Simulating the Distribution of Correlation, Geometric Approach

We simulate on a unit sphere by Monte Carlo, in higher dimensions, n - sphere or ball

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{rand1[[1]] Sin[rand1[[2]]] Cos[rand1[[3]]], rand1[[1]] Sin[rand1[[2]]] Sin[rand1[[3]]], rand1[[1]] Cos[rand1[[2]]], {10^4}];
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   Show[SphericalPlot3D[1, {θ, 0, Pi}, {φ, 0, 2 Pi}, PlotStyle → Transparent], Graphics3D[{PointSize[.006], Red, Point[ta]}]]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         r Cos [\phi] Sin [\theta_1] Sin [\theta_2] Sin [\theta_3] Sin [\theta_4] Sin [\theta_5] Sin [\theta_6]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                r Sin[\phi] Sin[\theta_1] Sin[\theta_2] Sin[\theta_3] Sin[\theta_4] Sin[\theta_5] Sin[\theta_6]
                                                                                              τ1 = FromPolarCoordinates[τ // Flatten]; TableForm[τ1]
+
h[π26]- τ = Join[{r}, Table[θ<sub>1</sub>, {i, 1, 6}], {φ}] // Flatten;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            r Cos[\theta_6] Sin[\theta_1] Sin[\theta_2] Sin[\theta_3] Sin[\theta_4] Sin[\theta_5]
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                                                                                                                                                                                                                                                                                                                                                       r Cos [\theta_3] Sin [\theta_1] Sin [\theta_2]
                                                                                                                                                                                                                                                                                           r \cos [\theta_2] Sin [\theta_1]
                                                                                                                                                                                                                                        r \cos [\theta_1]
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