are very successful, but incomplete
 - generalization to parameterized refinement mappings
 - auxiliary variables can yield completeness results
 - simple prophecy variables + arrays easier to apply?
- Validation of the approach
 - catalogue of directly applicable TLA⁺ rules
 - applied to toy examples and linearizability proofs
 - formalization in Isabelle/HOL ongoing

Lamport, M.: Auxiliary Variables in TLA⁺. arXiv, 2017.

