

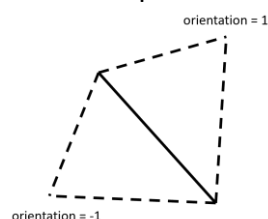
# Unfolding

test/test\_unfolding.py: tests used during development

src/Unfolding.py: an example script for using the functions in utils\_unfolding.py

src/utils\_unfolding.py:

- **create\_simplified\_tessellation(label, num\_vertices=30)** creates a simplified tessellation of the masked region in label using *pymeshlab* with a target number of final vertices = num\_vertices
  - Inputs:
    - label: 3D numpy array label map (binary values)
    - num\_vertices: number of vertices (default = 30)
  - Outputs:
    - verts: vertices of the tessellation
    - faces: faces of the tessellation
- **unfold\_tessellation(verts, faces, base\_triangle, draw)** unfolds the tessellation created by *create\_simplified\_tessellation* into 2D
  - Inputs:
    - verts, faces: 3D vertex coordinates and triangle faces from *create\_simplified\_tessellation*
    - base\_triangle: index of the first triangle to draw (this will be the middle of the unfolded image)
    - draw: if ==1, this function will also plot the triangles of the unfolded tessellation
  - Outputs:
    - verts\_2d: 2D vertex coordinates
    - faces\_2d: 2D faces
    - dict\_2d\_3d: dictionary that relates the index of a vertex in 2D to a vertex in 3D (multiple 2D vertices can point to the same 3D vertex due to the nature of the unfolding)
  - Additional helper functions called by *unfold\_tessellation*:
    - **draw\_2d\_triangle(vertices)** draws a triangle defined by *vertices*
    - **find\_2d\_coordinates(vertices\_3D, vertices\_2D, orientation)** finds the 2D coordinates of the third vertex of a triangle of 3D coordinates *vertices\_3D* when the 2D coordinates of the first 2 vertices are in *vertices\_2D*. *orientation* determines which “side” of the 2 given vertices to put the third one on:



- **unfolded\_layers(verts, faces, verts\_2d, faces\_2d, dict\_2d\_3d, im, n\_layers)** exports the layers parallel with the surface of the tessellation
  - Inputs:
    - **verts, faces:** 3D vertice coordinates and triangle faces from *create\_simplified\_tessellation*
    - **verts\_2d, faces\_2d, dict\_2d\_3d:** 2D vertice coordinates and triangle faces, and the correspondence dictionary between 3D and 2D vertices from *unfold\_tessellation*
    - **im:** 3D numpy array containing the grayscale image
    - **n\_layers:** number of layers to be exported on both sides of the tessellation
  - Outputs:
    - **layers:** 3D numpy array where each slice contains a layer parallel to the surface of the tessellation. It contains  $2 \times \text{num\_layers} + 1$  layers in total and the middle slice contains the values directly on the surface of the tessellation
  - Additional helper functions called by *unfolded\_layers*:
    - **get\_perp\_layers(coord\_3d, coord\_2d, im, n\_layers)** extracts all layers from *im* for a single triangle in the tessellation represented by *coord\_3d*, and *coord\_2d* coordinates in 3D and 2D respectively
    - **triangle\_area(vertices)** calculates the area of a triangle with coordinates in *vertices*
    - **rotate\_im\_and\_mask(im, mask, angle, axes)** rotates both *im* and *mask* by *angle* about axes *axes*