

Vinogradov Sergey

📍 Moscow, Russia ✉ vinogradov.so@phystech.edu ☎ +79174991699 in [biscuitslayer](#) 🍪 [BiscuitsLayer](#)

Experience

Beagle, Senior Backend Developer

- Built template system for documents processing with flexible configuration
- Implemented Excel/CSV export functionality with advanced filtering capabilities
- Developed complex search and highlight logic with persistent annotation storage and retrieval
- Improved dataset indexing system with user-specific parameters and multi-format document support

Belgrade, Serbia
Jun 2025 – Ongoing

SberDevices, Computer Vision Engineer

- Developed an algorithm for detecting damaged QR-codes based on alignment patterns grid
- Improved the binarization stage of the QR-code detection pipeline, which resulted in increased detection stability
- Used graph algorithms to detect corrupted finder and alignment patterns

Moscow, Russia
Apr 2025 – Jun 2025

QLAN.AI, Technical Lead

- Developed a micro-service architecture for processing thermal data from a large number of cameras and sensors
- Worked with Grafana API, made functionality for enabling and disabling metrics, creating and deleting dashboards and panels using API calls
- Made a selenium-based tool for interaction with the Mobotix web interface to receive and send different zone parameters to the camera
- Managed backend development team with 3 engineers

Moscow, Russia
Mar 2025 – Jun 2025

ReML, Computer Vision Engineer / Backend Developer

- Developed backend micro-services for PPE detection with low latency
- Added support for multiple RTSP-stream processing using Gstreamer
- Responsible for Spark-based post-processing module to create events for violation detections on camera

Moscow, Russia
Feb 2025 – May 2025

UBO Group, Computer Vision Engineer

- Developed face-recognition module with FAISS database
- Worked with various vision models and MLLM-s, fine-tuned NNs for segmentation and tracking
- Developed an app to get highlights from a hockey game video for a specific player
- Implemented various filters and algorithms to improve recognition accuracy
- Deployed models to production, did inference testing and optimizations

Moscow, Russia
Oct 2024 – Mar 2025

ScaleGen AI, Backend Developer

- Developed API Gateway setup pipelines using AWS and GCP
- Developed billing service and price estimation for various cloud computing instances
- Responsible for main CLI project
- Added support for on-prem instances, including all networking setup

Mumbai, India (remote)
Oct 2023 – Oct 2024

Huawei, Graphics Engineer




- Built ground-truth raytracer to verify approximations for main RT pipeline
- Improved Vulkan API validation layers
- Added shaders for different materials processing in PBR algorithms
- Responsible for Python CI/CD framework for mobile devices testing and performance measurements

Moscow, Russia
Jul 2021 – Oct 2023

Education

MS	School of Data Analysis, Department of Innovation and High Technology, MIPT + Yandex , Data Science	Sept. 2023 – Ongoing
	<ul style="list-style-type: none">• Courses: CV (2D and 3D), Self-Driving cars, CUDA, MLOps and DevOps courses• Developed a startup for travellers for efficient route building using AI• Diploma on the topic "Method for robust decoding of damaged QR codes with nonlinear geometric distortions for use on mobile devices"	
BS	Department of Radio Engineering and Cybernetics, MIPT , Mathematics and Computer Science	Sept. 2019 – Aug. 2023
	<ul style="list-style-type: none">• Mostly involved in compiler and architecture simulator development• Participated in mobile development and AI hackathons• Diploma on the topic "Mesh Simplification using algorithms and GNNs"	

Projects

RCCarRemoteControl	RCCarRemoteControl 
<ul style="list-style-type: none">• Remote car with Arduino UNO (or Arduino Micro), controlled via Bluetooth• Aruco marker based localization in ROS2• Tools used: Python, Arduino, ROS2	
SmartCarProject	SmartCarProject 
<ul style="list-style-type: none">• OpenGL based self-driving car simulator using RL and CV• Tools used: C++, OpenGL, Assimp, LibTorch, Q-Learning	
Scheme language with LLVM IR Generator and simple Raytracer	SchemeRaytracer 
<ul style="list-style-type: none">• Raytracer on self-made functional programming language with LLVM IR Frontend and C++/OpenGL Backend• Tools used: C++, C, Google Test, GNU Bison, GNU Flex, LLVM IR, OpenGL	

Skills

Science: Math, Linear Algebra, Probability and statistics, Physics and Theoretical mechanics, Algorithms, Graph Algorithms, Concurrency, Deep Learning, Computer Vision, NLP, Self-driving cars, Reinforcement Learning

Languages: C++, C, Assembly, Python, Dart/Flutter, PHP, JavaScript

Tools: PostgreSQL, Docker, Ansible, Spark, Kafka and RabbitMQ, MongoDB, S3 storage, NGINX, Prometheus, Grafana, Loki, Promtail, Swagger, Bootstrap, Selenium

ML Tools: PyTorch, LibTorch, PyTorch Lightning, Tensorflow, OpenCV, GGML, Numpy, Scipy

Graphics: OpenGL, Vulkan, OpenCL, CUDA, RenderDoc, SmartPerf

Robotics: ROS2, Open3D, Carla, Foxglove, Calibration, MPCC

Cloud and Deploy: AWS, GCP, Microsoft Azure, Datacrunch, Gitlab CI/CD

Compilers: Clang, LLVM IR, GNU Bison, GNU Flex