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MODULE *Stuttering*

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This module is explained in Section 5 of the paper “Auxiliary Variables in TLA+”. It defines operators used to add a stuttering variable  $s$  to a specification  $Spec$  to form a specification  $SpecS$ . It is mean to be instantiated with  $s$  replaced by the stuttering variable to be added and  $vars$  replaced by the tuple of all variables in the original specification.

If  $Init$  is the initial predicate of  $Spec$ , then the initial predicate of  $SpecS$  is  $Init \wedge (s = top)$ , where  $top$  is defined below.

The next-state action of  $SpecS$  is obtained by replacing each subaction  $A$  of a disjunctive representation of the next-state action  $Next$  of  $Spec$  with an action  $AS$  written in terms of operators defined below. (Disjunctive representations are described in Section 3.2 of “Auxiliary Variables in TLA+”.) Action  $AS$  executes  $A$  and stuttering steps added either before or after an  $A$  step. The basic idea is that  $s$  equals  $top$  except while stuttering steps are being taken, when it is a record with the following fields:

*id*: A value that identifies the action  $A$ .

*ctxt*: A value identifying the context under which  $A$  is executed. For example, if  $A$  appears in a formula  $\exists i, j \in S : A$ , this would equal the value of the pair  $\langle i, j \rangle$  for which  $A$  is being executed.

*val*: A value that is decremented by each stuttering step, until it reaches a minimum value.

The arguments of the operators defined in this module have the following meanings.

$A$

The subaction  $A$  of  $Next$ .

*id*

A string identifying action  $A$ .

*Sigma*

A set of values ordered by some “less-than” relation. This is the set of possible values of  $s.val$  when executing stuttering steps before or after subaction  $A$ .

*bot*

The minimum element of *Sigma* under its less-than relation.

*initVal*

The initial value to which  $s.val$  is set for executing stuttering steps before or after  $A$ .

*decr*

An operator such that each stuttering step changes  $s.val$  to  $decr(s.val)$ .

*context*

The context in which  $A$  appears. It is the expression that is evaluated to determine the value to which  $s.ctx$  is set.

*enabled*

A formula equivalent to  $ENABLED A$ . You can always take it to be  $ENABLED A$ , but you can usually find an expression that equals  $ENABLED A$  in every reachable state of  $Spec$  but is easier for  $TLC$  to compute.

EXTENDS *Naturals*, *TLC*

$top \triangleq [top \mapsto \text{“top”}]$

VARIABLES  $s, vars$

$$\begin{aligned}
NoStutter(A) &\triangleq (s = top) \wedge A \wedge (s' = s) \\
PostStutter(A, actionId, context, bot, initVal, decr(_)) &\triangleq \\
&\text{IF } s = top \text{ THEN } \wedge A \\
&\quad \wedge s' = [id \mapsto actionId, ctxt \mapsto context, val \mapsto initVal] \\
&\quad \text{ELSE } \wedge s.id = actionId \\
&\quad \wedge \text{UNCHANGED } vars \\
&\quad \wedge s' = \text{IF } s.val = bot \text{ THEN } top \\
&\quad \quad \text{ELSE } [s \text{ EXCEPT } !.val = decr(s.val)] \\
PreStutter(A, enabled, actionId, context, bot, initVal, decr(_)) &\triangleq \\
&\text{IF } s = top \\
&\quad \text{THEN } \wedge enabled \\
&\quad \wedge \text{UNCHANGED } vars \\
&\quad \wedge s' = [id \mapsto actionId, ctxt \mapsto context, val \mapsto initVal] \\
&\quad \text{ELSE } \wedge s.id = actionId \\
&\quad \wedge \text{IF } s.val = bot \text{ THEN } \wedge s.ctxt = context \\
&\quad \quad \wedge A \\
&\quad \quad \wedge s' = top \\
&\quad \quad \text{ELSE } \wedge \text{UNCHANGED } vars \\
&\quad \quad \wedge s' = [s \text{ EXCEPT } !.val = decr(s.val)] \\
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MayPostStutter(A, actionId, context, bot, initVal, decr(_)) &\triangleq \\
&\text{IF } s = top \text{ THEN } \wedge A \\
&\quad \wedge s' = \text{IF } initVal = bot \\
&\quad \quad \text{THEN } s \\
&\quad \quad \text{ELSE } [id \mapsto actionId, ctxt \mapsto context, \\
&\quad \quad \quad val \mapsto initVal] \\
&\quad \text{ELSE } \wedge s.id = actionId \\
&\quad \wedge \text{UNCHANGED } vars \\
&\quad \wedge s' = \text{IF } decr(s.val) = bot \\
&\quad \quad \text{THEN } top \\
&\quad \quad \text{ELSE } [s \text{ EXCEPT } !.val = decr(s.val)] \\
MayPreStutter(A, enabled, actionId, context, bot, initVal, decr(_)) &\triangleq \\
&\text{IF } s = top \\
&\quad \text{THEN } \wedge enabled \\
&\quad \wedge \text{UNCHANGED } vars \\
&\quad \wedge \text{IF } initVal = bot \\
&\quad \quad \text{THEN } A \wedge (s' = s) \\
&\quad \quad \text{ELSE } s' = [id \mapsto actionId, ctxt \mapsto context, val \mapsto initVal] \\
&\quad \text{ELSE } \wedge s.id = actionId \\
&\quad \wedge \text{IF } s.val = bot \text{ THEN } \wedge s.ctxt = context \\
&\quad \quad \wedge A \\
&\quad \quad \wedge s' = top \\
&\quad \quad \text{ELSE } \wedge \text{UNCHANGED } vars
\end{aligned}$$

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$$\wedge s' = [s \text{ EXCEPT } !.val = \text{decr}(s.val)]$$


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StutterConstantCondition(Sigma, bot, decr(_))  $\triangleq$ 
  LET InverseDecr(S)  $\triangleq$  {sig  $\in$  Sigma  $\setminus$  S : decr(sig)  $\in$  S}
    R[n  $\in$  Nat]  $\triangleq$  IF n = 0 THEN {bot}
                  ELSE LET T  $\triangleq$  R[n - 1]
                      IN T  $\cup$  InverseDecr(T)

  IN Sigma = UNION {R[n] : n  $\in$  Nat}
    LET InverseDecr(S)  $\triangleq$  {sig  $\in$  Sigma  $\setminus$  S : decr(sig)  $\in$  S}
      ReachBot[S  $\in$  SUBSET Sigma]  $\triangleq$ 
        IF InverseDecr(S) = {} THEN S
        ELSE ReachBot[S  $\cup$  InverseDecr(S)]
    IN ReachBot[{bot}] = Sigma

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\ * Modification History
\ * Last modified Thu Oct 20 06:27:41 PDT 2016 by lamport
\ * Created Tue Dec 08 11:51:34 PST 2015 by lamport

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