

# Investigating the Impact of AI Techniques on Inter-Flock Dynamics

Matt Hunter

2019-02-17

## Contents

<b>1</b>	<b>Abstract</b>	<b>1</b>
<b>2</b>	<b>Introduction</b>	<b>2</b>
2.1	General Introduction and Background Information . . . . .	2
2.2	Aim, Objectives and Research Question . . . . .	2
<b>3</b>	<b>Literature Review</b>	<b>4</b>
3.1	Flocking in Nature - Swarm Behaviour . . . . .	4
3.2	Flocking Algorithm . . . . .	4
3.3	The Interaction of Flocking Algorithms . . . . .	5
3.4	Genetic Algorithm . . . . .	5
3.5	The Effect of AI on Flocking Algorithms . . . . .	5
3.6	The Interaction of an AI Flock with another Flock . . . . .	5

## List of Figures

## List of Tables

# 1 Abstract

**Context** Artificial intelligence is a rapidly expanding field, there is a clear useful context in their use in Flocking Techniques.

**Aim** Investigate the impact of AI techniques on the dynamic interaction of flocks with each other to see if this has a beneficial effect in comparison to regular flocking algorithms.

**Method - description here needs updating!** Using an application that models flocking behaviour (developed by the author), observe and compare AI flocking strategies to those of regular flocking algorithms. This will be developed using the AI techniques found to be most likely to produce viable intelligent flocking behaviour.

**Results** The analysis of the effectiveness of strategies that the AI come up with in their interactions with other flocks, with contrast and comparison to the behaviour of standard flocking algorithms.

**Conclusion** This project will display the flocking strategies that emerge in their interactions with other flocks, and conclude on their effectiveness in relation to other strategies and flock type. This will demonstrate the impact the AI techniques have on this kind of flocking interaction.

## 2 Introduction

### 2.1 General Introduction and Background Information

Flocking is a behaviour in which all social organisms engage; it is the common movement of organisms guided by both social and environmental pressures. These flocks of organisms can be found interacting with other flocks in nature, and the way they interact is as varied as it is interesting.

Producing flocking behavior that recreates those found in nature is an endeavor already undertaken and in constant update. The field, taking off in 1987 with Craig Reynolds' influential paper (Reynolds 1987), shows how realistic flocking behaviour can already be achieved by applying 3 simple rules to each boid ('boid' as coined in the prior paper, this is essentially an agent) in regard to its neighbours: Cohesion, movement toward the average position; Alignment, movement toward the average direction; and Separation, movement to avoid collision.

Since then, the original flocking algorithm has been extended in various ways, with communication techniques, mathematical models for how leadership arises in the flock, as well as models for how consensus is made in a flock. These expansions allow for more complex behaviours and reactions to the environment and surroundings.

Learning behaviours have also been added. The behaviour and strategies flocks produce are patterns. This means if a flock can learn and understand those patterns it has a significant advantage over that other flock – an interesting example would be a group of honey hunters and smoke; bees flee the nest if they think there is a fire, the first warning sign to this is smoke, as a group (or flock) they take advantage of this by releasing smoke into the hive. The bees evacuate the nest; they get honey.

This dissemination of new knowledge, either through behaviour or communication is interesting because it can increase the complexity of the reactions the flock has to a given situation. This added complexity may lead to new behaviours that may not have been easily predicted or thought of as something a flock could produce.

### 2.2 Aim, Objectives and Research Question

**Aim** To investigate the impact of a genetic algorithm on the dynamic interaction of flocks with each other to see if this has a beneficial effect in comparison to regular flocking algorithms.

#### Objectives

- To research and evaluate AI techniques, studying their relevance and potential for further development in applying them to flocking algorithms, with particular focus on artificial life techniques.

- To produce an application that models flocking behaviour, and allows the observation and comparison of AI flocking strategies to regular flocking algorithms. This will be developed using the prior identified AI techniques most likely to produce viable flocking behaviours.
- To analyse the effectiveness of strategies that the AI come up with in their interactions with other flocks, comparing and contrasting that to the behavior of standard flocking algorithms.

**Research Question** What impact can a genetic algorithm have on the dynamic interaction of flocks with each other in comparison to that of regular flocking techniques?

## 3 Literature Review

### 3.1 Flocking in Nature - Swarm Behaviour

Flocking algorithms draw a lot of their inspiration from the behaviour of flocks in the natural world (Flake 1998). As there are many examples of this behaviour in organisms across the planet, there is a lot of information and insight that can be gleaned on how to design these algorithms. Flocks are included in the field of Swarm Behaviour, that is, the study of swarms in the natural world

**Decision Making** The way decisions are made in a flock emerges is varied. The two main ways are via consensus and leadership. An interesting look at this can be found in the behaviour of pigeons. A study conducted into the behaviour of these birds in a flock (Jorge & Marques 2012) found that leadership initially emerged from younger pigeons in the flock, but as the flight went on older members of the flock led the group, the paper then goes on to discuss how social versus personal information affects the behaviour of the flock. What this displays, is how the extra experience of older members of the flock is taken advantage of in determining leadership and therefore the actions they take as a flock, in this way they build consensus on their leadership through the choices individual flock members make in their group. This is further confirmed in '*Misinformed leaders lose influence over pigeon flocks*' Watts et al. (2016). What this displays is the interaction between consensus and leadership in making decisions, and demonstrates that they can both be present in the process.

**Eusocial Behaviour** While not specifically flocking as it pertains to biology, this falls under the bracket of swarm behaviour and has interesting relationships which can inform us on how to expand flocking algorithms in beneficial ways. For example, communication can occur in a variety of ways; ants use pheromones to find shortest paths (Dorigo & Gambardella 1997); bees use a waggle dance

#### Dynamic Adaptation to Environmental Pressures

**Why this is relevant** This is relevant as it inspires the work done in flocking algorithms and the work of similar fields, which has influence on the design of said algorithms.

### 3.2 Flocking Algorithm

Flocking algorithms draw inspiration from the natural world, however the design of these algorithms involves mathematical approximations of the behaviours involved, the interactions that take place and the systems overall.

**Reynolds Boids** In the often cited paper when it comes to discussions of flocks: '*Flocks, herds and schools: A distributed behavioral model*' Reynolds (1987), we see that we have the three main forces that make up a basic flock: Separation, Cohesion and Alignment. These are approximative forces that represent the aggregate motion of a collection of boids (representing flock members, which in turn can represent different species in nature).

**Expanded Boids**

**Decision Making**

**Learning and Curiosity**

### **3.3 The Interaction of Flocking Algorithms**

In the paper '*Simulating Species Interactions and Complex Emergence in Multiple Flocks of Boids with GPUs*' Husselmann & Hawick (2011)

### **3.4 Genetic Algorithm**

### **3.5 The Effect of AI on Flocking Algorithms**

### **3.6 The Interaction of an AI Flock with another Flock**

## References

- Dorigo, M. & Gambardella, L. M. (1997), ‘Ant colonies for the travelling salesman problem’, *Biosystems* **43**(2), 73 – 81.  
**URL:** <http://www.sciencedirect.com/science/article/pii/S0303264797017085>
- Flake, G. (1998), *The Computational Beauty of Nature: Computer Explorations of Fractals, Chaos, Complex Systems, and Adaptation*, A Bradford book, Cambridge, Massachusetts.  
**URL:** <https://books.google.co.uk/books?id=0aUhuw7fjxMC>
- Husselmann, A. & Hawick, K. (2011), Simulating species interactions and complex emergence in multiple flocks of boids with gpus, in ‘Proc. IASTED International Conference on Parallel and Distributed’, IASTED, pp. 100–107.
- Jorge, P. E. & Marques, P. A. M. (2012), ‘Decision-making in pigeon flocks: a democratic view of leadership’, *Journal of Experimental Biology* **215**(14), 2414–2417.  
**URL:** <http://jeb.biologists.org/content/215/14/2414>
- Reynolds, C. W. (1987), ‘Flocks, herds and schools: A distributed behavioral model’, *SIGGRAPH Comput. Graph.* **21**(4), 25–34.  
**URL:** <http://doi.acm.org/10.1145/37402.37406>
- Watts, I., Nagy, M., de Perera, T. B. & Biro, D. (2016), ‘Misinformed leaders lose influence over pigeon flocks’, *Biology Letters* **12**(9), 20160544.  
**URL:** <https://royalsocietypublishing.org/doi/abs/10.1098/rsbl.2016.0544>