

PERSONAL

- Name
 Bisma Mutiargo
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- **Ģ Gender** Male
- Nationality
 Indonesian (SPR)
- Married Married
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INTERESTS

- Football
- Scuba diving (NAUI Master Diver)
- Tinkering with Arduino

LANGUAGES

English Indonesian



BISMA MUTIARGO

Employers in the seeking for expertise in data-driven process for metrology and NDT sentencing, will find Bisma's proficiency in deep learning development, especially in image and pointcloud processing highly beneficial.



WORK EXPERIENCE

Jun 2013 - Jul 2015 Assistant Applications Engineer

Cairnhill Metrology, Singapore

Jul 2015 - Jul 2017 Assistant Development Engineer

Advanced Remanufacturing & Technology Centre, A*STAR, Singapore

Jul 2017 - Jul 2019 Senior Assistant Development Engineer

Advanced Remanufacturing & Technology Centre, A*STAR, Singapore

Jul 2019 - Jul 2021 Development Engineer

 $Advanced\ Remanufacturing\ \&\ Technology\ Centre,\ A^*STAR,\ Singapore$

Jul 2021 - Present Senior Development Engineer

Advanced Remanufacturing & Technology Centre, A*STAR, Singapore

In the last 7 years my active role has been to spearhead development projects for the manufacturing industry for industry leaders such as Rolls Royce, Hyundai, Shell and IHI, or public agencies such as Housing Development Board, or universities. These projects focuses on the area of automatic image and pointcloud analysis for measurement and non-destructive evaluations, by the means of traditional algorithmic development, or data driven approach (DL/ML), to improve productivity, or to implement a fully autonomous robotic decision making and spatial positioning.

I am also been actively engaged within the scientific community to share new technology and research through publications in reputable journals and speaking in scientific conferences.



EDUCATION AND QUALIFICATIONS

Aug 2015 - May 2019 Bachelor (B.Eng) in Mechanical Engineering (Hons) with Specialisation in Innovative Design

Nanyang Technological University, Singapore



SKILLS

Python

Keras/Tensorflow/PyTorch

C++

Image Processing

CAD Reverse Engineering + 3D

Scanning

Project Management &
Leadership

Metrology



- AR-assisted automated 3D scanning cell (Co-Technical Lead)
 - Developed HoloLens-to-robot syncronisation scripts to build a self-programming 3D scanning robot cell with the help of a spatial scanner in a HoloLens device. This was created in-house to remove operator dependencies and was found to increase productivity by 3000%. This was deemed as an ARTC Success Story in its Year Book 2018. TD-ARTC-2017-PV-007
- 2. <u>Augmented Reality Surgical trainer for surgeons</u>- Performed live scans of a surgery patient in an operating theatre in KKH in order to build 3D models of human bodies to assist in the creation of an AR-assisted training program for surgeons.
- 3. Automated Toolpath Generation with vision system (Technology Lead)- Developed 3D-scanner to robot synchronization algorithm for a codeless robot programming platform to eliminate the need for a skilled programmer to create a new toolpath for a robot. This solution was implemented in a number of local SMEs (e.g. ACP and Abrasive Engineering), and it was also featured in A*CCELERATE NOW! event as part of the Guest of Honour station which was graced by Minister Masagos Zulkifli. This solution was also showcased at the Singapore Airshow 2020. The code to this solution is now licensed to a local startup, Augmentus Pte. Ltd.
- 4. **Creation of Augmented Reality Tour** As part of A*STAR Annual Makeathon 2019, we created an augmented reality tour with Microsoft HoloLens that serves as a digital tour guide for visitors to ARTC's open model factory exhibit to reduce the need for manpower. This creation was the winner of the makethon.
- 5. Development of defect detection capabilities in internal 3D printed components (Technical Lead)

 Secured a grant of \$260,000 to develop defect quantification capabilities e.g cracks, porosities, broken lattices, and trapped powder in 3D printed metal components using deep learning (UNET, MaskRCNN & SSD). The method was shared at the IMFIA2019, IWAIT2019, and SINCE2019 international conferences and was further published in SPIE journal & NDT.net. We have also since collaborated with NUS to build and maintain an open-source database for X-ray CT images containing 3D printed component defects.
- 6. <u>A part of Singapore's project Stronghold (COVID19 Project)</u>- Reverse engineered, and remanufactured thousands of viral transport media (VTM) tubes in a short timeframe to meet the urgent need for mass PCR testing during the early phase of the pandemic.
- Creation of a robotised marking system for Greyform (HDB) Developed a self-positioning algorithm
 with LiDAR sensor to enable robots to recognise its location in a room. This solution enables adaptive
 toolpath planning and has since been implemented by Greyform for automated marking in BTO prefab
 flats-TD/IP No: 08052020_ARTC_QUEK
- Creation of synthetic image generator for AI training (Technical Lead)- Created a digital platform for a Korean automotive manufacturer to generate simulated defect images which are used to build a quality control AI model within its assembly line - TD/IP No: PTD-IPV-21-001
- XCTPore- An Open Source Database for Porosity in X-ray CT scanned components
 Developed,
 maintained, and launched an open source image database containing XCT scanned images of porosity in AM scanned components. this database is free for use for individuals and enterprise, and is published under the BSD-2 Creative common license.



PUBLICATIONS

- Defect detection using trainable segmentation, SPIE DOI: 10.1117/12.2521768
- Evaluation of X-ray Computed Tomography (CT) Images of Additively Manufactured Components using Deep Learning, NDT.net - DOI: 10.3850/978-981-11-2719-9
- Effects of Post-Processing Route on Fatigue Performance of Laser Powder Bed Fusion Inconel 718-Additive Manufacturing - DOI: 10.1016/j.addma.2020.101442
- Internal surface roughness measurement of metal additively manufactured samples via X-ray CT: the influence of surrounding material thickness - Surface Topography Metrology and Properties -DOI: 10.1088/2051-672X/ac0e7c
- On the uncertainty of porosity measurements of additively manufactured metal parts-Measurement - DOI: 10.1016/j.measurement.2021.110616
- Automatic Mirror Polishing of Rough, Freeform AM Surfaces Using a Toolpath Generation
 Framework INCASE2021 DOI: 10.1007/978-981-16-5763-4_56
- Defect imaging in carbon fiber composites by acoustic shearography- Composites DOI: 10.1016/j.compscitech.2022.109417
- XCTPore- An Open Source Database for Porosity in X-ray CT scanned components- SINCE2022 -Approved manuscript: Pending publication

• <u>Digital Manufacturing Textbook series</u>- Wrote Chapter B: Robots in intelligent manufacturing, focusing on 3D scanning technology and its post-processing algorithms for robotics and manufacturing application. *Approved Technical editor peer review: Pending publication*



References available on request.