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Spline Interpolation technique:

$$\begin{array}{ccccccc} x & x_0 & x_1 & \dots & x_n & & y = f(x) \\ y & y_0 & y_1 & \dots & y_n & & \end{array}$$

$p_n(x)$ by using all the $(n+1)$ data points, which is global interpolation polynomial for $y = f(x)$ valid in $I[x_0, x_1, \dots, x_n]$

↓
Smallest interval containing x_i 's.

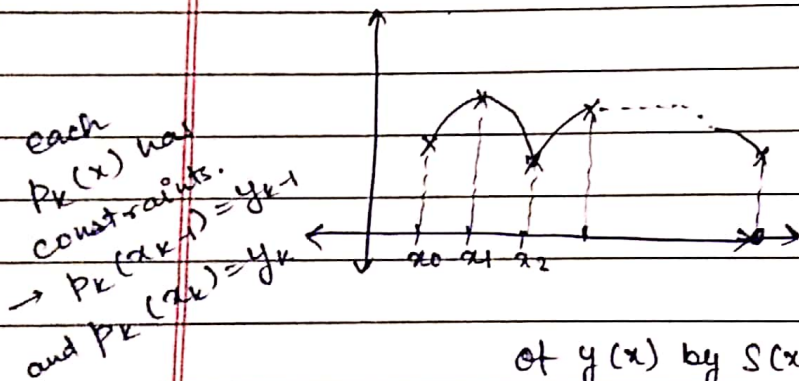
Piecewise interpolation polynomial:-

Instead of taking the whole set of data points and constructing the polynomial, we create polynomials b/w each interval.

$$S(x) = \begin{cases} p_k(x) & , \quad x_{k-1} \leq x \leq x_k \quad | \quad k=1, 2, \dots, n \end{cases}$$

$$p_1(x), p_2(x), \dots, p_n(x)$$

$$y \sim S(x) \quad y \sim p_k(x) \quad \text{for} \quad x_{k-1} \leq x \leq x_k \quad k=1, 2, \dots, n-1.$$



knot points are,

$$x_1, x_2, \dots, x_{n-1}$$

If $p_k(x)$ are cubic polynomial

Then the set of $S(x)$ is called

the cubic spline and the representation

of $y(x)$ by $S(x)$ is termed as Spline interpolation.

Interpolation polynomial at $x_k = y_k$. (Given)

$$y \sim p_m(x)$$

$$y_k = p_m(x_k)$$

$$k=0, 1, 2, \dots, n.$$

$$p_m(x) = a_0 + a_1 x + \dots + a_m x^m$$

$$a_0 + a_1 x_0 + a_2 x_0^2 + \dots + a_m x_0^m = y_0$$

$$a_0 + a_1 x_1 + a_2 x_1^2 + \dots + a_m x_1^m = y_1$$

$$a_0 + a_1 x_n + \dots + a_m x_n^m = y_n$$

$(n+1)$ eqⁿ. $(n+1)$ variables \rightarrow (a_i's).

If $m=n$, then we surely have a solⁿ.

$$A = \begin{vmatrix} 1 & x_0 & \dots & x_0^n \\ 1 & x_1 & \dots & x_1^n \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & \dots & x_n^n \end{vmatrix} = \prod_{\substack{i,j=0 \\ i \neq j}}^n (x_i - x_j) \neq 0 \text{ if } x_i \neq x_j, \forall i, j.$$

If the node points $x_0, x_1, x_2, \dots, x_n$ are distinct then, we have a unique solⁿ, ~~the~~ hence the interpolation polynomial is unique and of degree n .

\rightarrow So, if you use all the data points then ~~there is~~ only one unique interpolating polynomial.

To find an interpolating polynomial :-

Let $y = f(x)$ s.t., ~~the~~ ~~the~~ $y(x_m) = 0, m = 0, 1, 2, \dots, k-1, k+1, \dots, n$

Consider, $y \sim p_n(x)$ s.t., $p_n(x_m) = 0, m = 0, 1, 2, \dots, k-1, k+1, \dots, n$
 $p_n(x_k) = y_k.$

So, $p_n(x) = a_n (x-x_0)(x-x_1)\dots(x-x_{k-1})(x-x_{k+1})\dots(x-x_n)$ is a polynomial of degree n which interpolates $y = f(x)$ at x_0, x_1, \dots, x_n points.

$$a_n = \frac{y_k}{(x_k - x_0)(x_k - x_1)\dots(x_k - x_{k-1})(x_k - x_{k+1})\dots(x_k - x_n)}.$$

So, the unique interpolation polynomial is $p_n(x)$.

Let, $l(x) = (x-x_0)(x-x_1)\dots(x-x_n).$

$$\text{then, } p_n(x) = \frac{y_k l(x)}{(x-x_k) l'(x_k)}$$

$$l'(x_k) = (x_k - x_0)(x_k - x_1)\dots(x_k - x_{k-1})(x_k - x_{k+1})\dots(x_k - x_n).$$

$$y_m = x_m \neq 0, \quad m = 0, 1, 2, \dots, n$$

$$y_m = y_0 + y_1 + y_2 + \dots + y_n$$

Generalize the technique for the above curve $p_n(x)$ as:-

$$p_n(x) = \sum_{k=0}^n \frac{y_k l(x)}{(x-x_k) l'(x_k)}$$

$$l(x) = \prod_{i=0}^n (x-x_i)$$

$p_n(x)$ is a polynomial of degree n and $p_n(x_i) = y_i$ $i=0, 1, 2, \dots, n$ which is unique interpolation polynomial, known as Lagrange's interpolation polynomial.

$$y \sim p_k(x), \quad x_{k-1} \leq x \leq x_k$$

$$l(x) = (x-x_{k-1})(x-x_k)$$

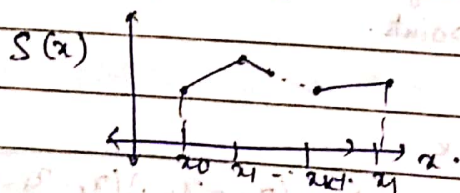
$$p_k(x_{k-1}) = y_{k-1}$$

$$p_k(x_k) = y_k$$

$$p_k(x) = \sum_{i=k-1}^k \frac{y_i l(x)}{(x-x_i) l'(x_i)}$$

$$= \frac{y_{k-1} (x-x_k)}{(x_{k-1}-x_k)} + \frac{y_k (x-x_{k-1})}{(x_k-x_{k-1})}$$

If we use Lagrange's polynomial, then each $p_k(x)$ is a straight line.



Spline interpolation, $p_k(x)$ is cubic polynomial.

$S(x)$ is continuous, twice differentiable, i.e. at each knot points $p_k(x)$ has the same slope and curvatures i.e.

$$p'_k(x_{k-1}) = p'_{k+1}(x_k)$$

$$p''_k(x_k) = p''_{k+1}(x_k)$$

$$k = 1, 2, \dots, n-1$$

$$p_k(x_k) = y_k$$

$$p_k(x_{k+1}) = y_{k+1}$$

$S(x)$ is the ~~piecewise~~ set of piecewise cubic polynomial, $S'(x)$ is piecewise linear. i.e. $p_k''(x)$ is linear polynomial with,

$$p_k''(x_k) = M_k, \quad p_k''(x_{k+1}) = M_{k+1}.$$

where $p_k(x)$ is valid in $[x_k, x_{k+1}]$.

By Lagrange's formula $p_k''(x)$ is

$$p_k''(x) = \frac{M_k (x - x_{k+1})}{(x_k - x_{k+1})} + \frac{M_{k+1} (x - x_k)}{(x_{k+1} - x_k)}$$

Let the points are equidistant

$$\text{i.e. } h = x_{k+1} - x_k, \quad k = 0, 1, 2, \dots$$

$$p_k''(x) = \frac{M_k}{h} (x - x_{k+1}) + \frac{M_{k+1}}{h} (x - x_k).$$

Integrate twice w.r. to x .

$$p_k(x) = \frac{M_k}{h} \frac{(x - x_{k+1})^3}{3!} + \frac{M_{k+1}}{h} \frac{(x - x_k)^3}{3!} + \underbrace{Ax + B}_{C_k(x - x_k) + D_k(x_{k+1} - x)}.$$

Now,

$$p_k(x_k) = y_k$$

$$p_k(x_{k+1}) = y_{k+1}$$

C_k & D_k are const. of integration.

$$p_k(x_k) = \frac{h^2}{6} M_k + D_k h = y_k \Rightarrow D_k = \frac{1}{h} \left(y_k - \frac{h^2}{6} M_k \right)$$

$$p_k(x_{k+1}) = \frac{h^2}{6} M_{k+1} + C_k h = y_{k+1} \Rightarrow C_k = \frac{1}{h} \left(y_{k+1} - \frac{h^2}{6} M_{k+1} \right)$$

$$p_k(x) = \frac{M_k}{6} \left[\frac{(x_{k+1} - x)^3}{h} - h (x_{k+1} - x) \right] + \frac{y_k}{h} (x_{k+1} - x) + \frac{M_{k+1}}{6} \left[\frac{(x - x_k)^3}{h} - h (x - x_k) \right] + \frac{1}{h} y_{k+1} (x - x_k).$$

We will apply the continuity eq. rel's.

$$p'_k(x_{k+1}) = p'_{k+1}(x_k).$$

$$p'_k(x) = \frac{M_k}{6} \left[(-3) \frac{(x_{k+1}-x)^2}{h} + h \right] - \frac{y_k}{h} + \frac{M_{k+1}}{6} \left[3 \frac{(x-x_k)^2}{h} - h \right] + \frac{y_{k+1}}{h}$$

$$p'_k(x_{k+1}) = \frac{M_k}{6} [h] - \frac{y_k}{h} + \frac{M_{k+1}}{6} [3h^2 - h] + \frac{y_{k+1}}{h}$$

$$= \frac{3M_{k+1}h^2 - M_k h^2}{6} + 1 =$$

$$p'_k(x_k) = p'_{k-1}(x_k) \quad k=1, 2, \dots, n-1.$$

$$p'_k(x_k) = \frac{M_k}{6} (-2h) - \frac{M_{k+1}h}{6} + \frac{1}{h} \Delta y_k.$$

$$p'_k(x_{k+1}) = \frac{M_k h}{6} + \frac{M_{k+1} h}{3} + \frac{1}{h} \Delta y_k.$$

$p_k(x)$

in $[x_k, x_{k+1}]$

replace $k \rightarrow k-1$

$$p'_{k-1}(x_k) = \frac{M_{k-1} h}{6} + \frac{M_k h}{3} + \frac{1}{h} \Delta y_{k-1}$$

$$\text{So, } -\frac{M_k h}{3} - \frac{M_{k+1} h}{6} + \frac{\Delta y_k}{h} = \frac{M_{k-1} h}{6} + \frac{M_k h}{3} + \frac{\Delta y_{k-1}}{h}$$

$$M_{k-1} + 4M_k + M_{k+1} = \frac{6}{h^2} [y_{k+1} - 2y_k + y_{k-1}]$$

$k=1, 2, \dots, n-1.$

for, $p_k(x)$ for, $k=0, 1, 2, \dots, n-1$

involves, $M_0, M_1, M_2, \dots, M_n \rightarrow$ i.e. $(n+1)$ M_k 's.

where as (*) is a tri-diagonal system of $(n-1)$ eqns.

We need to impose two more cond's for the 2nd derivative

1) $M_0, M_n \rightarrow$ given.

2)

$M_0 = M_1, M_{n-1} = M_n \rightarrow$ periodic cond.

3) $M_0 = 0 = M_n \Rightarrow$ flat end cond.