Unit 2. Linear programming. Duality

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Preliminary

This course is strongly based on the monography on Operations Research by Carter, Price and Rabadi [1], and in material obtained from different sources (quoted when needed through the slides).

Learning outcomes

- Understanding Dual and Primal problems in LP
- Economic interpretation
- Conditions of optimality
- Resolution of the dual by the primal and penalty method

Summary

• Duality

- 2 Some theory
- References





A first example I

Linear programming problems come in pairs!

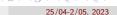
maximize
$$\begin{aligned} 4x_1 + x_2 + 5x_3 + 3x_4 & \leq & 1 \\ subject to & \begin{cases} x_1 - x_2 - x_3 + 3x_4 & \leq & 1 \\ 5x_1 + x_2 + 3x_3 + 8x_4 & \leq & 55 \\ -x_1 + x_2 + 3x_3 - 5x_4 & \leq & 3 \\ x_1, x_2, x_3 & \geq & 0 \end{aligned}$$

note that

$$y_1(x_1 - x_2 - x_3 + 3x_4) +$$

 $y_2(5x_1 + x_2 + 3x_3 + 8x_4) +$
 $y_3(-x_1 + x_2 + 3x_3 - 5x_4) \le y_1 + 55y_2 + 3y_3$





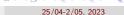
Primal and Dual

We see that maximizing the **Primal objective function** $4x_1 + x_2 + 5x_3 + 3x_4$ is equivalent to minimize the **Dual objective function** $y_1 + 55y_2 + 3y_3$:

minimize
$$y_1 + 55y_2 + 3y_3$$

$$\begin{cases} y_1 + 5y_2 - y_3 & \geq 4 \\ -y_1 + y_2 + y_3 & \geq 1 \\ -y_1 + 3y_2 + 3y_3 & \geq 5 \\ 3y_1 + 8y_2 - 5y_3 & \geq 3 \\ y_1, y_2, y_3, y_4 & \geq 0 \end{cases}$$





Generalization

In general, if we can write the LP problem in its normal formulation:

$$\begin{aligned} & \min \quad \mathbf{c}^t \mathbf{x} \\ & \text{subject to} \quad A \mathbf{x} \geq \mathbf{b}, \forall x_i \geq 0 \end{aligned} \end{aligned} \text{PRIMAL}$$

$$\begin{aligned} & \max \quad \mathbf{b}^t \mathbf{y} \\ & \text{subject to} \quad A^t \mathbf{y} \leq \mathbf{c}, \forall y_i \geq 0 \end{aligned}$$

The dual problem is a transposition of the primal problem. Since any LP can be written in the standard form above, any LP has a dual.





Problem transformations

- if you are asked to minimize f(x), this is equivalent to maximize -f(x);
- add slack/surplus variables if you want to transform an inequality into an equality contraint;
- 3 $a \cdot x = b$ is equivalent to having, simultaneously, $a \cdot x \le b$ and $a \cdot x \ge b$;
- replace an unconstrained variable x_i by $u_i v_i$ and impose that $u_i, v_i \ge 0$

Trick: Leave equality constraints to use the simplex algorithm. Use the inequality constraints for the duality theorem to be used.





Exercise 1

Find the dual problem of

maximize
$$3x_1 + 2x_2$$
 subject to
$$\begin{cases} 2x_1 + x_2 & \leq & 4 \\ 2x_1 + 3x_2 & \leq & 6 \\ & x_1, x_2 & \geq & 0 \end{cases}$$

Solve it graphically and using Simplex.





Exercise 2

Find the dual problem of

minimize
$$4x_1 + 4x_2 + x_3$$

subject to
$$\begin{cases} x_1 + x_2 + x_3 & \leq 2 \\ 2x_1 + x_2 & = 3 \\ 2x_1 + x_2 + 3x_3 & \geq 3 \\ x_1, x_2, x_3 & \geq 0 \end{cases}$$

Trick: normalize the problem first: eg
$$2x_1+x_2=3 o \begin{cases} 2x_1+x_2 \geq 3 \\ 2x_1+x_2 \leq 3 \end{cases}$$
 .





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Dual of the dual

Theorem

In the case of linear programming, the dual of the dual is the primal.

Proof.

$$\max_{\mathbf{b}^t \mathbf{y}} \mathbf{b}^t \mathbf{y}
\text{subject to} A^t \mathbf{y} \leq \mathbf{c}, \forall y_i \geq 0$$

is equivalent to

$$\begin{vmatrix}
min & -\mathbf{b}^t\mathbf{y} \\
subject to & -A^t\mathbf{y} \ge -\mathbf{c}, \forall y_i \ge 0
\end{vmatrix}$$
 DUAL

where, by taking again the Dual, leads to the original Primal.



Meaning of Duality I

Let us retake the example we saw in the last session:

maximize
$$z = 8x_1 + 5x_2$$
 $x_1 \le 150$ $x_2 \le 250$ $2x_1 + x_2 \le 500$ $x_1, x_2 \ge 0$

We found out that, from the initial tableau:



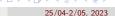
Meaning of Duality II

and after applying the different steps of the Simplex method we ended up with the final tableau:

Now, if we multiply the original availability of each resource (shown in the original tableau) by its marginal worth (taken from the final tableau) and get the sum, we obtain the optimal objective function value:

$$z* = 2250 = 0(150) + 1(250) + 4(500)$$





Duality properties

Theorem (Weak Duality)

In a max LP, the value of primal objective function for any feasible solution is bounded from above by any feasible solution to its dual:

$$max \bar{z} \leq \bar{w}$$

The statement is analogous to a minimization problem.

Theorem (Unboundness property)

If primal (dual) problem has an unbounded solution, then the dual (primal) is unfeasible.

$$max \bar{z} \leq \infty$$





Duality properties I

Theorem (Strong Duality)

If the primal problem has an optimal solution,

$$x^* = (x_1^*, \dots, x_n^*)$$

then the dual also has an optimal solution,

$$y^* = (y_1^*, \dots, y_m^*)$$

and

$$z^* := \sum_i c_j x_j^* = \sum_i b_i y_i^* := w^*$$





Duality properties II

Thus: if feasible objective function values are found for a primal and dual pair of problems, and if these values are equal to each other, then both of the solutions are optimal solutions.

The Shadow prices that appear at the top of the optimal tableau of the primal problem are precisely the optimal values of the dual variables!





A useful table

For any two given LP problems:

Primal / Dual	not feasible	unbounded	has a solution
not feasible	possible	possible	no
unbounded	possible	no	no
has a solution	no	no	same values





Cases with no optimal solutions for primal and dual

Exactly one of the following mutually exclusive cases always occurs:

- Both primal and dual problems are feasible, and both have optimal (and equal) solutions.
- Both primal and dual problems are infeasible (have no feasible solution).
- The primal problem is feasible but unbounded, and the dual problem is infeasible.
- The dual problem is feasible but unbounded, and the primal problem is infeasible.





The simplex algorithm solves the primal and dual problems simultaneously.





Complementary slackness

Because each decision variable in a primal problem is associated with a constraint in the dual problem, each such variable is also associated with a slack or surplus variable in the dual.

In any solution, if the primal variable is basic (with value ≥ 0 , hence having slack), then the associated dual variable is non-basic (= 0, hence having no slack), and viceversa.

Theorem

If in an optimal solution to a LP problem and inequality constraint is not binding, then the dual variable corresponding to that constraint has a value of zero in any optimal solution to the dual problem. In other words: suppose x_0 and y_0 are feasible solutions of (max) and (min) representations. Then, x_0 , y_0 are optimal solutions if and only if

$$(b - Ax_0) \cdot y_0 = 0$$
$$(A^t y_0 - c) \cdot x_0 = 0$$

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References



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References

[3]

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