

## 5.3 Numerical Solutions to PDEs

# Differentials expressed as finite differences

From the Taylor series

- $u(x + \Delta x) = u(x) + u'(x)\Delta x + O(\Delta x^2)$

Therefore

- $u'(x) = \frac{u(x+\Delta x) - u(x)}{\Delta x} + \frac{O(\Delta x^2)}{\Delta x}$   
 $\quad \quad \quad \underbrace{\hspace{1.5cm}}_{O(\Delta x)}$

On a discrete grid

$$u'_{m+1} = \frac{u_{m+1} - u_m}{\Delta x} + O(\Delta x)$$

# Discrete 2<sup>nd</sup> order differentials

Writing Taylor series

- $u(x + \Delta x) = u(x) + u'(x)\Delta x + \frac{\Delta x^2}{2!}u''(x) + \frac{\Delta x^3}{3!}u'''(x) + O(\Delta x^4)$
- $u(x - \Delta x) = u(x) - u'(x)\Delta x + \frac{\Delta x^2}{2!}u''(x) - \frac{\Delta x^3}{3!}u'''(x) + O(\Delta x^4)$

Adding these together

- $u''(x) = \frac{u(x+\Delta x) - 2u(x) + u(x-\Delta x)}{(\Delta x)^2} + O(\Delta x^2)$

$$u''_m = \frac{u_{m+1} - 2u_m + u_{m-1}}{(\Delta x)^2}$$

# Discrete Heat Equation

$m$  - SPACE ( $x$ )  
 $n$  - TIME ( $t$ )

$$\frac{\partial T}{\partial t} = D \frac{\partial^2 u}{\partial x^2}$$

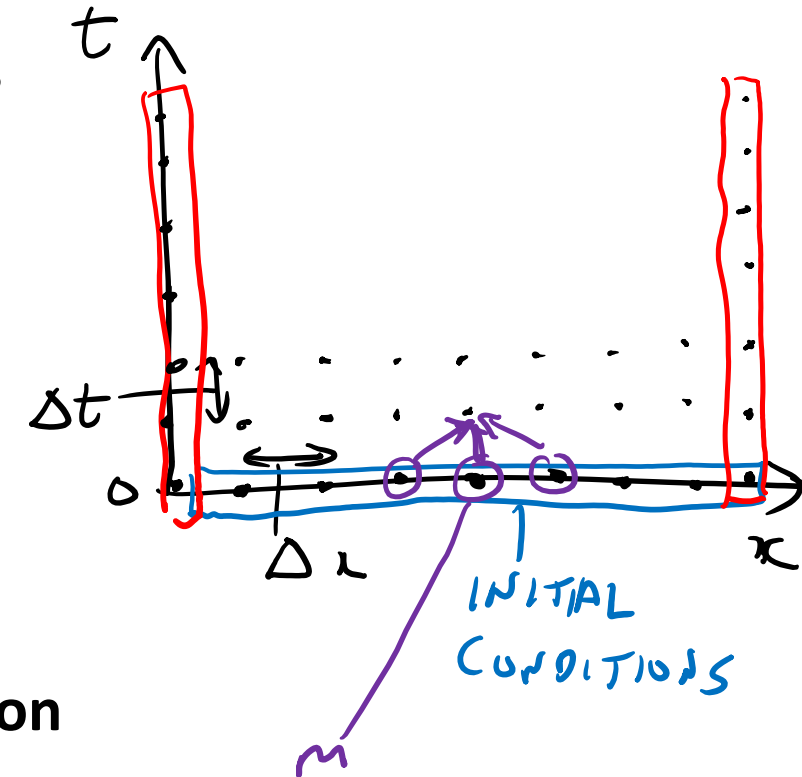
The heat equation is a parabolic 2<sup>nd</sup> order PDE, solved by **marching forward in time**

- The continuous function is mapped onto a grid

Using the discrete finite difference forms of the differentials

$$\frac{\partial T}{\partial t} = \frac{T_{m,n+1} - T_{m,n}}{\Delta t}$$

$$\frac{\partial^2 T}{\partial x^2} = \frac{T_{m+1,n} - 2T_{m,n} + T_{m-1,n}}{(\Delta x)^2}$$



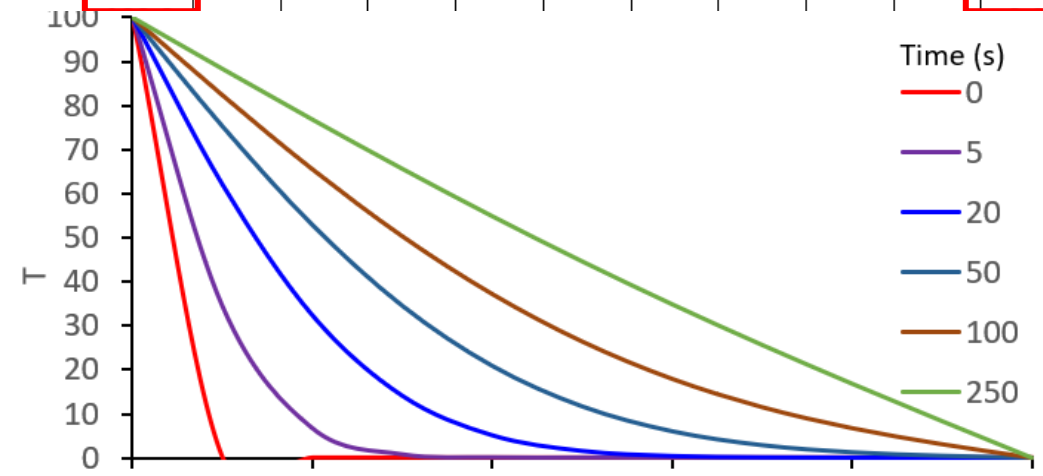
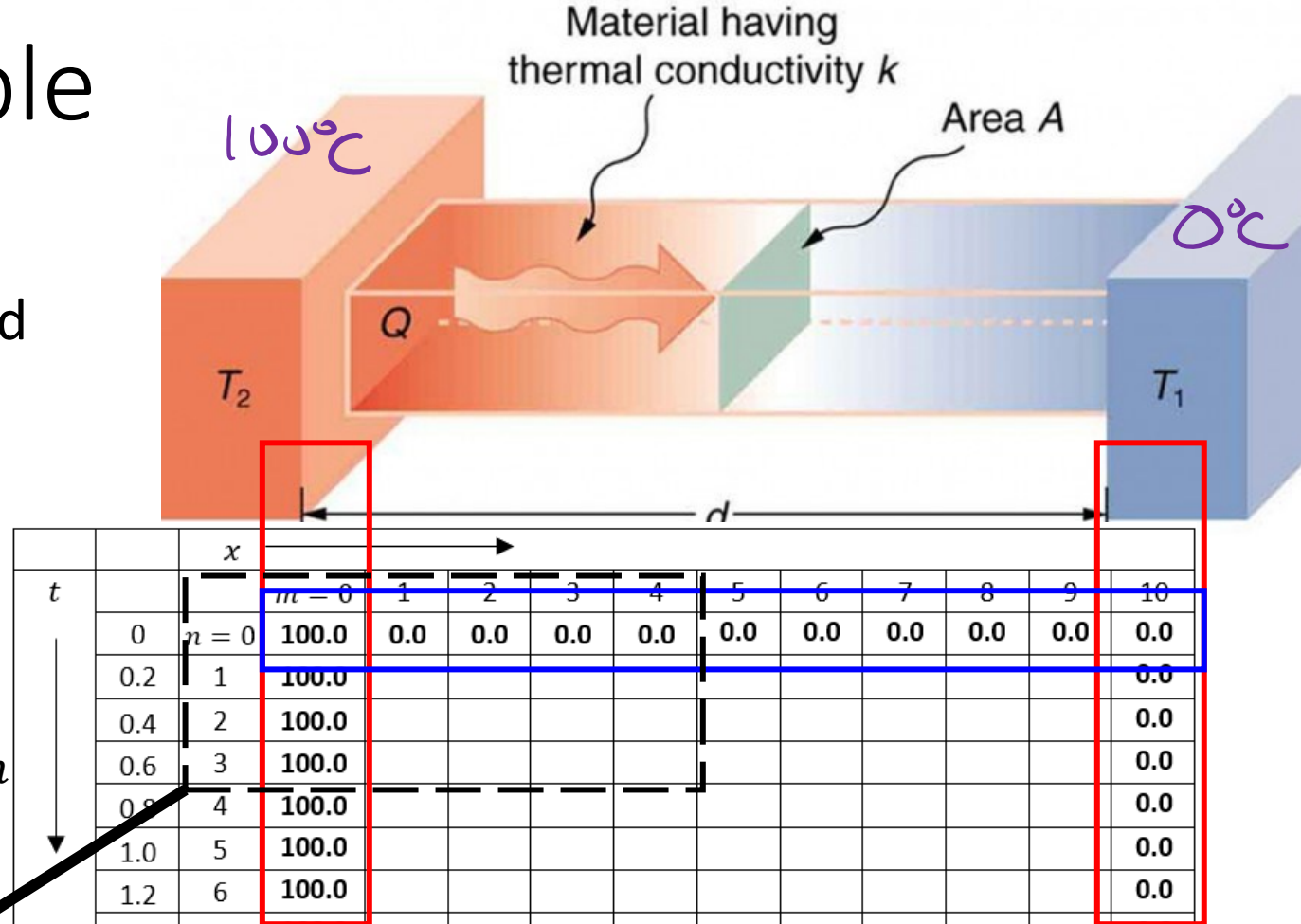
- This gives the Forward in Time (Explicit) **Finite Difference Equation**
- $T_{m,n+1} = \lambda T_{m+1,n} + T_{m,n}(1 - 2\lambda) + \lambda T_{m-1,n}$  where  $\lambda = D \frac{\Delta t}{(\Delta x)^2}$

# Heat Equation Example

- Consider a straight, well insulated metal rod with its ends in good thermal contact with heat reservoirs of temperature  $T_1$  and  $T_2$  with  $\lambda = 0.2$
- BC:  $T(0, t) = 100^\circ\text{C}$ ,  $T(d, t) = 0^\circ\text{C}$
- IC:  $T(x, 0) = 0^\circ\text{C}$ ,  $T(0, 0) = 100^\circ\text{C}$

$$T_{m,n+1} = \lambda T_{m+1,n} + T_{m,n}(1 - 2\lambda) + \lambda T_{m-1,n}$$

	$m=0$	1	2	3	4
$n=0$	100.0	0.0	0.0	0.0	0.0
1	100.0	20.0	0.0	0.0	0.0
2	100.0	32.0	4.0	0.0	0.0
3	100.0	40.0	8.8	0.8	0.0



# Backward (Implicit) Finite Difference Method

- Forward (explicit) method is fast and simple but unstable if  $\lambda > 0.5$
- Backward in time method is implicitly stable
- 2<sup>nd</sup> order space derivative is now evaluated at  $n+1$  rather than  $n$

- $\frac{T_{m,n+1} - T_{m,n}}{\Delta t} \approx D \frac{T_{m+1,n+1} - 2T_{m,n+1} + T_{m-1,n+1}}{(\Delta x)^2}$  *EVALUATED AT NEXT TIME STEP  $n+1$*

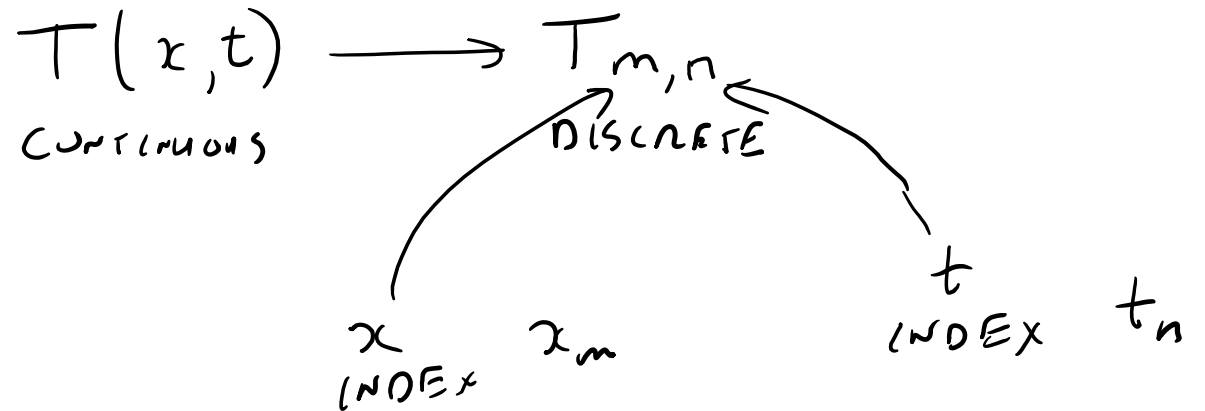
- $T_{m,n} = -\lambda T_{m+1,n+1} + T_{m,n+1}(1 + 2\lambda) - \lambda T_{m-1,n+1}$  where  $\lambda = D \frac{\Delta t}{(\Delta x)^2}$

	$m = 0$	1	2	3
$n = 0$	100.0	0.0	0.0	0.0
1	100.0	$\times -\lambda$	$\times (1 + 2\lambda)$	$\times -\lambda$
2	100.0			
3	100.0			

- Linear algebra algorithms used to solve the resulting simultaneous equations
- Implicit methods slower than explicit but stable

$$\left( \frac{\partial T}{\partial t} \right) = D \left( \frac{\partial^2 T}{\partial x^2} \right)$$

$x$  CONSTANT  $m$  "   
 $t$  CONSTANTS  $n$  "



$$\frac{T_{m, n+1} - T_{m, n}}{\Delta t} = D \frac{T_{m+1, n} - 2T_{m, n} + T_{m-1, n}}{(\Delta x)^2}$$

$$T_{m, n+1} = \lambda T_{m+1, n} + (1 - 2\lambda) T_{m, n} + \lambda T_{m-1, n}$$

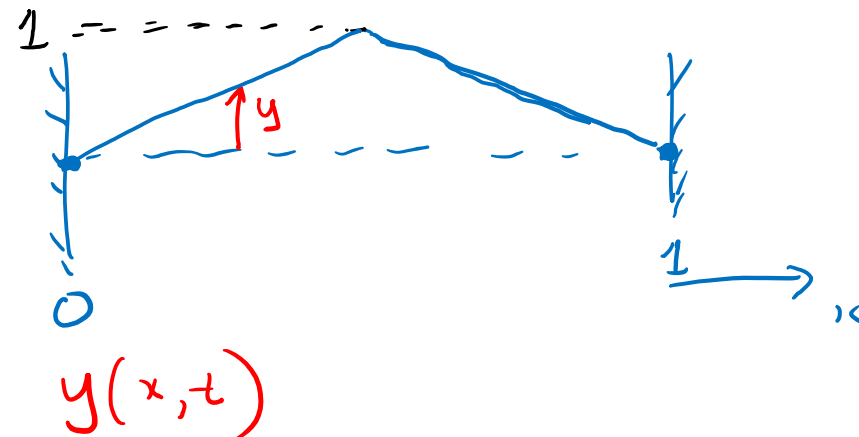
FORWARD IN TIME SOLUTION

$$\lambda = \frac{\Delta t}{(\Delta x)^2} D$$

METHOD FORWARD	$\left. \frac{\partial^2 T}{\partial x^2} \right _n$	EXPLICIT	FAST	UNSTABLE $\lambda > 0.5$
BACKWARD	$\left. \frac{\partial^2 T}{\partial x^2} \right _{n+1}$	IMPLICIT	SLOW	STABLE INHERENTLY
CRANK-NICOLSON	→ MORE ACCURATE		$\left. \frac{\partial^2 T}{\partial x^2} \right _{n+\frac{1}{2}} = \frac{1}{2} \left( \left. \frac{\partial^2 T}{\partial x^2} \right _n + \left. \frac{\partial^2 T}{\partial x^2} \right _{n+1} \right)$	

**C.2** A wire of length  $L = 1$  m and density per unit length  $\mu = 0.01 \text{ kg m}^{-1}$ , is attached rigidly at both ends and placed under tension  $T = 1$  N. At a position  $x$  along the wire, it is displaced a distance  $y(x, t)$  from equilibrium at time  $t$ . The motion of the wire is governed by the wave equation

$$\frac{\mu}{T} \frac{\partial^2 y}{\partial t^2} = \frac{\partial^2 y}{\partial x^2}$$



(a) The following is a Taylor expansion to third order for a function  $u(x)$

$$u(x + \Delta x) = u(x) + \underline{\Delta x} u'(x) + \frac{\Delta x^2}{2!} \underline{u''(x)} + \frac{\Delta x^3}{3!} u'''(x) + O(\Delta x^4)$$

By considering  $u(x + \Delta x)$  and  $u(x - \Delta x)$ , obtain an approximate expression for the second order derivative  $u''(x)$ . To what order of  $\Delta x$  does the error in this expression depend?

$$u(x - \Delta x) = u(x) - \Delta x u'(x) + \frac{(\Delta x)^2}{2!} u''(x) - \frac{(\Delta x)^3}{3!} u'''(x) + O(\Delta x^4)$$

$$u(x + \Delta x) + u(x - \Delta x) = 2u(x) + (\Delta x)^2 u''(x) + O(\Delta x^4)$$

$$u''(x) = \frac{u(x + \Delta x) - 2u(x) + u(x - \Delta x)}{(\Delta x)^2} + \underbrace{\frac{O(\Delta x^4)}{(\Delta x)^2}}_{O(\Delta x)^2}$$



- (b) To obtain a solution to the wave equation,  $y(x, t)$  can be represented on a grid  $y_{m,n}$  and solved numerically. Show that the wave equation can be written as the following finite difference equation

$$y(x, t) \longrightarrow y_{m,n}$$

$$y_{m,n+1} = r(y_{m+1,n} + y_{m-1,n}) + 2y_{m,n}(1 - r) - y_{m,n-1}$$

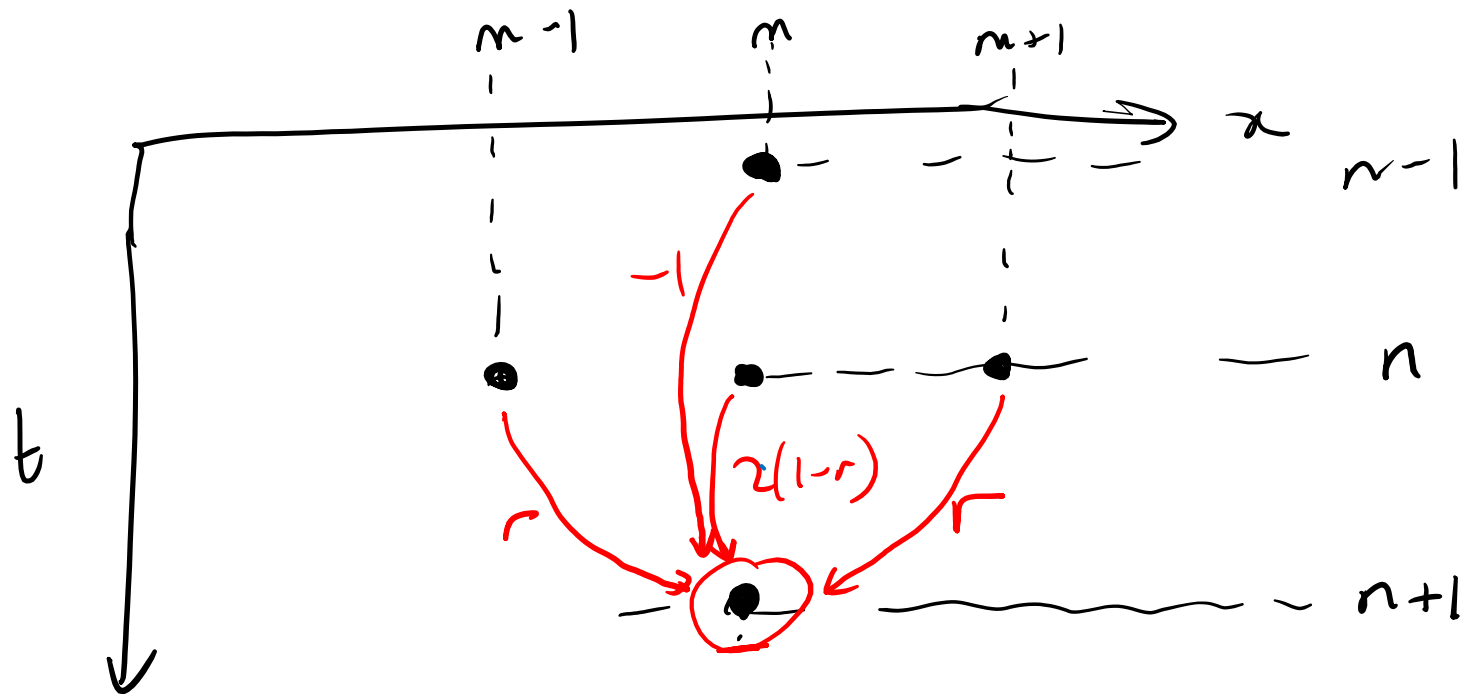
where  $m, n$  are the grid indices for the variables  $x, t$  and

$$r = \frac{T}{\mu} \left( \frac{\Delta t}{\Delta x} \right)^2$$

$$\underbrace{\frac{\mu}{T} \frac{\partial^2 y}{\partial t^2}}_{\mu \text{ constant } m} = \underbrace{\frac{\partial^2 y}{\partial x^2}}_{t \text{ constant } n}$$

$$\frac{\mu}{T} \frac{y_{m,n+1} - 2y_{m,n} + y_{m,n-1}}{(\Delta t)^2} = \frac{y_{m+1,n} - 2y_{m,n} + y_{m-1,n}}{(\Delta x)^2}$$

$$\underbrace{y_{m,n+1} - 2y_{m,n} + y_{m,n-1}}_r = \underbrace{\frac{T}{\mu} \frac{(\Delta t)^2}{(\Delta x)^2}}_r (y_{m+1,n} - 2y_{m,n} + y_{m-1,n})$$



(c) The wire is pulled a distance  $y = 1$  from equilibrium at its midpoint and released from rest so that

$$y(x, 0) = \begin{cases} 2x & \text{for } 0 < x < 1/2 \\ 2(1-x) & \text{for } 1/2 < x < 1 \end{cases}$$

A numerical solution based on the grid shown below (where  $\Delta x = 0.25$ ,  $\Delta t = 0.01$ ) can be obtained using these initial conditions by “marching forward in time”. Explaining your methodology, fill the first 3 rows of this grid with the values of  $y_{m,n}$  for  $n = 0, 1, 2$ .

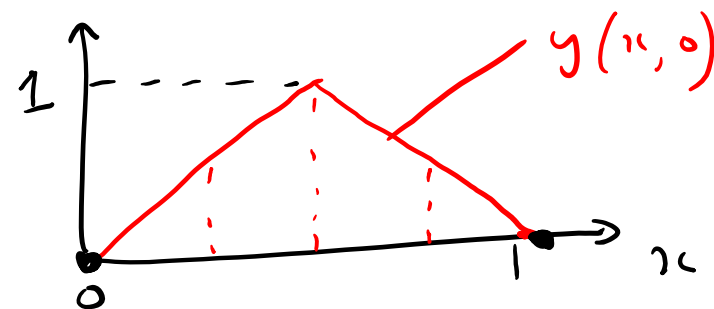
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n \ m	x	0	1	2	3	4
		0.0	0.25	0.50	0.75	1.0
0	t	0.00	0.5	1	0.5	0
1	t	0.01	0	0.5	0.84	0.5
2	t	0.02	0	0.47	0.57	0.47

As the wire is originally at rest you may assume that  $y_{m,-1} = y_{m,0}$

$$y_{1,1} = 0.16(0 + 1) + \underbrace{2(1 - 0.16)}_{1.68}(0.5) = 0.5$$

$$y_{2,1} = 0.16(0.5 + 0.5) + (1.68)(1) = 0.84$$



INITIAL CONDITIONS

$$1. \ y(x, 0)$$

$$2. \ \left. \frac{\partial y}{\partial t} \right|_{t=0} = 0$$

BOUNDARY CONDITIONS

$$1. \ y(0, t) = 0$$

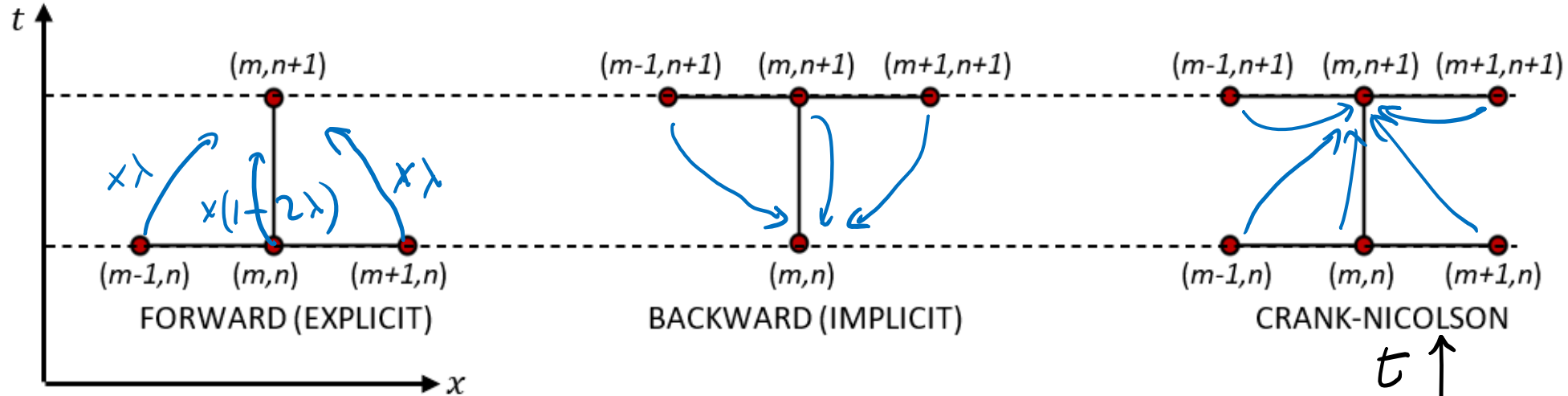
$$2. \ y(1, t) = 0$$

$$r = \frac{T}{\mu} \left( \frac{\Delta t}{\Delta x} \right)^2 = \frac{1}{0.01} \left( \frac{0.01}{0.25} \right)^2$$

$$r = 0.16$$

# Stencils

- Stencils show how grid values are determined by surrounding points
- For **Parabolic equations** such as Heat and Schrodinger Equation

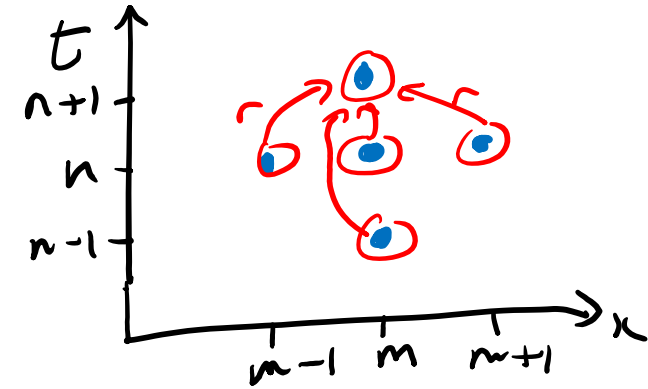


- For **Hyperbolic equations** such as the wave equation

$$v^2 \frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial t^2}$$

$$u(x, t) \rightarrow u_{m,n}$$

$\uparrow$   $\uparrow$   
 $x$   $t$



$$v^2 \frac{u_{m+1,n} - 2u_{m,n} + u_{m-1,n}}{(\Delta x)^2} = \frac{u_{m,n+1} - 2u_{m,n} + u_{m,n-1}}{(\Delta t)^2}$$

$$u_{m,n+1} = r(u_{m+1,n} + u_{m-1,n}) + 2u_{m,n}(1 - r) - u_{m,n-1} \text{ where } r = \left(\frac{v\Delta t}{\Delta x}\right)^2$$

# Elliptical PDEs – Relaxation Techniques

- E.g. Laplace/Poisson's Equation

- $$\frac{\partial^2 V(x,y)}{\partial x^2} + \frac{\partial^2 V(x,y)}{\partial y^2} = 0$$

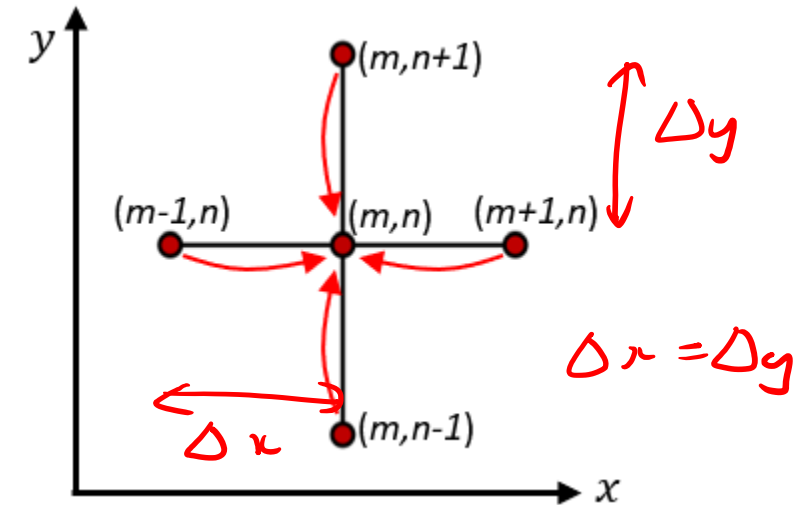
- $$\frac{V_{m,n-1} - 2V_{m,n} + V_{m,n+1}}{(\Delta x)^2} + \frac{V_{m+1,n} - 2V_{m,n} + V_{m-1,n}}{(\Delta y)^2} = 0$$

- If  $\Delta x = \Delta y$

- $$V_{m,n} = \frac{1}{4} (V_{m,n-1} + V_{m,n+1} + V_{m+1,n} + V_{m-1,n})$$

$V(x,y) \rightarrow V_{m,n}$   
↑  $x$     ↑  $y$

NO TIME  
DEPENDENCE



# Relaxation Techniques

- All grid points are calculated. This is repeated many times (iterations) until convergence

Iteration 0

0	0	100	100	100	100	100	100	100	0	0
0	0	0	0	0	0	0	0	0	0	0
-100	0	0	0	0	0	0	0	0	0	-100
-100	0	0	0	0	0	0	0	0	0	-100
-100	0	0	0	0	0	0	0	0	0	-100
-100	0	0	0	0	0	0	0	0	0	-100
-100	0	0	0	0	0	0	0	0	0	-100
-100	0	0	0	0	0	0	0	0	0	-100
-100	0	0	0	0	0	0	0	0	0	-100
-100	0	0	0	0	0	0	0	0	0	-100
0	0	0	0	0	0	0	0	0	0	0
0	0	100	100	100	100	100	100	100	0	0

Iteration 1

0	33.3	100	100	100	100	100	100	100	33.3	0
-33	0	25	25	25	25	25	25	25	0	-33
-100	-25	0	0	0	0	0	0	0	-25	-100
-100	-25	0	0	0	0	0	0	0	-25	-100
-100	-25	0	0	0	0	0	0	0	-25	-100
-100	-25	0	0	0	0	0	0	0	-25	-100
-100	-25	0	0	0	0	0	0	0	-25	-100
-100	-25	0	0	0	0	0	0	0	-25	-100
-100	-25	0	0	0	0	0	0	0	-25	-100
-100	-25	0	0	0	0	0	0	0	-25	-100
-33	0	25	25	25	25	25	25	25	0	-33
0	33.3	100	100	100	100	100	100	100	33.3	0

Iteration 2

0	33.3	100	100	100	100	100	100	100	33.3	0
-33	0	31.3	37.5	37.5	37.5	37.5	37.5	31.3	0	-33
-100	-31	0	6.25	6.25	6.25	6.25	6.25	0	-31	-100
-100	-38	-6.3	0	0	0	0	0	-6.3	-38	-100
-100	-38	-6.3	0	0	0	0	0	-6.3	-38	-100
-100	-38	-6.3	0	0	0	0	0	-6.3	-38	-100
-100	-38	-6.3	0	0	0	0	0	-6.3	-38	-100
-100	-38	-6.3	0	0	0	0	0	-6.3	-38	-100
-100	-38	-6.3	0	0	0	0	0	-6.3	-38	-100
-100	-38	-6.3	0	0	0	0	0	-6.3	-38	-100
-33	0	31.3	37.5	37.5	37.5	37.5	37.5	31.3	0	-33
0	33.3	100	100	100	100	100	100	100	33.3	0

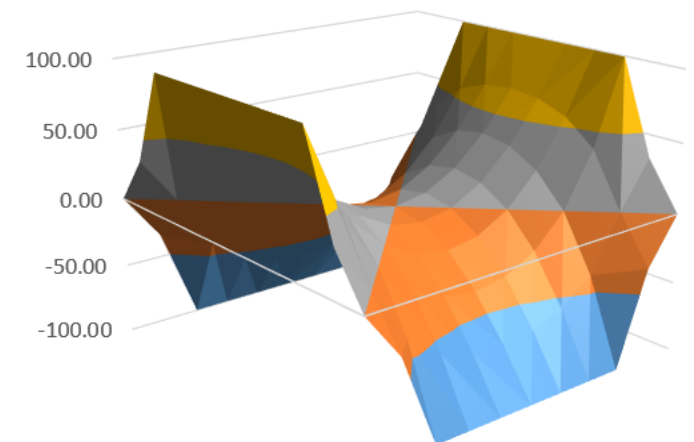
Iteration 20

0.00	33.33	100	100	100	100	100	100	100	33.33	0.00
-33.33	0.00	39.12	56.51	64.33	66.61	64.33	56.51	39.12	0.00	-33.33
-100	-39.12	0.00	22.70	34.40	38.00	34.40	22.70	0.00	-39.12	-100
-100	-56.51	-22.70	0.00	12.78	16.89	12.78	0.00	-22.70	-56.51	-100
-100	-64.33	-34.40	-12.78	0.00	4.21	0.00	-12.78	-34.40	-64.33	-100
-100	-66.61	-38.00	-16.89	-4.21	0.00	-4.21	-16.89	-38.00	-66.61	-100
-100	-64.33	-34.40	-12.78	0.00	4.21	0.00	-12.78	-34.40	-64.33	-100
-100	-56.51	-22.70	0.00	12.78	16.89	12.78	0.00	-22.70	-56.51	-100
-100	-39.12	0.00	22.70	34.40	38.00	34.40	22.70	0.00	-39.12	-100
-33.33	0.00	39.12	56.51	64.33	66.61	64.33	56.51	39.12	0.00	-33.33
0.00	33.33	100	100	100	100	100	100	100	33.33	0.00

Iteration 20 – Iteration 19

0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
0.00	0.00	0.01	0.03	0.06	0.07	0.06	0.03	0.01	0.00	0.00
0.00	-0.01	0.00	0.04	0.08	0.09	0.08	0.04	0.00	-0.01	0.00
0.00	-0.03	-0.04	0.00	0.05	0.07	0.05	0.00	-0.04	-0.03	0.00
0.00	-0.06	-0.08	-0.05	0.00	0.02	0.00	-0.05	-0.08	-0.06	0.00
0.00	-0.07	-0.09	-0.07	-0.02	0.00	-0.02	-0.07	-0.09	-0.07	0.00
0.00	-0.06	-0.08	-0.05	0.00	0.02	0.00	-0.05	-0.08	-0.06	0.00
0.00	-0.03	-0.04	0.00	0.05	0.07	0.05	0.00	-0.04	-0.03	0.00
0.00	-0.01	0.00	0.04	0.08	0.09	0.08	0.04	0.00	-0.01	0.00
0.00	0.00	0.01	0.03	0.06	0.07	0.06	0.03	0.01	0.00	0.00
0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

Laplace Solution for quadrupole field



- Faster convergence can be obtained using over-relaxation (see notes)