- 1. A translation is applied to an object by
- a) Repositioning it along with straight line path
- b) Repositioning it along with circular path
- c) Only b
- d) All of the mentioned
- 2. We translate a two-dimensional point by adding
- a) Translation distances
- b) Translation difference
- c) X and Y
- d) None of the mentioned
- 3. The translation distances (dx, dy) is called as
- a) Translation vector
- b) Shift vector
- c) Both a and b
- d) Neither a nor b
- 4. In 2D-translation, a point (x, y) can move to the new position (x', y') by using the equation
- a) x'=x+dx and y'=y+dx
- b) x'=x+dx and y'=y+dy
- c) X'=x+dy and Y'=y+dx
- d) X'=x-dx and y'=y-dy
- 5. \_\_\_\_\_is a rigid body transformation that moves objects without deformation.
- a) Rotation
- b) Scaling
- c) Translation
- d) All of the mentioned
- 6. Polygons are translated by adding \_\_\_\_\_\_ to the coordinate position of each vertex and the current attribute setting.
- a) Straight line path
- b) Translation vector
- c) Differences
- d) None of the mentioned
- 7. To change the position of a circle or ellipse we translate
- a) Center coordinates
- b) Center coordinates and redraw the figure in new location
- c) Outline coordinates
- d) All of the mentioned

- 8. The basic geometric transformations are
- a) Translation
- b) Rotation
- c) Scaling
- d) All of the mentioned
- 9. A two dimensional rotation is applied to an object by
- a) Repositioning it along with straight line path
- b) Repositioning it along with circular path
- c) Both a and b
- d) Any of the mentioned
- 10. To generate a rotation, we must specify
- a) Rotation angle Θ
- b) Distances dx and dy
- c) Rotation distance
- d) All of the mentioned
- 11. Positive values for the rotation angle  $\Theta$  defines
- a) Counterclockwise rotations about the end points
- b) Counterclockwise translation about the pivot point
- c) Counterclockwise rotations about the pivot point
- d) Negative direction
- 12. The rotation axis that is perpendicular to the xy plane and passes through the pivot point is known as
- KIIO WII US
- a) Rotation
- b) Translation
- c) Scaling
- d) Shearing
- 13. An ellipse can also be rotated about its center coordinates by rotating
- a) End points
- b) Major and minor axes
- c) Only a
- d) None
- 14. The transformation that is used to alter the size of an object is
- a) Scaling
- b) Rotation
- c) Translation
- d) Reflection

- 15. Scaling of a polygon is done by computinga) The product of (x, y) of each vertexb) (x, y) of end pointsc) Center coordinatesd) Only a
- `16. If the scaling factors values sx and sy < 1 then
- a) It reduces the size of object
- b) It increases the size of object
- c) It stunts the shape of an object
- d) None
- 17. If the scaling factors values sx and sy are assigned to the same value then
- a) Uniform rotation is produced
- b) Uniform scaling is produced
- c) Scaling cannot be done
- d) Scaling can be done or cannot be done
- 18. We control the location of a scaled object by choosing the position is known as
- a) Pivot point
- b) Fixed point
- c) Differential scaling
- d) Uniform scaling
- 19. f the value of sx=1 and sy=1 then
- a) Reduce the size of object
- b) Distort the picture
- c) Produce an enlargement
- d) No change in the size of an object
- 20. Reversing the order in which a sequence of transformations is performed may affect the transformed position of an object.
- a) True
- b) False
- 21. Which one of the following is the correct notation of a matrix with 'm' rows and 'n' columns?
- a) m + n
- b) m n
- c) m x n
- d) m/n

<ul> <li>22. How many minimum numbers of zeros are there in '3 x 3' triangular matrix?</li> <li>a) 4</li> <li>b) 3</li> <li>c) 5</li> <li>d) 6</li> </ul>
23. Which of the following represents shearing? a) $(x, y) \rightarrow (x+a, y+b)$ b) $(x, y) \rightarrow (ax, by)$ c) $(x, y) \rightarrow (x \cos(\theta)+y \sin(\theta), -x \sin(\theta)+y \cos(\theta))$ d) $(x, y) \rightarrow (x+ay, y+bx)$
24. Shearing is also termed as a) Selecting b) Sorting c) Scaling d) Skewing
25. Which of this is compulsory for 2D reflection.  a) Reflection plane. b) Origin c) Reflection axis d) Co-ordinate axis.  26. A is a system which uses one or more numbers, or coordinates, to uniquely determine the position of a point. a) co-ordinate system b) binary-system c) vector-system d) euclid geometry
<ul> <li>27. Which co-ordinates allow common vector operations such as translation, rotation, scaling and perspective projection to be represented as a matrix by which the vector is multiplied.</li> <li>a) vector co-ordinates</li> <li>b) 3d co-ordinates</li> <li>c) affine co-ordinates</li> <li>d) homogenous co-ordinates</li> </ul>
<ul><li>28. A view is selected by specifying a sub-area of the picture area.</li><li>a) half</li><li>b) total</li><li>c) full</li></ul>

	d) quarter
	<ul><li>29. Co-ordinates are ranging according to the screen resolution.</li><li>a) True</li></ul>
	b) False
	30. Any convenient co-ordinate system or Cartesian co-ordinates which can be used to define the picture is called
	a) spherical co-ordinates
	b) vector co-ordinates
	c) viewport co-ordinates
	d) world co-ordinates
	31. The process of elimination of parts of a scene outside a window or a viewport is called
	a) cutting
	b) plucking
	c) clipping
	d) editing
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	32. For a 2d transformation viewing, in how many ways a clipping algorithm can be applied?
1	a) 3
	b) 2 d l l l l l l l l l l l l l l l l l l
	b) 2 c) 1 d) 5 E
II L	(d) 5
	33. Which of the following is NOT a type of clipping algorithm used on the raster system?
	a) line clipping
	b) point clipping
	c) area clipping
	d) solid clipping
	34. For a point to be clipped, which of the following conditions must be satisfied by the point?
	a) $xw_{min} < x < xw_{max}$
	b) $xw_{min} = x = xw_{max}$
	c) $xw_{min} > x > xw_{max}$
	d) $yw_{min} = y = yw_{max}$
	35. In polygon clipping, line clipping algorithms can be used.
	a) True
	b) False

36. The object space or the space in which the application model is defined is called	
a) World co-ordinate system b) Screen co-ordinate system c) World window d) Interface window	
<ul><li>37. What is the name of the space in which the image is displayed?</li><li>a) World co-ordinate system</li><li>b) Screen co-ordinate system</li><li>c) World window</li><li>d) Interface window</li></ul>	
38. The process of mapping a world window in World Coordinates to the Viewport is called Viewing transformation.  a) True b) False	
39. By changing the dimensions of the viewport, the and of the objecting displayed can be manipulated.  a) Number of pixels and image quality b) X co-ordinate and Y co-ordinate c) Size and proportions d) All of these  40. A polygon can be clipped using clipping operations. a) True b) False	ects
<ul><li>41. Which vertex of the polygon is clipped first in polygon clipping?</li><li>a) top right</li><li>b) bottom right</li><li>c) bottom left</li><li>d) top left</li></ul>	
<ul><li>42. We can change the size or resize the bitmap image.</li><li>a) True</li><li>b) False</li></ul>	
43. In line clipping, the portion of line which is of window is cut and the portion is the window is kept.  a) outside, inside b) inside, outside	tion

	c) exact copy, different
	d) different, an exact copy
	44. Cohen-Sutherland clipping is an example of
	a) polygon clipping
	b) text clipping
	c) line clipping
	d) curve clipping
	45. The Cohen-Sutherland algorithm divides the region into number of spaces.
	a) 8
	b) 6
	c) 7
	d) 9
	46. The centre region of the screen and the window can be represented as
	a) 0000
	b) 1111
	c) 0110
	d) 1001
	47. The Cohen–Sutherland algorithm can be only be used on a rectangular clip window.
1 1	a) True
- 411	b) False
	N E
	48. If both codes are 0000, (bitwise OR of the codes yields 0000) line lies
	the window.
	a) completely outside
	b) half inside half outside
	c) completely inside
	d) can't say anything
	49. The 4-bit code of top-left region of the window is
	a) 1001
	b) 1100
	c) 0101
	d) 1010