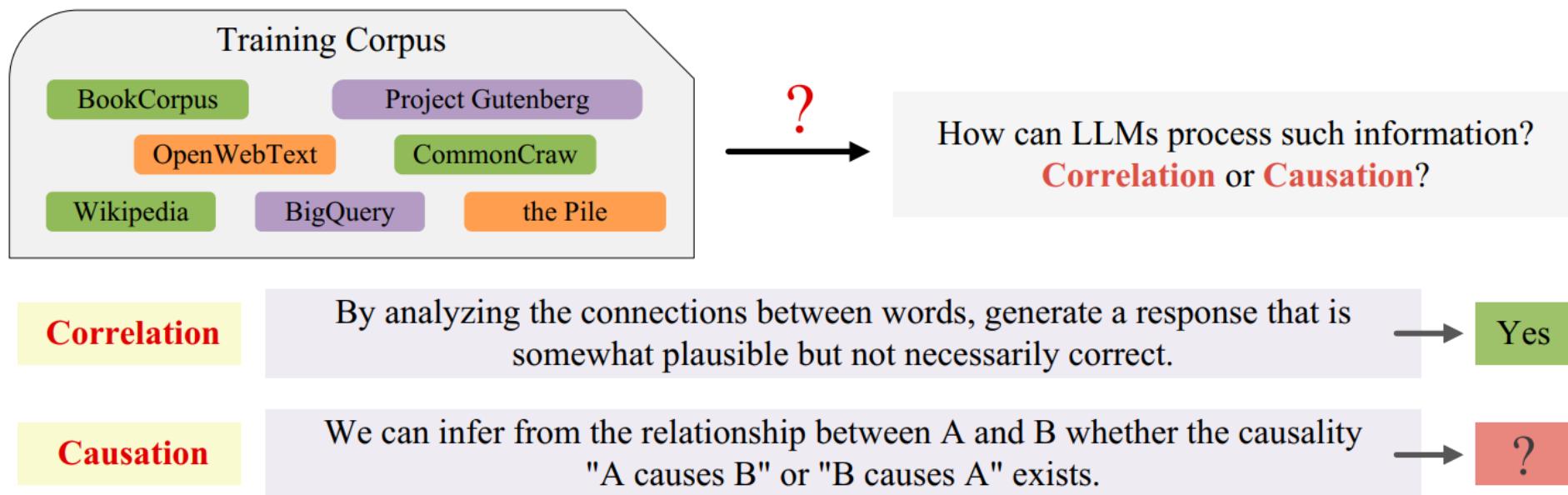


Outlier Robust Causal Discovery

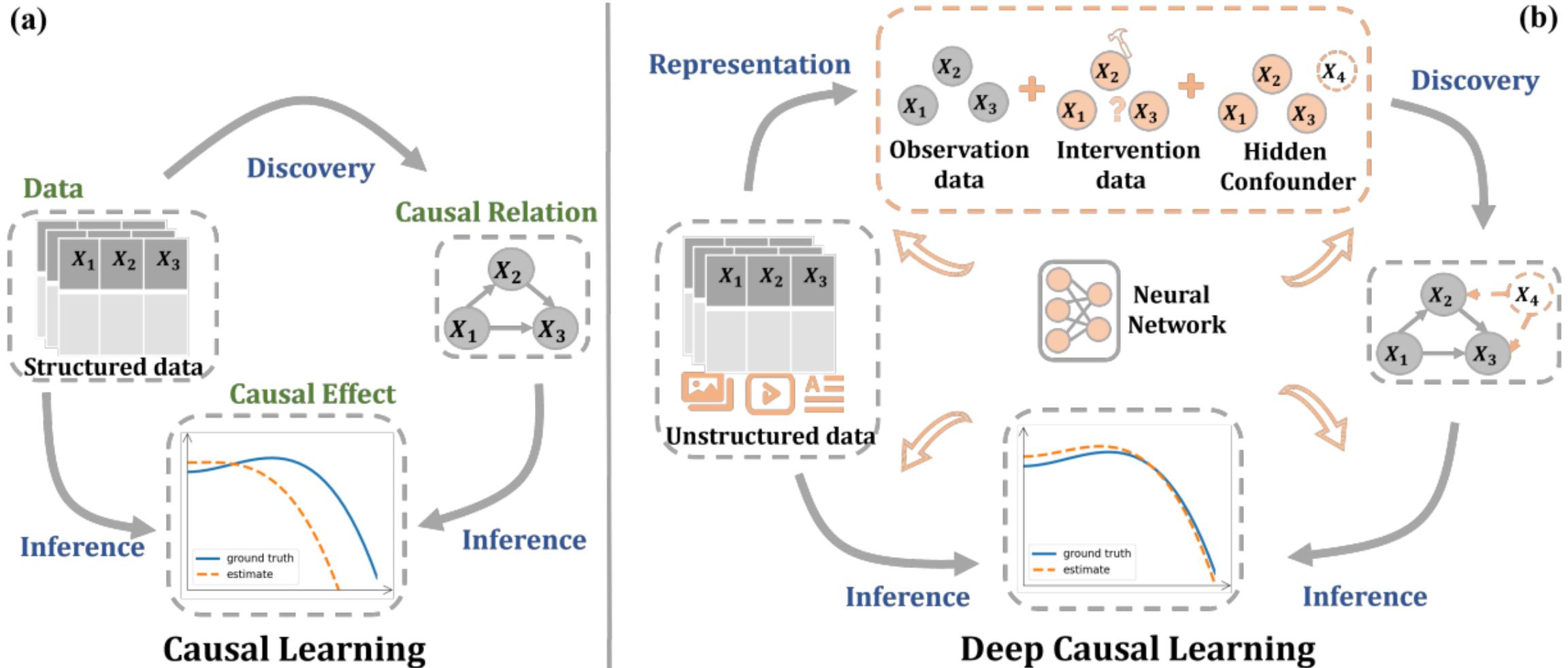
서울대학교 DSML Lab 송의종

Recent Works of Causal Learning in Age of AI

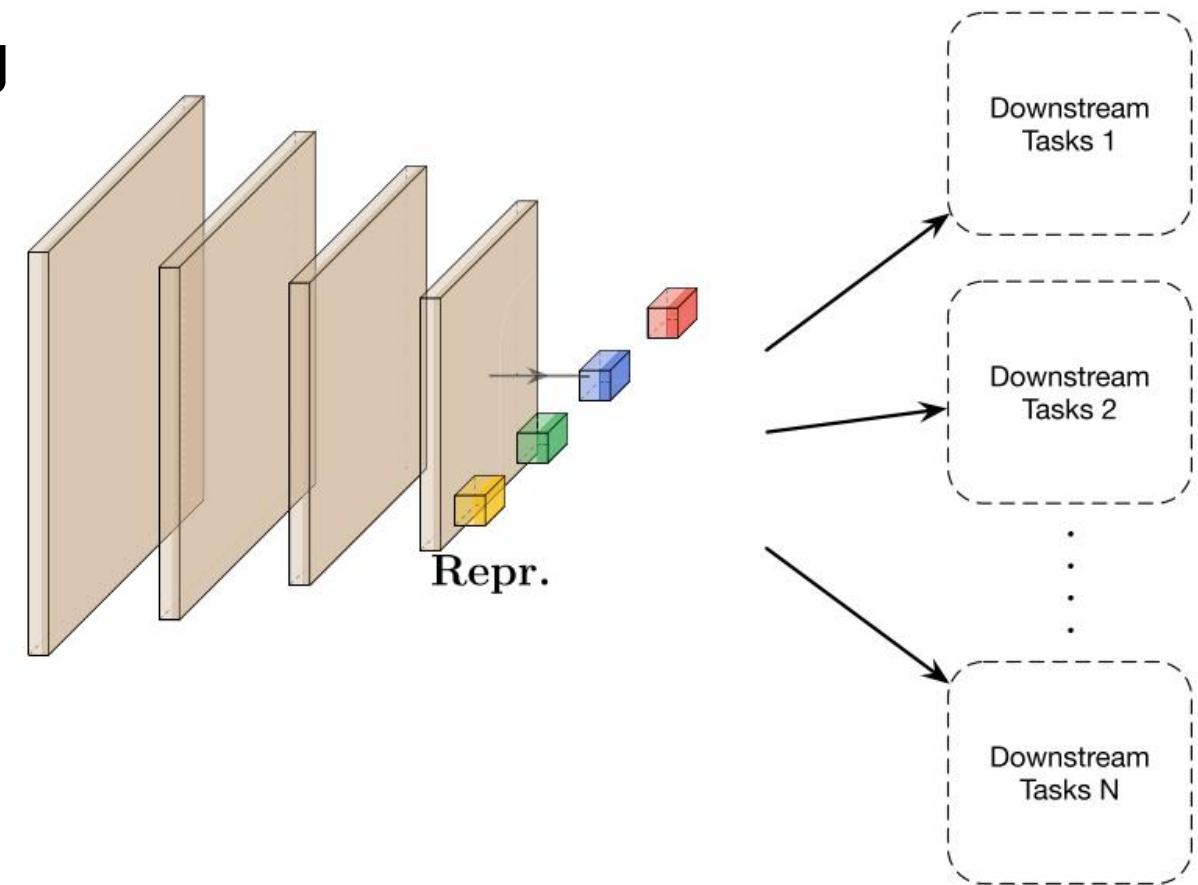
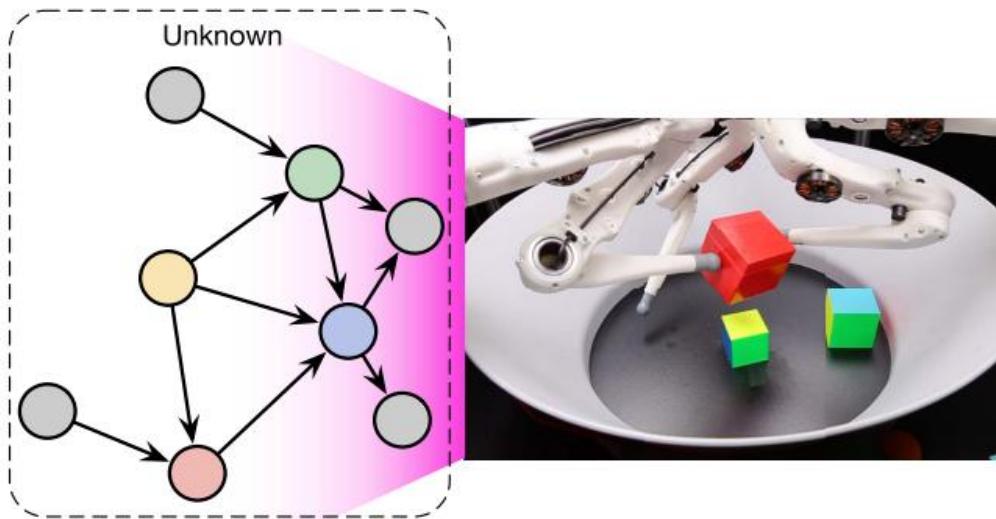
LLM and Causation



Deep Causal Learning

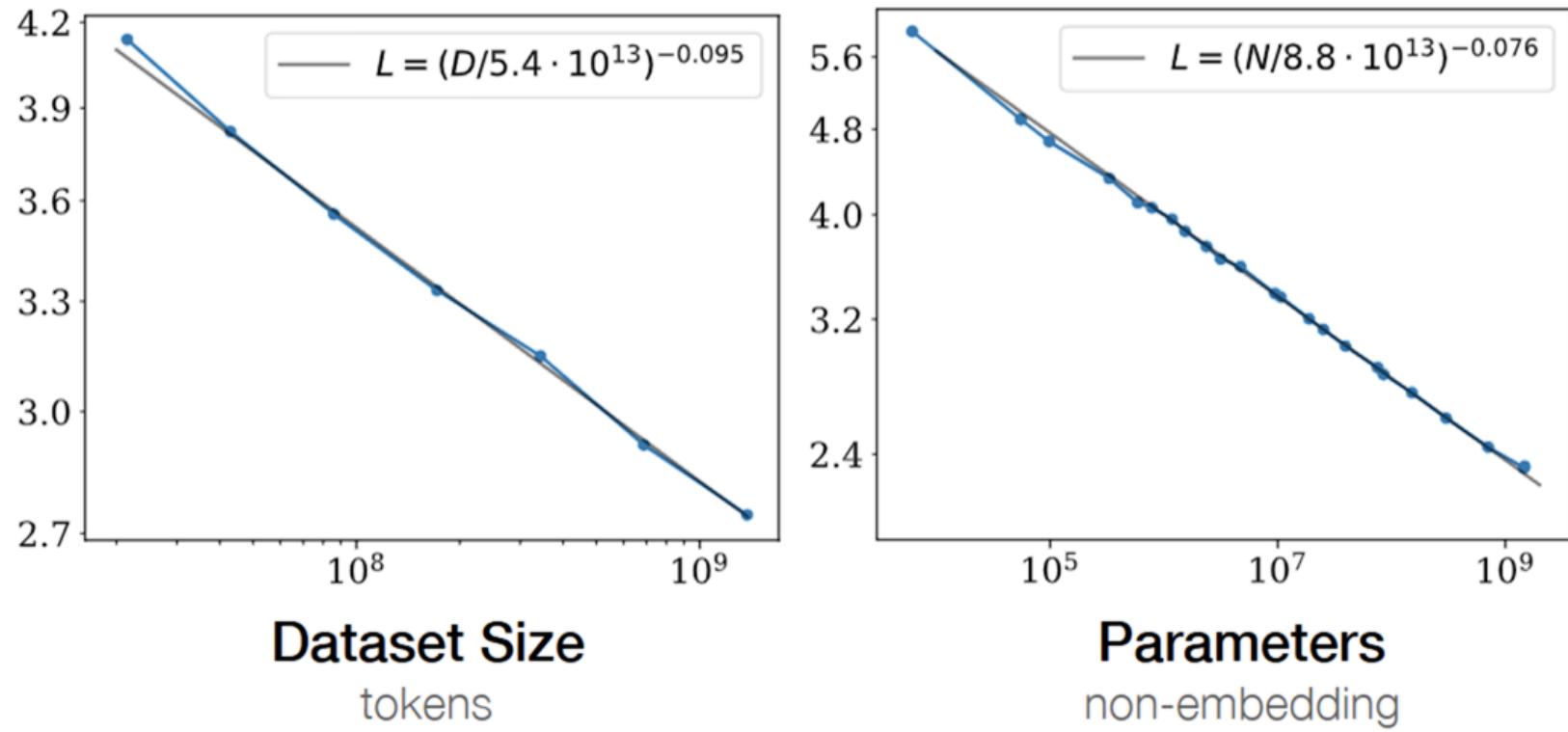


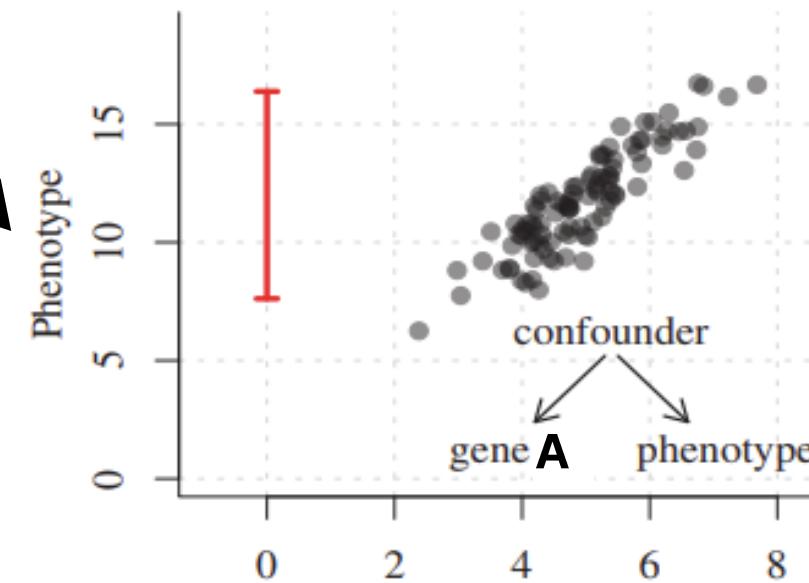
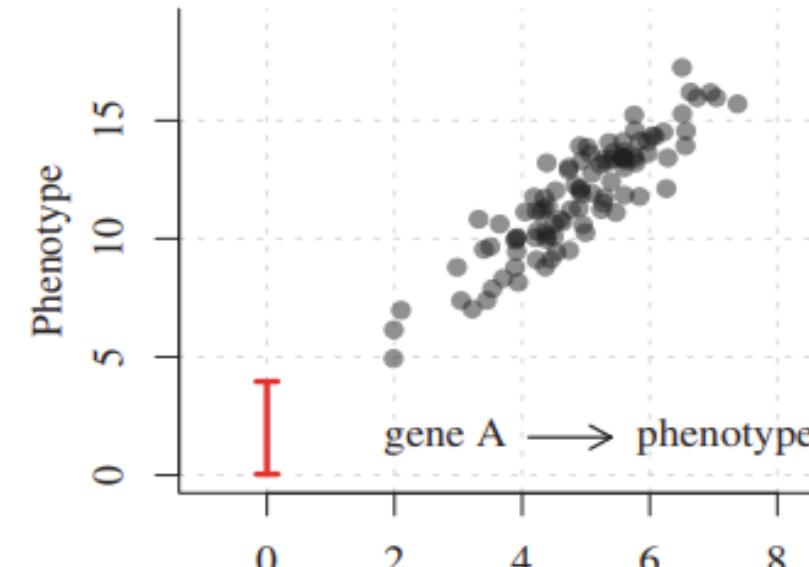
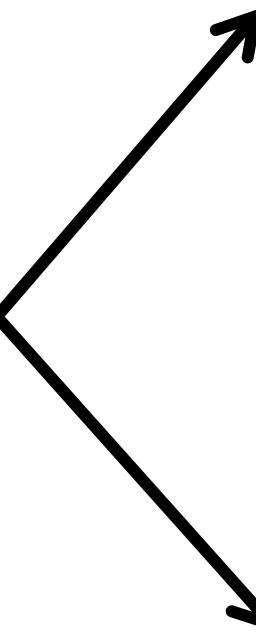
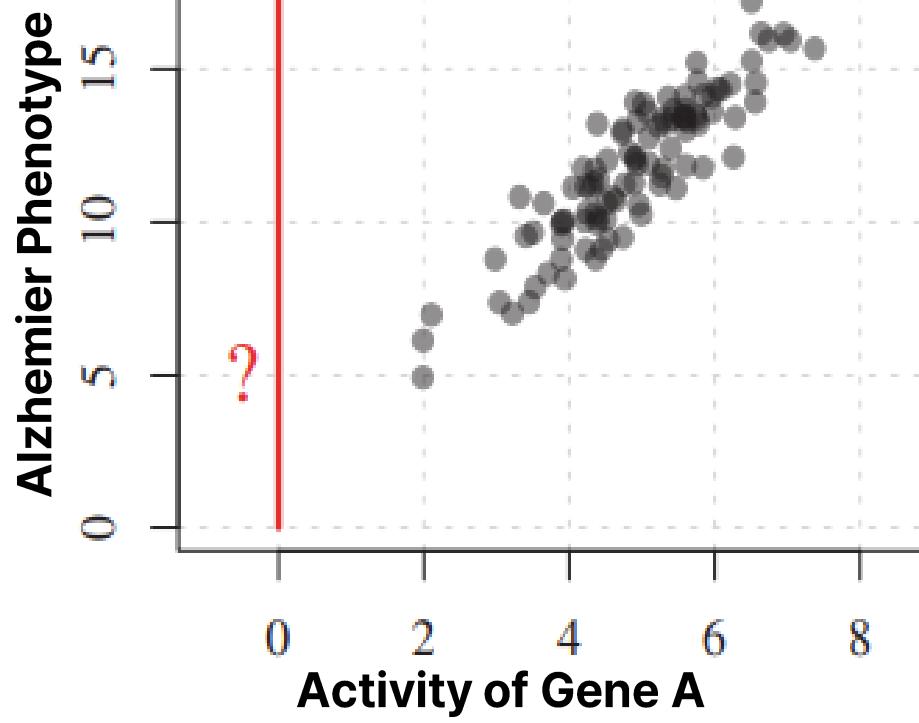
Causal Representation Learning



Motivation of Causal Learning







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2. Outlier Robust Causal Discovery

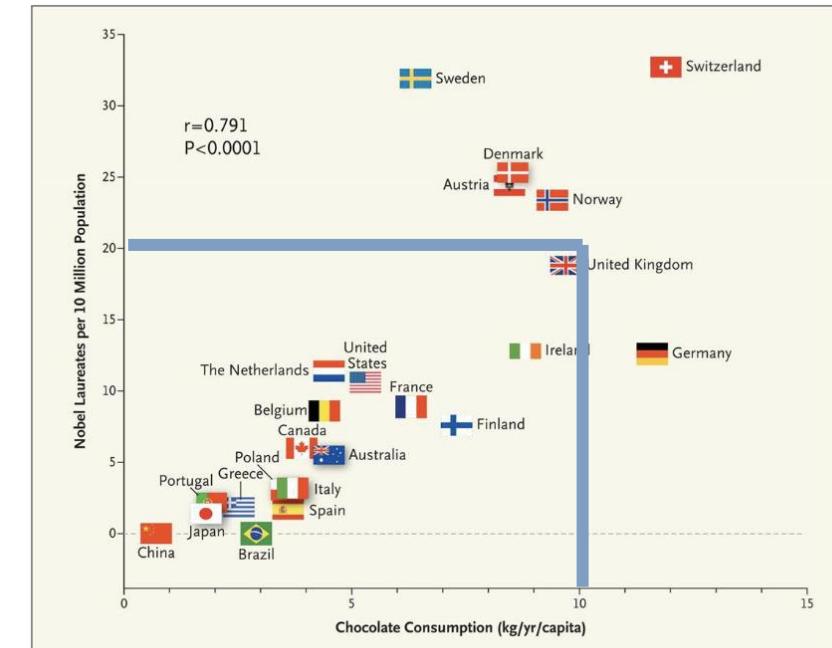
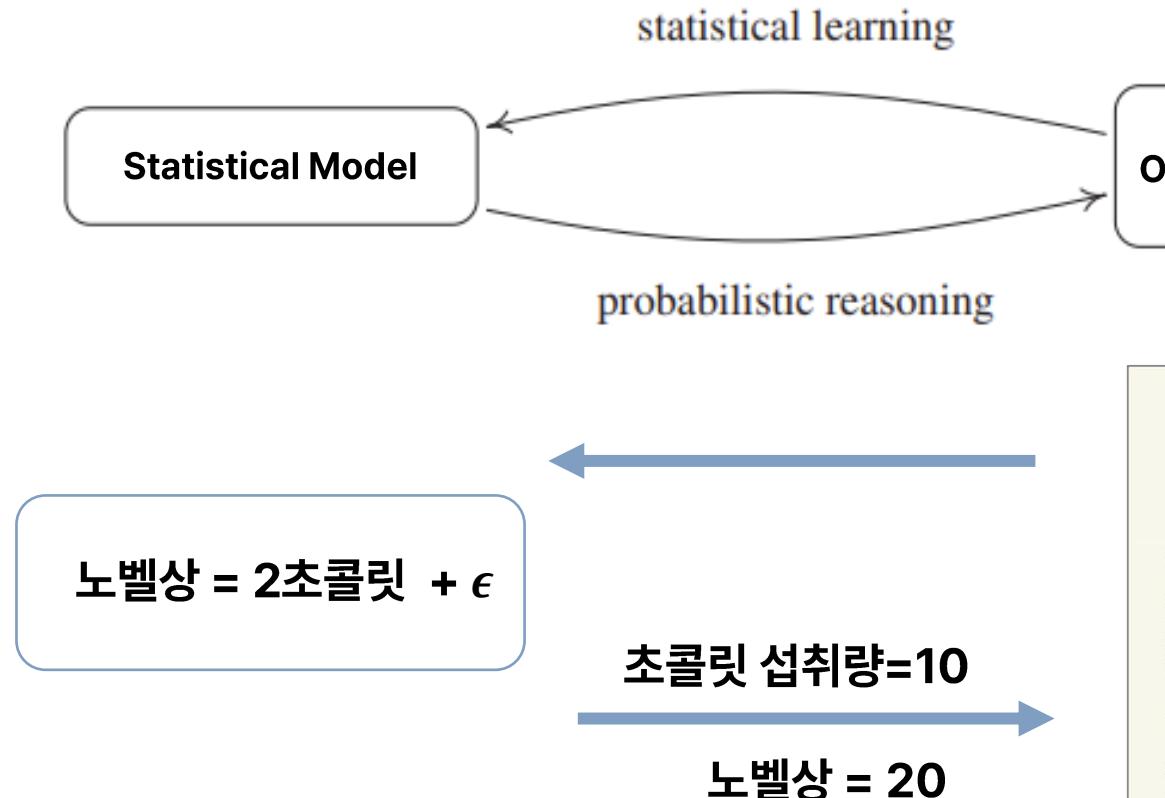
Outlier Model(CCSEM)

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1. Introduction to Causal Inference

1.1. Causal Reasoning & Learning

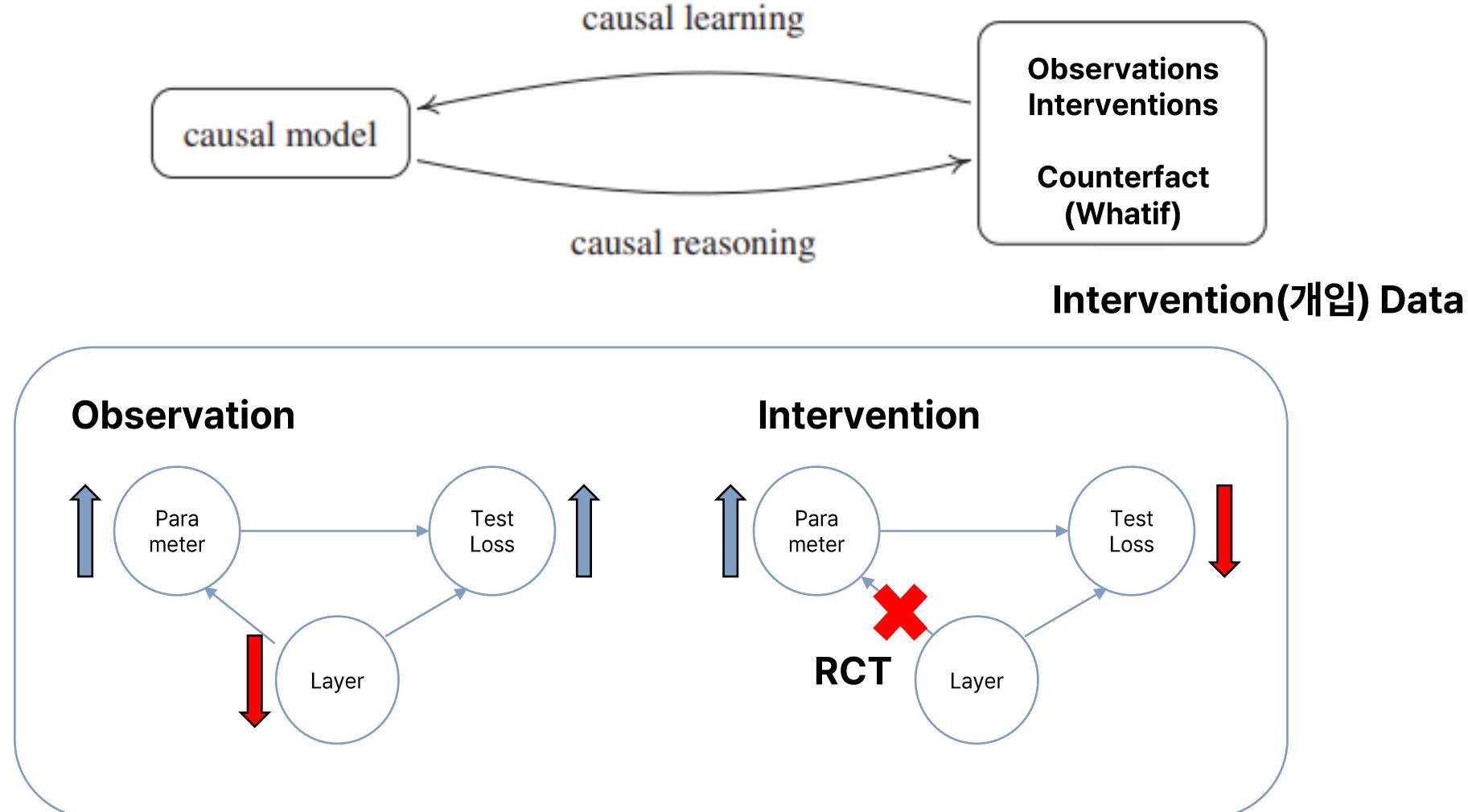
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F. H. Messerli: Chocolate Consumption, Cognitive Function, and Nobel Laureates, N Engl J Med 2012

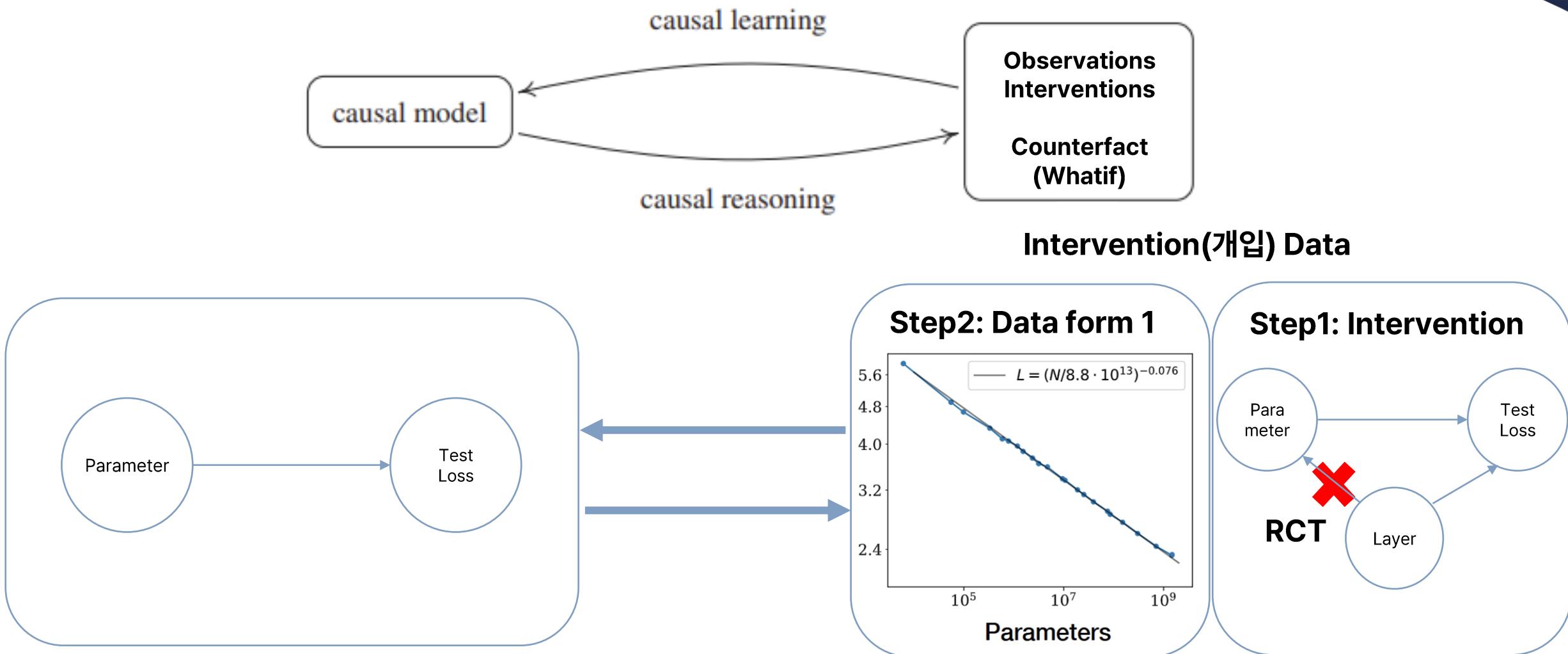
1.1. Causal Reasoning & Learning

[Causal Learning & Reasoning]



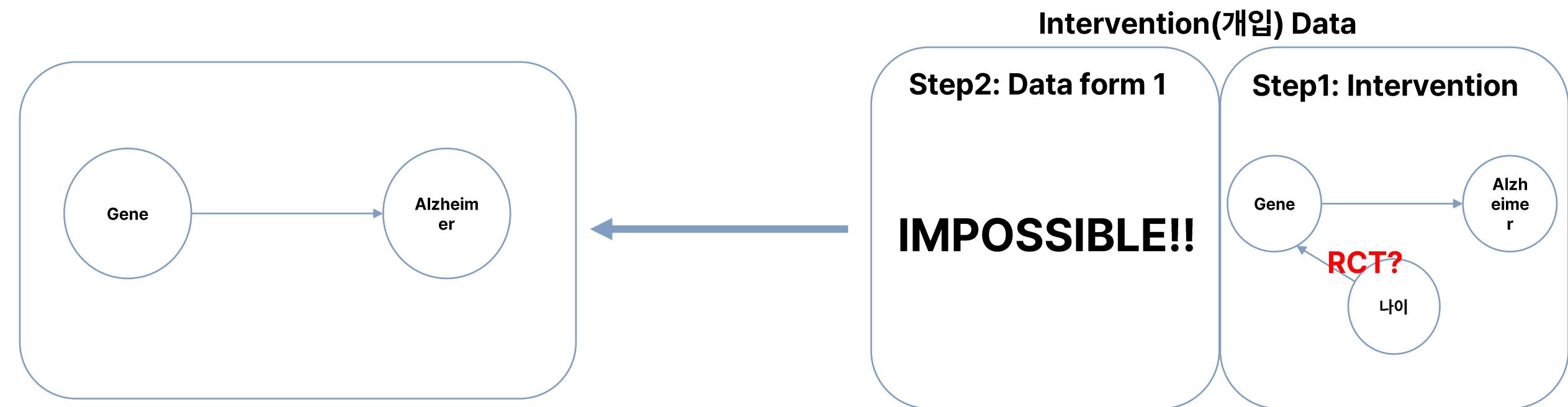
1.1. Causal Reasoning & Learning

[Causal Learning & Reasoning]



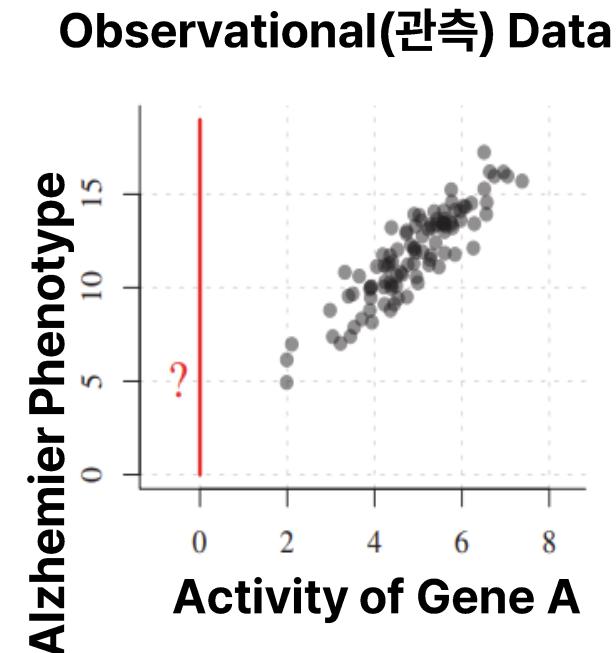
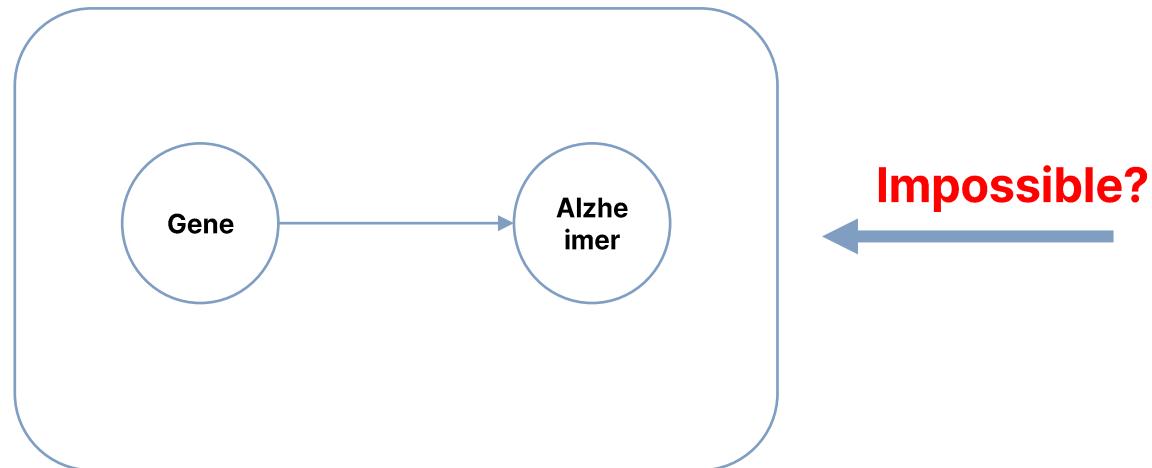
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[Causal Learning & Reasoning]



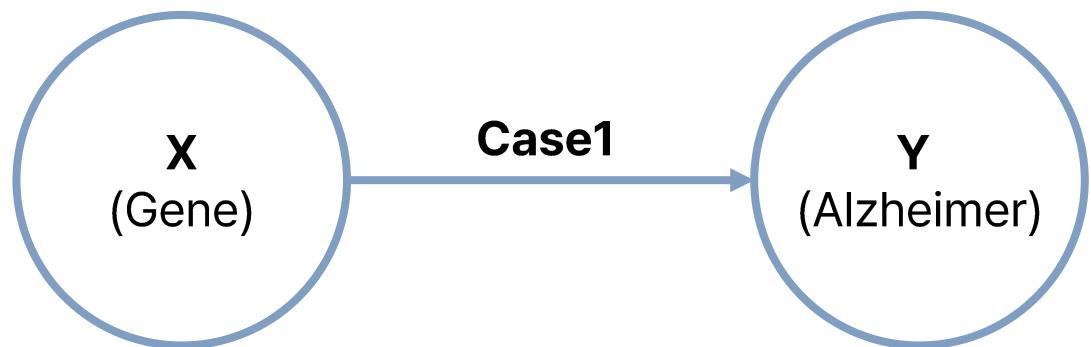
1.1. Causal Reasoning & Learning

[Causal Learning & Reasoning]



1.1. Causal Reasoning & Learning

[Causal Learning from Observation]



- $X = \varepsilon_X, Y = aX + \varepsilon_Y, \varepsilon_X \perp \varepsilon_Y,$
 - $\text{Var}(\varepsilon_X) = \text{Var}(\varepsilon_Y) = \sigma^2$
- ↓
- $\text{Var}(X) = \sigma^2 \leq \text{Var}(Y) = \sigma^2(1 + a^2)$

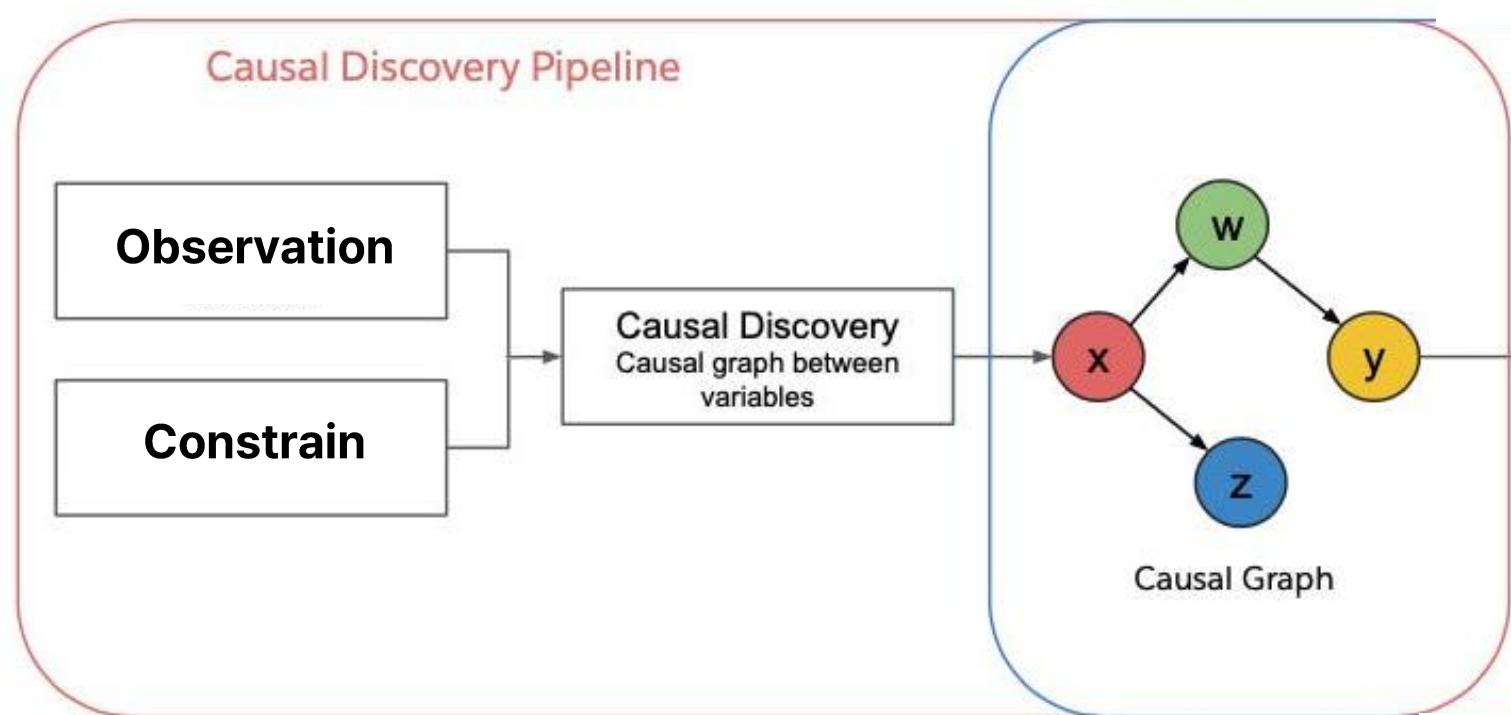
- $X = bY + \varepsilon_X, Y = \varepsilon_Y, \varepsilon_X \perp \varepsilon_Y,$
 - $\text{Var}(\varepsilon_X) = \text{Var}(\varepsilon_Y) = \sigma^2$
- ↓
- $\text{Var}(Y) = \sigma^2 \leq \text{Var}(X) = \sigma^2(1 + b^2)$

Now We can Identify Cause and Effect!!

- $(\text{Var}(X) < \text{Var}(Y) \Leftrightarrow X \rightarrow Y) \wedge (\text{Var}(Y) < \text{Var}(X) \Leftrightarrow Y \rightarrow X)$

1.1. Causal Reasoning & Learning

[Causal Discovery and Inference]



2. Outlier Robust Causal Discovery



2.1 . The Principles of Causal Reasoning

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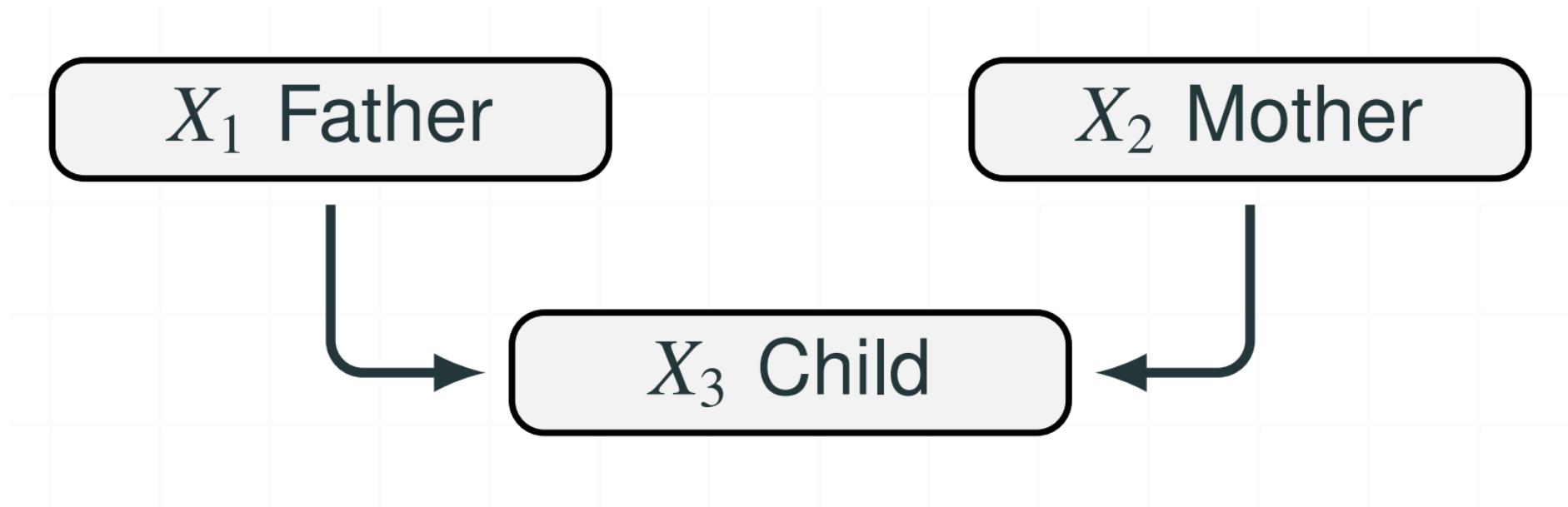
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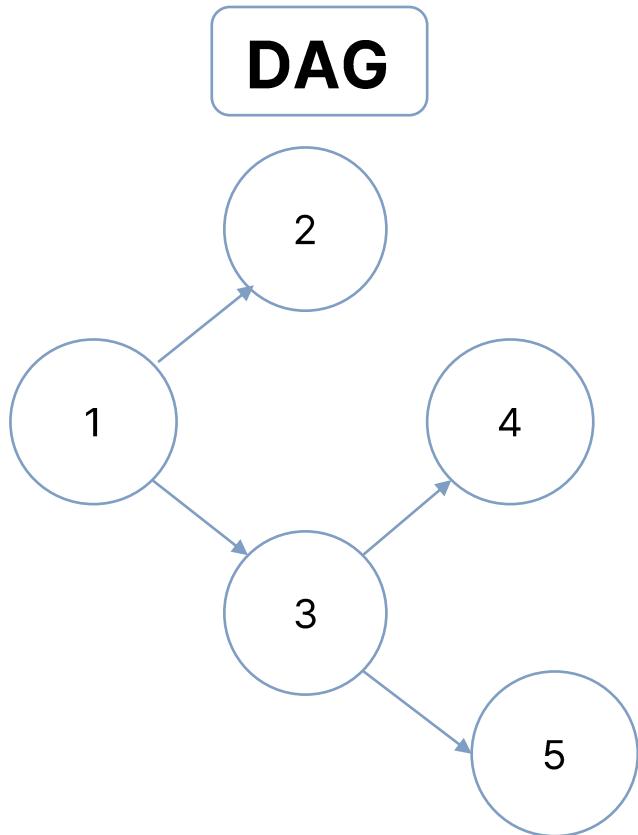
2.0 . Preliminaries

[Definitions]



2.0 . Preliminaries

[Definitions]



Graph Structure

- Parent (Pa): $1 \rightarrow \{2, 3\}$, $Pa(3) = \{1\}$
- Child (Ch): $Ch(3) = \{4, 5\}$
- Ancestor (An): $An(4) = \{1, 3\}$
- Descendant (De): $De(1) = \{2, 3, 4, 5\}$

Orderings

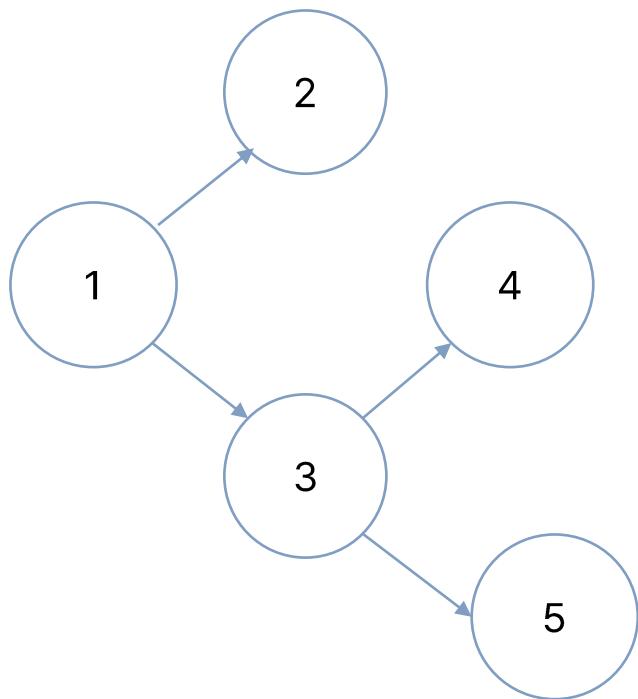
- $\pi = (1, 2, 3, 4, 5)$ or $(1, 3, 2, 5, 4)$

Maximum Indegree

- $d_{in} = 1$

2.0 . Preliminaries

[Definitions]



Graph Structure

- Parent (Pa): $1 \rightarrow \{2, 3\}$, $Pa(3) = \{1\}$
- Child (Ch): $Ch(3) = \{4, 5\}$
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Orderings

- $\pi = (1, 2, 3, 4, 5)$ or $(1, 3, 2, 5, 4)$

Maximum Indegree

- $d_{in} = 1$

2.0 . Preliminaries

[Causal Discovery]

Order-based & Two-Stage (Order → Parent)

Definition. First infer a ordering, then select parent set.

Key characteristics. If the order is correct, search is fast.

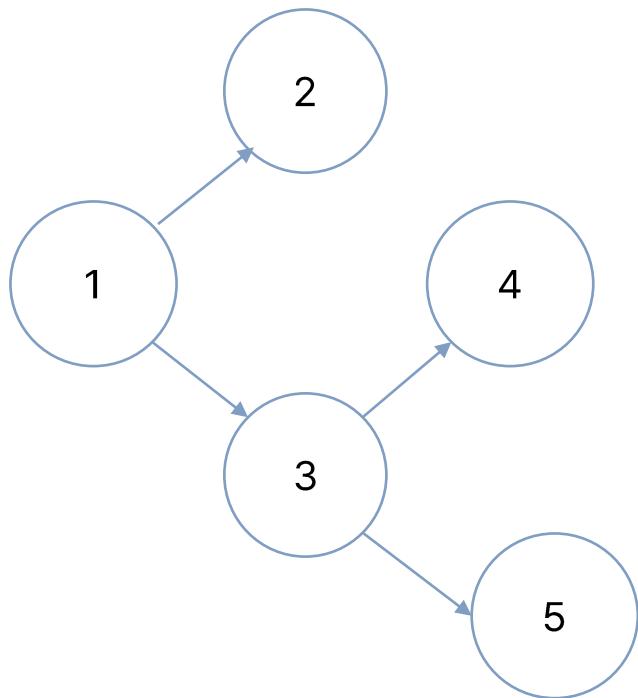
Representative methods (mixed classic+recent).

- *K2* (G. F. Cooper & E. Herskovits, 1992)
- *Ordering-Based Search* (M. Teyssier & D. Koller, 2005)
- *BOSS — Best Order Score Search* (B. Andrews, J. Ramsey, R. Sanchez-Romero, J. Camchong, & E. Kummerfeld, 2023)



2.0 . Preliminaries

[Backward Selection]



Backward Selection: Order then Parents

- Order fixed: $(1, 2, 3, 4, 5)$

Parent selection (check & pick)

- 5: $\{1, 2, 3, 4\}$ Check $\Rightarrow 5 \leftarrow 3$
- 4: $\{1, 2, 3\}$ Check $\Rightarrow 4 \leftarrow 3$
- 3: $\{1, 2\}$ Check $\Rightarrow 3 \leftarrow 1$
- 2: $\{1\}$ Check $\Rightarrow 2 \leftarrow 1$

2.0 . Preliminaries

[Causal Learning]

Differentiable DAG Learning

Definition. learning as continuous optimization with a smooth acyclicity constraint.

Key characteristics. Works well with deep learnin models.

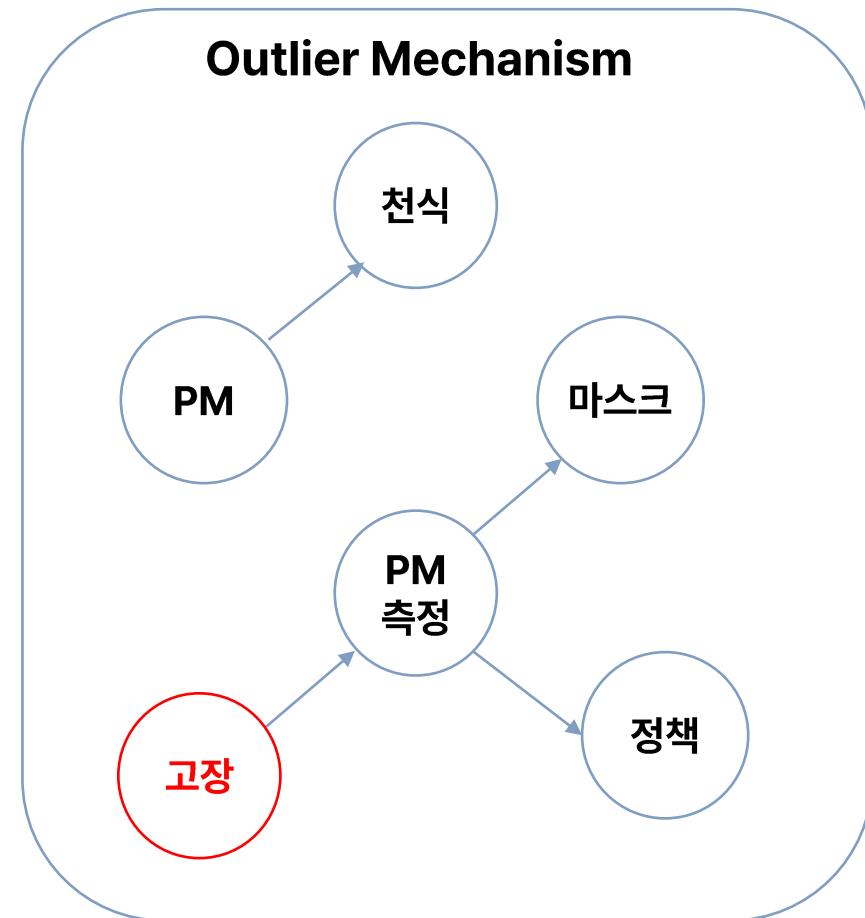
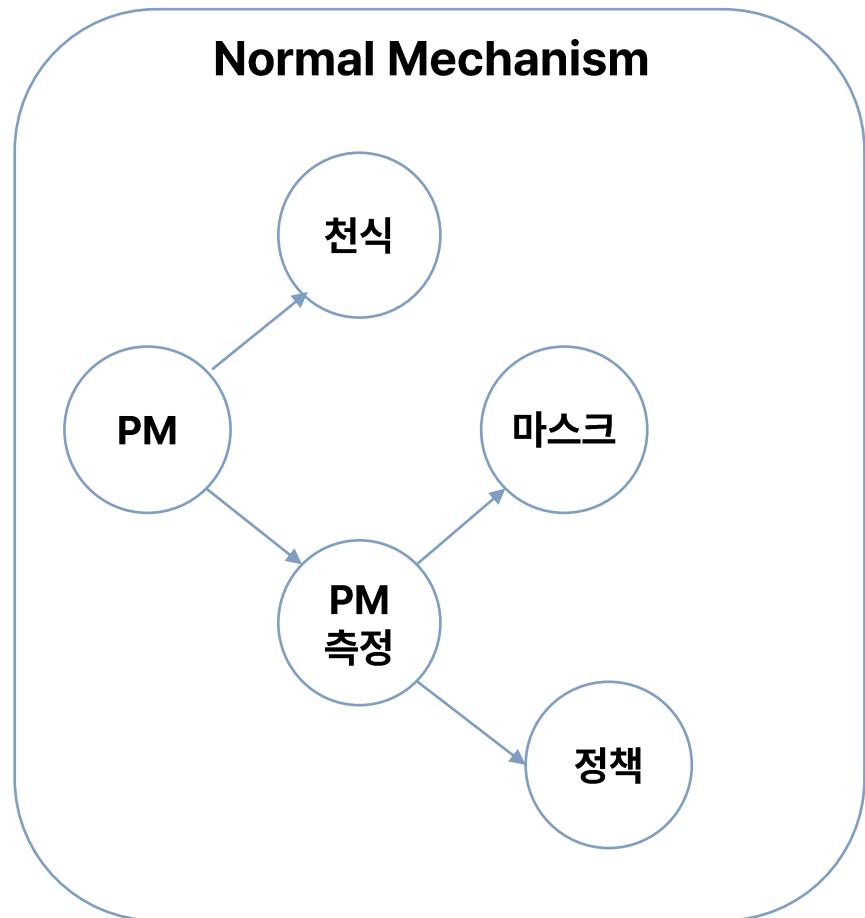
Representative methods (mixed classic+recent).

- *NOTEARS* (X. Zheng, B. Aragam, P. K. Ravikumar, & E. P. Xing, 2018)
- *GOLEM* (I. Ng, A. E. Ghassami, & K. Zhang, 2020)
- *SDCD* — Stable Differentiable Causal Discovery (Achille Nazaret, Justin Hong, Elham Azizi, David M. Blei, 2024)

Discrete $\min_{W \in \mathbb{R}^{d \times d}} F(W)$ subject to $G(W) \in \text{DAGs}$	\iff Continuous!! $\min_{W \in \mathbb{R}^{d \times d}} F(W)$ subject to $h(W) = 0,$
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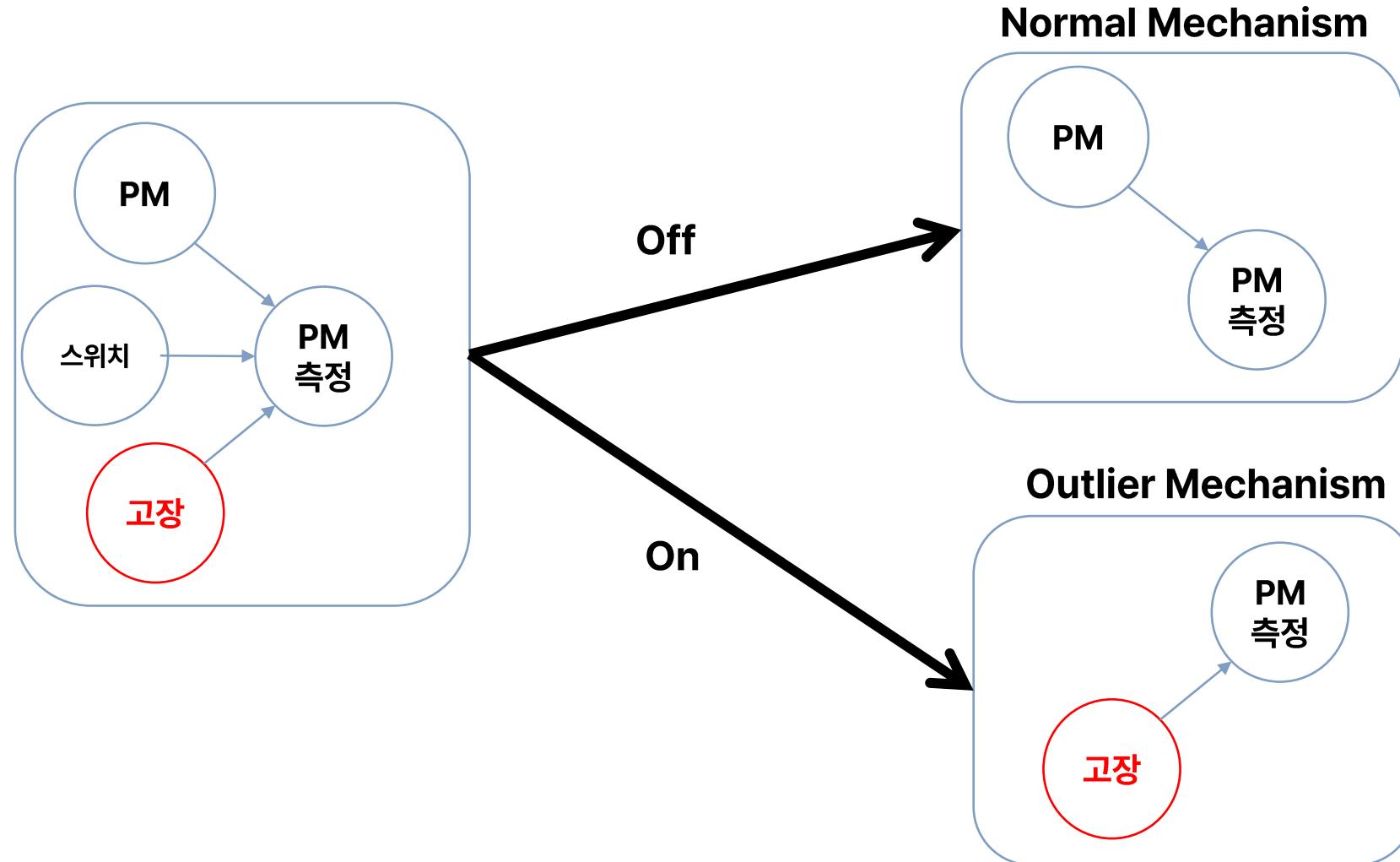
2.0 . Preliminaries

[Outlier]



2.0 . Preliminaries

[Outlier]



2.1. Outlier Model

[Cellwise Contaminated SEM]

CCSEM

Structural assignments (for $j = 1, \dots, p$):

$$X_j = O_j \zeta_j + (1 - O_j) \left(\sum_{k \in \text{Pa}_G^X(j)} \beta_{k,j} X_k + \varepsilon_j \right).$$

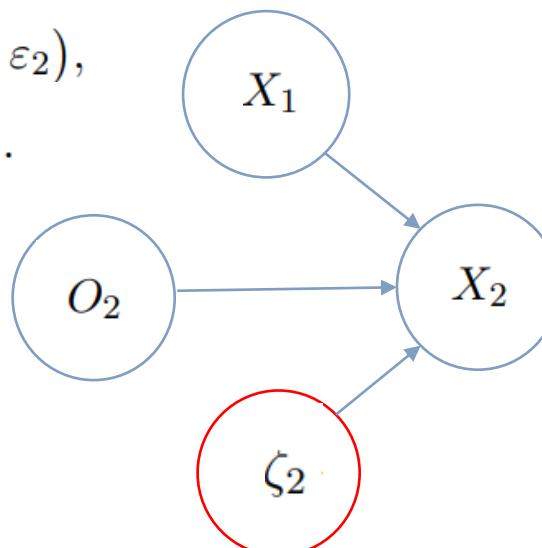
$$O_j = \mathbf{1}\{U_j \leq q_j(O_{\text{Pa}_G^O(j)})\}.$$

$$\zeta_j = g_j(\text{Pa}_G(\zeta_j)) + \xi_j.$$

Errors: $\varepsilon_j \sim N(0, \sigma_j^2)$ and are independent across j .

$$X_2 = O_2 \zeta_2 + (1 - O_2)(\beta X_1 + \varepsilon_2),$$

$$O_2 \sim \text{Bernoulli}(0.2), \quad X_1 = \varepsilon_1.$$



2.2 . Outlier Robust Algorithm

[Structure of Algorithm]

Step1: Order Recovery

$$\hat{\pi}_r := \arg \max_{j \in V \setminus \{\hat{\pi}_{p+1-r}, \dots, \hat{\pi}_p\}} \left[\hat{\Sigma}_{S'_j(r)}^{\hat{G}_j(r)} \right]_{j,j}^{-1}$$

- where $\hat{\Sigma}_{S'_j(r)}^{\hat{G}_j(r)}$ is the sample covariance of $X_{S'_j(r)}^{G_j(r)}$.
- $X_{S'_j(r)}^{G_j(r)} \in \mathbb{R}^{|\hat{G}_j(r)| \times |S'_j(r)|}$ (genuine observations).
- $S'_j(r) := \{j\} \cup \text{Supp}(\theta_j^*(r))$.
- $\hat{G}_j(r)$:= estimated good indices via residual thresholding.

Step2: Parent Recovery

$$\widehat{\text{Pa}}(j) := \text{Supp}(\hat{\theta}_j(r)),$$

- $\hat{\theta}_j(r)$ is the solution of the ℓ_1 -regularized LTS.
- $(\hat{\theta}_j(r), \hat{H}_j(r)) := \arg \min_{\theta_j \in \mathbb{R}^{|S_j(r)|}, H \subset \{1, \dots, n\}, |H|=h} \frac{1}{2h} \sum_{i \in H} (X_j^{(i)} - \langle X_{S_j(r)}^{(i)}, \theta_j \rangle)^2 + \lambda_j(r) \|\theta_j\|_1$

2.2 . Outlier Robust Algorithm

[Structure of Algorithm]

Step1: Order Recovery

$$\widehat{\pi}_r := \arg \max_{j \in V \setminus \{\widehat{\pi}_{p+1-r}, \dots, \widehat{\pi}_p\}} \widehat{\text{Var}}(X_j | X_{S'_j(r)})$$

- where $\widehat{\Sigma}_{S'_j(r)}^{G_j(r)}$ is the sample covariance of $X_{S'_j(r)}^{G_j(r)}$.
- $X_{S'_j(r)}^{G_j(r)} \in \mathbb{R}^{|\widehat{G}_j(r)| \times |S'_j(r)|}$ (genuine observations).
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2.2 . Outlier Robust Algorithm

[Pseudo Code]

Algorithm 1: Robust Gaussian Linear SEM Learning Algorithm

Input : n independent samples, $X^{1:n}$

Output: Estimated graph structure, $\hat{G} = (V, \hat{E})$

Set $\hat{\pi}_{p+1} = \emptyset$;

for $r = \{1, 2, \dots, p - 1\}$ **do**

for $j \in V \setminus \{\hat{\pi}_{p+1}, \dots, \hat{\pi}_{p+2-r}\}$ **do**

$S_j(r) = V \setminus (\{j\} \cup \{\hat{\pi}_{p+1}, \dots, \hat{\pi}_{p+2-r}\})$;

Estimate $\hat{\theta}_j(r)$ for ℓ_1 -regularized LTS in Equation (2);

Estimate truncated conditional variances $\widehat{\text{Var}}(X_j \mid X_{S_j(r)})$ using Equation (3);

end

Determine $\hat{\pi}_{p+1-r} = \arg \max_j \widehat{\text{Var}}(X_j \mid X_{S_j(r)})$;

Determine $\widehat{\text{Pa}}(\hat{\pi}_{p+1-r}) = \{k \in S_{\hat{\pi}_{p+1-r}}(r) : [\hat{\theta}_{\hat{\pi}_{p+1-r}}(r)]_k \neq 0\}$;

end

Return: Estimate an edge set, $\hat{E} = \cup_{r \in \{1, 2, \dots, p-1\}} \{(k, \hat{\pi}_{p+1-r}) : k \in \widehat{\text{Pa}}(\hat{\pi}_{p+1-r})\}$

2.3 . Consistency of Algorithm

[Order Recovery]

Assumption (Outlier–distance separation)

- For $r \in \{1, \dots, p-1\}$, $j \in \{\pi_1, \dots, \pi_{p+1-r}\}$, $T_j(r) := \{\pi_1, \dots, \pi_{p+1-r}\} \setminus \{j\}$.
- There exists $\eta_{\min} > 0$ such that

$$\min_{i \in B_j(r, o)} \left| X_j^{(i)} - \mathbb{E}[X_j^{(i)} | X_{T_j(r)}] \right| > \eta_{\min}.$$

- Bad–row set: $B_j(r, o) := \{ i \in \{1, \dots, n\} : \exists k \in \{j\} \cup T_j(r) \text{ with } o_k^{(i)} = 1 \}$.

Assumption (Truncated conditional–variance gap)

- For $r \in \{1, \dots, p-1\}$, $j \in \{\pi_1, \dots, \pi_{p+1-r}\}$, $T_j(r) := \{\pi_1, \dots, \pi_{p+1-r}\} \setminus \{j\}$.
- For any $\eta \in (0, \eta_{\min})$, $\exists \tau_{\min} > 0$ such that for every $\ell \in \text{An}(j)$,

$$\begin{aligned} & \text{Var}\left(X_j \mid X_{T_j(r)}, |X_j - \mathbb{E}(X_j | X_{T_j(r)})| < \eta\right) \\ & - \text{Var}\left(X_\ell \mid X_{T_j(r)}, |X_\ell - \mathbb{E}(X_\ell | X_{T_j(r)})| < \eta\right) > \tau_{\min}. \end{aligned}$$

2.3 . Consistency of Algorithm

[Order Recovery]

Theorem (Recovery of the Ordering)

- Gaussian linear CCSEM with cellwise contamination. Assume (Outlier–distance separation) and (Truncated conditional–variance gap) hold.
- Suppose, for each $r \in \{1, \dots, p-1\}$, $j \in \{\pi_1, \dots, \pi_{p+1-r}\}$, the supports of $\theta_j^*(r)$ are provided, and choose $\eta \in (0, \eta_{\min})$.
- If the truncated–variance sample size $h' := \min_{j,r} |\widehat{G}_j(r)| \geq C'_\epsilon d^2 \log p$,
 $\Rightarrow \Pr(\widehat{\pi} \in \Pi^*) \geq 1 - \epsilon$, for any $\epsilon > 0$, with some constant $C'_\epsilon > 0$.

2.3 . Consistency of Algorithm

[Parent Recovery]

Assumption (Clean–row fraction under CCSEM)

- Fix iteration $r \in \{1, \dots, p - 1\}$ and $j \in \{\pi_1, \dots, \pi_{p+1-r}\}$.
- Let $S_j(r)$ be the design set and define the bad–row set under config. o by
$$B_j(r, o) := \{ i \in \{1, \dots, n\} : \exists k \in \{j\} \cup S_j(r) \text{ with } o_k^{(i)} = 1 \}.$$
- There exists $\alpha_{\min} \in (0, 1]$ such that $|B_j(r, o)| \leq \min\{(1 - \alpha_{\min}) h, n - h\}$.

2.3 . Consistency of Algorithm

[Parent Recovery]

Assumption (Spectral bound)

- $X_{S_j(r)}^{B_j(r,o)} \in \mathbb{R}^{|B_j(r,o)| \times (p-1)}$ collects rows $B_j(r, o)$ and columns $S_j(r)$.
- There exists $c_{\max} > 0$ such that

$$\max_{j,r} \max_{\substack{K_j \subset V \setminus \{j\} \\ |K_j| = |B_j(r,o)|}} \|X_{K_j}^{B_j(r,o)}\| \leq c_{\max} \sqrt{|B_j(r,o)| \log p},$$

where $\|A\| := \sup_{\|v\|_2 \leq 1} \|Av\|_2$ (spectral norm).

Assumption (Parameter bound)

- $\forall r \in \{1, \dots, p-1\}$, $j \in \{\pi_1, \dots, \pi_{p+1-r}\}$, $\exists c_1 > 0$ such that
$$\theta_{\min} < \min_{j,r} \|\theta_j^*(r)\|_{\min} \leq \max_{j,r} \|\theta_j^*(r)\|_1 \leq \rho \leq \frac{c_1}{2} \sqrt{\frac{h}{\log p}},$$
- ρ is the tuning parameter used in the ℓ_1 -regularized LTS step.

2.3 . Consistency of Algorithm

[Parent Recovery]

Theorem (Sign Recovery)

- Consider the ℓ_1 -regularized LTS. with solution $\hat{\theta}_j(r)$.
- Assume (Clean–row fraction), (Spectral bound), and (Parameter bound) hold.
- Then for any $\epsilon > 0$, $\exists c_\epsilon, \kappa_1 > 0$ such that

$$\lambda_j(r) = c_\epsilon \sqrt{\frac{\log p}{h}},$$

$$h \geq \left(\frac{c_\epsilon}{\kappa_1 \alpha_{\min} \theta_{\min}^2} \right)^2 \left(\frac{9}{4} d + 4 |B_j(r, o)| \right) \log p,$$

$$\Rightarrow \Pr(\text{sign}(\hat{\theta}_j(r)) = \text{sign}(\theta_j^*(r))) \geq 1 - \frac{\epsilon}{p^2}.$$

2.3 . Consistency of Algorithm

[Consistency]

Corollary (Consistency of the Algorithm)

- Setting: Gaussian linear CCSEM with cellwise contamination.
- Assume (Clean–row fraction), (Spectral bound), (Parameter bound), and (Truncated conditional–variance gap) hold, with appropriate tuning (λ, η) .
- If $h = \Omega((d + |B|) \log p)$ and $h' = \Omega(d^2 \log p)$,
where $|B| := \max_{j,r} |B_j(r, o)|$, $h' := \min_{j,r} |\hat{G}_j(r)|$,
 $\Rightarrow \Pr(\hat{G} = G) \rightarrow 1 \quad (n \rightarrow \infty)$.

2.4 . Simulations and Real-Data

[Simulations]

Simulation Settings (CCSEM)

- **Graph size:** $p \in \{5, 10, \dots, 25\}$; 100 realizations per p .
- **Sparsity:** max degree $d \leq 4$, min indegree = 1; no isolated nodes.
- **Edge weights:** $\beta_{k,j}$ i.i.d. uniform in $(-1, -0.75) \cup (0.75, 1)$.
- **Noise:** $\sigma_j^2 = 0.75$ for all j .
- **Outliers:** $B \in \{1, 30, 60, 90\}$,
values generated from $N(100, \sigma_j^2)$.

2.4 . Simulations and Real-Data

[Number of Trimmed Sample]

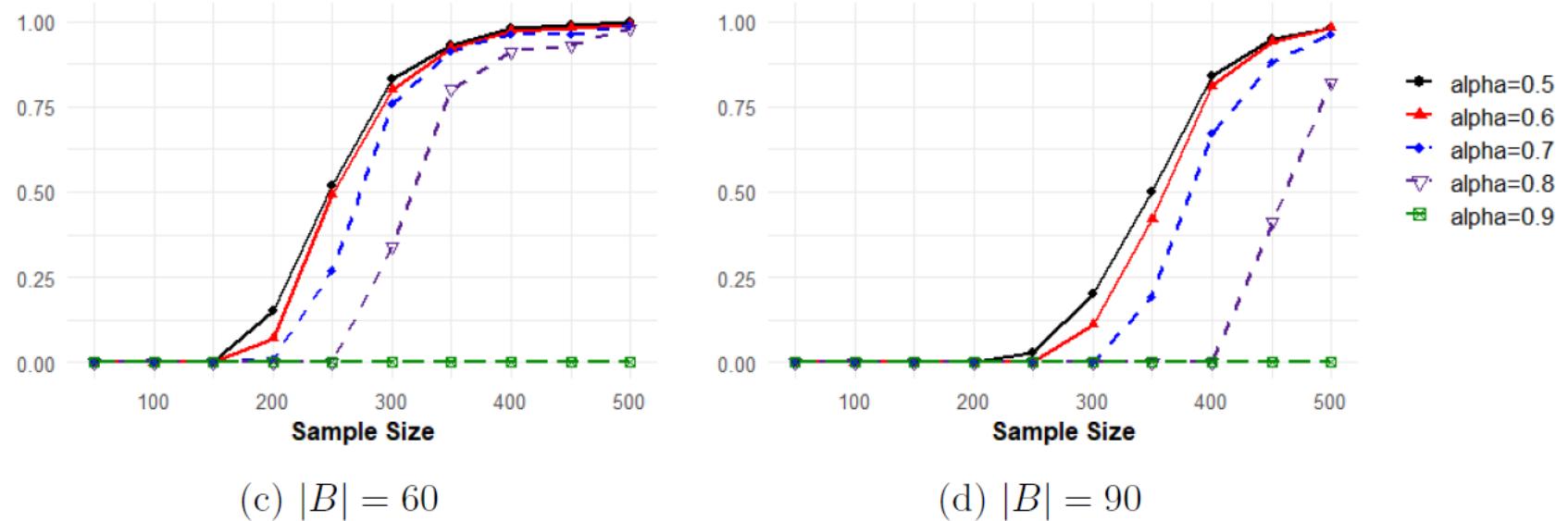
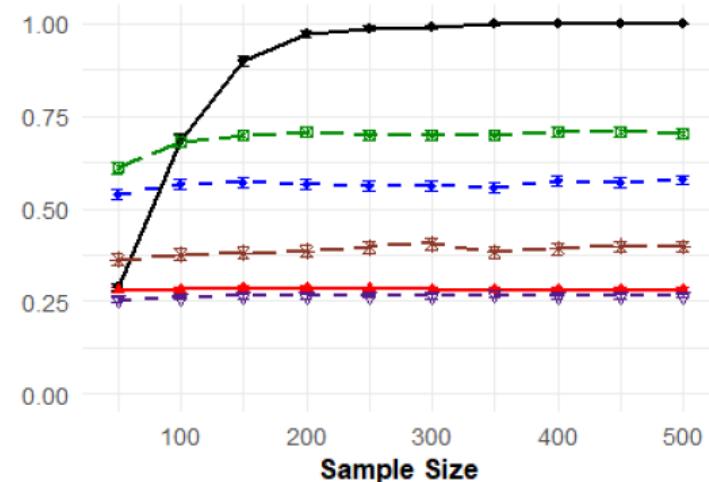


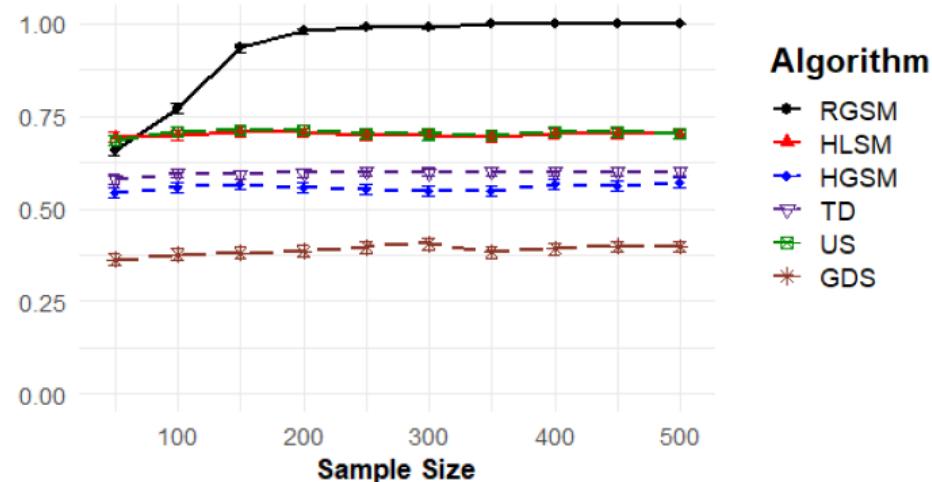
Figure 2: Performance of the proposed algorithm with various fractions of the sample size, $\alpha \in \{0.5, 0.6, \dots, 0.9\}$, for learning 10-node corrupted Gaussian linear SEMs with the different maximum number of bad samples ($|B| \in \{1, 30, 60, 90\}$) on the first element of the ordering. The empirical probability of successful graph recovery is shown versus sample size.

2.4 . Simulations and Real-Data

[Comparison with Other Algorithms]



(c) Precision: $|B| = 30$

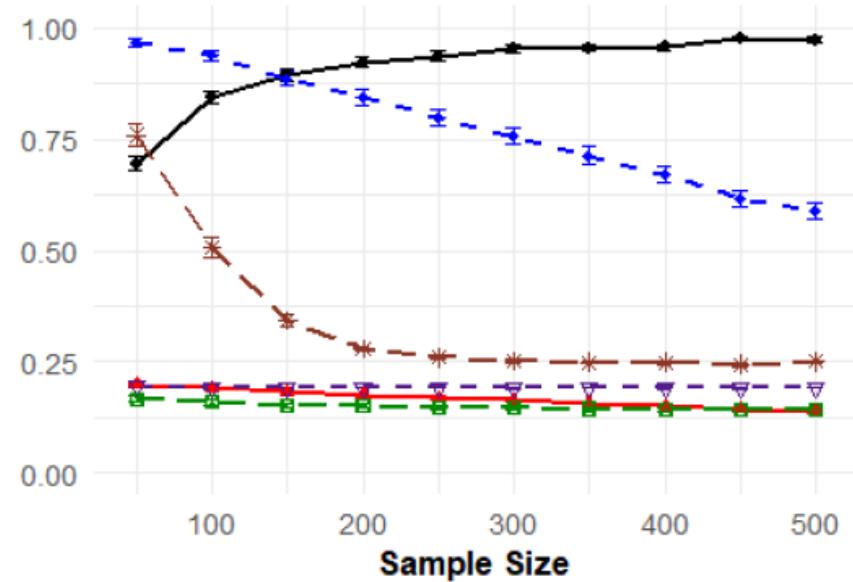


(d) Recall: $|B| = 30$

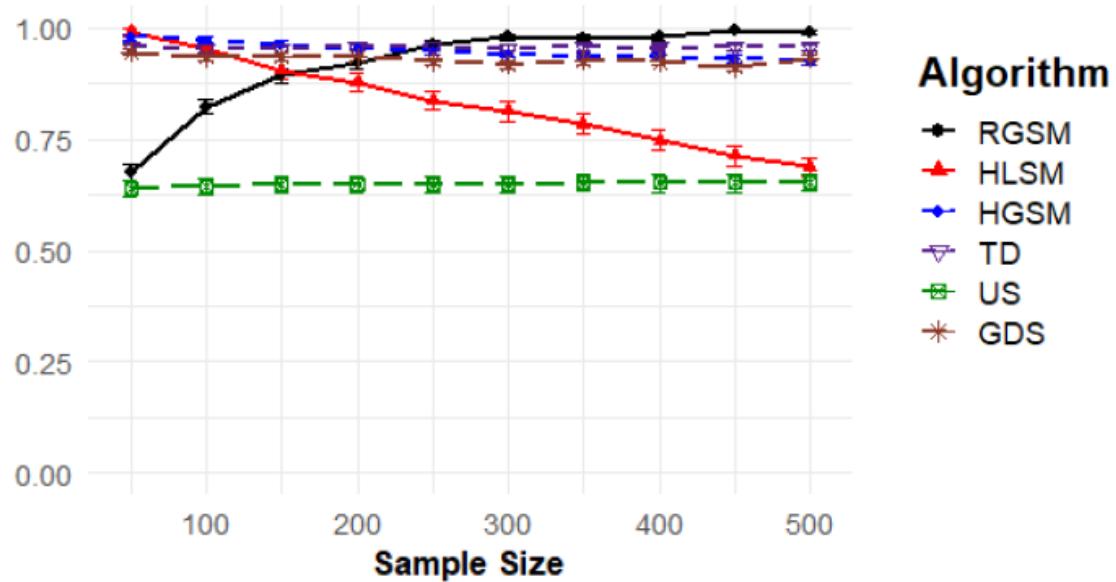
Figure 6: Comparison of the proposed algorithm (RGSM) against the HLSM, HGSM, TD, and US algorithms in terms of the average precision and recall for learning 10-node corrupted Gaussian linear SEMs with $|B| \in \{1, 30\}$.

2.4 . Simulations and Real-Data

[All Outliers]



(a) Precision



(b) Recall

Figure 10: Comparison of the proposed algorithm (RGSM) against the HLSM, HGSM, TD, and US algorithms in terms of average Hamming distance for learning 10-node corrupted Gaussian linear SEMs when all observation are outliers.

2.4 . Simulations and Real-Data

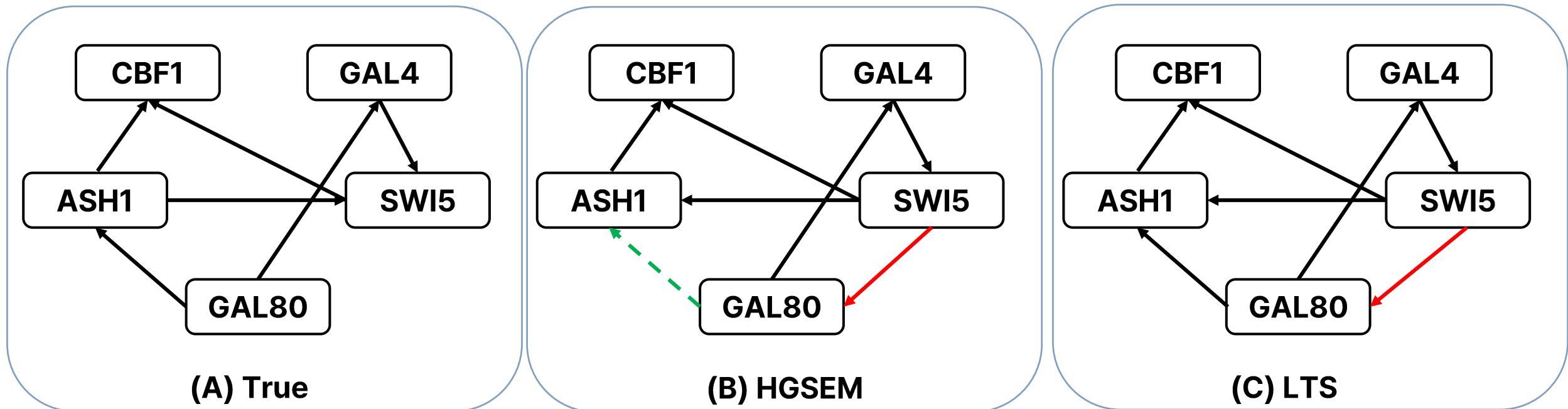
[Real-Data]

IRMA Yeast Real Data: Dataset

- **IRMA Yeast Network:**
 - 5 genes (CBF1, GAL4, SWI5, GAL80, ASH1)
 - Ground-truth DAG with 8 directed edges
- **Experimental Conditions:**
 - “Off” (glucose medium, network repressed)
 - “On” (galactose medium, network induced)
- **Measurements:**
 - 21 time-points per condition ($n = 42$ samples)
 - Steady-state mRNA expression (DNA microarrays)

2.4 . Simulations and Real-Data

[Real-Data]



감사합니다.

