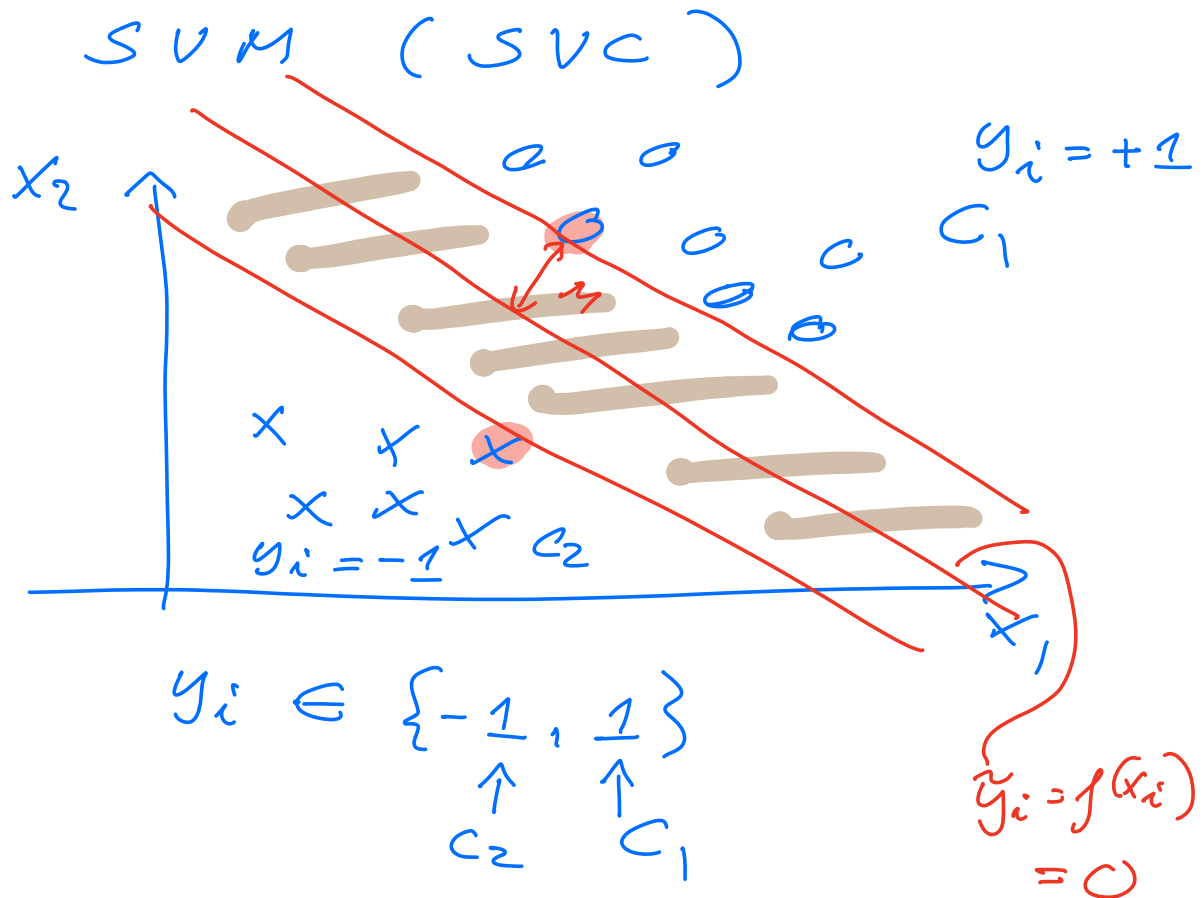


FYS-STK 4155, NOV 17, 2022

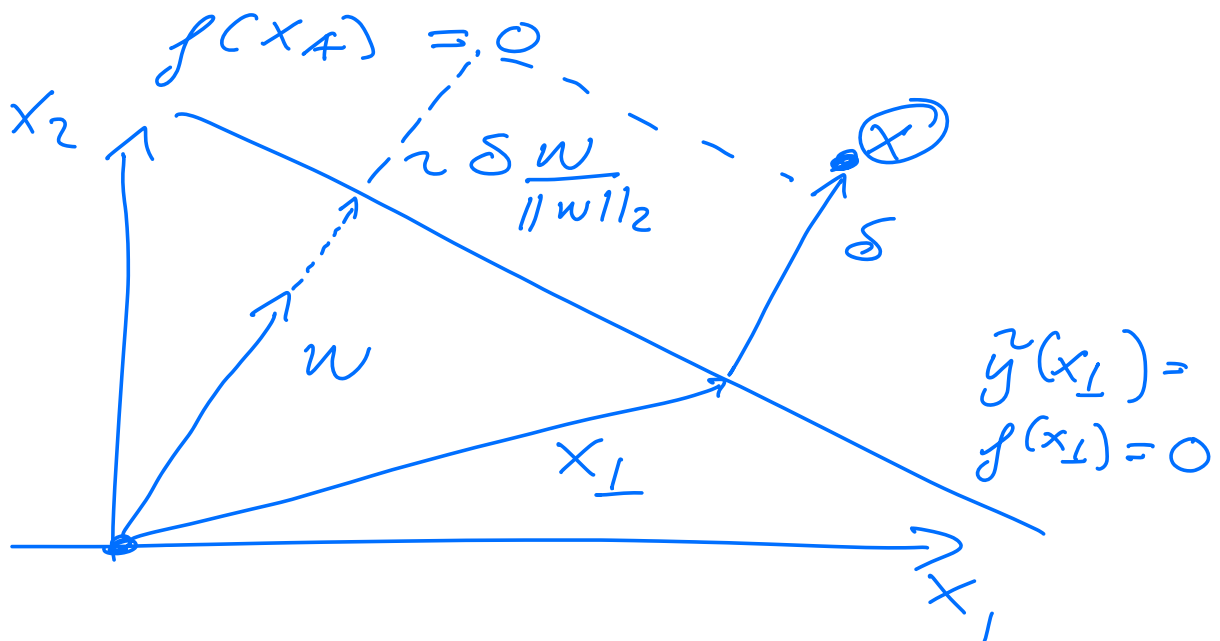


$y_i f(x_i) > 0$ correct prediction

$$\tilde{y}_i = f(x) = w^T x + w_0$$

$$= w_1 x_1 + w_2 x_2 + w_0$$

A point on the midpoint line x_A



$$x = x_{\perp} + \delta \frac{w}{\|w\|_2}$$

$$\tilde{y}(x_{\perp}) = 0 = w^T x_{\perp} + w_0$$

$$\delta = \frac{\tilde{y}(x)}{\|w\|_2}$$

$$y_i \left(\frac{w^T x_i + w_0}{\|w\|_2} \right) \geq M$$

$$y_i \tilde{y}_i = y_i (w^T x_i + w_0) \geq M \|w\|_2$$

for all $i = 0, 1, \dots, n-1$

maximize M subject to
the constraint

$$M \|w\|_2 = 1$$

$$M = \frac{1}{\|w\|_2}$$

max M

w, w_0

with constraint

$$y_i (w^T x_i + w_0) \geq 1$$

or

$$\min_{w, w_0} \frac{1}{2} w^T w$$

with constraint

$$y_i (w^T x_i + w_0) \geq 1$$

optimization with
constraint,

Example

find extreme values of

$$f(x_1, x_2) = x_1^2 - x_2^2 \quad \text{when}$$

$$x_1 \geq 0 \quad \wedge \quad x_2 \geq 0$$

$f(x) \in \mathbb{R}^n$ and
constraints of the type

$$g_1(x) = b_1, \quad g_2(x) = b_2, \dots$$

$$g_m(x) = b_m$$

b_i are constants.

introduce the Lagrangian

$$\mathcal{L}(x, \lambda) = f(x) - \lambda_1(g_1(x) - b_1)$$

$$- \dots - \lambda_m(g_m(x) - b_m)$$

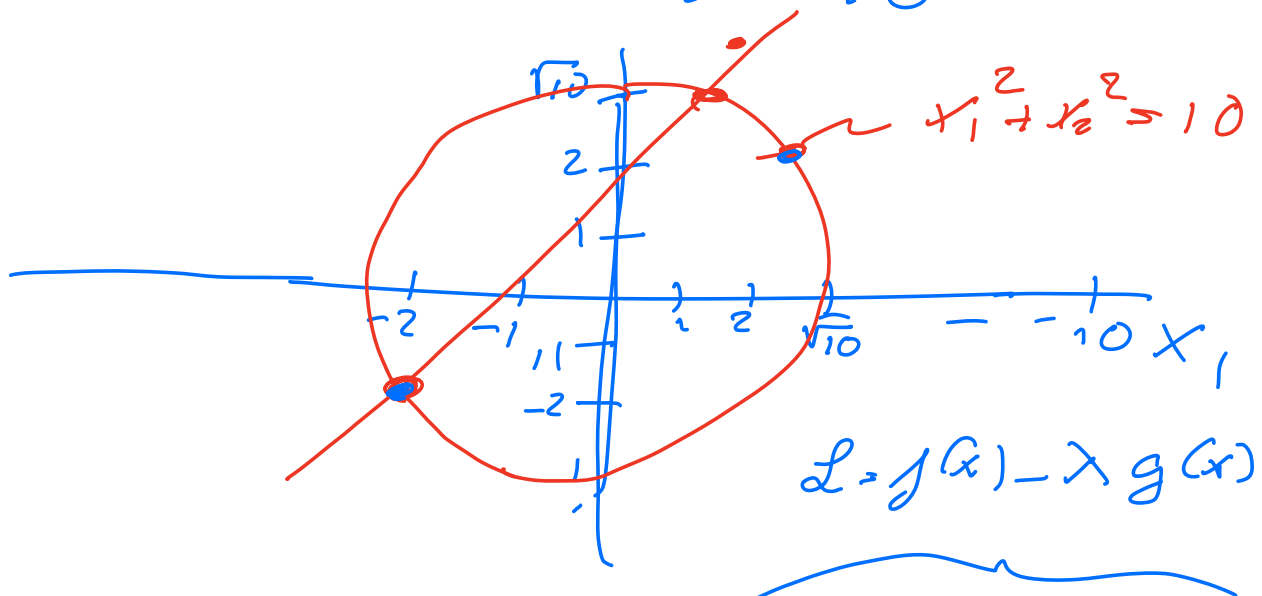
$\lambda_1, \lambda_2, \dots, \lambda_m$ are called
Lagrange multipliers.

$$\frac{\partial \mathcal{L}}{\partial x_i} = 0 \quad \text{for } i = 0, 1, \dots, n-1$$

$$\frac{\partial \mathcal{L}}{\partial \lambda_j} = 0 \quad \text{for } j = 1, 2, \dots, m$$

Example

$$f(x_1, x_2) = x_1 + 3x_2 \text{ subject to } x_1^2 + x_2^2 = 10$$



$$\frac{\partial L}{\partial x_1} = \frac{\partial}{\partial x_1} (x_1 + 3x_2 - \lambda(x_1^2 + x_2^2 - 10))$$

$$= 0 \Rightarrow 1 - 2\lambda x_1 = 0$$
$$x_1 = \frac{1}{2} \lambda$$

$$\frac{\partial L}{\partial x_2} = 0 \Rightarrow x_2 = \frac{3}{2\lambda}$$

$$\frac{\partial L}{\partial \lambda} = 0 \Rightarrow x_1^2 + x_2^2 = 10$$

$$\frac{1}{4\lambda^2} + \frac{9}{4\lambda^2} = 10$$

$$\lambda = \pm 1/2$$

$$(i) \quad \lambda = +1/2 \quad x_1 = 1 \quad x_2 = 3$$

$$\lambda = -1/2 \quad x_1 = -1 \quad x_2 = -3$$

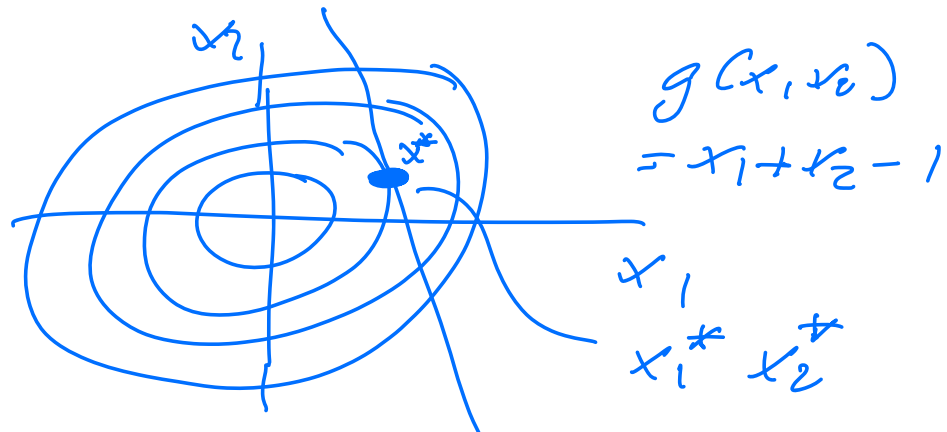
K (Kushner) K (Kuhn) T (Tucker)
conditions

constrained solutions

(i) $g(x) > 0$ (constraint is inactive)

(ii) $g(x) = 0$ constraint is active

$$f(x_1, x_2) = 1 - x_1^2 - x_2^2$$



* when $g(x) > 0$, it plays no role in the optimization and the stationary points are given by $\nabla_x f(x) = 0$ with $\lambda = 0$

* when solution is on the boundary, $g(x) = 0$
 $\lambda \neq 0$

For either case

$$\lambda \cdot g(x) = 0$$

if maximize $f(x)$ subject to $g(x) \geq 0$, we optimize

\mathcal{L} w.r.t x and λ

subject to

$g(x) \geq 0$	$\lambda \geq 0$
$\lambda g(x) = 0$	

KKT - conditions

For minimization

$$\mathcal{L}(x, \lambda) = f(x) - \lambda g(x)$$

with same KKT conditions

SVM with classification
and margin M

$$\min_{w, w_0} \frac{1}{2} w^T w$$

subject to

$$y_i (w^T x_i + w_0) = 1 \quad \forall i=0, 1, \dots, n-1$$

$$\mathcal{L} = \frac{1}{2} w^T w - \sum_{i=0}^{n-1} \lambda_i [y_i (w^T x_i + w_0) - 1]$$

$$\frac{\partial \mathcal{L}}{\partial w_0} = 0 = - \sum y_i \lambda_i$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}^T} = 0 = \mathbf{w} - \sum_i \lambda_i y_i \underset{\substack{\uparrow \\ \text{vector}}}{\mathbf{x}_i}$$

$$\frac{\partial \mathcal{L}}{\partial \lambda_i} = 0 = y_i (\mathbf{w}^T \mathbf{x}_i + w_0) - 1$$

$$\mathbf{w} = \sum_i \lambda_i y_i \mathbf{x}_i$$

insert \mathbf{w} in \mathcal{L}

$$\mathcal{L} = \sum_{i=0}^{n-1} \lambda_i - \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j$$

subject to $(\mathbf{K} \mathbf{K}^T)$

$$\boxed{\lambda_i \geq 0} \quad \mathbf{K} \mathbf{K}^T$$

$$\sum \lambda_i y_i = 0 \quad \text{and}$$

$$\boxed{\begin{aligned} &\lambda_i [y_i (\mathbf{w}^T \mathbf{x}_i + w_0) - 1] \quad \mathbf{K} \mathbf{K}^T \\ &\lambda_i > 0 \quad \text{then} \\ &\quad y_i (\mathbf{w}^T \mathbf{x}_i + w_0) = 1 \end{aligned}}$$

x_n is on the boundary
(Margin M) and
define the support
vector

This is referred to as a
hard margin problem?

Define

$$\lambda^T = [\lambda_0, \lambda_1, \dots, \lambda_{n-1}]$$

$$y^T = [y_0, y_1, \dots, y_{n-1}]$$

Rewrite

$$\mathcal{L} = \frac{1}{2} \lambda^T$$

$$\frac{1}{2} \lambda^T \begin{bmatrix} y_0 y_0 x_0^T x_0 & y_0 y_1 x_0^T x_1 & \dots & y_0 y_{n-1} x_0^T x_{n-1} \\ \vdots & \times & \times & \times \\ \vdots & \times & \times & \times \\ \vdots & & & \\ y_{n-1} y_0 x_{n-1}^T x_0 & \dots & y_{n-1} y_{n-1} x_{n-1}^T x_{n-1} \\ & & & \times \times \times \end{bmatrix}$$

$$x \lambda$$

subject to $y^T \lambda = 0$

+ KKT conditions

we can find the "intercept"

$$y_i (w^T x_i + w_0) = 1$$

$$w_0 = \frac{1}{y_i} - w^T x_i$$