

1.2. Multivariable Calculus

Partial/total derivatives, Notation

Partial Derivatives

- Denoted by ∂

- For function $u(x, y)$, possible partial derivatives

$$\frac{\partial u}{\partial x} \Big|_y \equiv \frac{\partial u}{\partial x}$$

$\leftarrow y \text{ constant}$

Differentiate u w.r.t. x , keep all other independent variables constant

$$\frac{\partial^2 u}{\partial x^2}, \frac{\partial^2 u}{\partial x \partial y} = \frac{\partial^2 u}{\partial y \partial x} \quad \text{COMMUTATIVE}$$

- Example $u(x, y) = \frac{x}{y} + x^2 y$

$$\frac{\partial u}{\partial x} = \frac{1}{y} + 2xy$$

$$\frac{\partial u}{\partial y} = -\frac{x}{y^2} + x^2$$

$$\frac{\partial^2 u}{\partial x^2} = 0 + 2y$$

$$\frac{\partial^2 u}{\partial y^2} = \frac{2x}{y^3}$$

$$\frac{\partial^2 u}{\partial x \partial y} = -\frac{1}{y^2} + 2x$$

Partial Derivatives

- Product rule

- $u(x, y) = A(x, y)B(x, y)$

$$\frac{\partial u}{\partial x} = \frac{\partial A}{\partial x} B + A \frac{\partial B}{\partial x}$$

- Chain rule

- $u(x, y) = A(B(x, y))$

$$\frac{\partial u}{\partial x} = \frac{\partial A}{\partial B} \cdot \frac{\partial B}{\partial x}$$

- Example $u = x \sin(xy)$, $A = x$, $B = \sin C$, $C = xy$

- $\frac{\partial u}{\partial x} = \frac{\partial A}{\partial x} B + A \frac{\partial B}{\partial C} \cdot \frac{\partial C}{\partial x}$

$$u = \frac{A \cdot B}{\sin C}$$

$$\begin{aligned} \frac{\partial u}{\partial x} &= \frac{\partial}{\partial x}(x) \cdot \sin C + x \frac{\partial}{\partial C}(\sin C) \cdot \frac{\partial}{\partial x}(xy) \\ &= \sin(xy) + xy \cos(xy) \end{aligned}$$

Total Derivatives

- For multi-variable functions, e.g. $u(x, y)$
 - $\frac{\partial}{\partial x}$ differentiation with respect to (w.r.t.) x while y constant
 - $\frac{d}{dx}$ differentiation w.r.t. x but y is non-constant
 - Total derivative $\frac{du}{dx}$ can only be obtained if there are constraints on x and y .

TOTAL PARTIAL

$$\frac{du}{dx} \neq \frac{\partial u}{\partial x}$$

$$\frac{du}{dx} = \frac{\partial u}{\partial x} \cdot \underbrace{\frac{dx}{dx}}_{=1} + \frac{\partial u}{\partial y} \cdot \underbrace{\frac{dy}{dx}}$$

$$y = f(x)$$

TOTAL DIFFERENTIAL

- Example $u(x, y) = \frac{x}{y} + x^2 y$ constraint $x = \cos y$

$$\frac{du}{dx} = \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \cdot \frac{dy}{dx}$$

$$\frac{\partial u}{\partial x} = \frac{1}{y} + 2xy$$

$$\frac{\partial u}{\partial y} = -\frac{x}{y^2} + x^2$$

$$\frac{dy}{dx} = -\sin y \frac{dy}{dx} = -\frac{1}{\sin y}$$

$$\frac{du}{dx} = \frac{1}{y} + 2xy + \left(-\frac{x}{y^2} + x^2\right) \left(-\frac{1}{\sin y}\right)$$

Shorthand Notation used in various texts

Ordinary Derivatives

$$\frac{du(x)}{dx} \equiv u'(x) \quad \frac{d^2u(x)}{dx^2} \equiv u''(x)$$

$$\frac{d^{(n)}u(x)}{dx^n} \equiv u^{(n)}(x)$$

Time derivatives

$$\frac{dx}{dt} = \dot{x}$$

$$\frac{d^2x}{dt^2} = \ddot{x}$$

$$\frac{d^3x}{dt^3} = \dddot{x}$$

Partial Derivatives

$$\frac{\partial u}{\partial x} \equiv \underline{u'_x} \equiv \underline{\partial_x u}$$

$$\frac{\partial^2 u}{\partial x^2} \equiv u''_{xx} \equiv \partial_{xx} u \equiv \partial_x^2 u$$

$$\frac{\partial^2 u}{\partial x \partial y} = u''_{xy} \equiv \partial_{xy} u$$

Derivative evaluated at a constant value of an independent variable

$$\left. \frac{df}{dx} \right|_{x=a} = f'(a)$$

1.3. Differential Operators

Grad, Div, Curl Definitions and Meaning

Gradient - Grad

- Gradient of a line $u(x)$ is $\frac{du}{dx}$
- What is the gradient at a point on a surface $u(x, y)$?
Magnitude and direction of greatest rate of change

$\underline{\hat{i}}, \underline{\hat{j}}, \underline{\hat{k}}$ UNIT VECTORS
DIRECTION x, y, z

∇ NABLA (DEL OPERATION)

$$\nabla = \frac{\partial}{\partial x} \underline{\hat{i}} + \frac{\partial}{\partial y} \underline{\hat{j}} + \frac{\partial}{\partial z} \underline{\hat{k}}$$

- Example: Temperature $T(x, y, z)$ Gradient

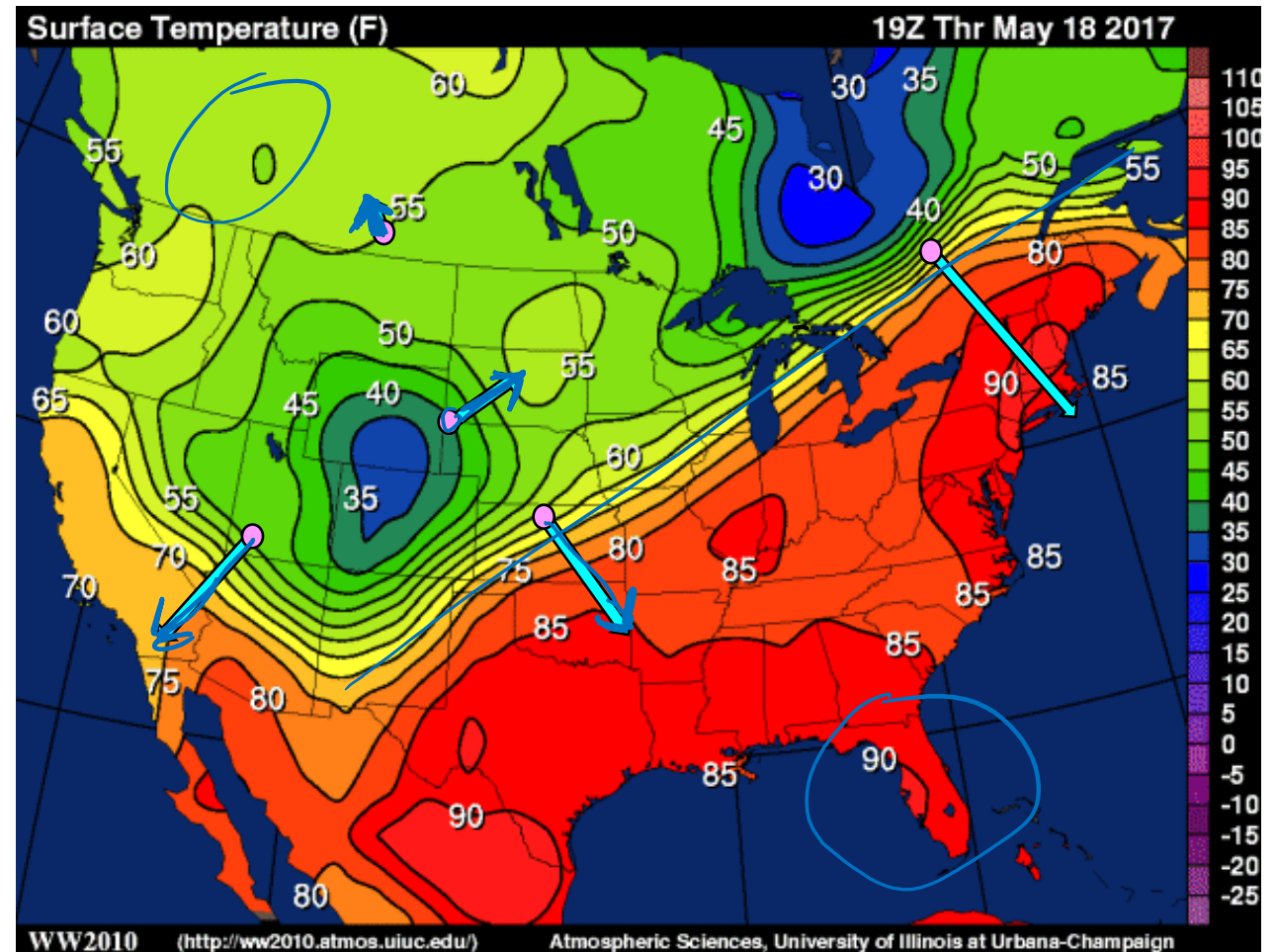
$$\text{GRAD}(T) = \nabla T = \frac{\partial T}{\partial x} \underline{\hat{i}} + \frac{\partial T}{\partial y} \underline{\hat{j}} + \frac{\partial T}{\partial z} \underline{\hat{k}}$$

$$T(x, y, z) = A + Bz - Cx$$

$$\nabla T = \underbrace{B \underline{\hat{k}} - C \underline{\hat{i}}}_{\text{VECTOR}}$$

\uparrow
SCALAR

- Grad acts on a scalar to give a vector

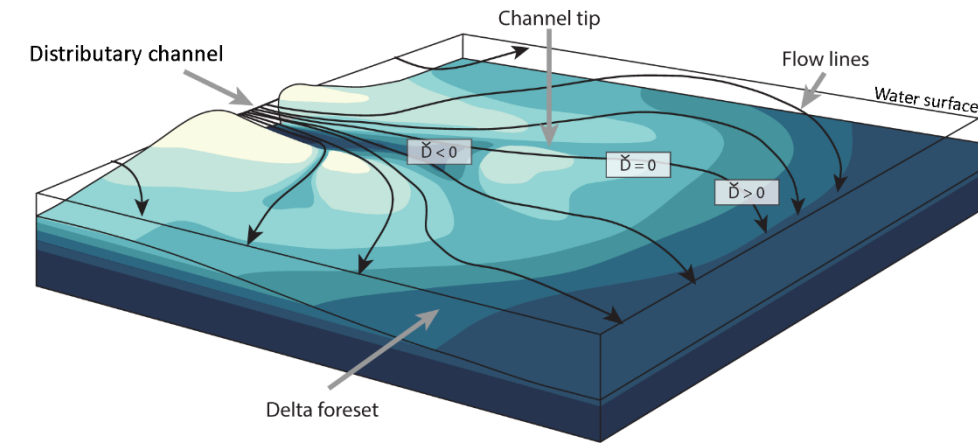


Divergence - Div

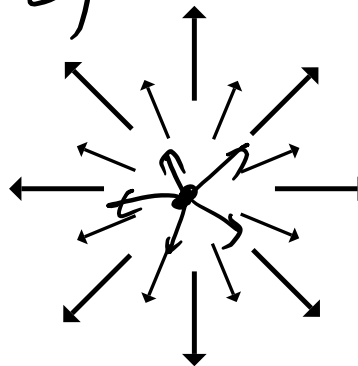
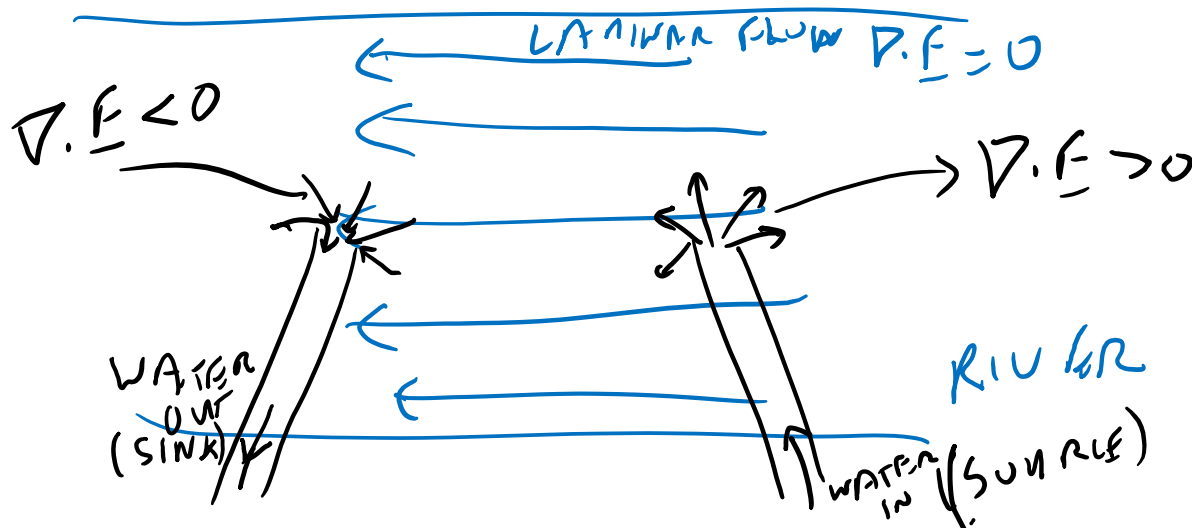
- Scalar product of Del operator with a vector field

$$\text{VECTOR} \quad \nabla \cdot \text{SCALAR} \quad \text{Div } F = \begin{pmatrix} \partial/\partial x \\ \partial/\partial y \\ \partial/\partial z \end{pmatrix} \cdot \begin{pmatrix} F_x \\ F_y \\ F_z \end{pmatrix} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$$

- F can represent flux of a quantity, e.g. directional flow of a fluid per unit area

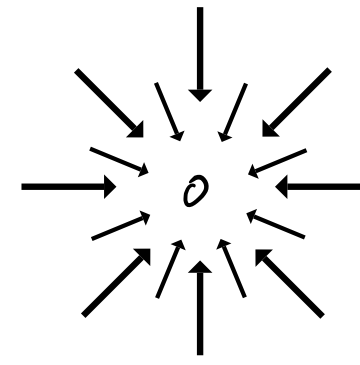


$\nabla \cdot F$ REPRESENTS EXPANSION (> 0)
CONPRESSION (< 0)



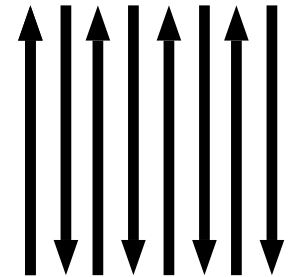
$$\begin{aligned} \frac{\partial}{\partial x}(\mathbf{V}_x) &> 0 \\ \frac{\partial}{\partial y}(\mathbf{V}_y) &> 0 \\ \nabla \cdot (\mathbf{V}) &> 0 \end{aligned}$$

SOURCE



$$\begin{aligned} \frac{\partial}{\partial x}(\mathbf{V}_x) &< 0 \\ \frac{\partial}{\partial y}(\mathbf{V}_y) &< 0 \\ \nabla \cdot (\mathbf{V}) &< 0 \end{aligned}$$

SINK



$$\begin{aligned} \frac{\partial}{\partial x}(\mathbf{V}_x) &= 0 \\ \frac{\partial}{\partial y}(\mathbf{V}_y) &= 0 \\ \nabla \cdot (\mathbf{V}) &= 0 \end{aligned}$$

Curl

- Cross Product of Del operator with a vector field

$$\text{Curl } \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} = \left(\frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \right) \hat{i} - \left(\frac{\partial F_z}{\partial x} - \frac{\partial F_x}{\partial z} \right) \hat{j} + \left(\frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right) \hat{k}$$

VECTOR VECTOR

- $\nabla \times \mathbf{F}$ represents the degree of circulation of \mathbf{F} about a point in space

- CURL PERPENDICULAR TO CIRCULAR DIRECTION

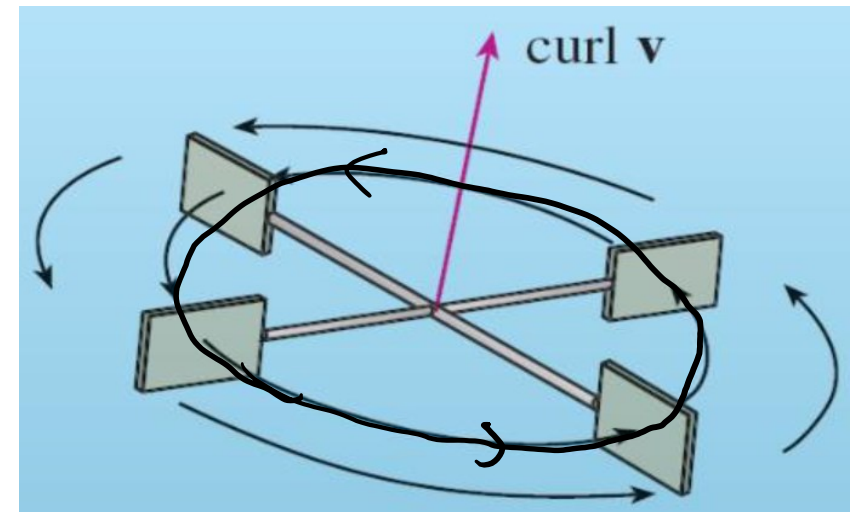
RIGHT HAND \leftarrow FINGERS \underline{F}
 — THUMB $\nabla \times \underline{F}$

$$\boxed{\nabla \times \underline{F} = 0}$$

FIELD IS CONSERVATIVE

WORK DONE IS INDEPENDENT OF
 PATH

E.G. GRAVITY



Laplacian ∇^2

- Div. (Grad Φ) = $\underline{\nabla} \cdot (\underline{\nabla} \Phi) = \boxed{\nabla^2} \Phi$
- Can act on scalar or vector quantity

- Wave equation in 1D

$$\underbrace{\frac{\partial^2 \Phi}{\partial x^2}} = \frac{1}{v^2} \frac{\partial^2 \Phi}{\partial t^2}$$

- Wave equation in 3D

$$\underbrace{\nabla^2 \Phi}_{\text{SCALAR}} = \frac{1}{v^2} \frac{\partial^2 \Phi}{\partial t^2}$$

$$\nabla^2 = \frac{\partial}{\partial x^2} + \frac{\partial}{\partial y^2} + \frac{\partial}{\partial z^2}$$

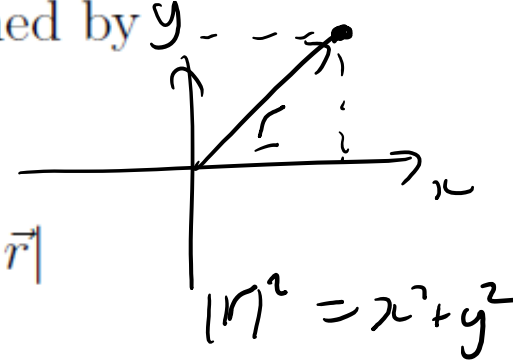
SCALAR
OPERATOR

SCALAR \longrightarrow SCALAR
VECTOR \longrightarrow VECTOR

Example – PHY2006 exam 2019-20

A.4 Consider the velocity distribution, \vec{v} , for points in the (x, y) -plane defined by

where $\vec{v} = \vec{\Omega} \times \vec{r}$
 $\vec{\Omega} = (0, 0, \cos(\pi r))$ $\vec{r} = (x, y, 0)$ and $r = |\vec{r}|$



(a) Calculate the velocity \vec{v} at all points in the (x, y) -plane in terms of x , y and r .

Note that $\vec{v} = \vec{\Omega} \times \vec{r}$

$$\begin{aligned} \underline{v} &= \underline{\Omega} \times \underline{r} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & \cos(\pi r) \\ x & y & 0 \end{vmatrix} = -y \cos(\pi r) \hat{i} - (-x \cos(\pi r)) \hat{j} \\ &= -y \cos(\pi r) \hat{i} + x \cos(\pi r) \hat{j} \end{aligned}$$

Example – PHY2006 exam 2019-20

- (b) Draw a schematic diagram to show the velocity vector field; indicate the direction and magnitude of the velocity at different points in the (x, y) -plane with arrows. (*Hint: Consider how the velocity depends on r and consider the cases $r = 1$ and $r = 2$.)* [2]

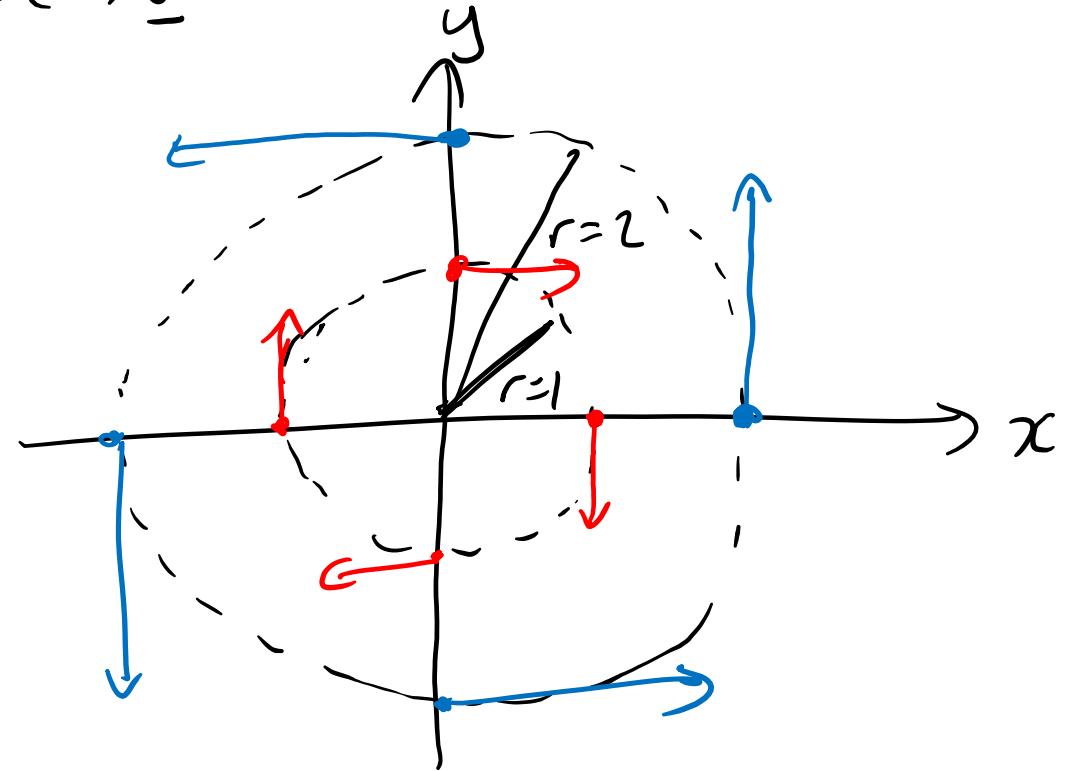
$$\underline{V} = -y \cos(\pi r) \underline{i} + x \cos(\pi r) \underline{j}$$

$$r=1 \quad \cos(\pi r) = -1$$

$$r=2 \quad \cos(2\pi) = +1$$

$$\underline{V}(r=1) = y \underline{i} - x \underline{j}$$

$$\underline{V}(r=2) = -y \underline{i} + x \underline{j}$$



Example – PHY2006 exam 2019-20

(c) Calculate the divergence of the velocity; $\text{div } \vec{v} = \nabla \cdot \vec{v}$

(d) Calculate the rotational of the velocity; $\text{curl } \vec{v} = \nabla \times \vec{v}$

$$r^2 = x^2 + y^2$$

$$2r \frac{\partial r}{\partial x} = 2x$$

$$\frac{\partial r}{\partial x} = \frac{x}{r}$$

$$(c) \quad \nabla \cdot \underline{v} = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} v_x = -y \cos(\pi r) \\ v_y = x \cos(\pi r) \\ v_z = 0 \end{pmatrix} = -y(-\pi \sin(\pi r) \frac{\partial r}{\partial x}) + x(-\pi \sin(\pi r) \frac{\partial r}{\partial y})$$

$$\nabla \cdot \underline{v} = \pi \frac{xy}{r} \sin \pi r - \pi \frac{xy}{r} \sin \pi r = 0$$

$$(d) \quad \nabla \times \underline{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y \cos(\pi r) & x \cos(\pi r) & 0 \end{vmatrix}$$

$$\nabla \times \underline{v} = (2 \cos(\pi r) - \pi \sin(\pi r)) \hat{k}$$

1.4. Taylor's Theorem

Power Series Expansion

Taylor Expansion

- $u(x)$ is a continuous single-valued function of x with continuous derivatives
- Near $x = a$ the value of the function can be approximated by

$$u(\underline{a} + \underline{\Delta x}) = \underline{u(a)} + \Delta x u'(a) + \frac{(\Delta x)^2}{2!} u''(a) + \frac{(\Delta x)^3}{3!} u'''(a) \dots = \sum_{n=0}^{\infty} \frac{(\Delta x)^n}{n!} u^{(n)}(a)$$

$a=0$ EXPAND AROUND $x=0$ MACLAURIN SERIES

- Example expand $u(x) = \ln x$ around $x = 1$ ($a = 1$)

$$\underline{u'} = \frac{1}{x} \quad u'' = -\frac{1}{x^2} \quad u''' = \frac{2}{x^3}$$

$$u(1 + \Delta x) = 0 + \Delta x - \frac{(\Delta x)^2}{2} + \frac{(\Delta x)^3}{3} - \dots$$

$u = \sin x$ AROUND $x=0$ (MACLAURIN)
 $\quad \quad \quad = 0$

$$u' = \cos x \quad u'' = -\sin x \quad u''' = -\cos x$$

$$u(\Delta x) = \Delta x - \frac{(\Delta x)^3}{3!} + \frac{(\Delta x)^5}{5!} \dots$$

Definition of Derivatives

- Taylor's theorem can be used to define derivative
- 1st order $\underline{u(a + \Delta x)} \approx \underline{u(a)} + \underline{\Delta x u'(a)} + \dots$

$$u'(a) = \left. \frac{du}{dx} \right|_a = \lim_{\Delta x \rightarrow 0} \frac{u(a + \Delta x) - u(a)}{\Delta x}$$

- 2nd order $\left. \frac{d^2 u}{dx^2} \right|_a = \lim_{\Delta x \rightarrow 0} \frac{\left. \frac{du}{dx} \right|_{a+\Delta x} - \left. \frac{du}{dx} \right|_a}{\Delta x}$ but using Taylor we can also express

- $u(\underline{a + \Delta x}) \approx u(a) + \Delta x u'(a) + \frac{\Delta x^2}{2!} \underline{u''(a)}$
- $u(\underline{a - \Delta x}) \approx u(a) - \Delta x u'(a) + \frac{\Delta x^2}{2!} u''(a)$

$$u(\underline{a + \Delta x}) + u(\underline{a - \Delta x}) \approx 2 \underline{u(a)} + (\Delta x)^2 \underline{u''(a)}$$

$$u''(a) = \left. \frac{d^2 u}{dx^2} \right|_a = \lim_{\Delta x \rightarrow 0} \frac{u(\underline{a + \Delta x}) + u(\underline{a - \Delta x}) - 2 \underline{u(a)}}{(\Delta x)^2}$$

- Approximate Taylor expression for derivatives key for numerical solutions of DEs

TAYLOR SERIES

$$u(a + \Delta x) = \overset{\text{0th}}{u(a)} + \overset{\text{1st}}{u'(a)} + \overset{\text{2nd}}{u''(a)} + u'''(a) \dots$$

$$\frac{(\Delta x)^0}{0!} \quad \frac{(\Delta x)^1}{1!} \quad \frac{(\Delta x)^2}{2!} \quad \frac{(\Delta x)^3}{3!}$$

$$= u(a) + \Delta x u'(a) + \frac{(\Delta x)^2}{2!} u''(a) \dots$$

$$u(x) = \frac{1}{1-x}$$

AT $x=0$ ($a=0$ MACLAURIN)

$$v = 1 - x \quad \frac{dv}{dx} = -1 \quad \underline{x=0, v=1}$$

$$u(x) = v^{-1}$$

$$u'(x) = -v^{-2} \frac{dv}{dx} = v^{-2}$$

$$u''(x) = -2v^{-3} \frac{dv}{dx} = 2v^{-3}$$

$$u'''(x) = -6v^{-4} \frac{dv}{dx} = 6v^{-4}$$

$u'(0)$	1	1!
$u''(0)$	2	2!
$u'''(0)$	6	3!

$$u(0+x) = u(0) + x u'(0) + \frac{x^2}{2!} u''(0) + \frac{x^3}{3!} u'''(0) \dots$$