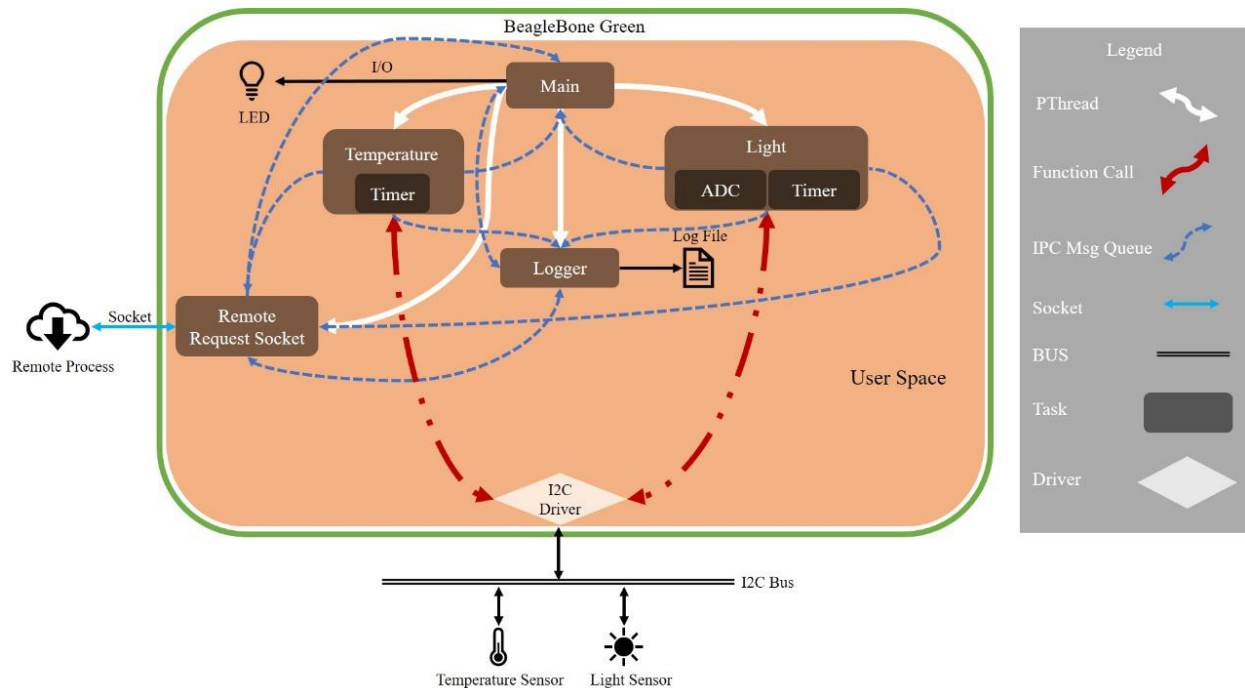


## Project-1 Report

**Git Hub Repository:** <https://github.com/devmittal/AESD-Project-1>

### Block Diagram



### Functions in brief by header file:

#### **i2c.h**

**init\_i2c:** This function initializes the I2C bus

**write\_i2c:** This function writes 8-bit data to the I2C Bus

**write\_i2c16:** This function writes 16-bit data to the I2C Bus

**read\_i2c16:** This function reads 16-bit data from the I2C Bus

**read\_i2c8:** This function reads 8-bit data from the I2C Bus

**close\_i2c:** This function concludes the I2C Communication.

**write\_i2c16\_config:** This function writes 24-bit data to the I2C Bus to write to the configuration register of the temperature sensor.

#### **led.h**

**led:** This function switches the LED on and off

**lightSensor.h**

startup\_test: This function checks the identification register as part of a startup test and confirms if the light sensor is working properly.

power\_up: This function powers up the light sensor.

read\_control\_register: This function reads control register of the light sensor.

set\_timing\_register: This function is used to set the integration time and gain of light sensor.

read\_timing\_register: This function reads timing register of the light sensor.

enable\_interrupt: This function enables interrupts in the interrupt control register of the light sensor.

disable\_interrupt: This function disable interrupts of the light sensor.

set\_interrupt\_threshold: This function sets the high and low interrupt threshold of the light sensor.

read\_interrupt\_threshold: This function reads the high and low interrupt threshold of the light sensor.

read\_visible\_light: This function reads channel 0 of light sensor.

read\_IR\_light: This function reads channel 1 of light sensor.

cal\_lumen: This function calculates actual luminosity based on channel 0 and channel 1 lux values of light sensor.

change: This function checks if there is any change in light state from the previous state.

state: This function determines current light state based on threshold value.

read\_LightSensor: This function calls functions to read channel 0 and 1, calculate lumen, determine current light state, and if there was a change from previous state and stores it in the allocated structure.

**logger.h**

write\_log: This function logs events, errors, and heartbeat notifications generated by the program

**message.h**

init\_MessageQueues: This function initializes all the message queues

dest\_MessageQueues: This function destroys (closes and unlinks) all the message queues

open\_MessageQueue: This function opens a message queue identified by its parameters

send\_Message: This function is used to send messages through a queue identified by the first parameter

recv\_Message: This function is used to receive messages through a queue identified by the first parameter

CloseUnlinkQueue: This function closes and unlinks a message queue identified by the first parameter

**remoteTask.h**

init\_socket: This function initializes the socket at the server side

send\_data: This function sends data through a socket from server to client

read\_data: This function reads data sent from client to server via a socket

**temperature.h**

read\_temperature: This function reads the temperature register of the temperature sensor

cal\_temp: This function calculates actual temperature in celsius, fahrenheit, and kelvin based on digital temperature values read from the temperature register

read\_Tlow: This function reads the lower temperature limit from the tlow register of the temperature sensor.

read\_Thigh: This function reads the higher temperature limit from the thigh register of the temperature sensor

read\_configuration\_reg: This function reads the configuration register of the temperature sensor

set\_shutdown: This function sets the shutdown mode in the configuration register of the temperature register

disable\_shutdown: This function disables the shutdown mode in the configuration register of the temperature register

read\_fault: This function reads the fault bits from the configuration register of the temperature register

read\_em: This function reads the extended mode bit in the configuration register of the temperature register.

write\_em: This function sets/disables the extended mode in the configuration register of the temperature register

read\_conversion\_rate: This function reads the conversion rate bits in the configuration register of the temperature register

set\_conversion\_rate: This function sets the conversion rate bits in the configuration register of the temperature register

write\_fault: This function sets the fault bits in the configuration register of the temperature register

## **clientprocess.h**

init\_socket: This function initializes the socket at the client side

send\_data: This function sends data through a socket from client to server

read\_data: This function reads data sent from server to client via a socket

## **main.c**

kill\_signal\_handler: Signal handler for signal SIGINT aka Ctrl-C

getSensorData: Common call back function for temperature and light timer

timer\_init: This function initializes a unique timer on demand for every requesting thread

temperature: Temperature thread callback function

light: Light thread callback function

logger: Logger thread callback function

remote: Remote task thread callback function

check\_heartbeat: This function registers heart beats from different threads and sends relevant data to the logger.

setup\_signalhandler: This function initialize a signal handler to kill any particular thread or the process itself.

## **Unit Tests**

### **Light Sensor Task**

**Start-up Test:** Read ID register to verify light sensor is functional

**Power-up Test:** Read Control register to verify that light sensor has powered up

**Timing Register Test:** Set random integration and gain values and check if it is writing to the register by reading it.

**Lumen Calculation Test:** With random channel 0 and channel 1 lux values, the lumen calculation formula is tested to see if we are getting correct luminosity.

### **Temperature Sensor Task**

**Temperature Calculation Test:** With random digital temperature values, it is tested whether the correct temperature values in Celsius, Fahrenheit and Kelvin are obtained.

**T<sub>low</sub> Register Test:** The T<sub>low</sub> register is read to test if the default value of 75 Celsius is obtained.

**T<sub>high</sub> Register Test:** The T<sub>high</sub> register is read to test if the default value of 80 Celsius is obtained.

**Configuration Register Test:** The configuration register is read to test if the default value of 0x60A0 is obtained.

### **Logger Task**

**File Creation Test:** The function which creates the file is called to test if the file is created without any errors.

## **Start-up Tests**

**Light Sensor Task:** The ID register is read and then checked if it correctly equals 0x50.

**Temperature Sensor Task:** The configuration register is read and checked if it correctly equals the default value of 0x60A0.

**Logger Task:** The start-up test constitutes the logger thread spawning and a file being created.