

# Open Design 3D-Printable Adjustable Micropipette that meets ISO Standard for Accuracy

Martin D. Brennan<sup>1</sup>, Fahad F. Bokhari<sup>1</sup>, David T. Eddington<sup>1,\*</sup>,

**1 Department of Bioengineering, University of Illinois at Chicago, Chicago, Illinois, USA**

\* [dte@uic.edu](mailto:dte@uic.edu)

## Abstract

Open source projects make use of 3D printing as an increasingly practical tool to share designs, fabricate parts, and decrease cost of production. Scientists We developed a micropipette that uses 3D-printable parts and some hardware to actuate a disposable syringe to a user adjustable limit. Graduations on the syringe are used to accurately adjust the set point to the desired volume. Our open design printed micropipette is assessed in comparison to a commercial pipette and meets ISO 8655 standards.

## Introduction

The open source development model, initially applied to software, is thriving in the development of open source scientific equipment due in part to increasing access of 3D printing [1,2]. Additive manufacturing methods have existed for decades although the recent availability of inexpensive desktop printers [3,4] have made it feasible for consumers to design and print prototypes and even functional parts, and consumer goods [5,6]. Proliferation of free CAD software [7–10] and design sharing sites [11–14] have also supported the growth and popularity of open designed parts and projects. Open design 3D-printable lab equipment is an attractive idea because, like open source software, it allows free access to technology that is otherwise inaccessible due to proprietary and/or financial barriers. Open design tools create opportunity for scientists and educational programs in remote or resource limited areas to participate with inexpensive and easy to make tools [1,15–18]. Open source development also enables the development of custom solutions to meet unique applications not met by commercial products that are shared freely and are user modifiable [5,19–21]. Some advanced, noteworthy, open-source scientific equipment include a PCR device [22], and a two-photon microscope [23] although simple tools have potential to be impactful as they can serve a wider community.

Some simple and clever printable parts that have emerged are ones that give a new function to a ubiquitous existing device, such as drill bit attachment designed to hold centrifuge tubes, allowing a dremel to be used as a centrifuge [24]. Although this may make a rather crude centrifuge it may be an adequate solution for a fraction of the cost of a commercial centrifuge. Other examples of open-design research tools that utilize 3D printed parts include optics equipment [25], microscopes [26,27], syringe pumps [28], reactionware [29] and the list continues to grow.

One example of a everyday scientific tool that provides opportunity for an open design solution is the micropipette. An open design micropipette that can be made

cheaply can cut costs and allow for more options for labs and educational settings. Micropipettes are an indispensable tool used routinely in lab tasks and can easily cost \$1000 USD for a set. Often a lab will require several sets each for a dedicated task. Some pipettes may even re-calibrated for use with liquids of different properties.

Air displacement pipettes use a piston operating principal to draw liquid into the pipette [30]. In a typical commercial pipette the piston is made to be gas-tight with a gasketed plunger inside a smooth barrel. Consumer grade fused deposition modeling (FDM) printers are unable to build a smooth surface do to the formation of ridges that occur as each layer is deposited. The ridges formed by FDM make it impractical to form a gas-tight seal between moving parts, even with a gasket. Existing printable open-design micropipettes get around this limitation by stretching a membrane over one end of a printed tube, which when pressed causes the displacement. The displacement membrane can be made from any elastic material such as a latex glove. A few open design micropipettes exist including a popular one which, in addition to the printed parts, uses parts scavenged from a retractable pen [31]. Because there is no built in feature such as a readout for the user to set the displacement to a desired volume, this design requires the user to validate the volumes dispensed with a high precision scale. Without verification with a scale the volumes dispensed can only be estimated based on calculations of the deflection of the membrane which is not a practical protocol.

We submit a new design whose major strength is the ability to adjust to any volume aided by the the built in scale. Our open design 3D-printable micropipette works by actuating a disposable syringe to a user adjustable set point. This allows the user to set the pipette to a volume by reading the graduations on the syringe barrel. We have also designed an adjusted graduation scale, to be used in place of the printed on scale, that corrects for the compressibility of air which allows the pipette to be set accurately. Additionally our pipette offers a simplified assembly requiring no glue, tape, or permanent connections.

## Methods

Our printed pipette is designed to actuate a 1 mL or 3 mL syringe to a user set displacement. The core of the design is two printed parts, the body and the plunger which are able to be printed on a consumer grade FDM printer (fig. 1), in this case a Makerbot Replicator. A 1 mL or 3 mL syringe twists to lock in the body part and is held into place by the syringe flanges. The 30-300  $\mu$ L configuration uses a 1 mL pipette and the 100-1000  $\mu$ L configuration uses a 3 mL pipette. The plunger part slides freely in the body part and actuates the syringe by pushing the thumb button (fig. 2). The pipette is spring loaded towards a set point which is adjustable by a set-screw. When the thumb button is pressed the system locks when it reaches the latched position, where it is ready to draw in fluid. The plunger is held in place with a latching button design which is released with the unlatching button drawing in fluid. The displacement is equal to the distance between the set position and the latched position. The pipette can also be pressed past the latched position to 'blow-out' the transferred fluid completely from the pipette tip. Additional materials required for assembly include two springs, a nut, a bolt and two washers. Attempts to make a printable luer lock adapter for tips was abandoned as the surface of printed parts is too rough to make an air tight seal with the luer or pipette tip. Instead, a combination of a barbed luer adapter and elastic tubing is used to attach the pipette tips. Our printed pipette mimics commercial pipettes design, function, and user operation, making it intuitive to use.

Our pipette uses the air-displacement method, where a vacuum is applied to a pocket of air to draw liquid into the pipette. As air is an compressible fluid, this pocket of air grows due to the weight of the liquid pulling on it. Due to this effect the

**Figure 1. CAD renderings of printable parts and cross-sections.** (A) The printed plunger part is a shaft pushes on the syringe plunger and slides in the printed body part. The printed plunger has a latching tongue and button which interfaces with the printed body part. (B) The printed body part holds the syringe and interfaces with the printed plunger part. The body part features the unlatching button and slots to hold the syringe in place by its flanges. The body part also has two cutouts in the top for the plunger button and for the hex nut and bolt.

**Figure 2. CAD renderings of assembled pipette and function.** The pipette actuates the syringe to three positions. (i) **The set position.** The position of the screw determines the total displacement. The pipette is spring loaded to return to this position. (ii) **The latched position.** When the plunger is pressed the pipette locks at this position. The tip is then placed in a liquid and the unlatching button is pressed to release the pipette back to the set position, drawing in liquid. (iii) **The blow-out position.** The fluid is transferred by pressing the plunger past the latched position to blow-out all the liquid.

graduations on the syringe are not accurate, as they are designed for measuring liquid within the syringe. At larger volumes this effect is more pronounced resulting in the volume measured being greater than the amount of liquid pulled into the syringe. We remedied this by creating a new scale to account for the expansion. The scale is printed on a transparency sheet and is taped onto the syringe for accurate measurements (See S1 Fig and S2 Fig).

## Fabrication & Assembly

Two parts are printed (body.stl and plunger.stl) at normal resolution with rafts on a Makerbot Replicator. A small amount of paraffin wax is applied to the screw to prevent slop from causing the set point to drift after each actuation. The nut is sunk into the hex inset in the printed body part. The bolt is threaded in from the top of the body into the nut. Springs and washers are threaded onto the plunger of a 1 mL syringe for the 30-300  $\mu\text{L}$  configuration. Springs are placed inside a 3 mL syringe for the 100-1000  $\mu\text{L}$  configuration. The plunger part is inserted in the body and the syringe assembly is pushed in and locked from the syringe flanges to the body part to complete assembly (fig. 3). Parts and cost are listed in Table 1 and 2.

**Table 1.** Parts and cost for the 30-300  $\mu\text{L}$  pipette.

Part	Unit Price	Source	Part number
Filament	\$1.63	Makerbot	NA
1 mL Syringe	\$0.15	BD Biosciences	309628
Bolt	\$0.12	McMaster-Carr	91287A026
Nut	\$0.01	McMaster-Carr	90591A121
Spring (2)	\$4.14	McMaster-Carr	94125K542
Washers (2)	\$0.16	McMaster-Carr	90107A012
total	\$6.21		

**Figure 3. Photos of assembled pipettes.** (A) Two assemblies of the pipette: the 100-1000  $\mu\text{L}$  configuration (above) and the 30-300  $\mu\text{L}$  configuration (below). (B) Close-up photo of the taped on scale for each of the syringes.

**Table 2.** Parts and cost for the 100-1000  $\mu\text{L}$  pipette.

Part	Unit Price	Source	Part number
Filament	\$1.63	Makerbot	NA
3 mL Syringe	\$0.73	BD Biosciences	309657
Bolt	\$0.12	McMaster-Carr	91287A026
Nut	\$0.01	McMaster-Carr	90591A121
Spring (2)	\$4.14	McMaster-Carr	94125K542
total	\$6.63		

## Validation

The printed pipette's accuracy and precision was characterized and compared to a commercial pipette as well as ISO 8655. The printed pipette was adjusted to the target volume by eye from the syringe graduations. Deionized water was transferred and measured with a scale. Five transfers were recorded and averaged to account for random variability. Data was taken for printed pipettes with existing syringe graduations as well as with the our adjusted scale. Data was taken with commercial pipettes of 30-300  $\mu\text{L}$  and 100-1000  $\mu\text{L}$  to compare to the printed pipette. Accuracy and precision are expressed as systematic error and random error, respectively, and are calculated according to ISO 8655 [30] (Table 3 and 4). The systematic error, or accuracy, is calculated according to the following equations where accuracy ( $A$ ) is the difference of the mean volume ( $\bar{V}$ ) and the nominal volume ( $V_o$ ):

$$A = \bar{V} - V_o, A\% = 100\% \times A/V_o \quad (1)$$

The precision or random error is the standard deviation ( $s$ ) of the measurements and ( $cv$ ) is the coefficient of variation:

$$s = \sqrt{\frac{\sum_{i=1}^n (V_i - \bar{V})^2}{n - 1}}, cv = 100\% \times s/\bar{V} \quad (2)$$

## Results and Discussion

Validation testing performed with the existing graduations printed on the syringes did not meet the ISO standards. According to ISO 8655 for a pipette with the maximum nominal volume of 1000  $\mu\text{L}$  the systematic error cannot exceed 8  $\mu\text{L}$  and the random error cannot exceed 3  $\mu\text{L}$ . For the maximum nominal volume of 300  $\mu\text{L}$  the systemic error cannot exceed 4  $\mu\text{L}$  and the random error cannot exceed 1.5  $\mu\text{L}$ . The commercial pipettes met these standards handily, but in our initial tests with our printed pipette we noticed large negative systematic error suggesting that we were missing a biasing factor. This error was exaggerated while transferring larger volumes. After further investigation we realized that the graduations are intended to measure incompressible fluids within the syringe while we were using them to measure air while under vacuum. Because the syringe graduations were used to measure the air under vacuum it could not be expected to serve as a 1:1 volume ratio of water that was pulled into the tip because under vacuum the air had expanded. This explains the negative systematic error we were experiencing. The water in the tip pulls on the air due to gravity which causes it to expand slightly but enough to make measuring with the graduation in this way inaccurate. Our solution was to replace the built-in scale with a scale that accounted for the expansion. Using the data from our initial testing we calculated a factor for the expansion and used that to make the new scale. With the new scale taped on the syringe our validation testing met the ISO 8655 standard. Replacing the scale with our

scale that accounts for the expansion corrected this effect. Our printed pipette with the adjusted scale meets ISO standards for accuracy and precision. (Table 3 and 4).

Our printed pipette improves on existing open design pipettes in several ways. Most significantly the user is able to adjust the syringe accurately without verifying the volume with a scale. The pipette can be adjusted to any discrete volume within range. In addition, the assembly requires no permanent connections using tape or glue which allows for re-configuration and easy replacement of parts. Conveniently, our design can also reach to the bottom of a 15 mL conical tube allowing tasks such as aspirating supernatant fluid from a cell pellet. Unlike existing designs our design does not use a membrane that may wear out and require tedious replacement. The only major limitation of this design compared to the biropipette is the option for a pipette tip ejector. The biropipette also uses arguably easier to source parts (a pen VS a syringe) relative to what is required from our design. The biropipette also was developed in OpenSCAD which is free and open source CAD software where our design was created in Solidworks a proprietary software.

The open design nature of this project encourages anyone to use and submit changes to improve and add features to this design. All of the working files and documentation are kept in a public repository [32].

**Table 3.** ISO 8655 for 100-1000  $\mu\text{L}$  comparing a commercial pipette with our printed pipette used with existing 3 mL syringe scale and an adjusted scale

		Mean	Systematic Error	% Sys. err.	Random Error	% Rand. err.
1000 $\mu\text{L}$	ISO 8655, 100-1000 $\mu\text{L}$	1000	8.00	0.80	3.00	0.30
	Commercial Pipette	1002.98	2.98	0.30	1.72	0.17
	Printed Pipette	949.29	-50.71	-5.07	0.60	0.06
	Printed Pipette Scale	1003.57	3.57	0.36	0.89	0.09
500 $\mu\text{L}$	ISO 8655, 100-1000 $\mu\text{L}$	500	8.00	1.60	3.00	0.60
	Commercial Pipette	503.67	3.67	0.73	0.49	0.10
	Printed Pipette	475.99	-24.01	-4.80	4.75	1.00
	Printed Pipette Scale	503.62	3.62	0.72	1.64	0.33
200 $\mu\text{L}$	ISO 8655, 100-1000 $\mu\text{L}$	200	8.00	4.00	3.00	1.50
	Commercial Pipette	204.61	4.61	2.30	0.15	0.07
	Printed Pipette	186.55	-13.45	-6.72	1.31	0.70
	Printed Pipette Scale	201.87	1.87	0.94	1.47	0.73
100 $\mu\text{L}$	ISO 8655, 100-1000 $\mu\text{L}$	100	8.00	8.00	3.00	3.00
	Commercial Pipette	104.29	4.29	4.29	1.65	1.58
	Printed Pipette	94.02	-5.98	-5.98	4.81	5.12
	Printed Pipette Scale	101.00	1.00	1.00	1.05	1.04

## Conclusion

We have presented an open design micropipette that uses 3D-printable parts in addition to a disposable syringe and a few easily sourced pieces of hardware. Our open design pipette is novel in that it allows the user to set the pipette to the desired volume without the need to calibrate or verify with a weighing scale. We validated the accuracy and precision of our pipette and developed a new graduation scale to correct for the use of the syringe for air-displacement measurements that meets the ISO standard for

**Table 4.** ISO 8655 for 30-300  $\mu\text{L}$  comparing a commercial pipette with our printed pipette used with existing 3 mL syringe scale and an adjusted scale

		Mean	Systematic Error	% Sys. err.	Random Error	% Rand. err.
300 $\mu\text{L}$	ISO 8655, 30-300 $\mu\text{L}$	300	4.00	1.33	1.50	0.50
	Commercial Pipette	301.19	1.19	0.40	0.53	0.18
	Printed Pipette	286.91	-13.09	-4.36	0.42	0.15
	Printed Pipette Scale	299.11	-0.89	-0.30	0.48	0.16
200 $\mu\text{L}$	ISO 8655, 30-300 $\mu\text{L}$	200	4	2	1.5	0.75
	Commercial Pipette	200.06	0.06	0.03	0.46	0.23
	Printed Pipette	193.40	-6.60	-3.30	2.86	1.48
	Printed Pipette Scale	200.57	0.57	0.28	0.86	0.43
50 $\mu\text{L}$	ISO 8655, 30-300 $\mu\text{L}$	50	4	8	1.5	3
	Commercial Pipette	49.02	-0.98	-1.96	0.10	0.20
	Printed Pipette	49.62	-0.38	-0.76	1.26	2.53
	Printed Pipette Scale	48.73	-1.27	-2.54	1.11	2.27
30 $\mu\text{L}$	ISO 8655, 30-300 $\mu\text{L}$	30	4	13.3	1.5	5
	Commercial Pipette	29.08	-0.92	-3.06	0.09	0.31
	Printed Pipette	29.22	-0.78	-2.59	0.31	1.07
	Printed Pipette Scale	27.78	-2.22	-7.41	1.37	4.93
20 $\mu\text{L}^*$	ISO 8655, 30-300 $\mu\text{L}$	20	4	20	1.5	7.5
	Commercial Pipette	NA	NA	NA	NA	NA
	Printed Pipette	18.70	-1.30	-6.48	0.38	2.01
	Printed Pipette Scale	17.94	-2.06	-10.29	1.87	10.42
10 $\mu\text{L}^*$	ISO 8655, 30-300 $\mu\text{L}$	10	4	40	1.5	15
	Commercial Pipette	NA	NA	NA	NA	NA
	Printed Pipette	11.95	1.95	19.52	0.73	6.08
	Printed Pipette Scale	7.64	-2.36	-23.64	0.38	4.92

\* The 20  $\mu\text{L}$  and 10  $\mu\text{L}$  volumes are out of the range in this case but we wanted to demonstrate that the pipette is capable of even smaller volumes.

adjustable pipettes. Our design is free to use and modify to encourage further collaborative development.

## Supporting Information

### S1 Fig

**Adjusted Scale Graduations for 30-300  $\mu\text{L}$  Pipette.** New scale graduations that can be printed on a transparency sheet and taped onto a 1 mL syringe. Using these graduations will correct for expansion of air and allow ISO standards to be met. PDF format for ease of printing to scale. 1 inch and 1 cm marks to check scale as well as reproduction of standard graduation marks.

### S2 Fig

**Adjusted Scale Graduations for 100-1000  $\mu\text{L}$  Pipette.** New scale graduations that can be printed on a transparency sheet and taped onto a 3 mL syringe. Using

these graduations will correct for expansion of air and allow ISO standards to be met. PDF format for ease of printing to scale. 1 inch and 1 cm marks to check scale as well as reproduction of standard graduation marks.

165  
166  
167

## References

1. Baden T, Chagas AM, Gage G, Marzullo T, Prieto-Godino LL, Euler T. Open Labware: 3-D Printing Your Own Lab Equipment. *PLOS Biology*. 2015;13(3):e1002086. Available from: <http://dx.plos.org/10.1371/journal.pbio.1002086>.
2. Pearce JM. Open-source Lab; 2013.
3. Makerbot Industries. Makerbot; 2017. Available from: <https://www.makerbot.com/>.
4. RepRap Project. RepRap; 2017. Available from: [reprap.org](http://reprap.org).
5. Fullerton JN, Frodsham GCM, Day RM. 3D printing for the many, not the few. *Nature Biotechnology*. 2014;32(11):1086–1087. Available from: <http://www.nature.com/doi/10.1038/nbt.3056>.
6. Wittbrodt BT, Glover AG, Laureto J, Anzalone GC, Oppliger D, Irwin JL, et al. Life-cycle economic analysis of distributed manufacturing with open-source 3-D printers. *Mechatronics*. 2013;23(6):713–726. Available from: <http://linkinghub.elsevier.com/retrieve/pii/S0957415813001153>.
7. Kintel M. OpenSCAD; 2017. Available from: <http://www.openscad.org/>.
8. Blender Foudation. Blender. 2017;Available from: [www.blender.org](http://www.blender.org).
9. Trimble Inc . SketchUp; 2016. Available from: [www.sketchup.com](http://www.sketchup.com).
10. Autodesk Inc . Autodesk 123D; 2017. Available from: [www.123dapp.com](http://www.123dapp.com).
11. Makerbot Industries. Thingiverse; 2017. Available from: <https://www.thingiverse.com/>.
12. National Institutes of Health. NIH 3D Print Exchange. 2017;Available from: <http://3dprint.nih.gov/>.
13. Stratasys. GrabCAD;. Available from: <https://grabcad.com/>.
14. GitHub Inc . GitHub. 2017;Available from: <https://github.com/>.
15. Marzullo TC, Gage GJ. The SpikerBox: A Low Cost, Open-Source BioAmplifier for Increasing Public Participation in Neuroscience Inquiry. *PLoS ONE*. 2012;7(3):e30837. Available from: <http://dx.plos.org/10.1371/journal.pone.0030837>.
16. Lang T. Advancing global health research through digital technology and sharing data. *Science (New York, NY)*. 2011;331(6018):714–717.
17. Baker E. Open source data logger for low-cost environmental monitoring. *Biodiversity data journal*. 2014;p. e1059. Available from: <http://www.pubmedcentral.nih.gov/articlerender.fcgi?artid=4030251&tool=pmcentrez&rendertype=abstract>.



18. Cybulski JS, Clements J, Prakash M. Foldscope: origami-based paper microscope. *PloS one*. 2014;9(6):e98781. Available from: <http://journals.plos.org/plosone/article?id=10.1371/journal.pone.0098781>.
19. Pearce JM. Building Research Equipment with Free, Open-Source Hardware. *Science*. 2012 sep;337(6100):1303–1304. Available from: <http://dx.doi.org/10.1126/science.1226328><http://www.ncbi.nlm.nih.gov/pubmed/22984060><http://www.sciencemag.org/cgi/doi/10.1126/science.1228183>.
20. Rankin TM, Giovinco NA, Cucher DJ, Watts G, Hurwitz B, Armstrong DG. Three-dimensional printing surgical instruments: are we there yet? *Journal of Surgical Research*. 2014;189(2):193–197. Available from: <http://linkinghub.elsevier.com/retrieve/pii/S0022480414001644>.
21. Sulkin MS, Widder E, Shao C, Holzem KM, Gloschat C, Gutbrod SR, et al. Three-dimensional printing physiology laboratory technology. *AJP: Heart and Circulatory Physiology*. 2013;305(11):H1569–H1573. Available from: <http://ajpheart.physiology.org/cgi/doi/10.1152/ajpheart.00599.2013>.
22. Chai Biotechnologies Inc. Open PCR; 2017. Available from: <http://openpcr.org/>.
23. Rosenegger DG, Tran CHT, LeDue J, Zhou N, Gordon GR. A High Performance, Cost-Effective, Open-Source Microscope for Scanning Two-Photon Microscopy that Is Modular and Readily Adaptable. *PLoS ONE*. 2014;9(10):e110475. Available from: <http://dx.plos.org/10.1371/journal.pone.0110475>.
24. Garvey C. DremelFuge; 2009. Available from: <https://www.thingiverse.com/thing:1483>.
25. Zhang C, Anzalone NC, Faria RP, Pearce JM. Open-Source 3D-Printable Optics Equipment. *PLoS ONE*. 2013;8(3).
26. Baden T. Raspberry Pi Scope. 2014; Available from: <http://3dprint.nih.gov/discover/3dpx-000609>.
27. Walus K. A Fully Printable Microscope; 2014. Available from: <http://3dprint.nih.gov/discover/3dpx-000304>.
28. Wijnen B, Hunt EJ, Anzalone GC, Pearce JM. Open-Source Syringe Pump Library. *PLoS ONE*. 2014;9(9):e107216. Available from: <http://dx.plos.org/10.1371/journal.pone.0107216>.
29. Symes MD, Kitson PJ, Yan J, Richmond C, Cooper GJT, Bowman RW, et al. Integrated 3D-printed reactionware for chemical synthesis and analysis. *Nature Chemistry*. 2012;4(5):349–354. Available from: <http://eprints.gla.ac.uk/68744/>.
30. International Organization for Standardization. ISO 8655-1:2002(en); 2002.
31. Baden T. Biropette: customisable, high precision pipette.; 2014. Available from: <http://www.thingiverse.com/thing:255519>.
32. Eddington Lab. 3D Printable Micropipette; 2017. Available from: <https://github.com/Biological-Microsystems-Laboratory/micropipette>.