Ahnaf Faisal, 1505005 Raihanul Alam, 1505010 Mahim Mahbub, 1505022 Zahin Wahab, 1505031 Bishal Basak Papan, 1505043

Department of Computer Science and Engineering, Bangladesh University of Engineering and Technology

September 21, 2020

### **Outline:**

- 1 Introduction
- 2 Longest Path Problem is NP-Complete
- 3 Longest Path Problem is in NP
- 4 Longest Path Problem is NP-Hard
- **5** Reduction from 3-SAT problem
- 6 Graph construction
- Reduction From 3-SAT
- 8 Variations
- 9 Problems that Longest Path Problem Reduces To

# Project Management 101

• This is my first project as a manager.



# Project Management 101

- This is my first project as a manager.
- Let's analyze the activities my team has to do for project completion.

# Project Management 101

- This is my first project as a manager.
- Let's analyze the activities my team has to do for project completion.
- Wish me luck!

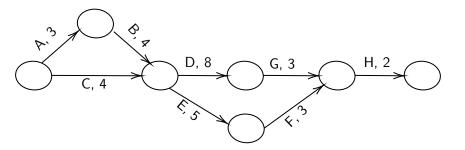


### List of Activities

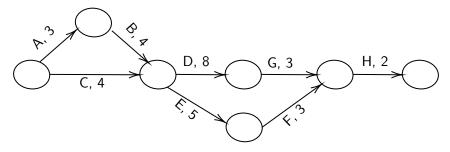
Activity ID	Activity	Duration	Dependencies
А	Market Survey	3	-
С	Provide questionnaires	4	-
В	Research company policies	4	A
D	Data flow analysis	8	B,C
Е	Prototyping	5	B,C
F	Get feedback for prototype	3	Е
G	Cost-benefit analysis	3	D
Н	Prepare and present proposal	2	F,G

Table: Activities, their duration (weeks) and dependencies

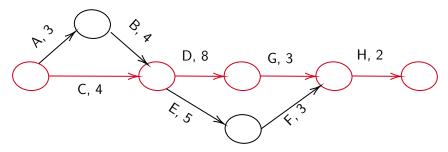
## Analysis using PERT Diagram



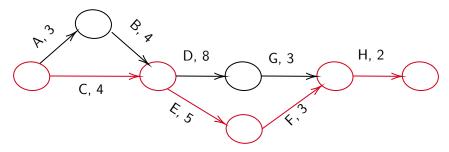
## Analysis using PERT Diagram



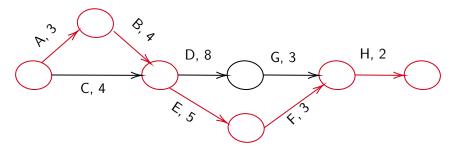
Time to spend resources to reduce total project time and get the well deserved bonus



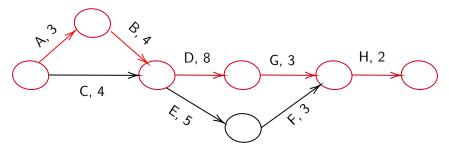
Path duration = 17 weeks



Path duration = 14 weeks



Path duration = 17 weeks



Path duration = 20 weeks !!

This directly leads to the problem we are tasked with analyzing:
 Longest Path Problem.

This directly leads to the problem we are tasked with analyzing: **Longest Path Problem**.

### **Decision Version (Weighted)**

Given a graph G, and an integer k, does the graph G have a longest path of *total weight* at **least** k ?

This directly leads to the problem we are tasked with analyzing: **Longest Path Problem**.

### **Decision Version (Weighted)**

Given a graph G, and an integer k, does the graph G have a longest path of *total weight* at least k?

### **Decision Version (Un-Weighted)**

Given a graph G, and an integer k, does the graph G have a longest path of total number of edges at least k?

## Longest Path Problem is NP-Complete

To prove longest path problem is NP-Complete, we need to prove that

### Longest Path Problem is NP-Complete

To prove longest path problem is NP-Complete, we need to prove that

• it is in NP

## Longest Path Problem is NP-Complete

To prove longest path problem is NP-Complete, we need to prove that

- it is in NP
- and it is NP-Hard.

### Longest Path Problem is in NP

We now prove longest path problem  $\epsilon$  NP

# Longest Path Problem is in NP

We now prove longest path problem  $\epsilon$  NP

• Given an integer k and a permutation of vertices  $v_1, v_2....v_n$  for unweighted graph, we can calculate whether the path between  $v_1$  and  $v_n$  is of length at least k.

# Longest Path Problem is in NP

### We now prove longest path problem $\epsilon$ NP

- Given an integer k and a permutation of vertices  $v_1,v_2....v_n$  for unweighted graph, we can calculate whether the path between  $v_1$  and  $v_n$  is of length at least k.
- Clearly this takes linear time.

## Longest Path Problem is NP-Hard

We now show longest path problem is NP-Hard.

## Longest Path Problem is NP-Hard

We now show longest path problem is NP-Hard.

 To do so, we show that the longest path problem is at least as hard as the 3-SAT problem.

#### Claim

3-SAT  $\leq_p$  Longest Path

• At first, we need to convert an instance of 3-SAT problem to an instance of LongestPath problem.

- At first, we need to convert an instance of 3-SAT problem to an instance of LongestPath problem.
- As the instance of LongestPath problem must be a graph, we will show the process of converting a 3-SAT equation, Y to a LongestPath problem instance, which will be a graph G = (V, E).

- At first, we need to convert an instance of 3 SAT problem to an instance of LongestPath problem.
- As the instance of LongestPath problem must be a graph, we will show the process of converting a 3-SAT equation, Y to a LongestPath problem instance, which will be a graph G = (V, E).
- This construction takes polynomial time.

- At first, we need to convert an instance of 3 SAT problem to an instance of LongestPath problem.
- As the instance of LongestPath problem must be a graph, we will show the process of converting a 3-SAT equation, Y to a LongestPath problem instance, which will be a graph G = (V, E).
- This construction takes polynomial time.

#### Value of k

$$k = 2 + 2n + (3 + n)q$$

#### Claim

Y is satisfiable if and only if G has a path of length at least k.

- At first, we need to convert an instance of 3 SAT problem to an instance of LongestPath problem.
- As the instance of LongestPath problem must be a graph, we will show the process of converting a 3-SAT equation, Y to a LongestPath problem instance, which will be a graph G = (V, E).
- This construction takes polynomial time.

#### Value of k

$$k = 2 + 2n + (3+n)q$$

#### Claim

Y is satisfiable if and only if G has a path of length at least k.

• Now we will show the conversion steps from 3-SAT to LongestPath.

S

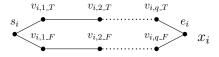
 There is a source vertex s and a destination vertex t in G.

Ĺ

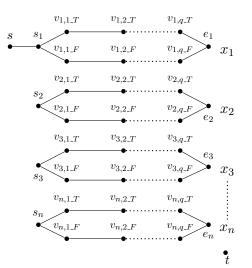
• For each variable  $x_i$  in Y, where  $1 \le i \le n$ , we construct a loop like this



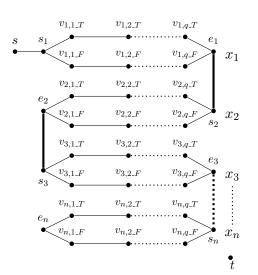
- Every loop has a start vertex, s<sub>i</sub>, and an end vertex, e<sub>i</sub>.
- Each loop contains two paths: upper and lower.
- Each vertex in the path corresponds to the  $\{0,1\}$  or  $\{\mathsf{True}, \, \mathsf{False}\}$  assignment of the variable in a clause  $c_j$ , where  $1 \leq j \leq q$ .
- Number of vertices in each path is q + 2.



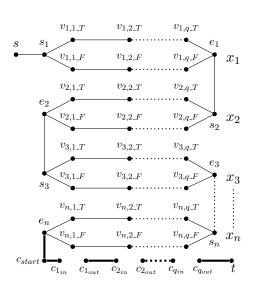
- n number of loops between s and t.
- Start node of the first variable will be adjacent to s.



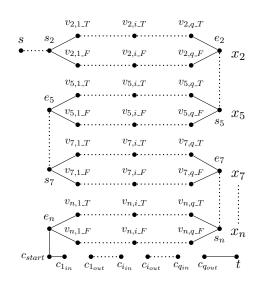
 Edge is added between the end vertex of a variable and the start vertex of its next variable.



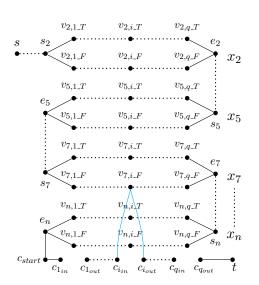
- Two vertices  $(c_{in} \text{ and } c_{out})$  are added per clause,  $c_j$  where  $1 \le j \le q$ .
- Edges are added between the out vertex of one clause to the in vertex of next clause.



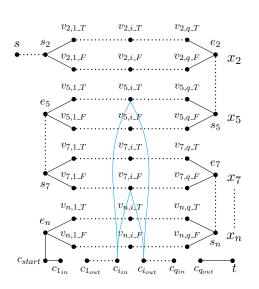
- We will add a gadget for each clause in Y.
- For example, if the  $i^{th}$  clause had the form  $x_7 \bigvee \overline{x_5} \bigvee x_2$  then



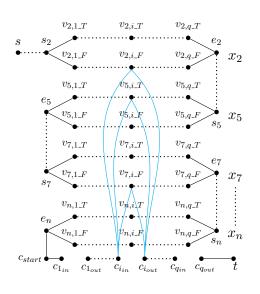
- We will add a gadget for each clause in Y.
- For example, if the  $i^{th}$  clause had the form  $x_7 \bigvee \overline{x_5} \bigvee x_2$  then
- one path would go through a vertex in the lower loop corresponding to x<sub>7</sub>,



- We will add a gadget for each clause in Y.
- For example, if the  $i^{th}$  clause had the form  $x_7 \bigvee \overline{x_5} \bigvee x_2$  then
- one path would go through a vertex in the lower loop corresponding to x<sub>7</sub>,
- another path would go through a vertex in the upper loop corresponding to  $x_5$  and



- We will add a gadget for each clause in Y.
- For example, if the  $i^{th}$  clause had the form  $x_7 \bigvee \overline{x_5} \bigvee x_2$  then
- one path would go through a vertex in the lower loop corresponding to x<sub>7</sub>,
- another path would go through a vertex in the upper loop corresponding to  $x_5$  and
- the third would go through the lower loop corresponding to x<sub>2</sub>.



• Let the 3-SAT equation be,  $Y = (x_1 \bigvee \overline{x_4} \bigvee x_3) \bigwedge (\overline{x_1} \bigvee x_2 \bigvee \overline{x_3}) \bigwedge (x_2 \bigvee x_3 \bigvee \overline{x_4})$ 

• Let the 3-SAT equation be,

$$Y = (x_1 \bigvee \overline{x_4} \bigvee x_3) \bigwedge (\overline{x_1} \bigvee x_2 \bigvee \overline{x_3}) \bigwedge (x_2 \bigvee x_3 \bigvee \overline{x_4})$$

$$-c_1 = (x_1 \bigvee \overline{x_4} \bigvee x_3)$$

$$-c_2 = \left(\overline{x_1} \bigvee x_2 \bigvee \overline{x_3}\right)$$

$$-c_3 = (x_2 \bigvee x_3 \bigvee \overline{x_4})$$

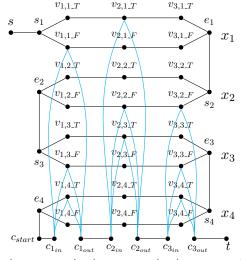
• Let the 3-SAT equation be,  $Y = (x_1 \bigvee \overline{x_4} \bigvee x_3) \bigwedge$   $(\overline{x_1} \bigvee x_2 \bigvee \overline{x_3}) \bigwedge$   $(x_2 \bigvee x_3 \bigvee \overline{x_4})$ 

$$-c_1 = (x_1 \bigvee \overline{x_4} \bigvee x_3)$$

$$-c_2 = \left(\overline{x_1} \bigvee x_2 \bigvee \overline{x_3}\right)$$

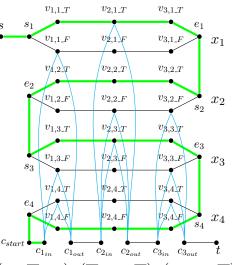
$$-c_3 = (x_2 \bigvee x_3 \bigvee \overline{x_4})$$

• Then the corresponding graph G according to the LongestPath formulation of Y will be:



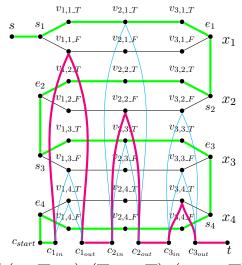
# Finding the Path

- Starting from s, we take exactly one path, either True Path or False Path from each loop representing a variable  $x_i$ . We color this path with green.
- According to this way, after reaching the end vertex of the  $n^{th}$  variable,  $e_n$ , we add  $c_{start}$  and  $c_{1in}$  to the path.



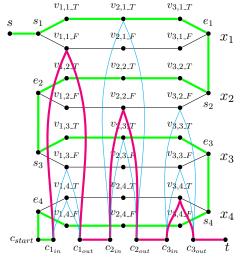
# Finding the Path

- For the gadget corresponding to each clause  $C_i$ , there are three choices.
- For each clause, we take any
  of the three choices so that
  no node on the green path
  is again traversed by the
  chosen path from the
  gadget. We color this path
  with pink.
- We add t to this path.



# Finding the Path

- We denote the path obtained in this way as P.
- Let the length of P be k.



Clearly this construction is polynomial.

#### Set k

$$k = n(q+1) + n - 1 + 2q + q - 1 + 4$$

Clearly this construction is polynomial.

#### Set k

$$k = n(q+1) + n - 1 + 2q + q - 1 + 4$$

### Simplifying

$$k = 2 + 2n + (3 + n)q$$

Clearly this construction is polynomial.

#### Set k

$$k = n(q+1) + n - 1 + 2q + q - 1 + 4$$

### Simplifying

$$k = 2 + 2n + (3 + n)q$$

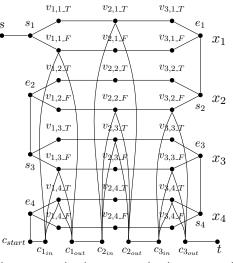
#### Claim

Y is satisfiable if and only if G has a path of length of at least k.

#### Necessity

If Y is satisfiable, then G has a path of length of at least k.

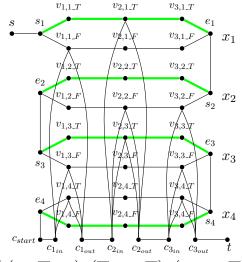
• Since Y is satisfiable, each clause  $c_j$  (where  $1 \le j \le q$ ) is true. There must be at least one true literal per clause.



#### Necessity

If Y is satisfiable, then G has a path of length of at least k.

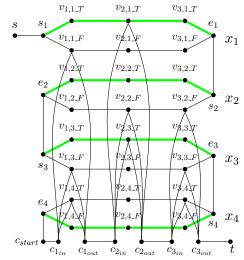
• Since Y is satisfiable, every variable must have an assignment (True or False). So upper path of variable  $x_i$  is taken if it is true and lower path is taken if it is false. Thus for every variable, either lower or upper path is taken.



#### Necessity

If Y is satisfiable, then G has a path of length of at least k.

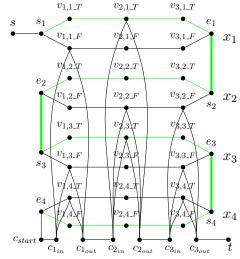
- Length of a path between the start and the end vertex in one loop is q+1. Thus total n\*(q+1) edges are taken.
- To construct a path, we need to take edges from ending vertex of each loop to starting vertex of next loop.
- So total n − 1 edges are taken.



#### Necessity

If Y is satisfiable, then G has a path of length of at least k.

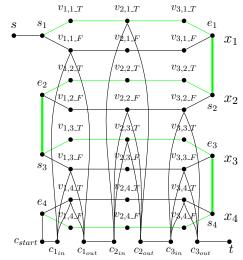
- Length of a path between the start and the end vertex in one loop is q+1. Thus total n\*(q+1) edges are taken.
- To construct a path, we need to take edges from ending vertex of each loop to starting vertex of next loop.
- So total n − 1 edges are taken.



### Necessity

If Y is satisfiable, then G has a path of length of at least k.

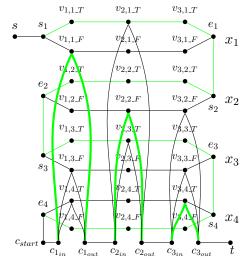
- Length of a path between the start and the end vertex in one loop is q+1. Thus total n\*(q+1) edges are taken.
- To construct a path, we need to take edges from ending vertex of each loop to starting vertex of next loop.
- So total n-1 edges are taken.



### Necessity

If Y is satisfiable, then G has a path of length of at least k.

- If the term  $x_i$  is true and clause  $c_j$  has the term  $x_i$ , we take edges from  $c_{j_{in}}$  to  $x_{i,j\_F}$  and from  $x_{i,j\_F}$  to  $c_{j_{out}}$ . And if the term  $x_i$  is false and clause  $c_j$  has the term  $\overline{x_i}$ , we need to take edges from  $c_{j_{in}}$  to  $x_{i,j\_T}$  and from  $x_{i,j\_T}$  to  $c_{j_{out}}$ .
- Thus for q clauses, total 2 \* q edges are taken.

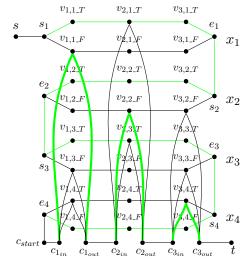


 $\mathsf{Y} \colon \big(x_1 \vee \overline{x_4} \vee x_3\big) \wedge \big(\overline{x_1} \vee x_2 \vee \overline{x_3}\big) \wedge \big(x_2 \vee x_3 \vee \overline{x_4}\big)$ 

#### Necessity

If Y is satisfiable, then G has a path of length of at least k.

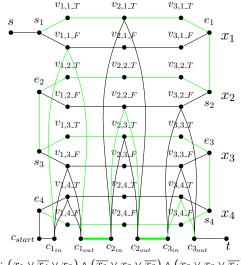
- If the term  $x_i$  is true and clause  $c_j$  has the term  $x_i$ , we take edges from  $c_{j_{in}}$  to  $x_{i,j\_F}$  and from  $x_{i,j\_F}$  to  $c_{j_{out}}$ . And if the term  $x_i$  is false and clause  $c_j$  has the term  $\overline{x_i}$ , we need to take edges from  $c_{j_{in}}$  to  $x_{i,j\_T}$  and from  $x_{i,j\_T}$  to  $c_{j_{out}}$ .
- Thus for q clauses, total 2 \* q edges are taken.



### Necessity

If Y is satisfiable, then G has a path of length of at least k.

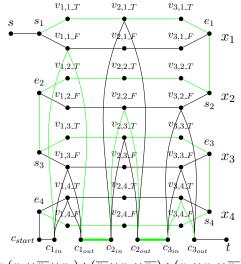
- To complete the path, edges from  $c_{jout}$  to  $c_{j+1_{in}}$  must be taken.
- Total q-1 edges are taken.
- Edges from s to  $s_1$ ,  $e_n$  to  $c_{start}$ ,  $c_{start}$  to  $c_{1in}$  and  $c_{qou}$  to t is taken.
- Thus total n\*(q+1)+n-1+2\*q+4 edges is taken. So the length of the path is k.



### Necessity

If Y is satisfiable, then G has a path of length of at least k.

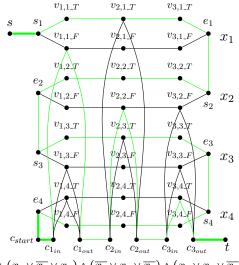
- To complete the path, edges from  $c_{jout}$  to  $c_{j+1_{in}}$  must be taken.
- Total q-1 edges are taken.
- Edges from s to  $s_1$ ,  $e_n$  to  $c_{start}$ ,  $c_{start}$  to  $c_{1in}$  and  $c_{qow}$  to t is taken.
- Thus total n\*(q+1)+n-1+2\*q+4 edges is taken. So the length of the path is k.



### Necessity

If Y is satisfiable, then G has a path of length of at least k.

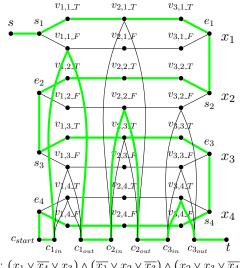
- To complete the path, edges from  $c_{j_{out}}$  to  $c_{j+1_{in}}$  must be taken.
- Total q-1 edges are taken.
- Edges from s to  $s_1$ ,  $e_n$  to  $c_{start}$ ,  $c_{start}$  to  $c_{1_{in}}$  and  $c_{q_{out}}$  to t is taken.
- Thus total n\*(q+1)+n-1+2\*q+4 edges is taken. So the length of the path is k.



### Necessity

If Y is satisfiable, then G has a path of length of at least k.

- To complete the path, edges from  $c_{jout}$  to  $c_{j+1_{in}}$  must be taken.
- Total q-1 edges are taken.
- Edges from s to  $s_1$ ,  $e_n$  to  $c_{start}$ ,  $c_{start}$  to  $c_{1_{in}}$  and  $c_{q_{out}}$  to t is taken.
- Thus total n\*(q+1)+n-1+2\*q+4 edges is taken. So the length of the path is k.



### Sufficiency

- Since G has a path P of length at least k, the value assigned to each literal  $x_i$  will have a corresponding path(True or False) to it.
- For a literal,  $x_i$ , we assign True to  $x_i$  if P contains the upper/true path in the loop of  $x_i$  and assign False if P contains the lower path
- Due to the construction of G, for each literal in clause  $c_j$ , the complement term will have two edges with that clause, one edge with  $c_{j_{in}}$  and another edge with  $c_{j_{out}}$ .
- If a clause  $c_j$  contains the literal  $x_i$ , then True is assigned to  $x_i$  which will make  $c_j$  True. And if a clause  $c_j$  contains the literal  $\overline{x_i}$ , then the value assigned to  $\overline{x_i}$  is False which will lead  $c_j$  to being True.
- This will hold for each clause in Y. So Y is satisfiable.

### Sufficiency

- Since G has a path P of length at least k, the value assigned to each literal  $x_i$  will have a corresponding path(True or False) to it.
- For a literal,  $x_i$ , we assign True to  $x_i$  if P contains the upper/true path in the loop of  $x_i$  and assign False if P contains the lower path.
- Due to the construction of G, for each literal in clause  $c_j$ , the complement term will have two edges with that clause, one edge with  $c_{j_{in}}$  and another edge with  $c_{j_{out}}$ .
- If a clause  $c_j$  contains the literal  $x_i$ , then True is assigned to  $x_i$  which will make  $c_j$  True. And if a clause  $c_j$  contains the literal  $\overline{x_i}$ , then the value assigned to  $\overline{x_i}$  is False which will lead  $c_j$  to being True.
- This will hold for each clause in Y. So Y is satisfiable.

### Sufficiency

- Since G has a path P of length at least k, the value assigned to each literal  $x_i$  will have a corresponding path(True or False) to it.
- For a literal,  $x_i$ , we assign True to  $x_i$  if P contains the upper/true path in the loop of  $x_i$  and assign False if P contains the lower path.
- Due to the construction of G, for each literal in clause  $c_j$ , the complement term will have two edges with that clause, one edge with  $c_{j_{in}}$  and another edge with  $c_{j_{out}}$ .
- If a clause  $c_j$  contains the literal  $x_i$ , then True is assigned to  $x_i$  which will make  $c_j$  True. And if a clause  $c_j$  contains the literal  $\overline{x_i}$ , then the value assigned to  $\overline{x_i}$  is False which will lead  $c_j$  to being True.
- This will hold for each clause in Y. So Y is satisfiable.

#### Sufficiency

- Since G has a path P of length at least k, the value assigned to each literal  $x_i$  will have a corresponding path(True or False) to it.
- For a literal,  $x_i$ , we assign True to  $x_i$  if P contains the upper/true path in the loop of  $x_i$  and assign False if P contains the lower path.
- Due to the construction of G, for each literal in clause  $c_j$ , the complement term will have two edges with that clause, one edge with  $c_{j_{in}}$  and another edge with  $c_{j_{out}}$ .
- If a clause  $c_j$  contains the literal  $x_i$ , then True is assigned to  $x_i$  which will make  $c_j$  True. And if a clause  $c_j$  contains the literal  $\overline{x_i}$ , then the value assigned to  $\overline{x_i}$  is False which will lead  $c_j$  to being True.
- This will hold for each clause in Y. So Y is satisfiable.

#### Sufficiency

- Since G has a path P of length at least k, the value assigned to each literal  $x_i$  will have a corresponding path(True or False) to it.
- For a literal,  $x_i$ , we assign True to  $x_i$  if P contains the upper/true path in the loop of  $x_i$  and assign False if P contains the lower path.
- Due to the construction of G, for each literal in clause  $c_j$ , the complement term will have two edges with that clause, one edge with  $c_{j_{in}}$  and another edge with  $c_{j_{out}}$ .
- If a clause  $c_j$  contains the literal  $x_i$ , then True is assigned to  $x_i$  which will make  $c_j$  True. And if a clause  $c_j$  contains the literal  $\overline{x_i}$ , then the value assigned to  $\overline{x_i}$  is False which will lead  $c_j$  to being True.
- This will hold for each clause in Y. So Y is satisfiable.

Special graphs	Complexity	Comments
Tree	Linear	Dijkstra's algorithm [1]
Cacti Graph	$O(n^2)$	[2]
Bipartite Permutation Graph	Linear	[3]
Directed Acyclic Graph	Linear	Dynamic approach
Interval Graph	$O(n^4)$	Dynamic approach [4]
Circular Arc Graph	$O(n^4)$	Dynamic approach [5]
Co-compatibility Graph	$O(n^7)$	From Hasse diagram [6]

 Tree is undirected acyclic graph. Dijkstra proposed an algorithm for this in 1960.

Special graphs	Complexity	Comments
Tree	Linear	Dijkstra's algorithm [1]
Cacti Graph	$O(n^2)$	[2]
Bipartite Permutation Graph	Linear	[3]
Directed Acyclic Graph	Linear	Dynamic approach
Interval Graph	$O(n^4)$	Dynamic approach [4]
Circular Arc Graph	$O(n^4)$	Dynamic approach [5]
Co-compatibility Graph	$O(n^7)$	From Hasse diagram [6]

• Cacti is a special kind of block graph which each block is a cycle. Two cycle share at most one vertex which is a separator.

Special graphs	Complexity	Comments
Tree	Linear	Dijkstra's algorithm [1]
Cacti Graph	$O(n^2)$	[2]
Bipartite Permutation Graph	Linear	[3]
Directed Acyclic Graph	Linear	Dynamic approach
Interval Graph	$O(n^4)$	Dynamic approach [4]
Circular Arc Graph	$O(n^4)$	Dynamic approach [5]
Co-compatibility Graph	$O(n^7)$	From Hasse diagram [6]

The class of bipartite permutation graphs is the intersection of two
well known graph classes: bipartite graphs and permutation graphs. A
complete bipartite decomposition of a bipartite permutation graph is
proposed in this reference.

Special graphs	Complexity	Comments
Tree	Linear	Dijkstra's algorithm [1]
Cacti Graph	$O(n^2)$	[2]
Bipartite Permutation Graph	Linear	[3]
Directed Acyclic Graph	Linear	Dynamic approach
Interval Graph	$O(n^4)$	Dynamic approach [4]
Circular Arc Graph	$O(n^4)$	Dynamic approach [5]
Co-compatibility Graph	$O(n^7)$	From Hasse diagram [6]

 The longest path for general graphs does not have a optimal substructure property but it has for weighted directed acyclic graphs.

Special graphs	Complexity	Comments
Tree	Linear	Dijkstra's algorithm [1]
Cacti Graph	$O(n^2)$	[2]
Bipartite Permutation Graph	Linear	[3]
Directed Acyclic Graph	Linear	Dynamic approach
Interval Graph	$O(n^4)$	Dynamic approach [4]
Circular Arc Graph	$O(n^4)$	Dynamic approach [5]
Co-compatibility Graph	$O(n^7)$	From Hasse diagram [6]

 An interval graph is an undirected graph formed from a set of intervals on the real line, with a vertex for each interval and an edge between vertices whose intervals intersect. It is the intersection graph of the intervals.

Special graphs	Complexity	Comments
Tree	Linear	Dijkstra's algorithm [1]
Cacti Graph	$O(n^2)$	[2]
Bipartite Permutation Graph	Linear	[3]
Directed Acyclic Graph	Linear	Dynamic approach
Interval Graph	$O(n^4)$	Dynamic approach [4]
Circular Arc Graph	$O(n^4)$	Dynamic approach [5]
Co-compatibility Graph	$O(n^7)$	From Hasse diagram [6]

 In graph theory, a circular-arc graph is the intersection graph of a set of arcs on the circle. It has one vertex for each arc in the set, and an edge between every pair of vertices corresponding to arcs that intersect.

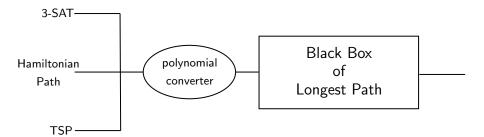
Special graphs	Complexity	Comments
Tree	Linear	Dijkstra's algorithm [1]
Cacti Graph	$O(n^2)$	[2]
Bipartite Permutation Graph	Linear	[3]
Directed Acyclic Graph	Linear	Dynamic approach
Interval Graph	$O(n^4)$	Dynamic approach [4]
Circular Arc Graph	$O(n^4)$	Dynamic approach [5]
Co-compatibility Graph	$O(n^7)$	From Hasse diagram [6]

 In graph theory, a comparability graph is an undirected graph that connects pairs of elements that are comparable to each other in a partial order.

#### Observation

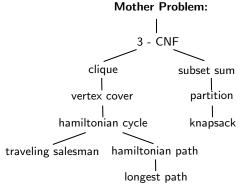
- The longest path problem is solvable in polynomial time on any class of graphs with bounded tree-width or bounded clique-width, such as the distance-hereditary graphs.
- Finally, it is clearly NP-hard on all graph classes on which the Hamiltonian path problem is NP-hard, such as on split graphs, circle graphs, and planar graphs.

### Problems that Reduce To Longest Path Problem



 The following diagram shows that 3-SAT, Hamiltonian Path, Traveling Salesman Problem are polynomial time reducible to Longest Path Problem.

# Problems that Reduced To Longest Path Problem



- We could not find any problem which is reduced to longest path problem. Because, as the tree moves down, the problems tend to get harder from the previous ones.
- As longest path problem is harder than any known NP-hard problems, we couldn't find any problem that reduced from longest path problem.

#### References I

R.W. Bulterman, F.W. van der Sommen, G. Zwaan, T. Verhoeff, A.J.M. van Gasteren, and W.H.J. Feijen.

On computing a longest path in a tree.

Information Processing Letters, 81(2):93 – 96, 2002.

Ryuhei Uehara and Yushi Uno.
Efficient algorithms for the longest path problem.
In Rudolf Fleischer and Gerhard Trippen, editors, *Algorithms and Computation*, pages 871–883, Berlin, Heidelberg, 2005. Springer Berlin Heidelberg.

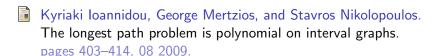
Ryuhei Uehara and Gabriel Valiente.

Linear structure of bipartite permutation graphs and the longest path problem.

Information Processing Letters, 103(2):71 – 77, 2007.



#### References II



George B. Mertzios and Ivona Bezáková.

Computing and counting longest paths on circular-arc graphs in polynomial time.

Discrete Applied Mathematics, 164:383 – 399, 2014. LAGOS'11: Sixth Latin American Algorithms, Graphs, and Optimization Symposium, Bariloche, Argentina — 2011.

Kyriaki Ioannidou and Stavros D. Nikolopoulos.
The longest path problem is polynomial on cocomparability graphs.

Algorithmica, 65(1):177–205, Jan 2013.