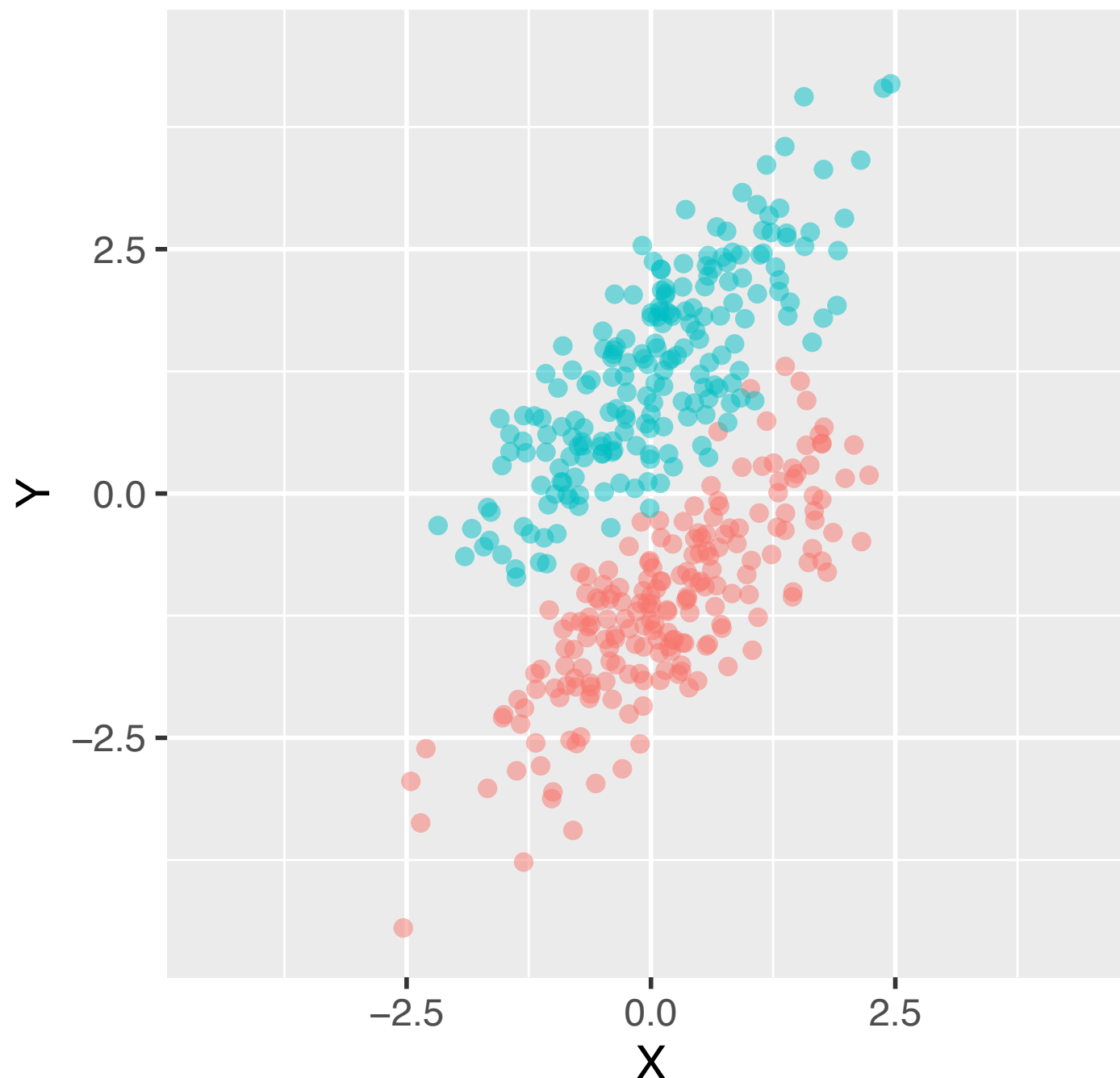


Canonical Variates (Linear Discriminant) Analysis

What is the direction that best separates the groups? What is the direction of the first PC axis?



Overview of Discriminant Analysis

Discrimination

Given an $n \times p$ data matrix, X , and a grouping of the n specimens into g groups, find the linear combination of the variables, Xa , that best discriminates between the groups.

$$\vec{y}_{\text{discrim}} = a_1 \vec{x}_1 + a_2 \vec{x}_2 + \cdots + a_p \vec{x}_p$$

Classification

Given g groups, define a function that assigns an object with unknown assignment to the 'best' group.

Fisher's Discriminant Function

- Applies to the two-group case.
- Solution: find \mathbf{a} that maximizes the ratio of the squared group mean difference to within-group variance:

$$F = \frac{(\bar{\mathbf{x}}_1 \mathbf{a} - \bar{\mathbf{x}}_2 \mathbf{a})^2}{\mathbf{a}' \mathbf{W} \mathbf{a}}$$

where

- $\bar{\mathbf{x}}_1 = \frac{1}{n_1} \sum_{i=1}^{n_1} \mathbf{x}_{1i}$ (row-vector of means of group 1)
- $\bar{\mathbf{x}}_2 = \frac{1}{n_2} \sum_{i=1}^{n_2} \mathbf{x}_{2i}$ (row-vector of means of group 2)
- $\mathbf{W} = \frac{1}{n_1 + n_2 - 2} \sum_{i=1}^2 \sum_{j=1}^{n_i} (\mathbf{x}_{ij} - \bar{\mathbf{x}}_i)(\mathbf{x}_{ij} - \bar{\mathbf{x}}_i)'$ (w/in-group pooled covariance matrix)
- n_i indicates the number of observations in the i th group and the $\mathbf{x}_{i1}, \dots, \mathbf{x}_{in_i}$ represent the specific observations (as vectors).

Geometry of the Two-Group Discriminant Function

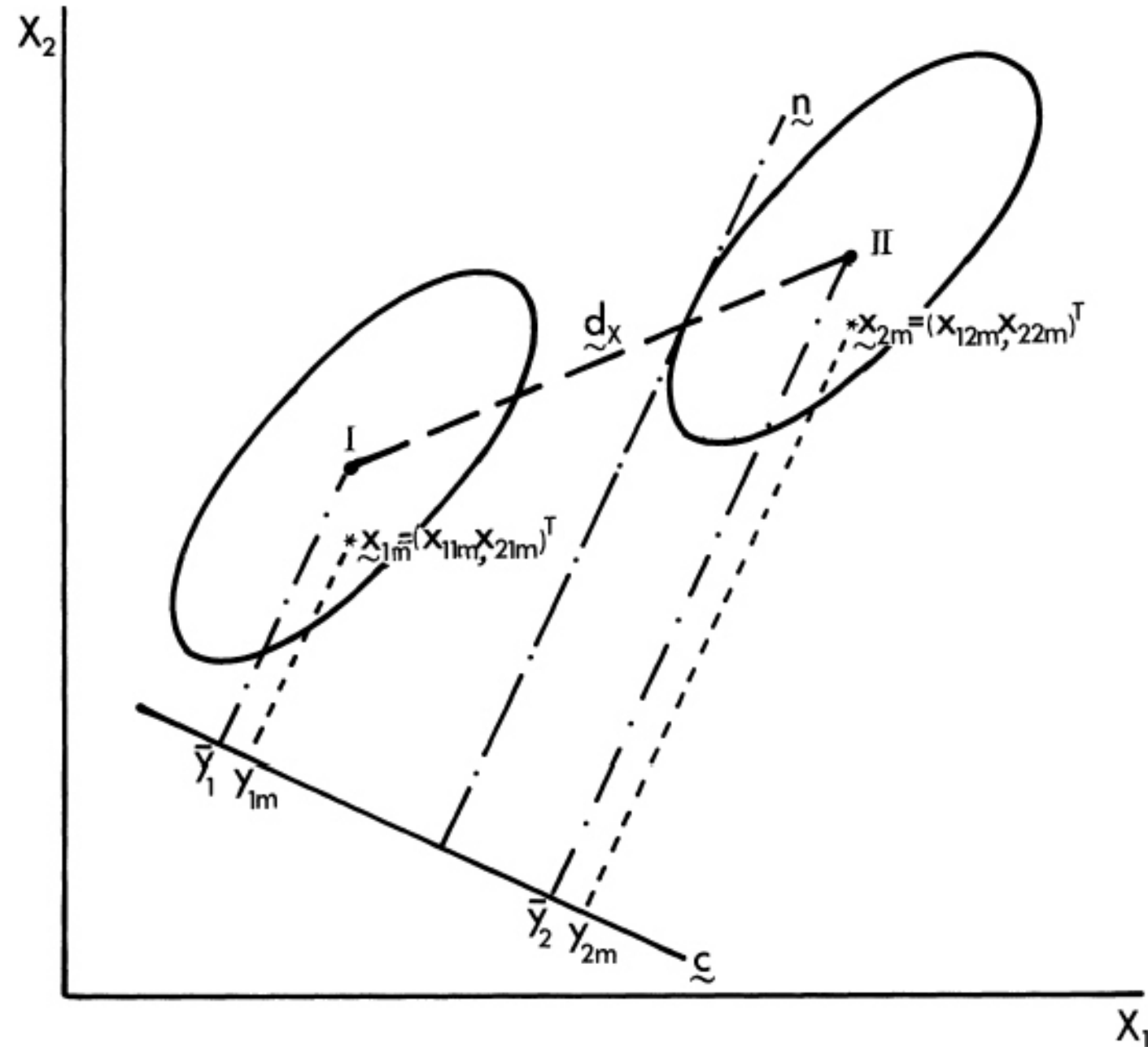


FIG. 4.—Representation of the discriminant function for two groups and two variables, showing the group means and associated 95% concentration ellipses. The vector c is the discriminant vector. The points \bar{y}_1 and \bar{y}_2 represent the discriminant means for the two groups.

The discriminant vector can be constructed by drawing the tangent n to the concentration ellipse at the point of intersection with the line d joining the group means; the discriminant vector is orthogonal to the tangent n .

Fisher's LDF

$$F = \frac{(\mathbf{a}' \bar{\mathbf{x}}_1 - \mathbf{a}' \bar{\mathbf{x}}_2)^2}{\mathbf{a}' W \mathbf{a}}$$

Maximizing F gives:

$$\mathbf{a} = c W^{-1} (\bar{\mathbf{x}}_1 - \bar{\mathbf{x}}_2)'$$

where c is an arbitrary constant (usually taken to be 1).

Fisher's LDF as Classification

Fisher's solution can also be setup as a classification solution using regression.

- setup a dummy variable, y that takes the values:
 - $y_1 = n_2 / (n_1 + n_2)$ for observations in group 1
 - $y_2 = -n_1 / (n_1 + n_2)$ for observations in group 2
- Solve the standard multivariate regression, $y = Xb + e$
- Allocate unknown individual to group 1 if it's predicted y is closer to y_1 than to y_2 , otherwise assign to group 2.

More than two groups?

- Multi-group extension of Fisher's linear discriminant function is called Canonical Variate Analysis (CVA)

Geometry of CVA

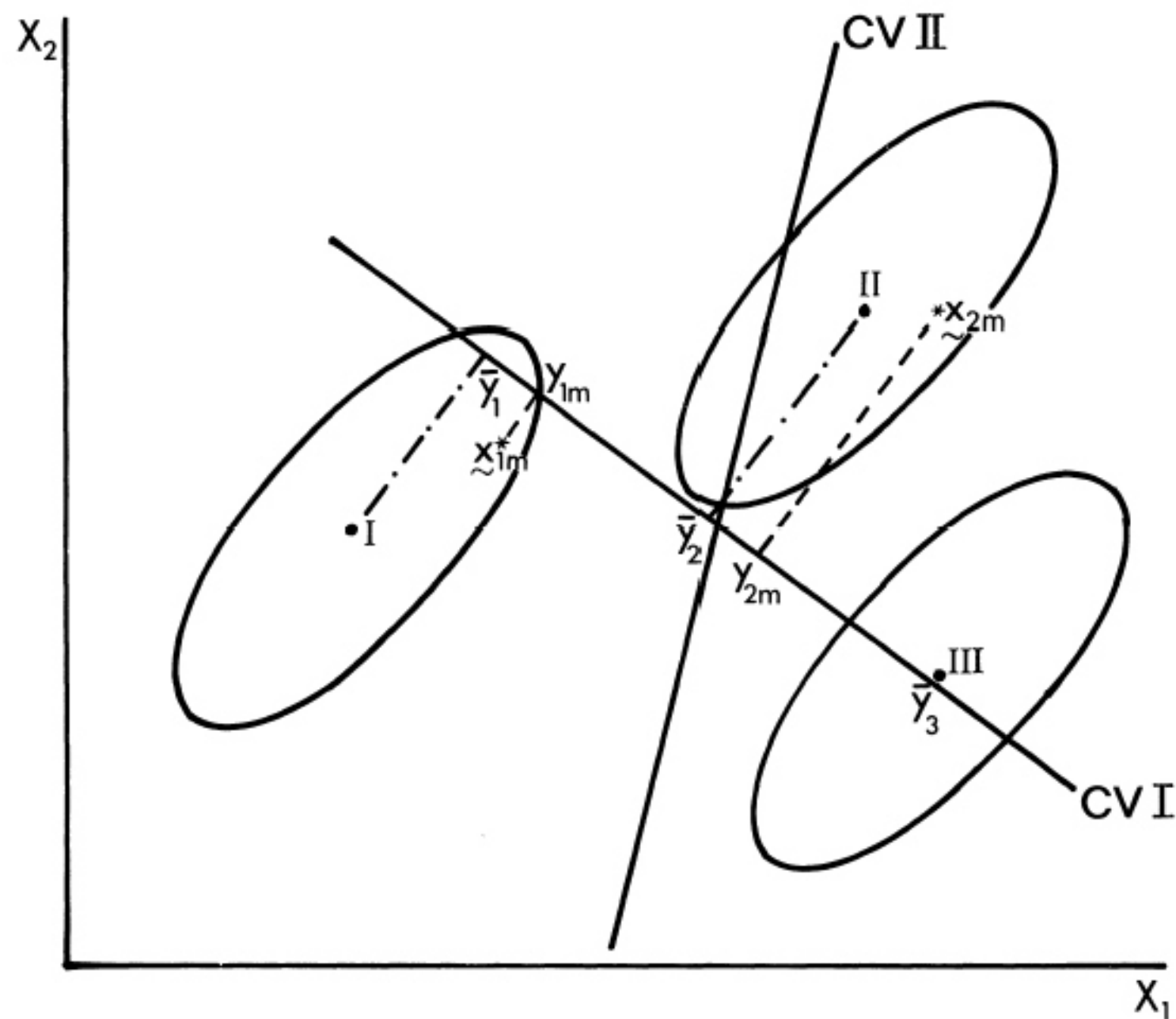


FIG. 2.—Representation of the canonical vectors for three groups and two variables. The group means (I, II and III) and 95% concentration ellipses are shown. The vectors CVI and CVII are the two canonical vectors. In the text, CVI = \mathbf{c} . The points y_{1m} and y_{2m} represent the canonical variate scores corresponding to the first canonical vector for the observations \mathbf{x}_{1m} and \mathbf{x}_{2m} .

CVA as a two-stage rotation I

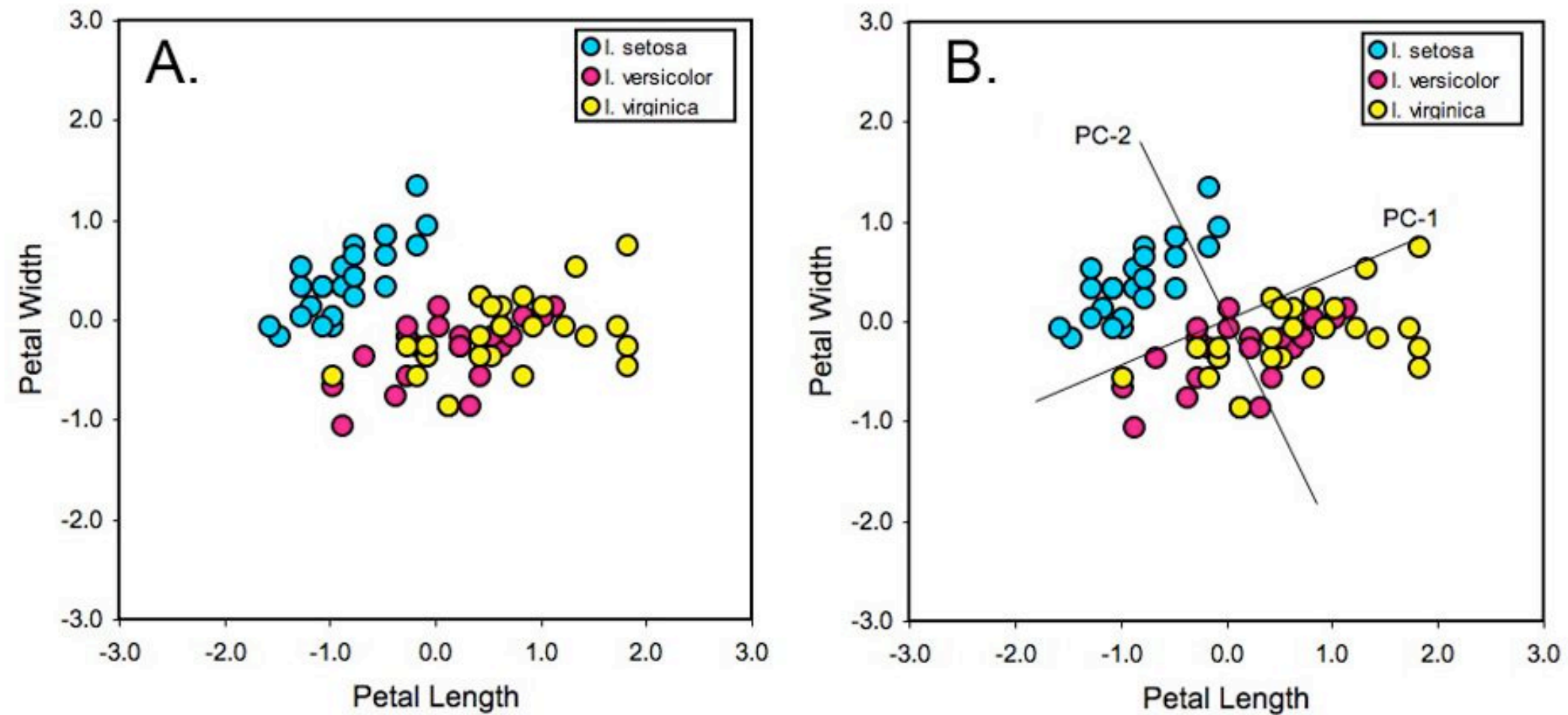


Figure 2. Stage 1 CVA implicit rotation. A. Scatterplot of first two *Iris* variables for example dataset. B. Orientation of the two pooled-sample principal components of the within-groups SSQCP matrix (W).

From MacLeod 2010, PalaeoMath newsletter

CVA as a two-stage rotation II

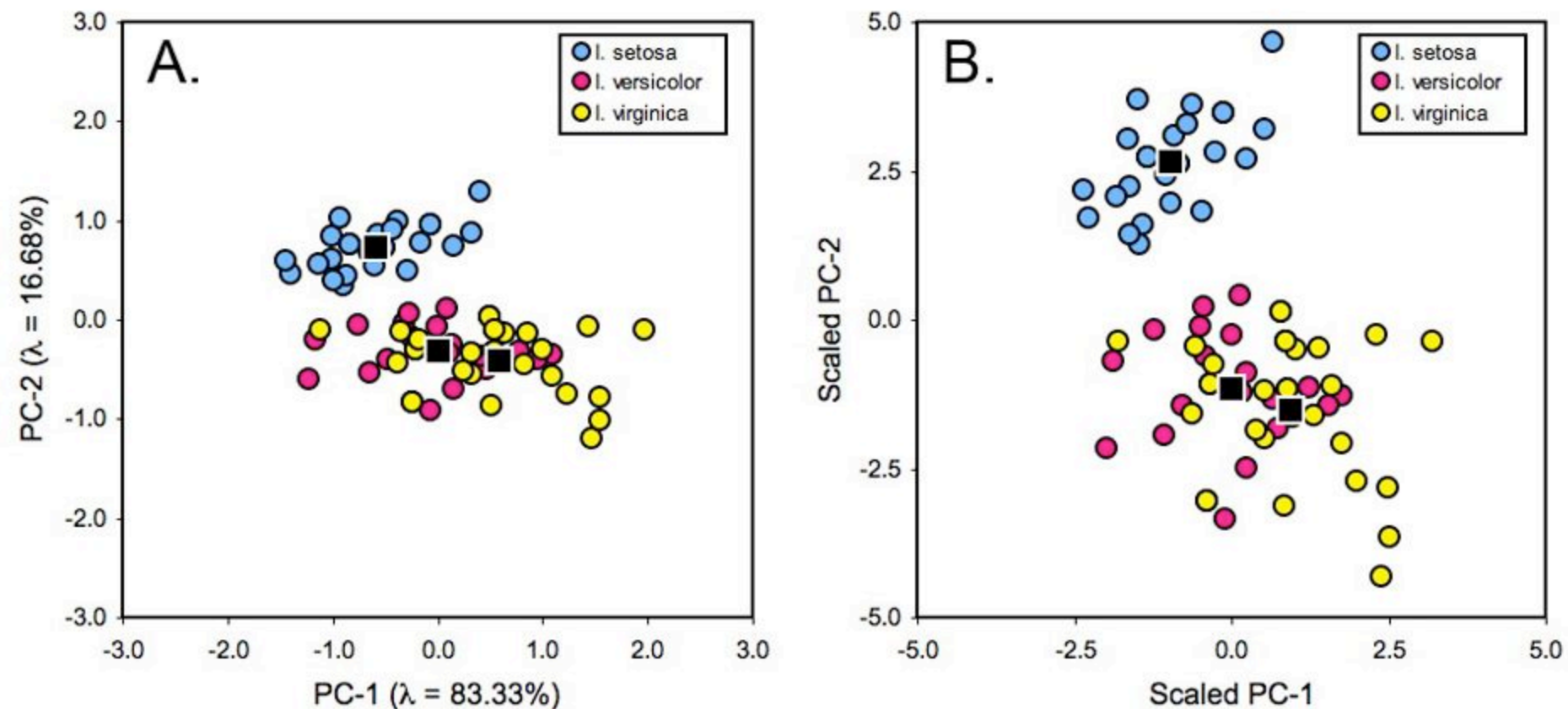


Figure 3. Intermediate scaling operation of a CVA. A. Scatterplot of *Iris* PC scores for the Stage 1 rotation (see Fig. 2). B. Result of scaling the two within-groups principal components by the square roots of their associated eigenvalues. Note difference in separation of the group centroids (black squares) after scaling.

From MacLeod 2010, PalaeoMath newsletter

CVA as a two-stage rotation III

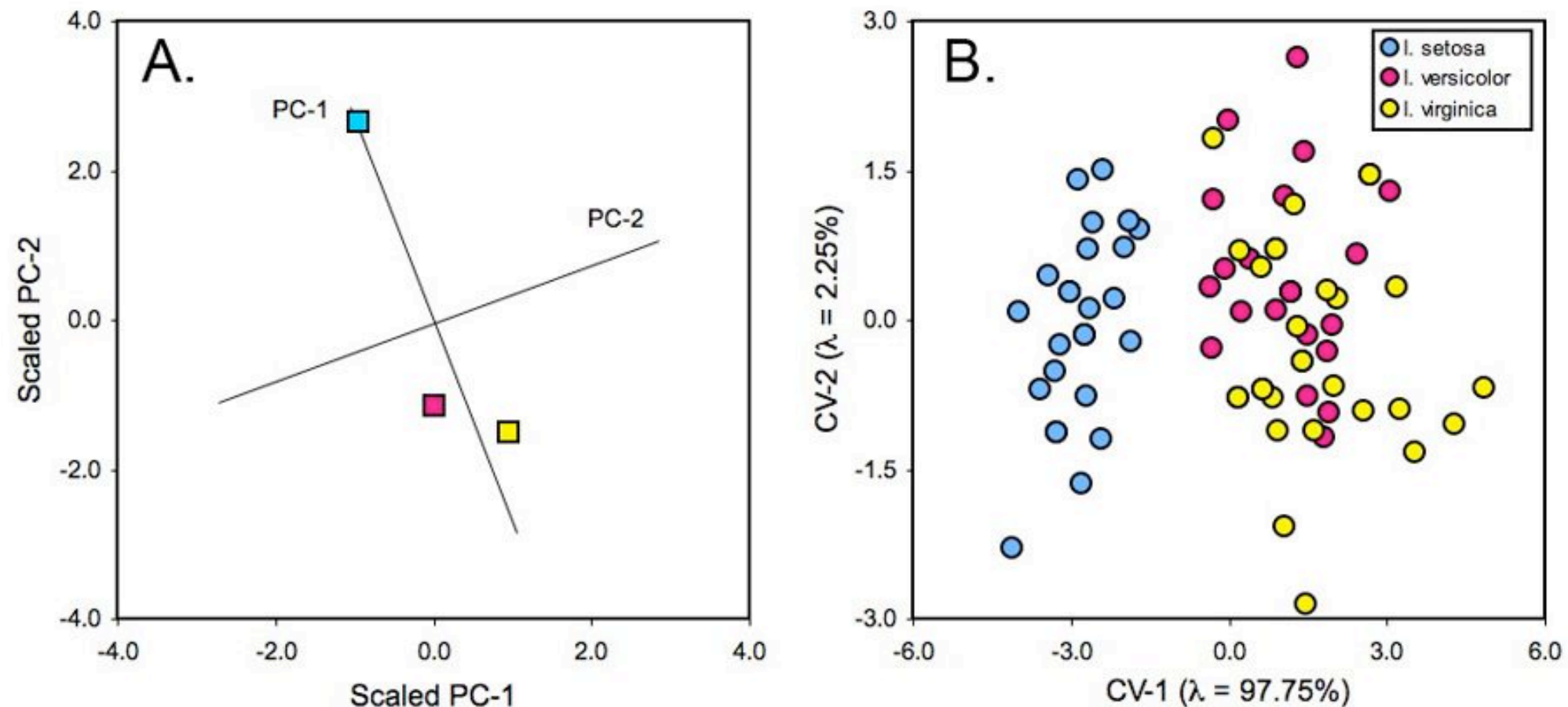


Figure 4. Stage 2 CVA implicit rotation. A. *Iris* group centroids plotted in the within-groups orthogonal-orthonormal space (see Fig. 3B) with between groups PC (= CVA) axes. B. Reduced *Iris* dataset plotted in the space defined by the CVA axes.

CVA as a two-stage rotation IV

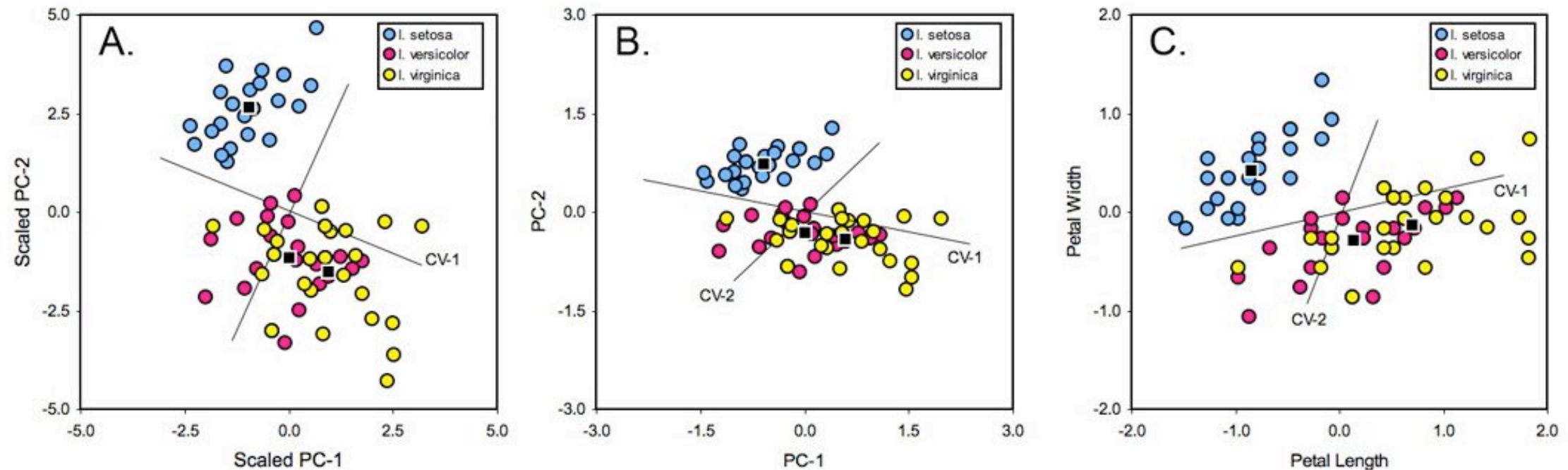


Figure 5. Back-calculation of final CVA axis orientation through the intermediate stages of the canonical rotations and scalings. A. Orientation of final CVA axes in the space of the scaled within-groups principal components (compare to Fig. 3A). B. Orientation of final CVA axes in the space of the raw within-groups principal components (compare to Fig. 3B). C. Orientation of final CVA axes in the space of the original variables (compare to Fig. 2).

From MacLeod 2010, PalaeoMath newsletter

What if there are more than two groups?

The multi-group equivalent of Fisher's LDF is called 'Canonical Variate Analysis' (CVA).

- straight forward extension of Fisher's solution
- Find \mathbf{a} that maximizes the ratio of between-group to within-group variance:

$$F = \frac{\mathbf{a}' \mathbf{B} \mathbf{a}}{\mathbf{a}' \mathbf{W} \mathbf{a}}$$

- \mathbf{W} is within-group matrix (as defined previously)
- \mathbf{B} is the between-group covariance matrix
 - $\mathbf{B}_w = \frac{1}{g-1} \sum_{i=1}^g n_i (\bar{\mathbf{x}}_i - \bar{\mathbf{x}})(\bar{\mathbf{x}}_i - \bar{\mathbf{x}})'$ where $\bar{\mathbf{x}}$ is the "grand-mean", $\bar{\mathbf{x}}_i$ is the mean in group i , and n_i is the sample size in group i (weighted version)
 - $\mathbf{B}_u = \frac{1}{g-1} \sum_{i=1}^g (\bar{\mathbf{x}}_i - \bar{\mathbf{x}})(\bar{\mathbf{x}}_i - \bar{\mathbf{x}})'$ (unweighted version)

CVA Solution

Maximizing F leads to the following:

$$(B - lW)a = 0$$

- l is an eigenvalue of $W^{-1}B$
- a is an eigenvector of $W^{-1}B$

There will be $s = \min(p, g - 1)$ non-zero eigenvalues.

Organize the eigenvectors, a_i , as columns of a $p \times s$ matrix A .

- The ***canonical variates*** are given by $Y = XA$
- The mean of the i -th group in the canonical variates space is given by $\bar{y}_i = \bar{x}_i A$, where \bar{x}_i is the mean row-vector for group i .

Similarities and Differences between CVA and PCA

PCA:

- Uncorrelated over the whole sample
- orthogonal transformation from the original variates, x , to the new variates y . PC axes at right angles to each other in the space of the original variables.

CVA:

- Canonical variates are uncorrelated both *within* and *between* groups
- Canonical variates have equal variance *within* groups, but in decreasing order *between* groups
- non-orthogonal transformation, CV axes *not* at right angle to each other in the original frame of reference.

Are any of the groups significantly different in the canonical variate space?

To test:

- $H_0 : \mu_1 = \mu_2 = \dots = \mu_3$
- H_1 : at least one μ_i differs from the rest

A couple of approaches:

- Compare the largest eigenvalue, l_1 , of $W^{-1}B$ to critical values in a F-table. H_0 is rejected for large values (> 1).
- Likelihood approach:
 - Wilks' lambda, $\Lambda = |W|/|B + W| = \prod_{i=1}^p (1 + l_i)^{-1}$
 - there is an approximation that has a χ^2 distribution.

Both boil down to a consideration of eigenvalues of $W^{-1}B$.

Which groups are different? Where does an unassigned observation belong?

Within groups the canonical variates are:

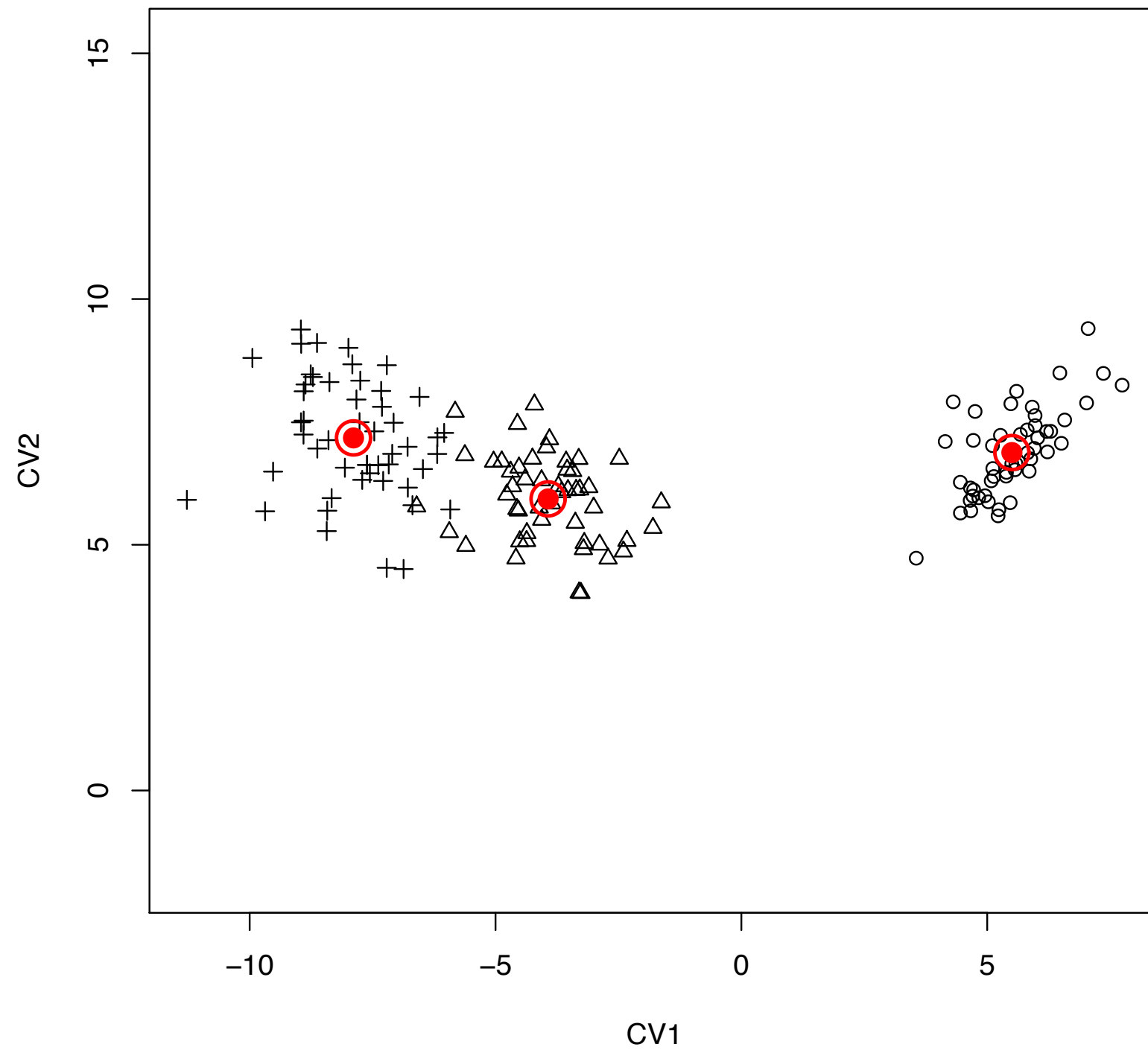
- uncorrelated
- have unit variance

If we assume multivariate normality of the data then we can exploit this to draw confidence intervals around the group means in the canonical variate space.

A $100(1-\alpha)$ percent confidence region for the true mean \mathbf{v}_i is given by:

- hypersphere centered at $\bar{\mathbf{y}}_i$
- with radius $(\chi^2_{\alpha,r}/n_i)^{1/2}$ where r is the number of canonical variate dimensions considered

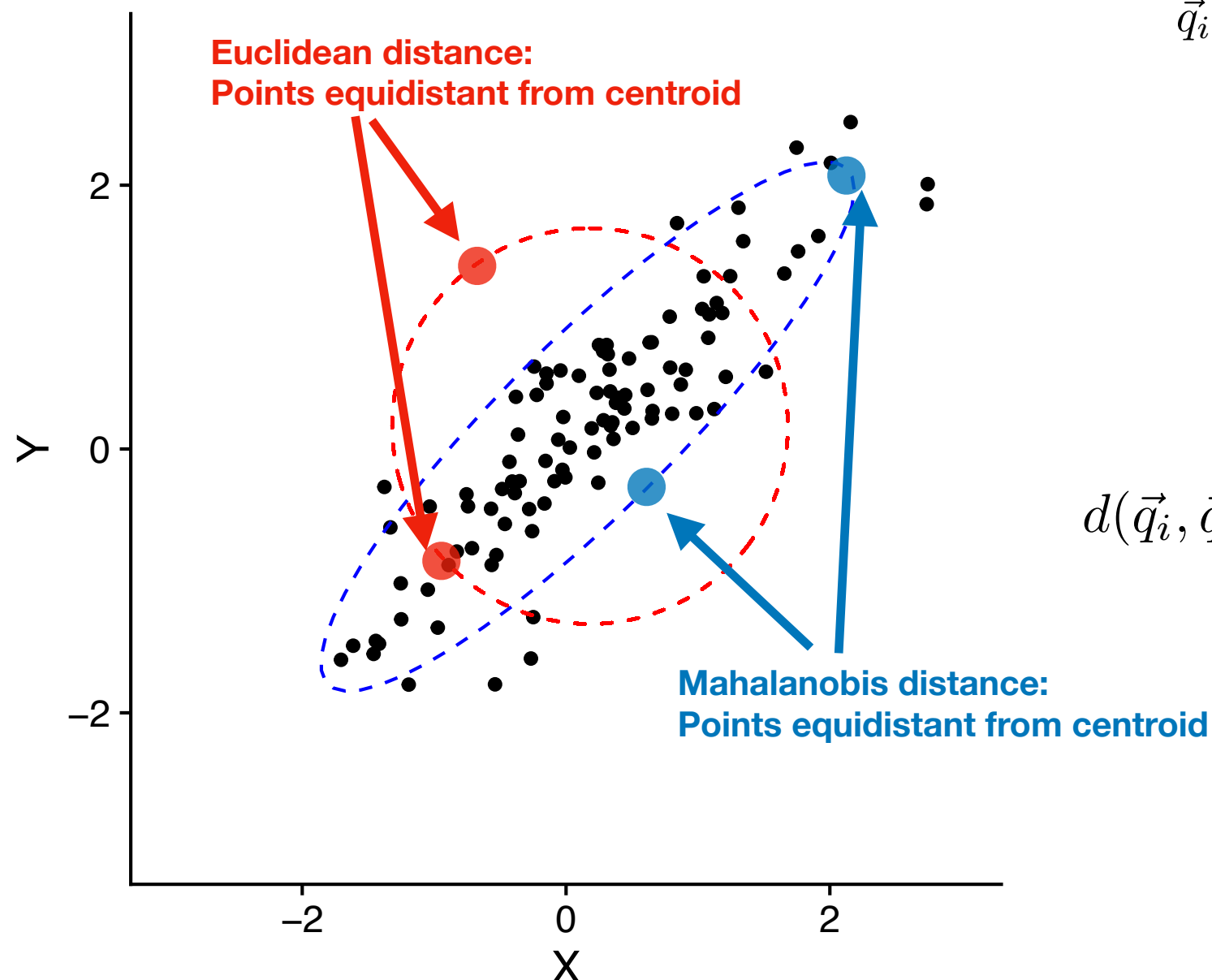
Illustration of group means and tolerance regions



Mahalanobis distance

Mahalanobis distance takes into account the covariance structure of the data.

- Deviations in the directions of greatest variance are "downweighted"



\vec{q}_i, \vec{q}_j : points i and j

\mathbf{S} : covariance matrix

$$\vec{q}_i = (\mathbf{X}_{i,1}, \mathbf{X}_{i,2}, \dots, \mathbf{X}_{i,p})$$

$$\vec{q}_j = (\mathbf{X}_{j,1}, \mathbf{X}_{j,2}, \dots, \mathbf{X}_{j,p})$$

$$d(\vec{q}_i, \vec{q}_j) = \sqrt{(\vec{q}_i - \vec{q}_j)^T \mathbf{S}^{-1} (\vec{q}_i - \vec{q}_j)}$$