

UNIT 3 Non-linear population models

Outline

Introduction

Population Examples

Continuous-time regulation

A simple, continuous-time model

Simulating model behaviour

Equilibria and time scales

Discrete-time regulation

A simple, discrete-time model

Simulating this system

Interpreting complex behaviour

Delayed regulation

Small populations and stochasticity

Allee effects

Stochastic effects

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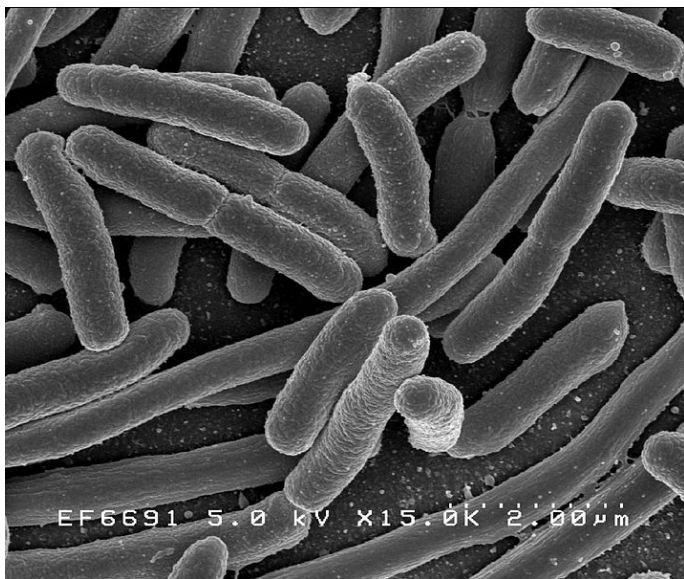
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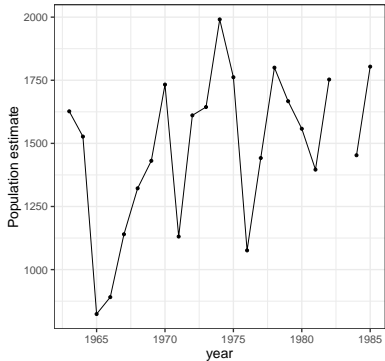
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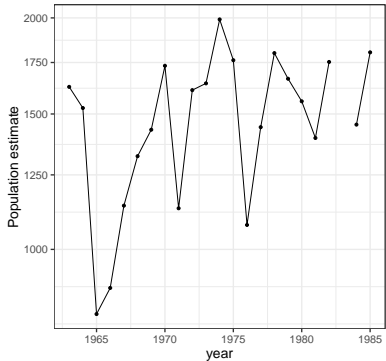
(preview)

Elk

Elks in Grand Teton

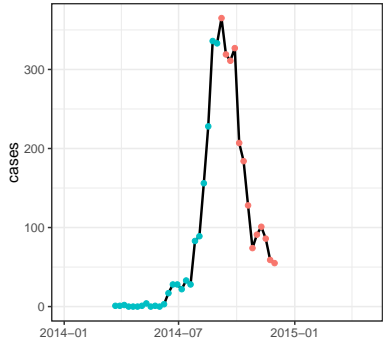


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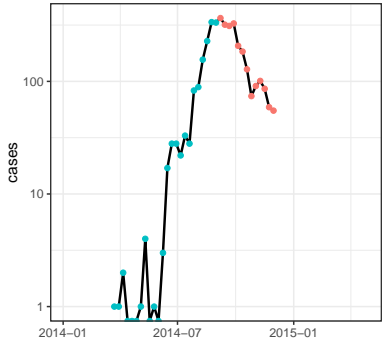


Ebola

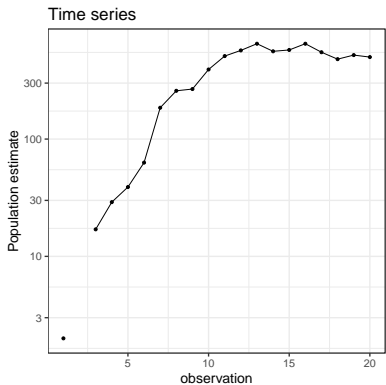
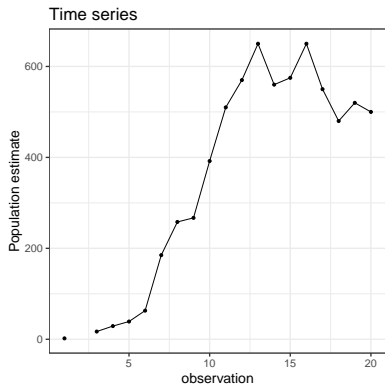
Liberia



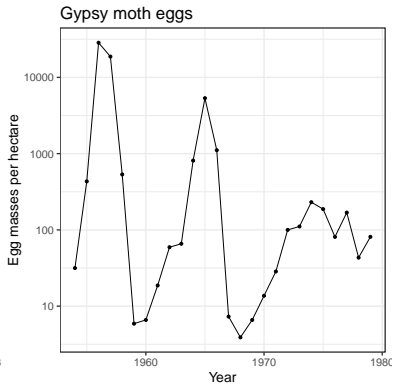
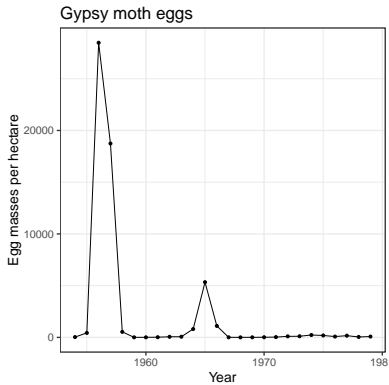
Liberia



Paramecia (preview)



Gypsy moths (preview)



Gypsy moths

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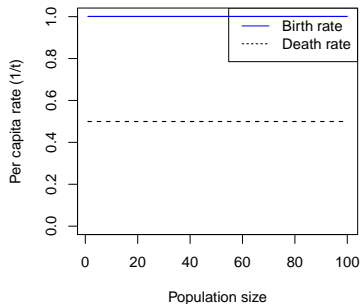
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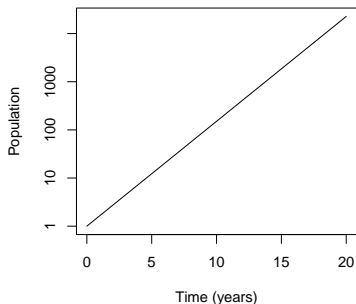
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Individual perspective

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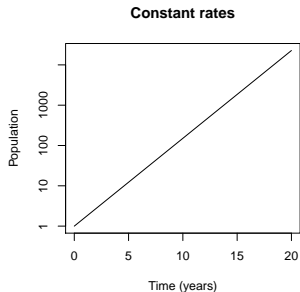
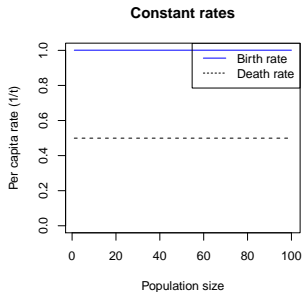


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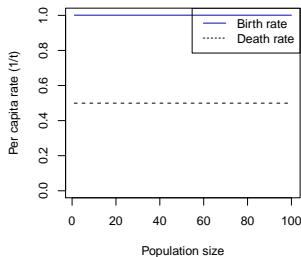
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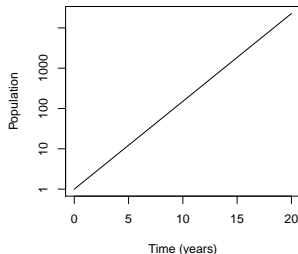
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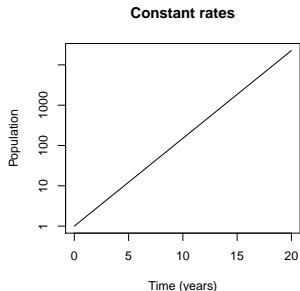
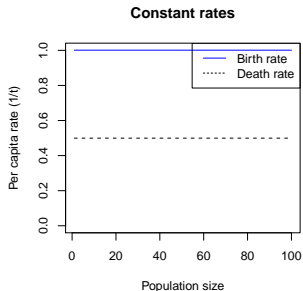


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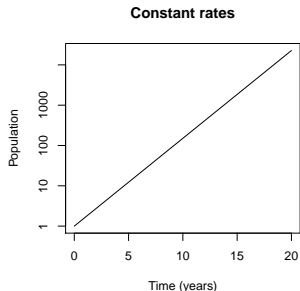
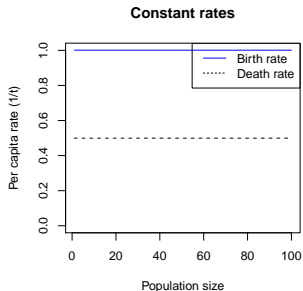
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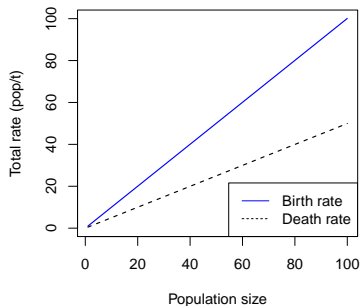
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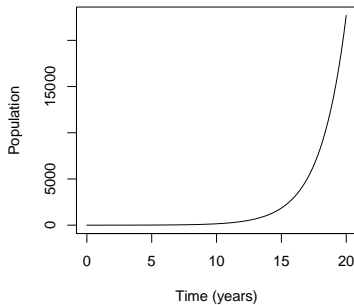


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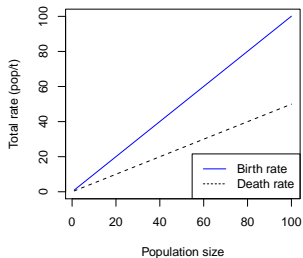
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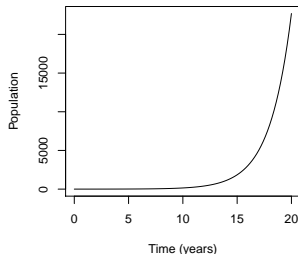
Population perspective

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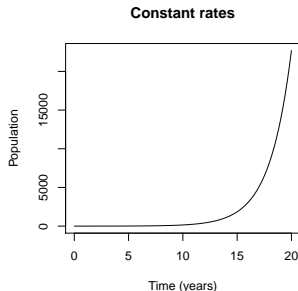
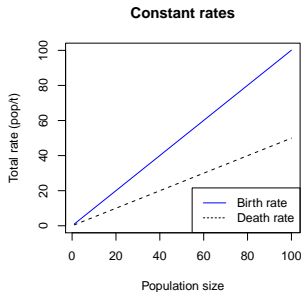


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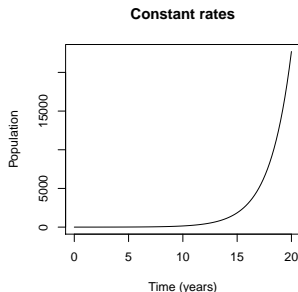
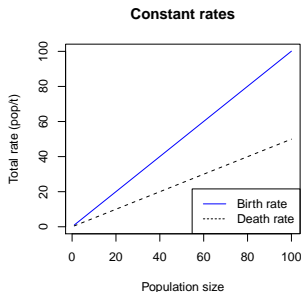
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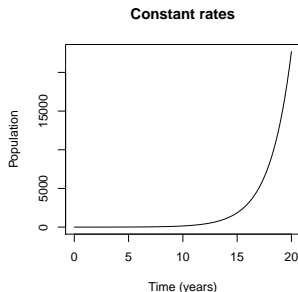
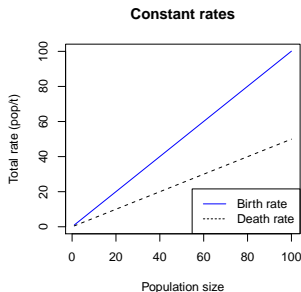
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Birth rates

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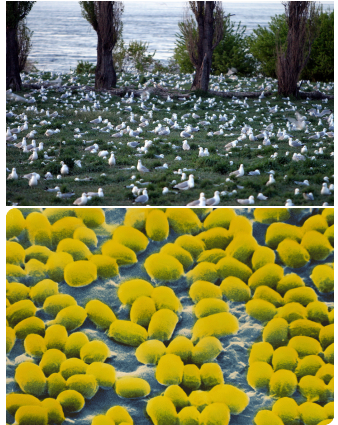
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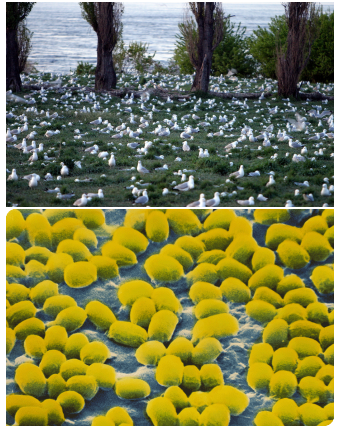
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Outline

Introduction

Population Examples

Continuous-time regulation

A simple, continuous-time model

Simulating model behaviour

Equilibria and time scales

Discrete-time regulation

A simple, discrete-time model

Simulating this system

Interpreting complex behaviour

Delayed regulation

Small populations and stochasticity

Allee effects

Stochastic effects

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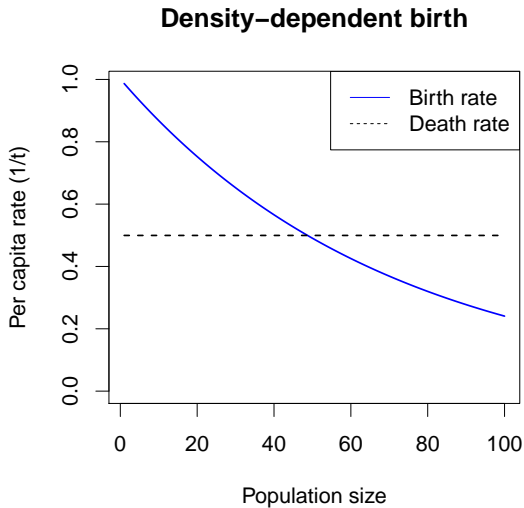
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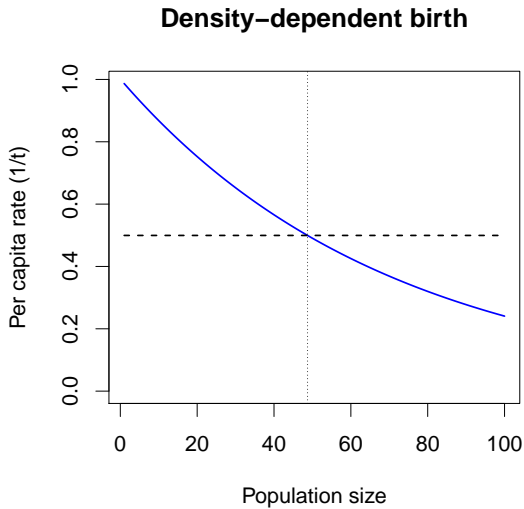
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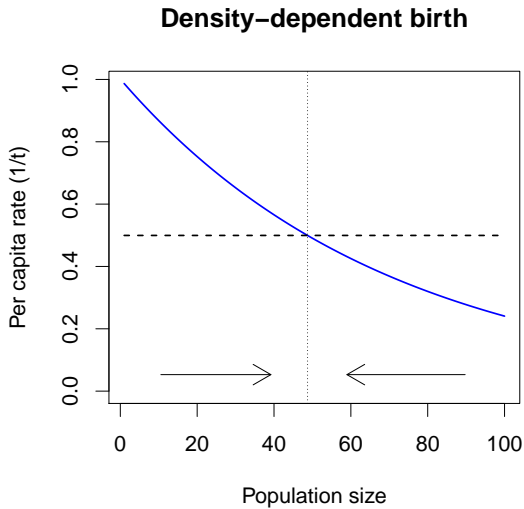
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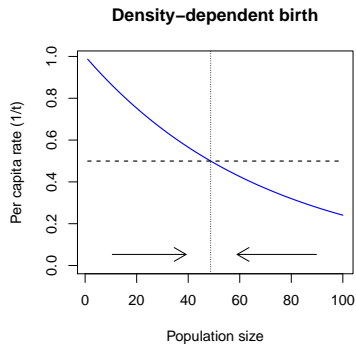
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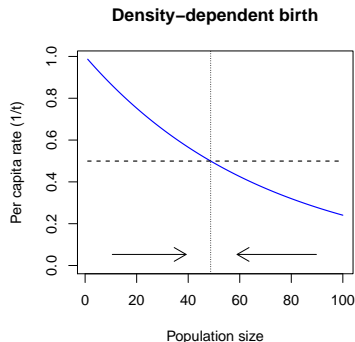


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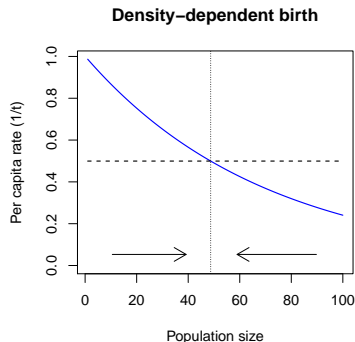
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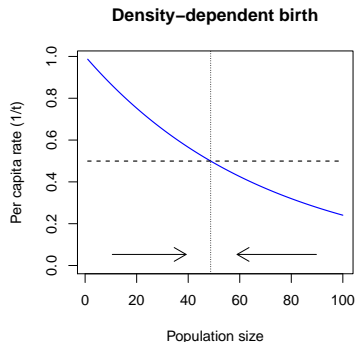
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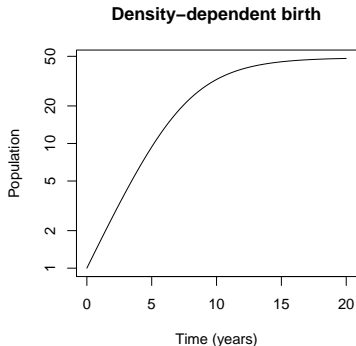
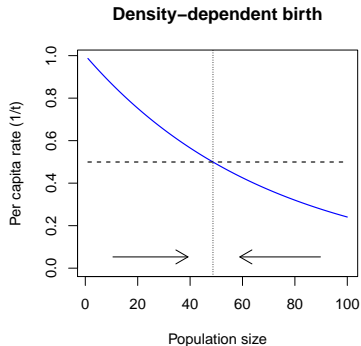
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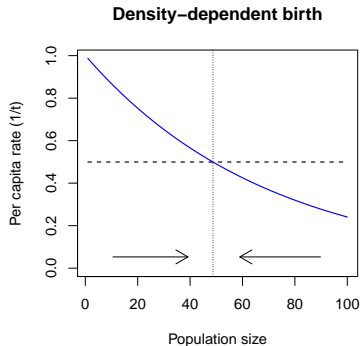


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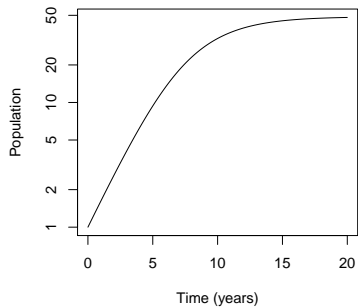


High starting population example

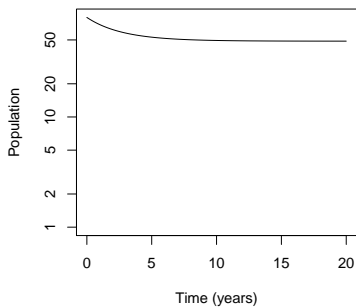


Examples

Density-dependent birth



Density-dependent birth



Outline

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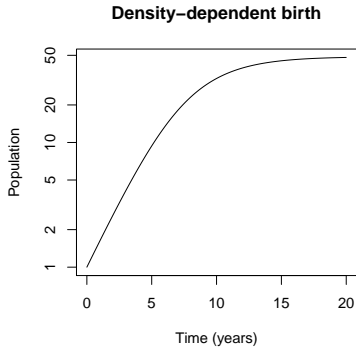
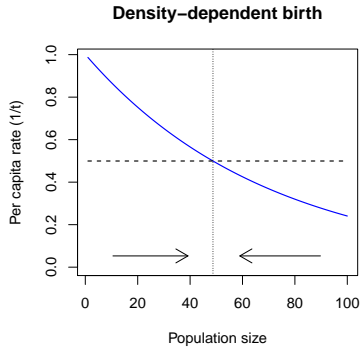
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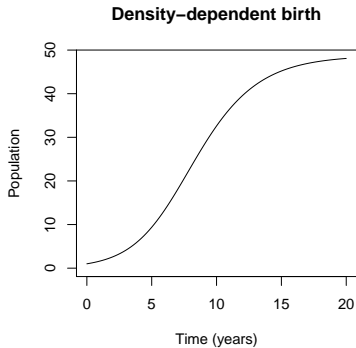
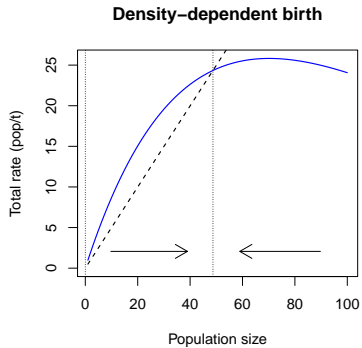
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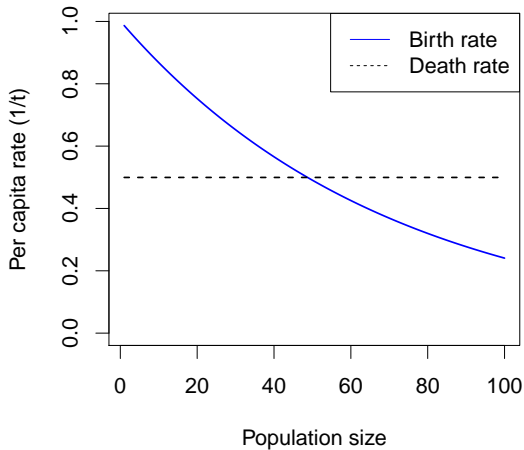
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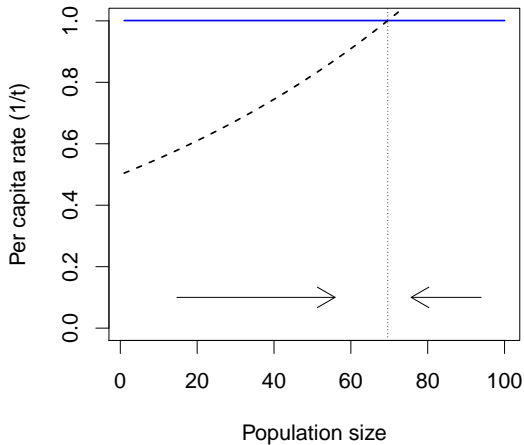
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Density-dependent birth



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Density-dependent death



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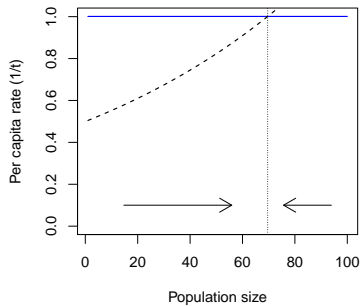
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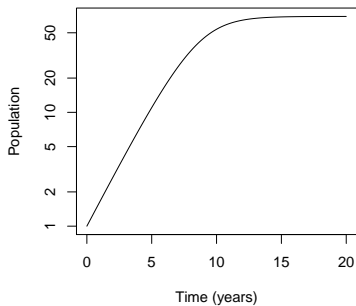


Individual perspective

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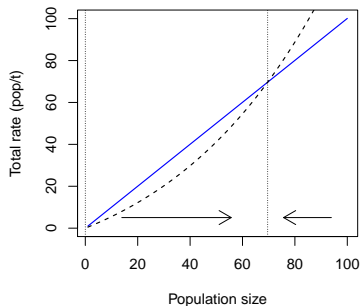


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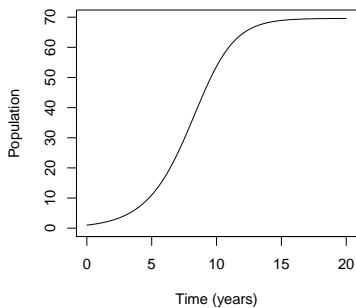


Population perspective

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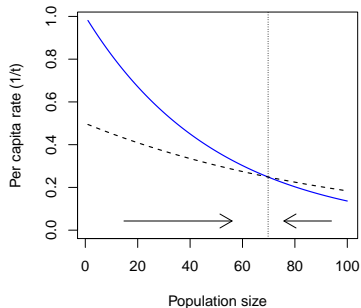
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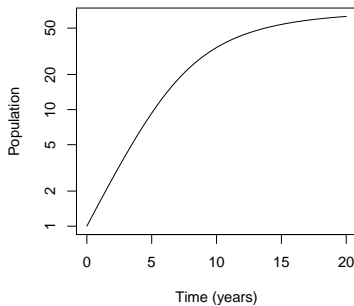


Individual perspective

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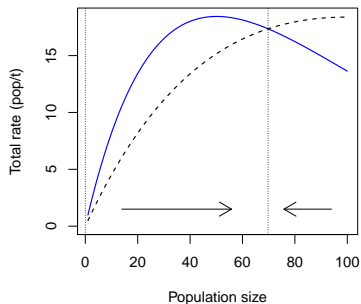


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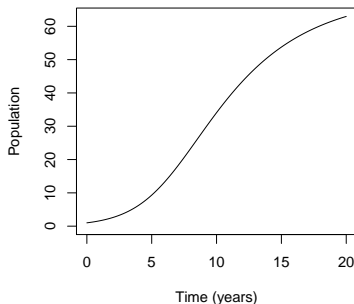


Population perspective

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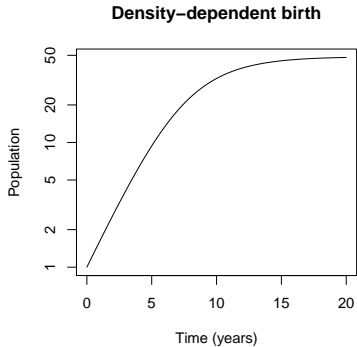
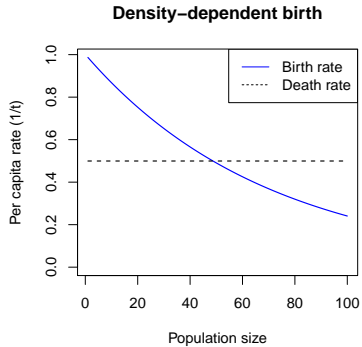
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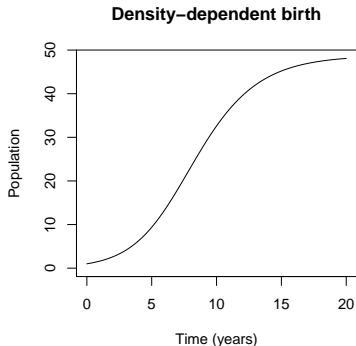
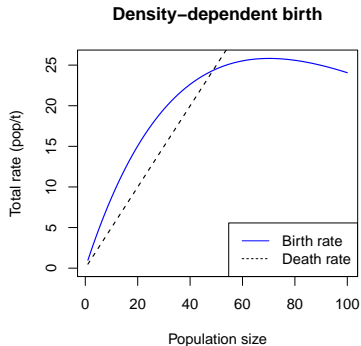
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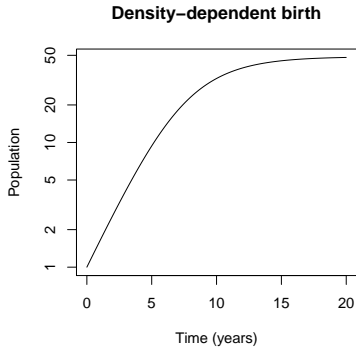
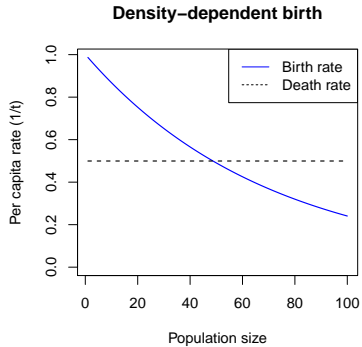
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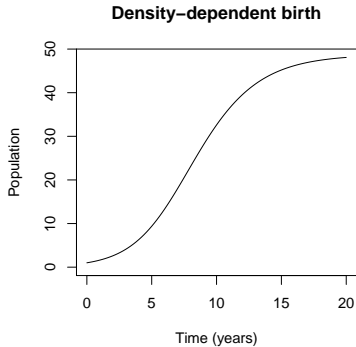
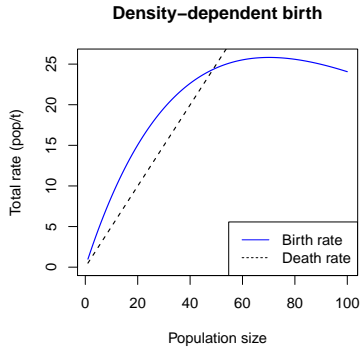
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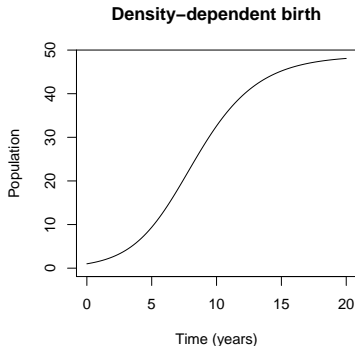
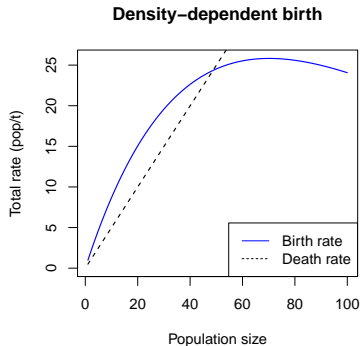
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- ▶ In this model, when $\mathcal{R}_0 < 1$ the population:
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 - ▶ * Increases when it is small
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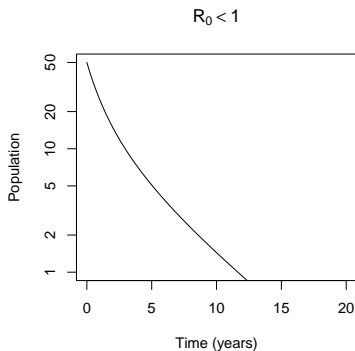
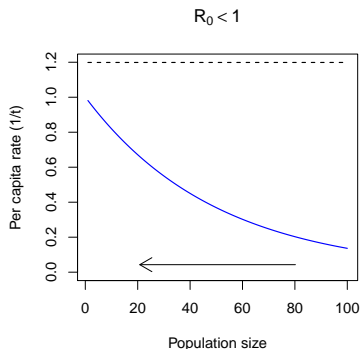
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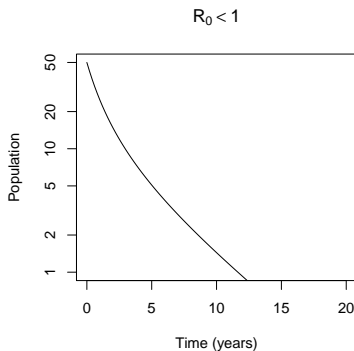
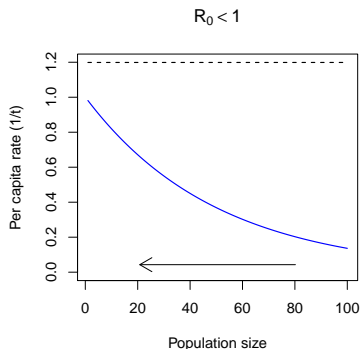
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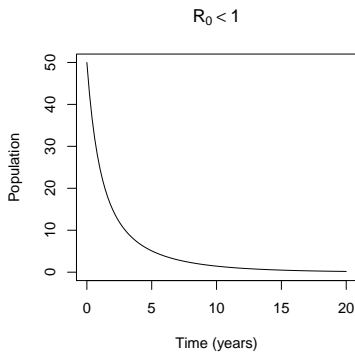
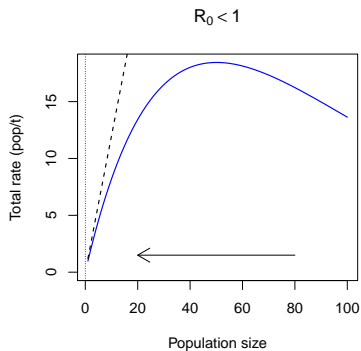
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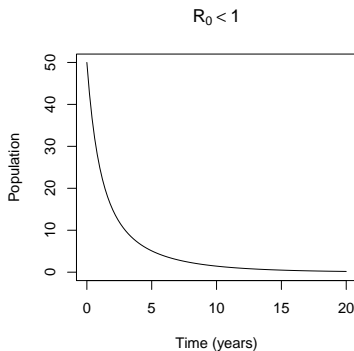
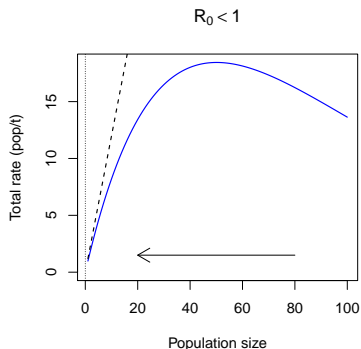
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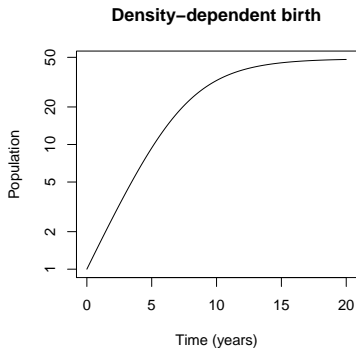
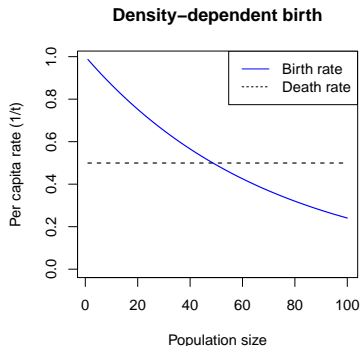
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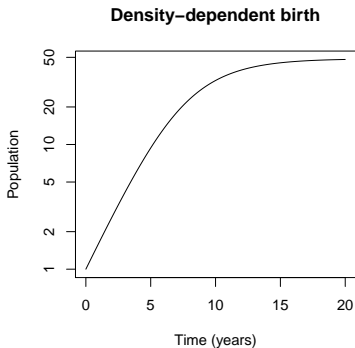
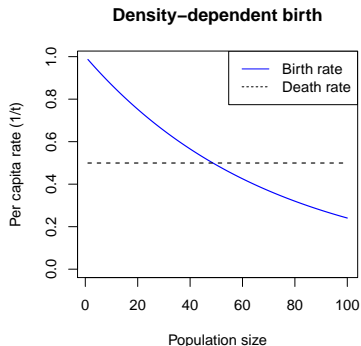
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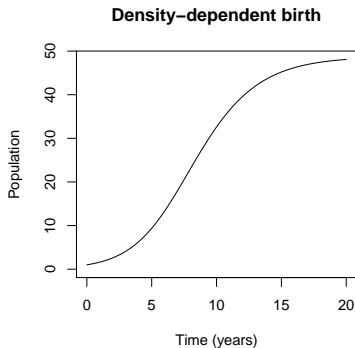
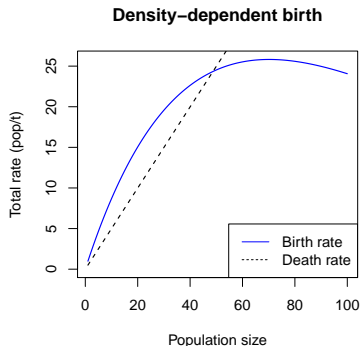
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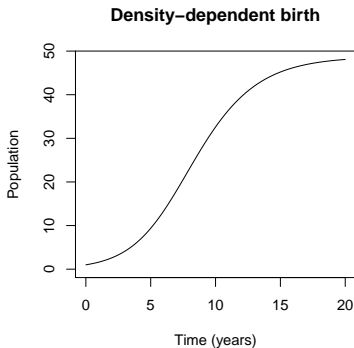
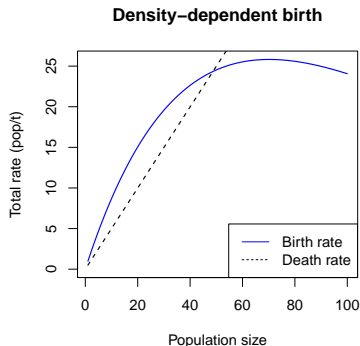
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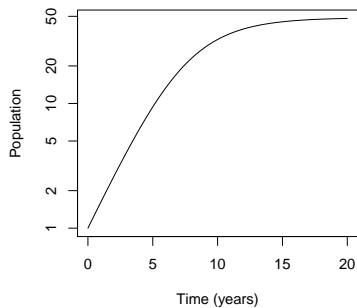
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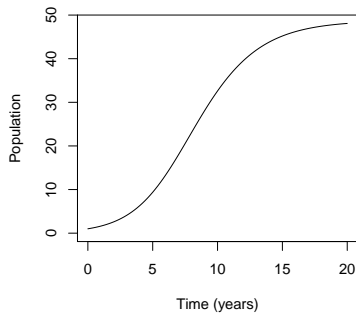
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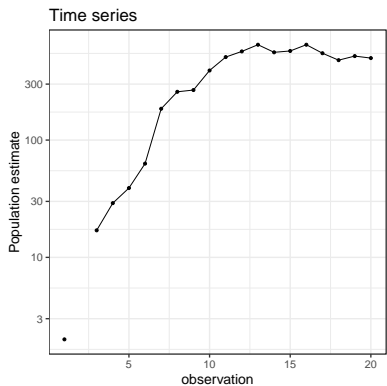
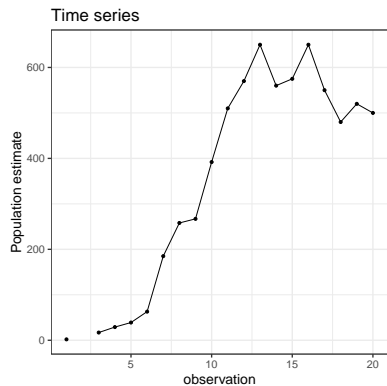
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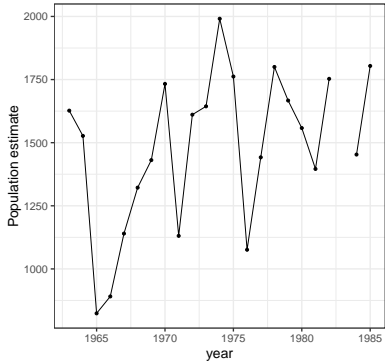
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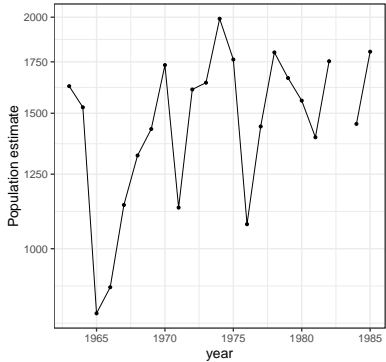


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Stochastic effects

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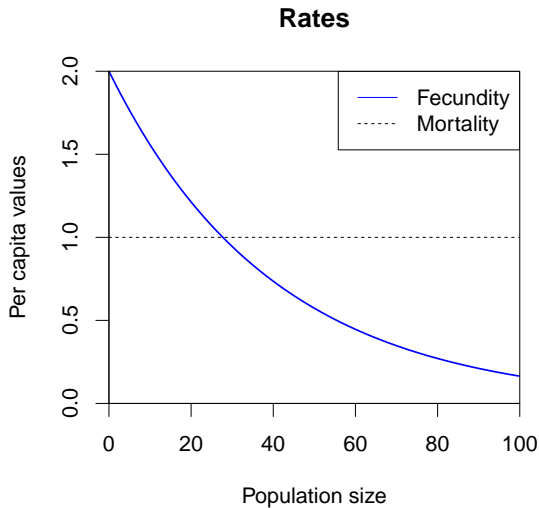
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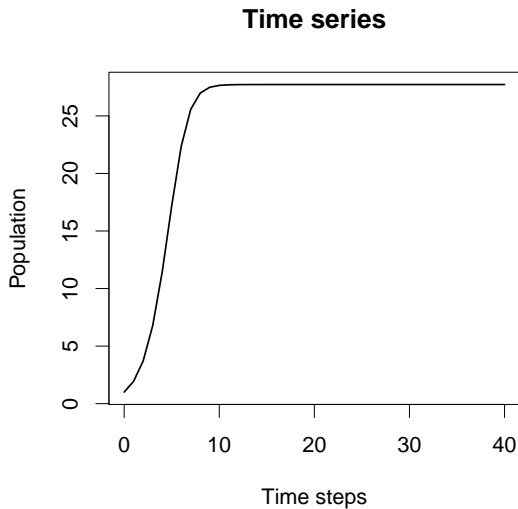
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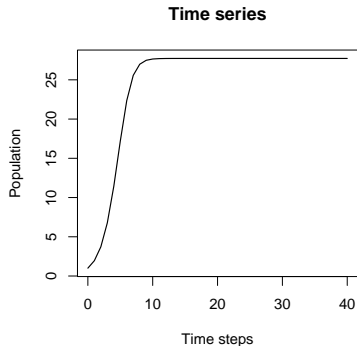
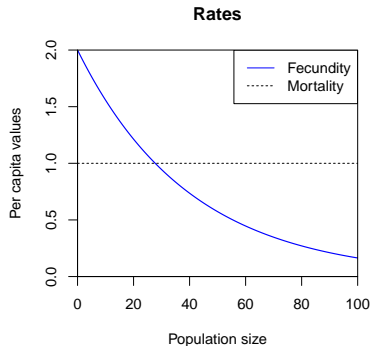
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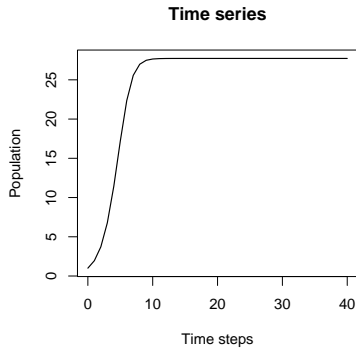
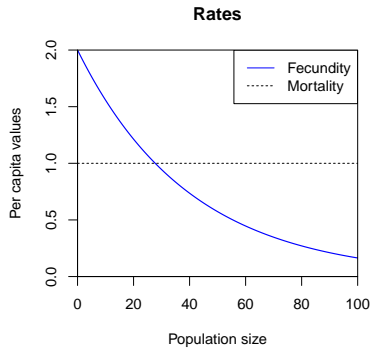


We expect simple dynamics

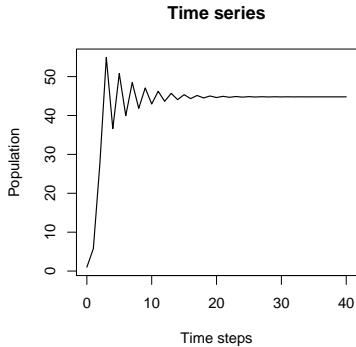
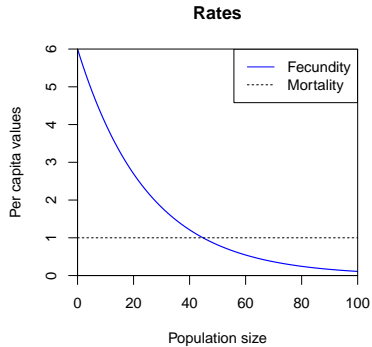


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Simple dynamics (repeat)

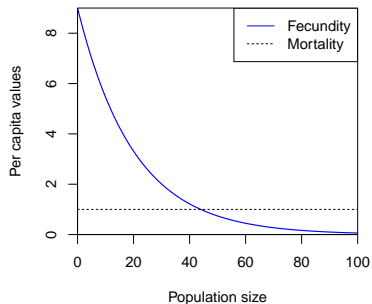


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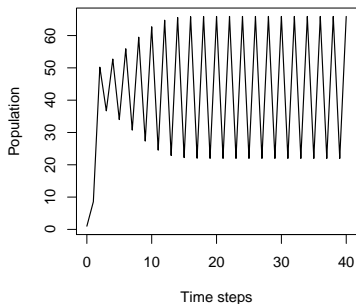


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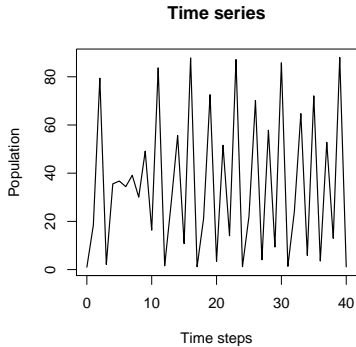
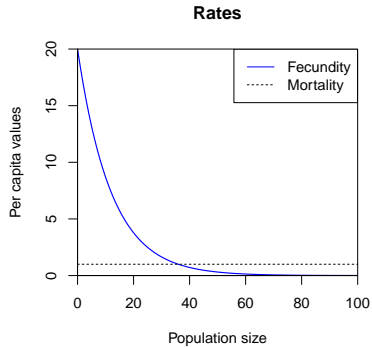
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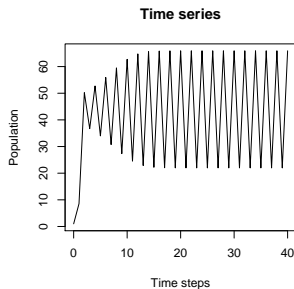
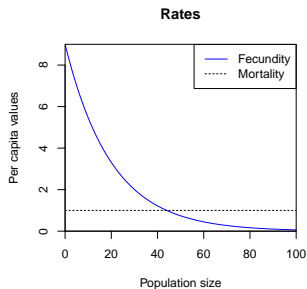
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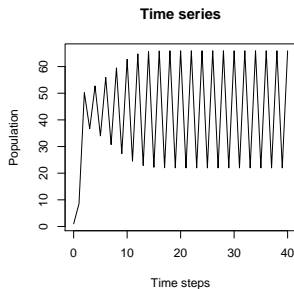
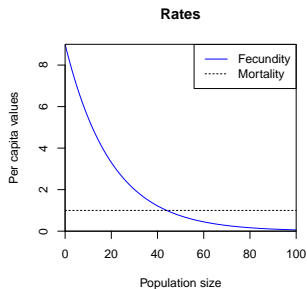
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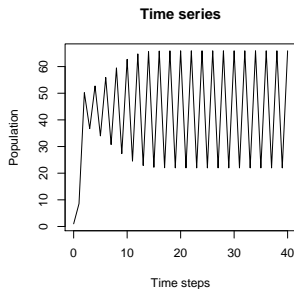
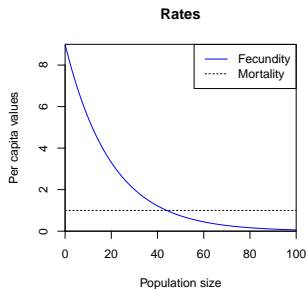
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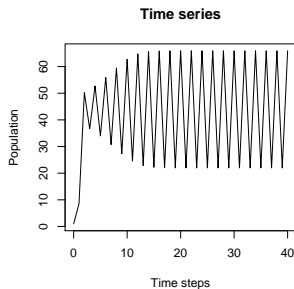
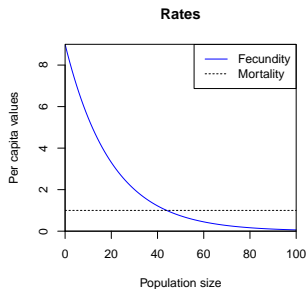
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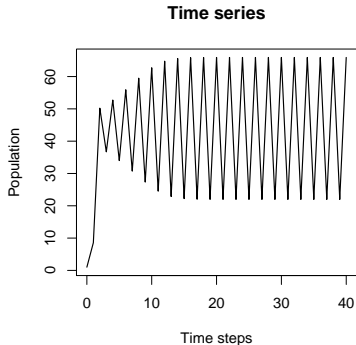
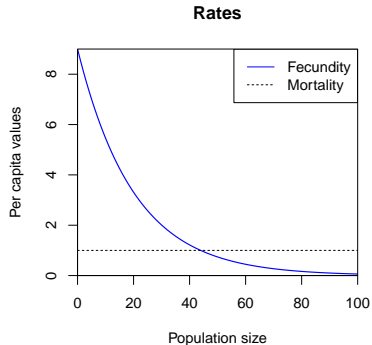


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Interpreting complex behaviour (repeat)



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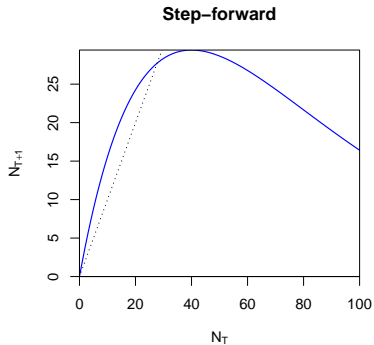
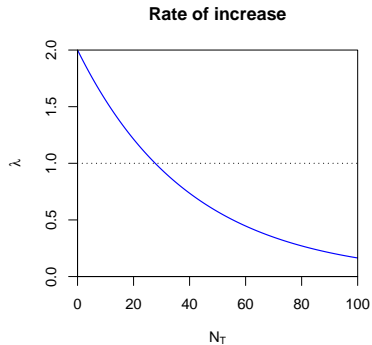
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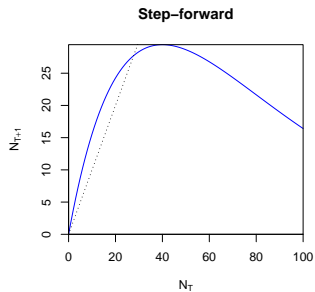
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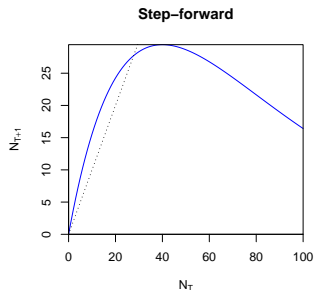
Turnover

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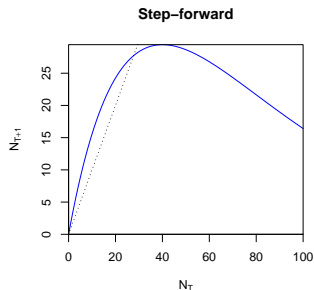
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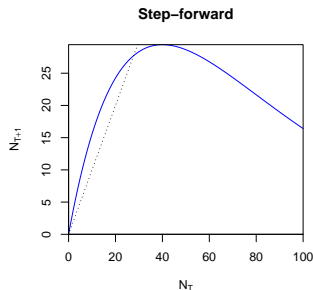
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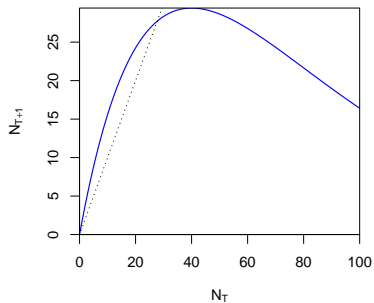
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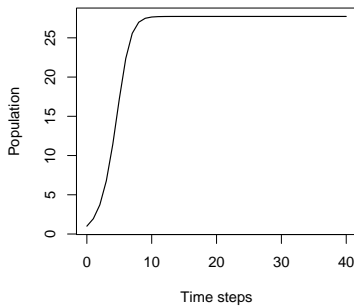


Simple dynamics

Step-forward

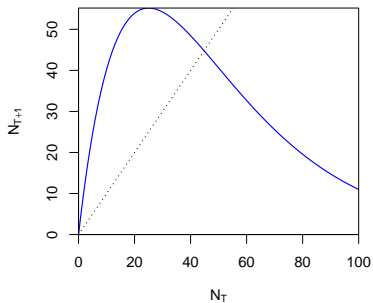


Time series

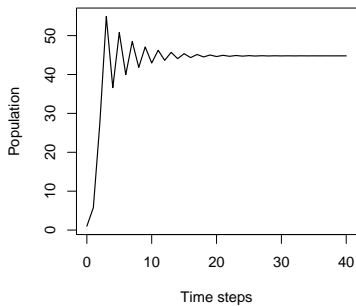


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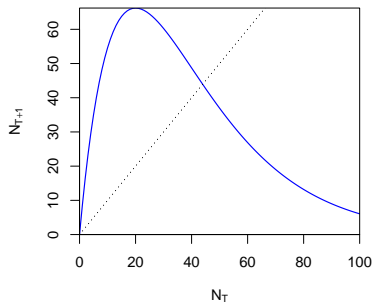


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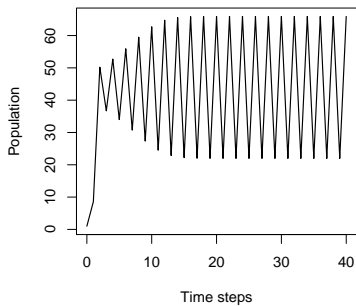


Persistent oscillations

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Time series



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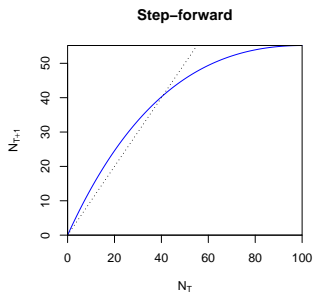
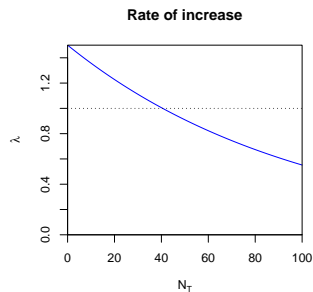
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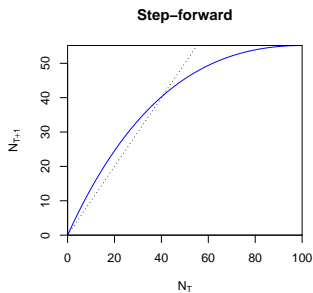
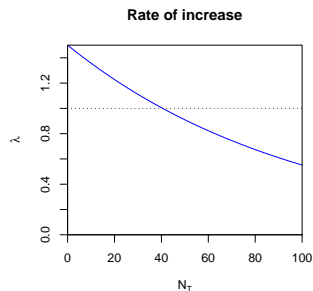
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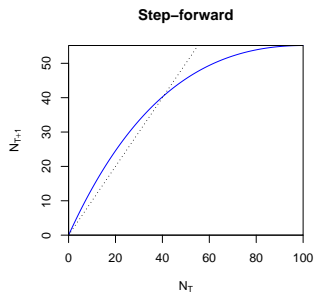
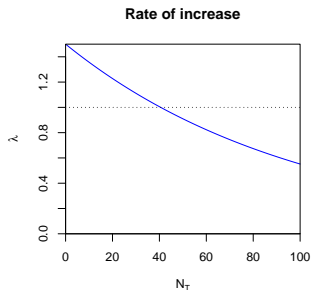
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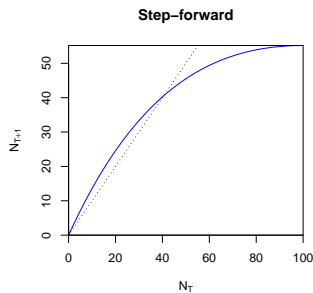
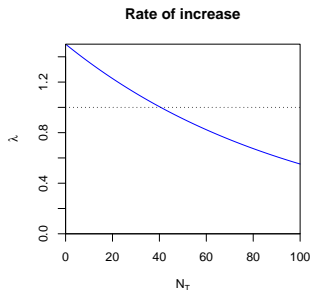
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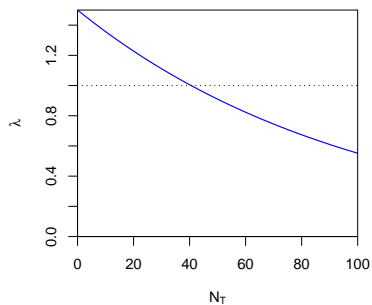
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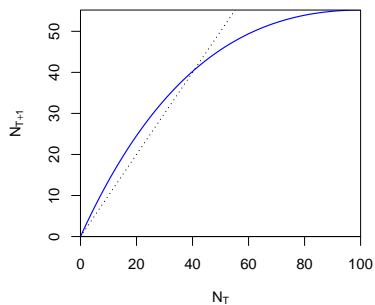


Contest regulation

Rate of increase



Step-forward



Songbirds

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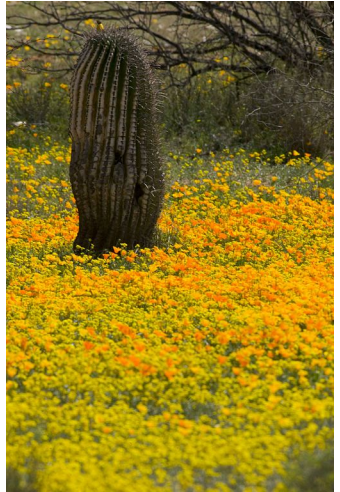
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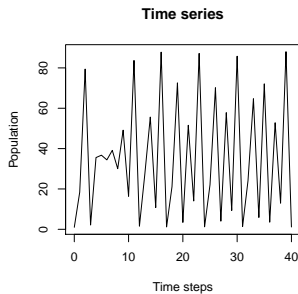
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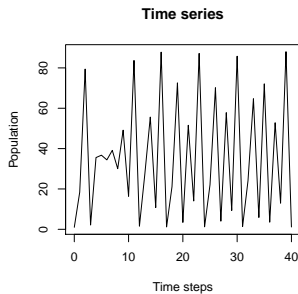
Complex behaviour from a simple model

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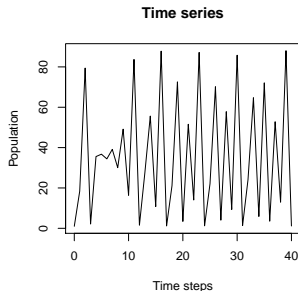
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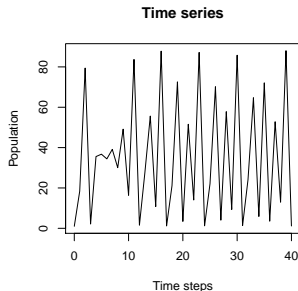
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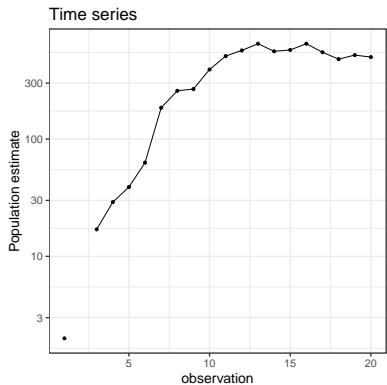
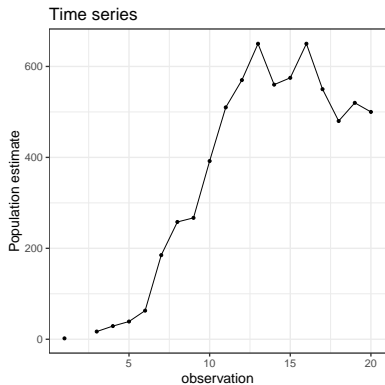
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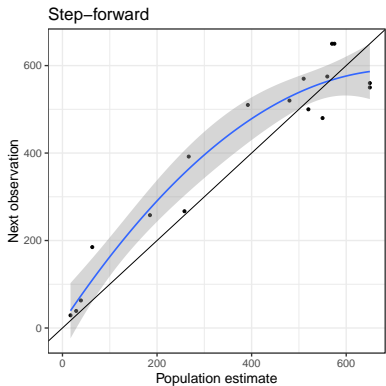
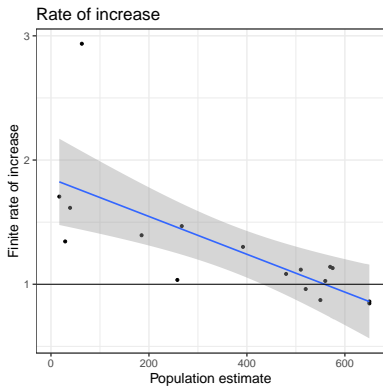
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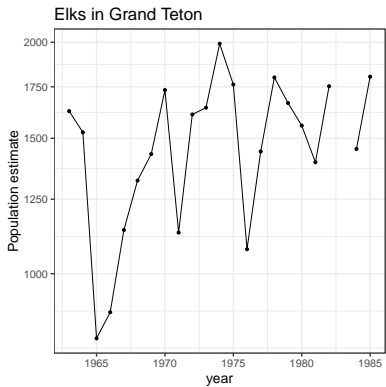
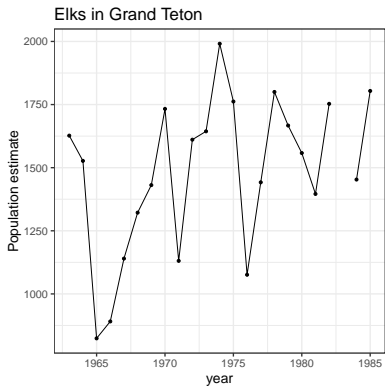
Paramecia (repeat)

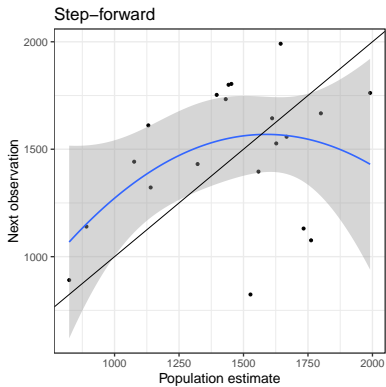
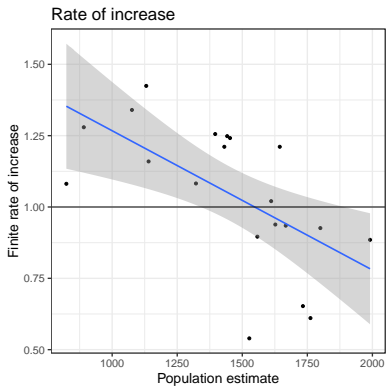


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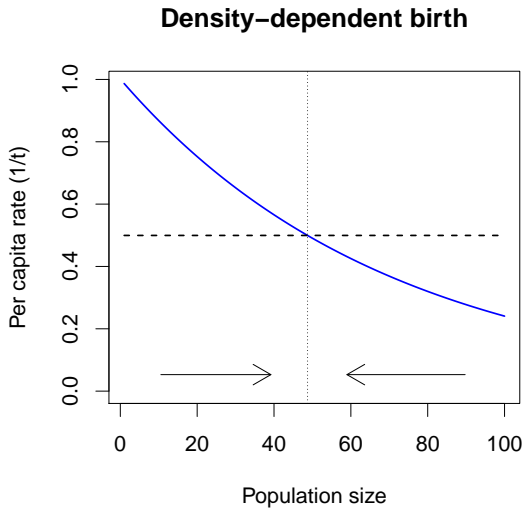
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Arrows with time delay



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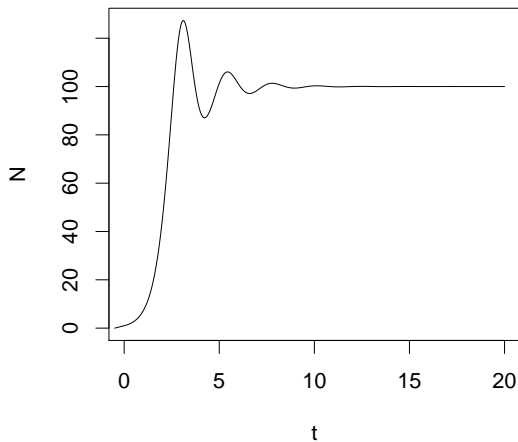
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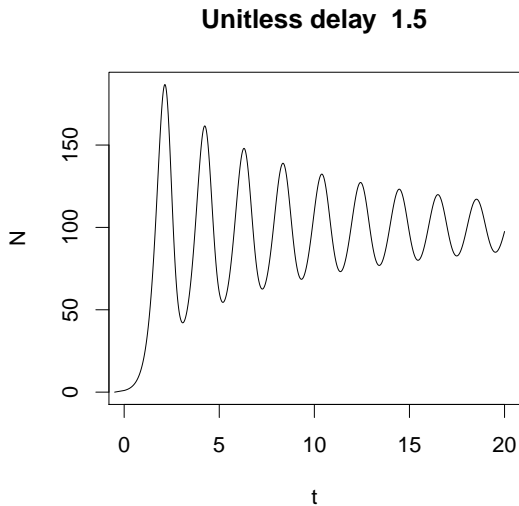
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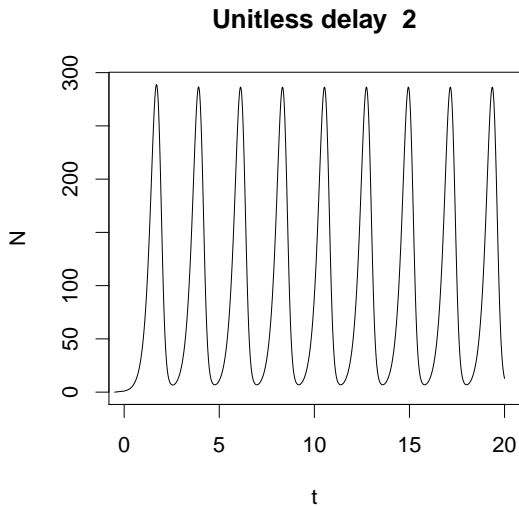
Unitless delay 1



Time-delayed dynamics



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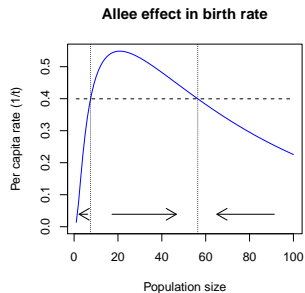
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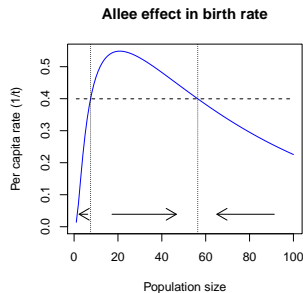
Allee effect models

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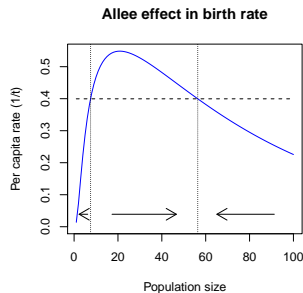
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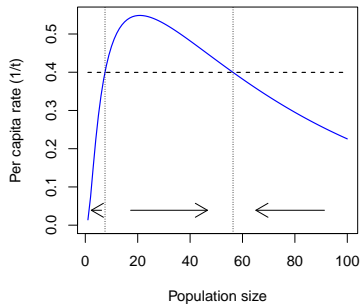
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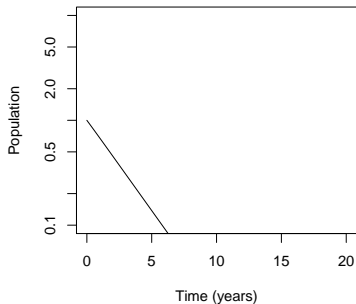


Individual perspective

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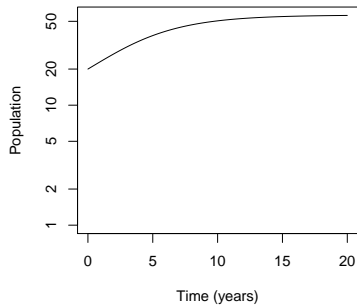


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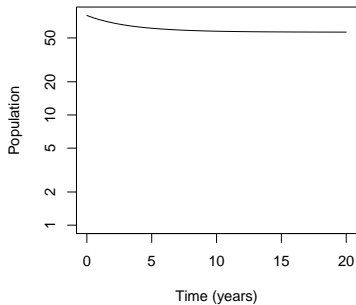


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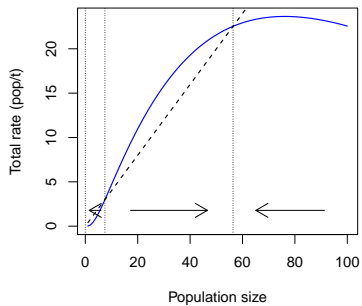


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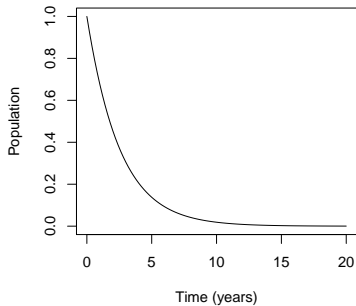


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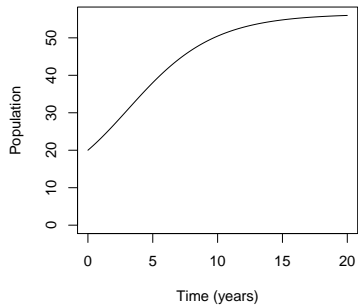


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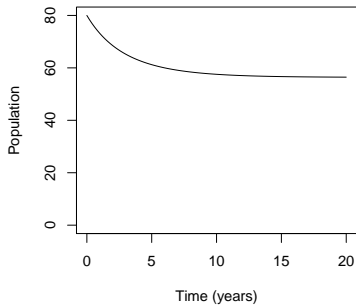


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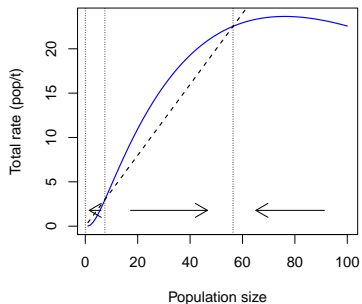


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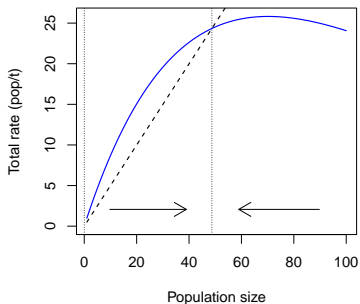


Population comparison (repeat)

Allee effect in birth rate

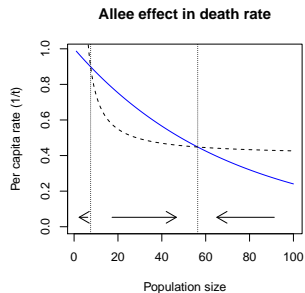


Density-dependent birth



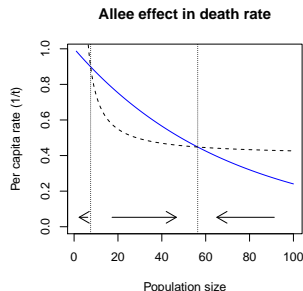
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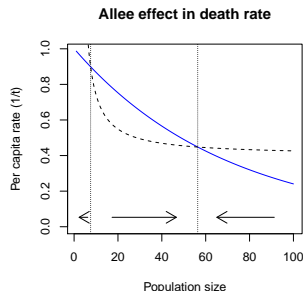
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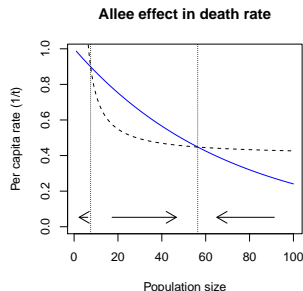
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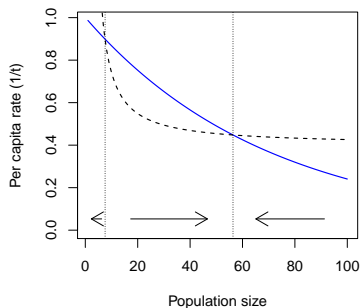
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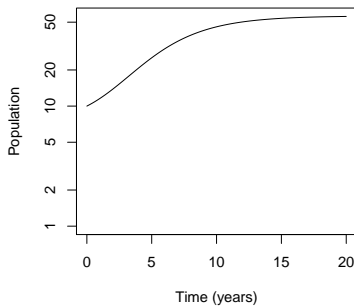


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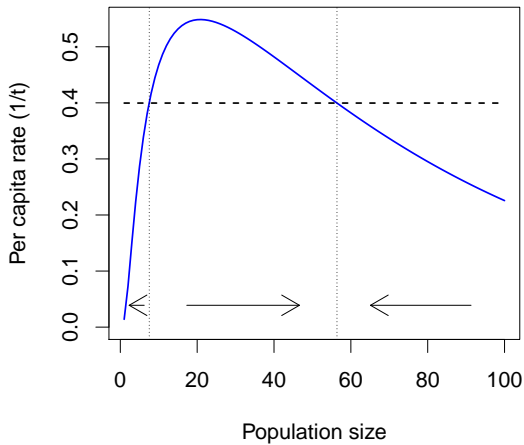
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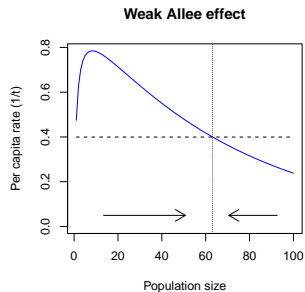
\mathcal{R}_0 and \mathcal{R}_{max} (repeat)

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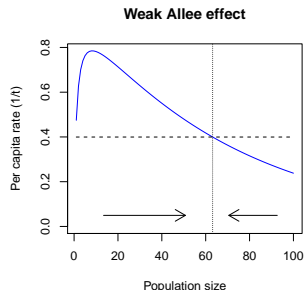
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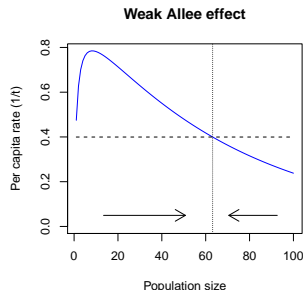
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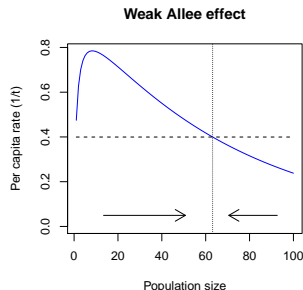
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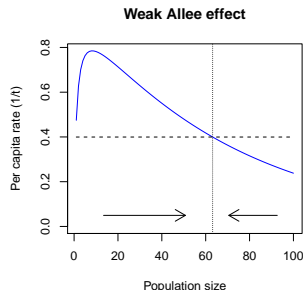
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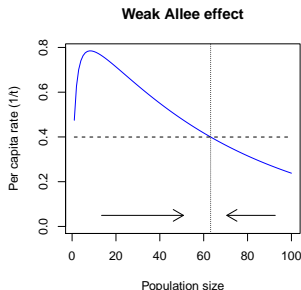
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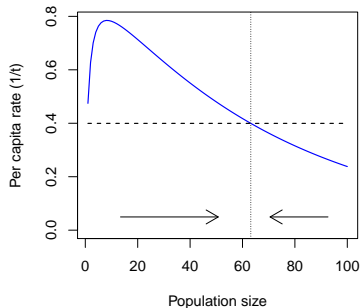
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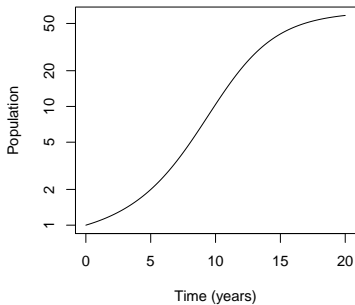


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Outline

Introduction

- Population Examples

Continuous-time regulation

- A simple, continuous-time model

- Simulating model behaviour

- Equilibria and time scales

Discrete-time regulation

- A simple, discrete-time model

- Simulating this system

- Interpreting complex behaviour

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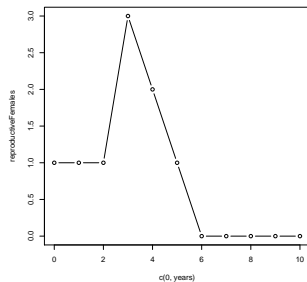
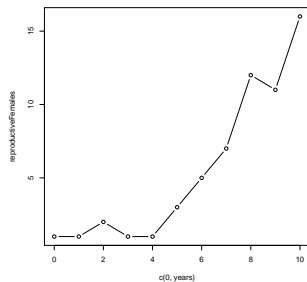
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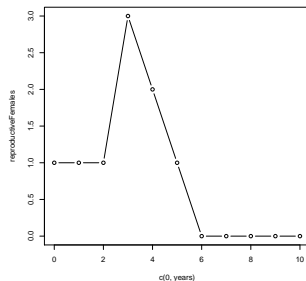
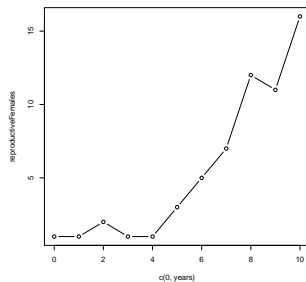
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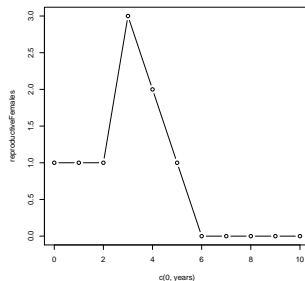
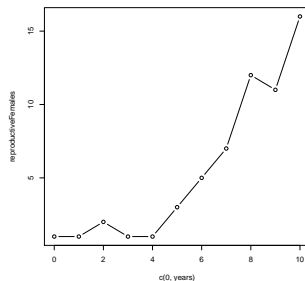
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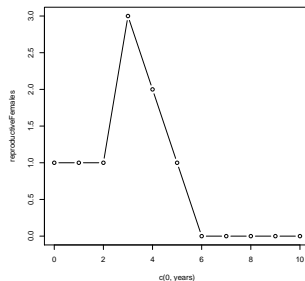
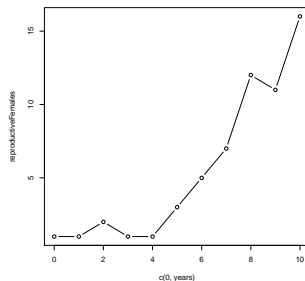
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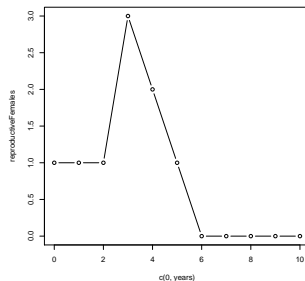
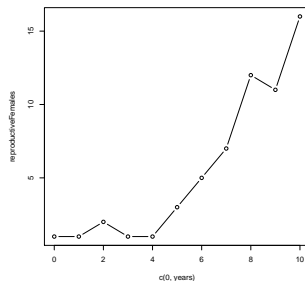
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