

By S.S. Rao.

Engineering Optimization:

Theory & Practice -

By S. S. Rao.

what you do in optimization?

maximize or minimize using constraints etc.

We have done for non-linear.

Here, we are doing for linear.

LPP - (Linear Programming Problem)

$$\textcircled{1} \quad \text{max : } Z = 2x_1 + 3x_2$$

$$\text{s.t. } 3x_1 + 2x_2 = 6$$

$$x_1, x_2 \geq 0$$

we want 1 basic solution.

$$\begin{cases} x_1 = 0 \\ x_2 = 3 \end{cases}, \text{ thus } Z = 9 \quad \text{max}$$

$$\begin{cases} x_1 = 2 \\ x_2 = 0 \end{cases}, \text{ thus } Z = 4 \quad \text{min}$$

$$\textcircled{2} \quad \text{min } Z = 2x_1 + 3x_2$$

$$\text{s.t. } 3x_1 + 2x_2 = 6$$

$$x_1, x_2 \geq 0$$

General Problem

$$\text{max. } Z = c_1x_1 + c_2x_2 + \dots + c_nx_n$$

$$\text{s.t. } \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1, \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2, \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m, \end{cases} b_i \geq 0$$

$$x_1, x_2, \dots, x_m \geq 0$$

Model I :

$$\text{max : } Z = \sum_{j=1}^n c_j x_j$$

$$\text{s.t. } \sum_{j=1}^n a_{ij} x_j = b_i, \quad i = 1, 2, \dots, m \quad b_i \geq 0$$

$$x_j \geq 0, \quad j = 1, 2, \dots, n$$

$$\text{max : } Z = C^T X$$

$$\text{s.t. } \begin{aligned} AX &= b \\ X &\geq 0 \end{aligned}$$

$$C = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} \quad X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad b = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

Model 2 :

$$\min Z = \sum_{j=1}^n c_j x_j$$

$$\text{s.t. } \sum_{j=1}^n a_{ij} x_j = b_i, \quad b_i \geq 0 \quad \forall i \quad i = 1, 2, \dots, m$$

$$x_j \geq c_j \quad \forall j \quad j = 1, 2, \dots, n$$

example (slides)

$$\text{max : } Z = 10x_1 + 20x_2 + 20x_3$$

$$\text{subject to } x_1 + x_2 + x_3 = 60 \quad \text{2 constraints}$$

$$x_1 + 5x_2 + 10x_3 = 416$$

$$x_1, x_2, x_3 \geq 0$$

$$\text{min: } Z = 10x_1 + 20x_2 + 30x_3$$

$$\text{s.t. } 2x_1 - 3x_2 + 5x_3 = 30$$

$$3x_1 + 5x_2 - 2x_3 = 40$$

$$x_1, x_2, x_3 \geq 0$$

Check whether they are linearly dependent or independent

Non-basic variables are always 0.

Basic variable

NBV		BV	
$x_1 = 0$		$x_1 = 38$	$Z = 1420 \rightarrow \text{max}$
$x_2 = 0$		$x_2 = 190/9$	$Z = \frac{12400}{9}$
$x_3 = 0$		$x_3 = 350/9$	
		$x_1 = -55/2$	
		$x_2 = 175/2$	Not a BFS so don't calculate value of Z.

$$2x_1 + 5x_3 = 30$$

$$3x_1 - 2x_3 = 40$$

$$\Rightarrow \begin{vmatrix} 30 & 5 \\ 40 & -2 \end{vmatrix} = \begin{vmatrix} -260 & 250 \\ -19 & 9 \end{vmatrix} \quad \begin{matrix} 1900 \\ 260 \end{matrix} + \frac{10500}{9} \quad \begin{matrix} x_3 = 0 \\ 2x_1 - 3x_2 = 30 \\ 3x_1 + 5x_2 = 40 \end{matrix}$$

$$3 \begin{vmatrix} -3 & 30 \\ 5 & 40 \end{vmatrix} = \frac{-120 - 150}{-19} = \frac{270}{19} \quad \begin{matrix} x_3 = 0 \\ 2x_1 - 3x_2 = 30 \\ 3x_1 + 5x_2 = 40 \end{matrix}$$

$$\begin{vmatrix} 30 & -3 \\ 40 & 5 \end{vmatrix} = \frac{150 + 120}{19} \quad \begin{matrix} x_3 = 0 \\ 2x_1 - 3x_2 = 30 \\ 3x_1 + 5x_2 = 40 \end{matrix}$$

$$\begin{pmatrix} 2 & 30 \\ 3 & 40 \end{pmatrix} = -\frac{10}{19}$$

$$x_2 = 0 \quad 2x_1 + 5x_3 = 30 \quad x_1 = \frac{\begin{vmatrix} 30 & 5 \\ 40 & -2 \end{vmatrix}}{\begin{vmatrix} 2 & 5 \\ 3 & -2 \end{vmatrix}} = -\frac{260}{-19} = \frac{260}{19}$$

$$\frac{\begin{vmatrix} 2 & 30 \\ 3 & 40 \end{vmatrix}}{\begin{vmatrix} 2 & 5 \\ 3 & -2 \end{vmatrix}} = \frac{10}{19}$$

$$Z =$$

BPS means everything has to be non negative.
Basic solutions means that it can be anything.

LPP either has
none
or infinitely many solⁿ

Operation Research by
H A Taha

Linear programming vol 1
George B Dantzig & R

L.P vol 2

Study of Business operations to improve the efficiency in industry is known as OR.

Variance - 2nd moment.

Normal Distribution

Lognormal distribution

Central limit theorem

Finding maximum profit / production / performance
or finding minimum cost / loss / risk of some
world decision making problems.

Type	Capital	Rajdhani	Hostel ug ⁿ
T	20	10	200
D	18	24	300
C	25	50	500
Cost per package	Rs 20,000	Rs 30,000	-

$$\begin{array}{l}
 20x + 18y + 25z = 20,000 \\
 10x + 24y + 50z = 30,000 \\
 x \geq 200 \quad y \geq 300 \quad z \geq 500
 \end{array}$$

15
Not these variables

Let x = no. of units of furniture from Capital

let y = no. of units of furniture from Rajdhani

These variables are known as control variables
(under control of the mathematician)

L.P model can be formulated as :

$$\text{Min cost in Rs} = 20,000x + 30,000y$$

$$20x + 10y \geq 200 \quad ①$$

$$18x + 24y \geq 300 \quad ②$$

$$25x + 50y \geq 500 \quad ③$$

$$x, y \geq 0 \text{ and integers} \dots \quad ④$$

$$2x + y \geq 20 \quad -⑤$$

$$3x + 4y \geq 50 \quad -⑥$$

$$x + 2y \geq 20 \quad -⑦$$

Restrictions imposed on problem .

Inequalities

Not solving

$$\boxed{AX = b}$$

$$AX = 0$$

Always has a

"trivial sol"

Only checking
lets' say not-a "sol"
or no "sol".

This system of
linear equation.

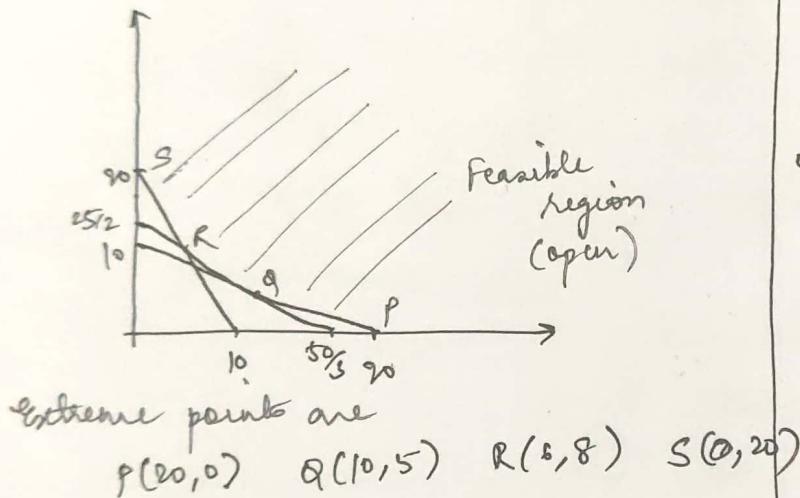
$$m = 3 \quad n = 5$$

out of 5, any 3 non-zero, remaining 0
 $5 - 3 = 2$

Any 2 variables are 0.

$${}^5C_2 = {}^5C_3 = \frac{5 \times 4}{2} = 10$$

- ① Choosing control variables
- ② Whether to max. or min.
- ③ According to requirement, we go for constraints.

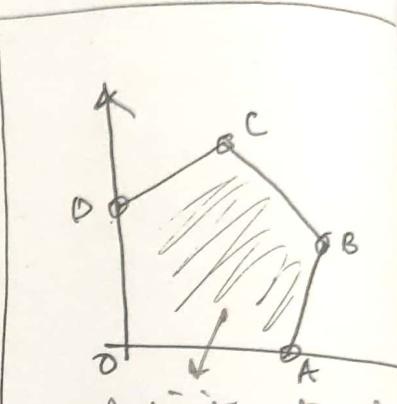


At P, cost of furniture = £ 400,000

$$Q, \text{ --- } = 350,000$$

$$R, \text{ --- } = 360,000$$

$$S, \text{ --- } = 600,000$$



Infinite pts. in feasible region
 every BFS - corresponds to an extreme pt. & optimum solⁿ or at the extrem only.

It has 1, no or infinitely many solⁿ like a linear system

min value at

$$x = 10, y = 5$$

using if it satisfies inequ

$$\left. \begin{array}{l} T_6 = 250 \\ D = 300 \\ C = 500 \end{array} \right\} \text{at a cost of } \text{£ } 350,000$$

finding Basic Feasible solutions of a linear system equations
 $AX = b$ be of m linear equations with n variables
 $(m > n)$ where A is a real matrix of size m by n ,
 x is a column vector having n elements, ie
 $x = (x_1, x_2, x_3 \dots x_n)^T$, and b is a non-zero
column vector having m elements

a system is consistent if

$(n > m)$

If $AX = b$ is consistent, select any m variables
and set remaining $(n-m)$ variables to zero.

After setting $(n-m)$ variables to zero the system
 $AX = b$ becomes $BX_B = b$ where B is a
non-singular matrix of order m (i.e $|B| \neq 0$)
and X_B is a column vector with m elements.

If a solⁿ

$$X_B = B^{-1}b$$

↓
Basic solⁿ

Max no. of possible basic solⁿ

$${}^n C_m = {}^n C_{n-m}$$

If all basic variables non-negative - Basic
feasible solⁿ.

$$\text{Max : } Z = x_1 + 4x_2$$

$$x_1 + x_2 \leq 10$$

$$x_1 + 4x_2 \leq 16$$

Introducing slack variables x_3, x_4

$$x_1 + x_2 + x_3 = 10$$

$$x_1 + 4x_2 + x_4 = 16$$

$$x_1, x_2, x_3, x_4 \geq 0$$

S. No	Non Basic Variables	Basic Variables
1.	$x_1 = 0, x_2 = 0$	$x_3 = 10, x_4 = 6$
2.	$x_1 = 0, x_3 = 0$	$x_2 = 10, x_4 = -24$
3.	$x_1 = 0, x_4 = 0$	$x_2 = 4, x_3 = 6$
4.	$x_2 = 0, x_3 = 0$	$x_1 = 10, x_4 = 6$
	$x_2 = 0, x_4 = 0$	$x_1 = ., x_3 = .$
	$x_3 = 0, x_4 = 0$	$x_1 = ., x_2 = .$

6 basic solⁿ, only 4 are BFS

optimal solⁿ b obtained

$$\text{sl. no. 3, i.e. } x_1 = 0, x_2 = 4$$

$$6. \text{ i.e. } x_1 = 8, x_2 = 2$$

$$\text{with } Z = 16$$

$$\dots x^{(1)} = \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \end{pmatrix} = \begin{pmatrix} 0 \\ 4 \end{pmatrix}$$

$$x^{(2)} = \begin{pmatrix} x_1^{(2)} \\ x_2^{(2)} \end{pmatrix} = \begin{pmatrix} 8 \\ 2 \end{pmatrix}$$

Exceptional

$$x_1 + x_2 + x_3 = 10$$

$$2x_1 + 2x_2 + x_4 = 19$$

$x_3 = 0$ NBV

$$x_4 + x_2 = 10$$

$$2x_1 + 2x_2 = 19$$

Not fulfilled, because
Matrix B is a sing

$$x^* = \begin{pmatrix} x_1^* \\ x_2^* \end{pmatrix} = \lambda \begin{pmatrix} 0 \\ 4 \end{pmatrix} + (1-\lambda) \begin{pmatrix} 8 \\ 2 \end{pmatrix}$$

$$\begin{array}{l} \lambda = 1/2 \quad \begin{pmatrix} 4 \\ 3 \end{pmatrix} \quad z = 16 \\ \lambda = \dots \quad \quad \quad \quad \quad \quad z = 16 \end{array}$$

R. Model II

H.E. 6 hours continuous
Work requirement given

x_4 = no. of H.E. in period 1

$$x_2 = \overbrace{\hspace{1cm}}^{11} \quad 2$$

$$x_3 = \overbrace{\hspace{1cm}}^{11} \quad 3$$

$$x_4 = \overbrace{\hspace{1cm}}^{11} \quad 4$$

$$\text{Min} = x_4 + x_2 + x_3 + x_4 \quad (\text{Ngrt. will want this})$$

s.t.

$$x_4 \geq 8$$

$$x_4 + x_2 \geq 12$$

$$x_4 + x_2 + x_3 \geq 9$$

$$x_2 + x_3 + x_4 \geq 12$$

$$x_3 + x_4 \geq 10$$

$$x_4 \geq 7$$

$$x_1, x_2, x_3, x_4 = 0, 1, 2, 3 \dots$$

as integers, solⁿ's are not infinite (they are countable)

DR Lab - I (Questions)

① Find the basic solution (b) and the Basic Feasible Solution (B.F.S.) of the linear system $AX=b$ where $n > m$.

Also write a program in C or C++ to find the Basic Feasible Solution (B.F.S.) of $AX=b$.

$$A = (a_{ij})_{m \times n} \quad X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad b = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

② a) $\max Z = C^T X$

s.t. $AX=b$

$X \geq 0$

b) $\min Z = C^T X$

s.t. $AX=b$

$X \geq 0$

Find the B.F.S. of $AX=b$. Then find the optimum solⁿ of (a) and (b). Also write a program in C or C++ to find the optimal solⁿ.

③ Find the optimal solⁿ of

a) $\max : Z = C^T X$

s.t. $AX \leq b$

$X \geq 0$

b) $\min : Z = C^T X$

s.t. $AX \geq b$

$X \geq 0$

$\boxed{\begin{matrix} X \\ AX \leq b \\ AX \geq b \end{matrix}}$

c) $\max : Z = C^T X$

s.t. $AX(*)b$

$X \geq 0$

$*$ ($\leq, \geq, =$)

d) $\min : Z = C^T X$

s.t. $AX(*)b \quad * \rightarrow \leq = \geq$

$X \geq 0$

sily you can change to integer programming problem.
All the variables are integers.

Find $\underline{x} = (x_1, x_2, \dots, x_n)^T$

so as to

$$\text{min: } Z = C^T \underline{x} + d$$

$$\text{s.t. } A\underline{x} \geq b$$

$$\underline{x} \geq 0$$

$$x_i = 0, 1, 2, \dots$$

Integer
programming
problem

innum seeking methods are known as Optimization
Techniques. It is a part of Operations Research.

Linear
model

Non-linear
models

Ex If no restrictions, variables are free. ($>0, <0,$)

$$\text{ex: } Z = 2x_1 + 5x_2$$

$$\text{s.t. } x_1 + x_2 \leq 100$$

$$\text{let } x_1 = y_1 - y_2 \quad y_1, y_2 \geq 0$$

$$x_2 = y_3 - y_4 \quad y_3, y_4 \geq 0$$

$$\Rightarrow \text{max: } Z = 2y_1 - 2y_2 + 5y_3 - 5y_4$$

$$\text{s.t. } y_1 - y_2 + y_3 - y_4 \leq 100$$

$$y_1, y_2, y_3, y_4 \geq c$$

size of the matrix has increased -

The variables are restricted, but no. of variables have increased

LPP - I

LPP - II

max: Z (minimization type problem
min: Z can be solved using
minimization type problem

Generally, in LP - we solve max. prob.

NLP - we solve min. prob.

a) Linear Programming Problem (LPP)

b) Integer Programming Problem (IPP)

c) Quadratic Programming Problem (QPP)

eg. max: $f(x) = X^T Q X + c^T x + d$
s.t. $g(x) \leq b$
 $x \geq 0$

d) Geometric Programming Problem (GPP)

(has been developed using the inequality
 $AM \geq GM$)

e) Goal Programming Problem (GPP)

f) Dynamic Programming Problem (DPP)

g) Separable Programming Problem (SPP)

h) Stochastic Programming Problem (SPP)

i) Fuzzy Programming Problem (FPP)

j) Binary Programming Problem (BPP)

variables
(be linear &
non-linear)
they are binary

Interior Point Method (1984) - developed for
(Karmarkar) large size optimization problem.

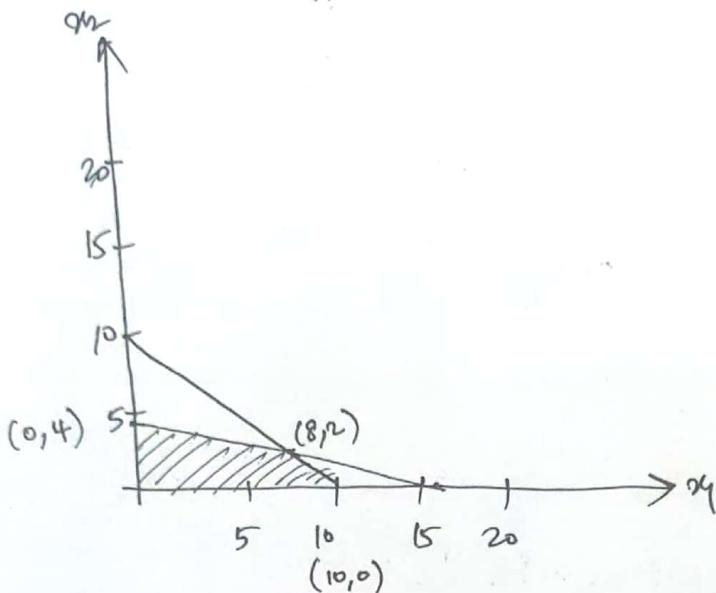
Graphical method for solving LPP:-

$$\text{Max: } Z = 2x_1 + 3x_2$$

$$\text{subject to } x_1 + x_2 \leq 10$$

$$x_1 + 4x_2 \leq 16$$

$$x_1, x_2 \geq 0$$



S.No.	x_1	x_2	Z	
1.	0	0	$Z=0$	min
2.	10	0	$Z=10$	
3.	6	4	$Z=12$	
4.	8	2	$Z=14$	max

$$\text{max. value of } Z^* = 14 \quad x_1^* = 8 \quad x_2^* = 2$$

Only one optimal solution

Primal is feasible, dual is feasible.

min Duality theorem.

$$\min: Z_1 \geq \max: Z$$

S.P.T

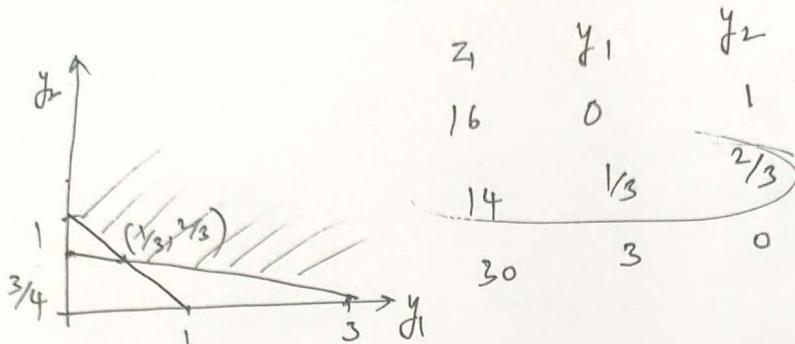
$$\min: Z_1 = \max: Z = 0$$

Dual LPP

$$\min : z_1 = 10y_1 + 15y_2$$

$$\text{s.t. } y_1 + y_2 \geq 1$$

$$y_1 + 4y_2 \geq 3$$



Complementary slackness principle

$$(x_1 + x_2 - 10)y_1 = 0 \quad y_1^* = 1/3 \quad y_2^* = 2/3$$

$$(x_1 + 4x_2 + 6)y_2 = 0 \quad x_1^* = 8 \neq 0$$

$$(y_1 + y_2 - 1)x_1 = 0 \quad x_2^* = 2 \neq 0$$

$$(y_1 + 4y_2 - 3)x_2 = 0$$

Final program (1)

$$\max : z = 2y_1 + 3y_2$$

$$\text{s.t. } 2y_1 + y_2 \leq 100$$

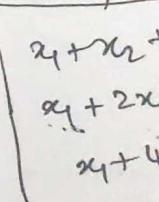
$$y_1 + 2y_2 \leq 110$$

$$y_1 + 4y_2 \leq 160$$

$$y_1, y_2 \geq 0$$

(Fading
in dual
variables)

ext example



3 diff dual variables $y_1, y_2, y_3 \geq 0$
(because 3 constraints)

$$\min z = 100y_1 + 110y_2 + 160y_3$$

$$a) \max: Z = \sum_{j=1}^n c_j x_j$$

$$\text{s.t. } \sum_{j=1}^n a_{ij} x_j \leq b_i \quad i=1, \dots, m$$

$$x_j \geq 0 \quad j=1, \dots, n$$

$$b) \min: Z = \sum_{j=1}^n c_j x_j$$

$$\text{s.t. } \sum_{j=1}^n a_{ij} x_j \leq b_i \quad i=1, \dots, m$$

$$x_j \geq 0 \quad j=1, \dots, n$$

variables are known as control variables

$$n \text{ no. of variables} = (x_1, x_2, \dots, x_n)^T$$

$$m \text{ ---} = x_j \geq 0 \forall j$$

Let x_j be a free variable.

$$\text{let } x_j = x_j' - x_j'' \quad \begin{cases} x_j' \geq 0 \\ x_j'' \geq 0 \end{cases} \quad \begin{array}{l} \text{non-negative} \\ \text{OR} \\ \text{sometimes continuous,} \\ \text{sometimes discrete.} \end{array}$$

$$r(A) = r(A|b) = m < n \quad \text{consistent}$$

If $m = n$ "infinite sol"

If $r(A) = m \quad \begin{cases} \text{inconsistent} \end{cases}$

example

$$r(A|b) = m+1$$

$$\boxed{\begin{aligned} x_1 + x_2 + x_3 &= 10 \\ x_1 + 2x_2 + x_4 &= 11 \\ x_1 + 4x_2 + \dots + x_5 &= 16 \end{aligned}}$$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_5 \end{pmatrix}$$

$$A = (a_{ij})_{3 \times 5}$$

$$b = \begin{pmatrix} 10 \\ 11 \\ 16 \end{pmatrix}$$

No. of basic variables $\Rightarrow r(A) = m = 3$

No. of Non-basic variables $n - m = 5 - 3 = 2$

S.No.	B.V.	N.B.V.	Rem.
1.	$x_3 = 10, x_4 = 11, x_5 = 16$	$x_1 = 0, x_2 = 0$	B.F.S
2.	$x_2 = 4, x_3 = 6, x_4 = 3$	$x_1 = 0, x_5 = 0$	B.F. Solving x_1
3.			
4.			
5.			
6.			
7.			
8.			
9.			
10.			

Single Objective Optimization

Linear Optimization - Many types of programming

Mathematical formulation of a problem.

Optimization is an act of obtaining best results under given restrictions.

Find $X = (x_1, x_2, \dots, x_n)^T \rightarrow$ Decision vector
 \uparrow control variables

so as to

Objective function $\rightarrow \max : Z = c^T x + d, d = 0$

s.t. $AX \leq b \quad \} \text{ set of constraints}$

$X \geq 0 \rightarrow$ Natural restrictions

LINEAR PROGRAMMING PROBLEM

s.t. $y_1 + y_2 + y_3$

$y_1 + 2y_2$

Any one is Pareto Optimal

①

②

③

Normal

$$y_1 + y_2 + y_3 \geq 1$$

$$y_1 + 2y_2 + 4y_3 \geq 3$$

solving x_1, x_2, z

$$x_1^* = 25 \quad x_2^* = 25 \quad z^* = 135$$

One is Primal, Another is Dual

$$\textcircled{1} \quad (x_1 + x_2 - 100)y_1 = 0$$

$$\textcircled{2} \quad (x_1 + 2x_2 - 110)y_2 = 0$$

$$\textcircled{3} \quad (x_1 + 4x_2 - 160)y_3 = 0$$

$$\textcircled{4} \quad (y_1 + y_2 + y_3 - 1)x_1 = 0$$

$$\textcircled{5} \quad (y_1 + 2y_2 + 4y_3 - 3)x_2 = 0$$

$$x_1, x_2 \geq 0$$

$$y_1 + y_2 + y_3 = 1$$

$$y_1 + 2y_2 + 4y_3 = 3$$

Now, substitute values of x_1, x_2 in \textcircled{1}

$$(60 + 25 - 100)y_1 = 0 \Rightarrow y_1 = 0$$

$$y_1 = 0$$

$$y_2 + y_3 = 1$$

$$2y_2 + 4y_3 = 3$$

$y_2 = y_3 = \frac{1}{2}$ is also an optimal solⁿ

max

dual

Primal

$$\text{Max : } Z = 2x_1 + 8x_2$$

$$\text{s.t. } x_1 + x_2 \leq 10$$

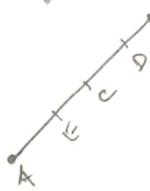
$$x_1 + 4x_2 \leq 16$$

$$x_1, x_2 \geq 0$$

$$y_1 + y_2 \geq 2$$

$$y_1 + 4y_2 \geq 8$$

Line segment



A is 0

B -

There a

Mathematically,

$$L =$$

Some Definitions and Theorem

Point in n -dimensional space: A point $X = (x_1, x_2, \dots, x_n)$

n co-ordinates x_i , $i = 1, 2, 3, \dots, n$. Each of them are

$$X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad X \in \mathbb{R}^n$$

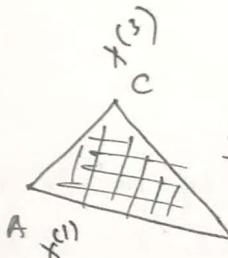
x_1, x_2, \dots, x_n are real numbers

In 2-D

$$\text{If } n=2 \quad X = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\begin{matrix} X^{(1)} \\ \sim \end{matrix} = \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \end{pmatrix} \quad \begin{matrix} X^{(2)} \\ \sim \end{matrix} = \begin{pmatrix} x_1^{(2)} \\ x_2^{(2)} \end{pmatrix}$$

$$\begin{matrix} X^{(k)} \\ \sim \end{matrix} = \begin{pmatrix} x_1^{(k)} \\ x_2^{(k)} \end{pmatrix} \quad X \in \mathbb{R}^2$$



If A is optimal solⁿ
considering the x

S.

This

If $n=3$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \quad X \in \mathbb{R}^3$$

$$\begin{matrix} X^{(1)} \\ \sim \end{matrix} = \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \\ x_3^{(1)} \end{pmatrix} \quad \begin{matrix} X^{(2)} \\ \sim \end{matrix} =$$

etc.

Line segment in n -dimensions:

$$x_A^{(1)} = \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \\ \vdots \\ x_n^{(1)} \end{pmatrix}, \quad x_B^{(1)} = \begin{pmatrix} x_1^{(2)} \\ x_2^{(2)} \\ \vdots \\ x_n^{(2)} \end{pmatrix}$$

A is one of the extreme points

B —————

There are infinite pts. on the line segment.

Mathematically, representing them

$$L = \{x(\lambda) \mid x(\lambda) = \lambda x_A^{(1)} + (1-\lambda)x_B^{(2)}, 0 \leq \lambda \leq 1\}$$

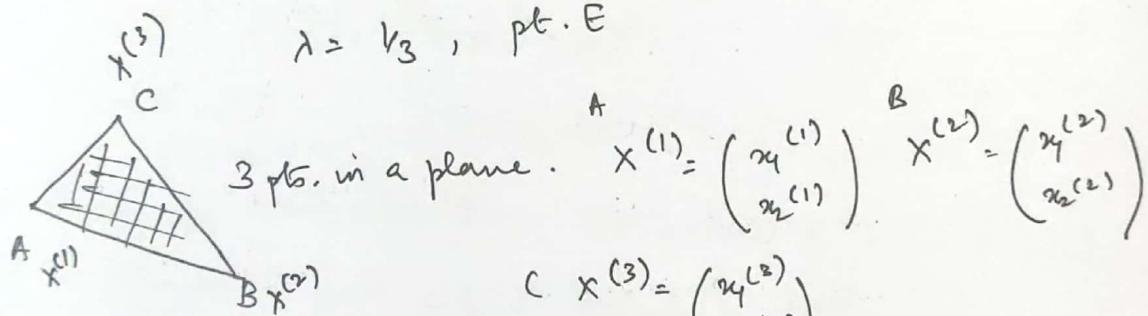
$\lambda = 0$, pt. B

$\lambda = 1$, pt. A

$\lambda = \frac{1}{2}$, mid-pt. (C)

$\lambda = \frac{3}{4}$, pt. D

$\lambda = \frac{1}{3}$, pt. E



A, B, C are 3 extreme points

A is optimal solⁿ, B is optimal solⁿ \Rightarrow AB bar is the solⁿ.

during the region S

$$S = \{x(\lambda_1, \lambda_2, \lambda_3) \mid x(\lambda_1, \lambda_2, \lambda_3) = \lambda_1 x_A^{(1)} + \lambda_2 x_B^{(2)} + \lambda_3 x_C^{(3)}, \lambda_1, \lambda_2, \lambda_3 \geq 0, \lambda_1 + \lambda_2 + \lambda_3 = 1\}$$

This is known as convex Hull.

Hyper-plane

A hyper-plane is defined as:

$$H = \{x \mid c^T x = b\}$$

$$\Rightarrow a_1 x_1 + a_2 x_2 + \dots + a_n x_n = b$$

A hyper-plane has $(n-1)$ -dimensions in n -dimensional space. In 2-dimensional space, a hyper-plane is a line. In 3-dimensional space, it is a plane.

e.g. $x \in \mathbb{R}^3 \quad c \in \mathbb{R}^3$

$$2x_1 + 3x_2 + 4x_3 = 10$$

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \quad c = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} \quad c^T x = 10$$

$$y = ax + b$$
$$ax + b$$

rep. of 1 variable
represented

A hyper-plane divides the n -dimensional space into 2 closed half-spaces.

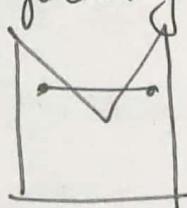
$$i) a_1 x_1 + a_2 x_2 + \dots + a_n x_n \leq b$$

$$ii) a_1 x_1 + a_2 x_2 + \dots + a_n x_n \geq b$$

Convex set: A convex set is a collection of points such that if x_1 and x_2 are any 2 points in the set S , the line segment joining them is also in the set S .



A convex set.



Not convex.
Some part is inside,
some is outside.

$$\text{Let, } x = \lambda x_1 + (1-\lambda) x_2 \quad 0 \leq \lambda \leq 1$$

If $x_1, x_2 \in S$, then $x \in S$.

Polyhedron and Polytope:

re Point : A pt. ~~on~~ in the convex set S which does not lie on a line segment joining 2 other points of set.

de point solution : In a LPP any solution X which satisfy $AX=b$ and $X \geq 0$ is called a feasible solⁿ.

Simplex :

Now: $Z = x_1 + 2x_2 + 3x_3 + 100$ const. doesn't matter.

s.t. $x_1 + x_2 + x_3 \leq 10$

$2x_1 + 2x_2 + x_3 \leq 20$

$x_1, x_2, x_3 \geq 0$

F.S. Method

$x_1 + x_2 + x_3 + x_4 = 10, \quad x_4 \geq 0$

$2x_1 + 2x_2 + x_3 + x_5 = 20, \text{ slack variable}$
 $x_5 \geq 0$

$x_1 + x_2 + x_3 + x_4 + 0x_5 = 10$

$2x_1 + 2x_2 + x_3 + 0x_4 + x_5 = 20$

$x_1, x_2, x_3 \geq 0$

$x_4, x_5 \geq 0$

B.V.

N.B.Y. (zeroes)

Z

x_1, x_2

x_3, x_4, x_5

10

$x_1 + x_2 = 10$
 $2x_1 + 2x_2 = 20$
 $x_1 + x_2 = 10$

} also has
so solⁿ

$x_4 = 10, x_2 = 0$

$x_2 = 10, x_4 = 0$

Degenerate solution

x_2, x_4, x_5

10

2. x_1, x_3
 $x_1 = 10, x_3 = 0$

x_2, x_3, x_5

16

3. x_1, x_4
 $x_1 = 10, x_4 = 0$

4. $x_4 = 10, x_5 = 0$
 5. $x_2 = 10, x_3 = 0$ These are ^{not} degenerate
 6. $x_2 = 10, x_4 = 0$
 7. $x_2 = 10, x_5 = 0$
 8. $x_3 = 0, x_4 = -10$ Not feasible
 9. $x_3 = 10, x_5 = 10$
 10. $x_4 = 10, x_5 = 20$

	20	Initial Simplex
- x_4	20	
1	20	
2	X	$\rightarrow -1$
on		icator
bottom is preferable)		
		x_4

$$\max z = 30 \quad | \quad \begin{array}{ll} x_4^* = 0 & x_4^* = 0 \\ x_2^* = 0 & x_5^* = 10 \\ x_3^* = 10 & \end{array}$$

Now going by simplex method

$$\text{max: } z = x_4 + 2x_2 + 3x_3$$

$$x_4 + x_2 + x_3 \leq 10$$

$$2x_4 + 2x_2 + x_3 \leq 20$$

$$x_4, x_2, x_3 \geq 0$$

$$x_4 + x_2 + x_3 + z_1 = 10, z_1 \geq 0, z_1 = x_4$$

$$2x_4 + 2x_2 + x_3 + z_2 = 20, z_2 \geq 0, z_2 = x_5$$

$$x_4 + 2x_2 + 3x_3 = z$$

$$z_1 = -x_4 - x_2 - x_3 + 10$$

$$z_2 = -2x_4 - 2x_2 - x_3 + 20$$

$$z = x_4 + 2x_2 + 3x_3 + 0$$

BV	$x_4 = 10$	

$$\underline{\text{BV}} \quad x_2 = 10$$

$$z_2 = 10$$

Initial Simplex Tableau:

$-x_1$	$-x_2$	$-x_3$	1	
1	1	1	10	$= z_1$
2	2	1	20	$= z_2$
$\rightarrow -1$	-2	-3	0	$= z$

for

(it is preferable)

Condensed simplex
tableau

B.F.S.

$$\begin{cases} x_1 = 0, x_2 = 0, x_3 = 0 \\ z_1 = 10, z_2 = 20 \end{cases} \quad \left. \begin{array}{l} \\ \end{array} \right\} z = 0$$

We will try to catch the hardcore criminal.

$$\min : \left\{ \frac{10}{1}, \frac{20}{1} \right\}$$

$\uparrow p \quad \downarrow$ only two ratios.



V & BV will be interchanged q/r
 $(z_1 < z_3)$ reciprocal of P

rule divide by this p.

x_1	x_2	$-z_1$		
$y_p = 1$	$y_p = 1$	y_1	10	$= z_3$
1	1	-1	$\frac{10}{20}$	$= z_2$
2	1	3	30	$= z$

we continue this until
all are +ve

$$s^* = \frac{p s - q r}{P} = \frac{20 - 10}{1} = 10$$

$$\frac{1 \times 0 - (-3 \times 10)}{1} = 30$$

BV $x_3 = 10$
 $Z_2 = 10$

NBV $x_1 = 0$, $x_2 = 0$, $Z_1 = 0$

$$\begin{aligned} x_1^* &= 0 \\ x_2^* &= 0 \\ x_3^* &= 10 \\ Z^* &= 30 \end{aligned}$$

$$\text{max} : Z = 3x_1 + 2x_2 + 3x_3$$

$$\text{s.t. } x_1 + x_2 + x_3 \leq 10$$

$$2x_1 + 2x_2 + x_3 \leq 20$$

	$-x_4$	$-x_5$	$-x_3$	1	
①		1	1	10	$= x_4$
	2	2	1	20	$= x_5$
	\checkmark	\checkmark	-2	-3	$= Z$

choose
any 1

$$\min(10/1, 20/2)$$

$$x_1 = 0, x_2 = 0, x_3 = 0, x_4 = 10, x_5 = 20$$

$$Z = 0$$

N.B.V.

	$-x_4$	$-x_5$	$-x_3$	1	
②	1/1	1/1	1/1	10/1	$= x_4$
	0	-1	0	$= x_5$	
	\checkmark	\checkmark	0	30	$= Z$

IR \Rightarrow
 x -ve

This table is optimal

$$x_4 = 0, x_2 = 0, x_3 = 0, x_4 = 10, x_5 = 20$$

B.V.

$$\text{degenerate soln } Z = 30$$

w.r.t. this 0, further iteration possible.

$$\begin{cases} x_1 = 10 \\ x_2 = 0 \\ x_3 = 0 \\ x_4 = 0 \\ x_5 = 0 \end{cases}$$

$$\begin{pmatrix} 0 \\ 1 \\ -1 \\ 10 \\ 1 \end{pmatrix}$$

we will not take it
has to be -ve

$$X^{(1)} = \begin{pmatrix} 10 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -x_4 \\ 1 \\ -1 \\ 3 \end{pmatrix}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix}$$

$$\begin{array}{cccc|c}
x_4 & -x_2 & -x_1 & | & \\
\hline
1 & 1 & 1 & 10 & = x_3 \\
-1 & 1 & +1 & 10 & = x_5 \\
3 & 1 & 0 & 30 & = z
\end{array}$$

$$\left. \begin{array}{l} x_1 = 0 \\ x_2 = 0 \\ x_3 = 10 \\ x_4 = 0 \end{array} \right\} \quad z^* = 30$$

$$x_2 = \begin{pmatrix} 0 \\ 0 \\ 10 \end{pmatrix}$$

$$x_5 = 10$$

2 optimal solⁿ, \therefore infinitely many.

$$x^* = \lambda x^{(1)} + (1-\lambda) x^{(2)}$$

$$= \lambda \begin{pmatrix} 10 \\ 0 \\ 0 \end{pmatrix} + (1-\lambda) \begin{pmatrix} 0 \\ 0 \\ 10 \end{pmatrix} \quad 0 \leq \lambda \leq 1$$

$$\lambda = 1/2 \quad x^* = \begin{pmatrix} 5 \\ 0 \\ 5 \end{pmatrix}$$

problem was Now check if it fulfills constraints.

It does!

$$\lambda = 1/3, \dots$$

Infinite no. of optimal solⁿ.

$$2. \text{ Max: } Z = x_1 + 3x_2$$

$$s.t. \quad x_1 + x_2 \leq 10$$

$$x_1 + 2x_2 \leq 11$$

$$x_1 + 4x_2 \leq 16$$

$$x_1, x_2 \geq 0$$

$$x_1 + x_2 + z_1 = 10$$

$$x_1 + 2x_2 + z_2 = 11$$

$$x_1 + 4x_2 + z_3 = 16$$

$$z_1, z_2, z_3 \geq 0$$

slack variable

$$z_1 = 10 - x_1 - x_2$$

$$z_2 = -x_1 - 2x_2 + 11$$

$$z_3 = -x_1 - 4x_2 + 16$$

Initial simplex tableau

$-x_1$	$-x_2$	$ $	
1	1	$\rightarrow 10$	
1	2	$\rightarrow 11$	
1	4 $\rightarrow p$	$\rightarrow 16$	
IR	-1	-3	0

most -ve

$$\left. \begin{array}{l} z_1 = x_3 \\ z_2 = x_4 \\ z_3 = x_5 \\ = z \end{array} \right\} \min \left(\frac{10}{1}, \frac{11}{2}, \frac{16}{4} \right)$$

implies
find

Type I
question

$-x_1$	$-x_3$	1	
$\frac{3}{4}$	$-\frac{1}{4}$	$\frac{24}{4} = 6$	$= z_1$
$\frac{2}{4}$	$-\frac{2}{4}$	3	$= z_2$
$\frac{1}{4}$	$\frac{1}{4}$ <small>row 1</small>	4	<small>row elements divided by 4</small>
$-\frac{1}{4}$	$\frac{3}{4}$	$\frac{48}{4} = 12$	$= z$

column
elements
divided by
-ve of P.

$z_1 = 6$
 $z_2 = 3$
 $x_2 = 4 \quad \left| \begin{array}{l} x_1 = 0 \\ z_3 = 0 \end{array} \right.$

$$\min \left(\frac{6}{\frac{3}{4}}, \frac{3}{\frac{2}{4}}, \frac{4}{\frac{1}{4}} \right)$$

$$z(8, 6, 16)$$

$-z_2$	$-z_3$	1	
$-\frac{3}{2}$	$\frac{1}{2}$	$\frac{3}{4}$	$= z_1$
2	-1	6	$= z_2$
$-\frac{1}{2}$	$\frac{1}{2}$	$\frac{5}{2}$	$= z_3$
$\frac{1}{2}$	$\frac{1}{2}$	$2\frac{1}{2}$	$= z$

divide by P

$z_1 = \frac{3}{2}$
 $x_1^* = 6$
 $x_2^* = \frac{5}{2}$

$z^* = \frac{27}{2}$

n Method : (Primal Simplex Method)

Find x_1, x_2, \dots, x_n so as to

max : $z = \sum_{j=1}^n c_j x_j + d \rightarrow \text{const.}$ linear objective function.

s.t. $\left\{ \begin{array}{l} \sum_{j=1}^n a_{ij} x_j \leq b_i, \quad i=1, 2, \dots, m \quad b_i \geq 0 \quad \forall i \\ x_1, x_2, \dots, x_n \geq 0 \quad 0 \leq x_j < \infty \end{array} \right.$

Dual simplex Method:

Find x_1, x_2, \dots, x_n so as to

$$\text{min: } Z = \sum_{j=1}^n c_j x_j + d$$

subject to $\sum_{j=1}^n a_{ij} x_j \geq b_i, i=1, 2, \dots, m, b_i \geq 0$
 → Type II equation

$$x_j \geq 0, j=1, 2, \dots, n$$

$$0 \leq x_j < \infty, j=1, 2, \dots, n$$

Step I:

of
N.B.

Introducing slack variables

$$\text{max: } Z = c_1 x_1 + c_2 x_2 + \dots + c_n x_n + d$$

$$s.t. \quad a_{11} x_1 + a_{12} x_2 + \dots + a_{1n} x_n + z_1 = b_1$$

$$a_{21} x_1 + a_{22} x_2 + \dots + a_{2n} x_n + z_2 = b_2$$

..... - - - - -

$$a_{i1} x_1 + a_{i2} x_2 + \dots + a_{in} x_n + z_i = b_i$$

..... - - - - -

$$a_{m1} x_1 + a_{m2} x_2 + \dots + a_{mn} x_n + z_m = b_m$$

$$x_1, x_2, \dots, x_n \geq 0$$

$$z_1, z_2, \dots, z_m \geq 0$$

Step II:

Initial Simplex Tableau:

$-x_1$	$-x_2$...	$-x_n$	$-x_m$	1	
a_{11}	a_{12}		a_{1n}	a_{1m}	b_1	$= z_1$
a_{21}	a_{22}		a_{2n}	a_{2m}	b_2	$= z_2$
.....
a_{m1}	a_{m2}		a_{mn}	a_{mm}	b_m	$= z_m$
d_{m1}	d_{m2}		d_{mn}	d_{mm}	d	$= Z$
$-c_1$	$-c_2$...	$-c_n$	$-c_m$		

$(M+1) \times (n+1)$

; N.B.Y. = n ; No. of B.V. = m

N.B.V. $x_1 = x_2 = x_3 = \dots = x_n = 0$

I: Select the most -ve element in the last row of the simplex tableau.

If no -ve element exists, then the maximum value of LPP is d and a maximizing point is

$x_1 = x_2 = \dots = x_n = 0$. Stop the method.

e.g. min: $Z = 2x_1 + 3x_2 + 4x_3 + 10$

$$\Rightarrow x_1 + x_2 + x_3 \leq 100$$

$$2x_1 + x_2 + 2x_3 \leq 150$$

$$x_1 - x_2 + x_3 \leq 80$$

Max: $x_1, x_2, x_3 \geq 0$

$$-Z = -2x_1 - 3x_2 - 4x_3 - 10$$

$$-c_1 = 2, -c_2 = 3, -c_3 = 4, d = -10$$

All +ve

$$\therefore -Z = -10 \rightarrow Z = 10$$

optimal pt.

* (if all are -ve - unbounded problem) Stop

Step II: Suppose step I gives the element $-a_{rj}$ at the bottom of the r-th column. Form all positive ratios of the element in the last column to corresponding elements in the r-th column. That is form ratios b_i/a_{rj} for which $a_{rj} > 0$. The element say a_{uv} which produces the smallest ratio b_i/a_{uv} is called the pivotal element. *

Step III : Form a new simplex Tableau using

- a) Interchange the role of x_v and z_u . Then let $x_p =$
relabel the row and column of the
element while keeping other labels
unchanged.
- b) Replace the pivotal element ($p > 0$) by its
reciprocal $1/p$ i.e. a_{uv} by $1/a_{uv}$.
- c) Replace the other elements of the row
of the pivotal element (row elements / pivotal
element).
- d) Replace the other elements of the column
of the pivotal element (- column elements)
- e) Replace all other elements (say s) of
the tableau by the elements of the form

$$s^* = \frac{ps - q_s}{p}$$

Step 3 leads to a new Tableau that pres.
an equivalent LPP.

Only for max. LPP where constraints ≤ 0 .

Theorem 1: Intersection of any no. of convex sets is also convex

Theorem 2: The feasible region of a LPP forms a convex set.

$$AX = b, X \geq 0$$

Let $x_1 \in S$

Let $x_2 \in S$

$$AX_1 = b$$

$$AX_2 = b$$

$$x_1 \geq 0$$

$$x_2 \geq 0$$

$$X_\lambda = \lambda X_1 + (1-\lambda) X_2$$

$$0 \leq \lambda \leq 1 \quad \lambda \geq 0$$

$$X_1 \geq 0 \quad 1-\lambda \geq 0$$

$$X_2 \geq 0$$

$$X_\lambda \geq 0$$

$$X_\lambda = \lambda X_1 + (1-\lambda) X_2$$

$$AX_\lambda = A(\lambda X_1 + (1-\lambda) X_2)$$

$$= \lambda AX_1 + (1-\lambda) AX_2$$

$$= \lambda b + (1-\lambda)b = b$$

$$\Rightarrow AX_\lambda = b \quad X_\lambda \geq 0$$

Implies that it fulfills the feasible region.

rem 3: In general a LPP has either one optimal solution or no optimal solution or infinite no. of optimal solⁿ.

Any local min/max solⁿ is a global min/max solⁿ of LPP.

rem 4: every B.F.S. is an extreme point of the convex set of the feasible region.

$$AX = b \quad X \geq 0$$

$$X = \begin{pmatrix} X_B \\ X_N \end{pmatrix}$$

$$BX_B = b$$

$$X_B = B^{-1}b$$

$$|B| \neq 0$$

$$X_B = \begin{pmatrix} \bar{b}_1 \\ \bar{b}_2 \\ \vdots \\ \bar{b}_m \end{pmatrix} \geq 0$$

B.V.

$$X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ \underline{x_m} \\ \hline x_{m+1} \\ x_{m+2} \\ \vdots \\ x_n \end{pmatrix}$$

N.B.

$$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_{m+1} \\ \vdots \\ y_n \end{pmatrix}$$

$$Z = \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_m \\ \vdots \\ z_n \end{pmatrix}$$

$$\text{let } Y \geq 0 \quad Z \geq 0$$

$$\lambda \geq 0 \quad (1-\lambda) \geq 0$$

$$X = \lambda Y + (1-\lambda)Z$$

$$\begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix} = \lambda \begin{pmatrix} y_{m+1} \\ y_{m+2} \\ \vdots \\ y_n \end{pmatrix} + (1-\lambda) \begin{pmatrix} z_{m+1} \\ z_{m+2} \\ \vdots \\ z_{m+n} \end{pmatrix}$$

$$\lambda y_{m+1} + (1-\lambda) z_{m+1} = 0$$

$$\lambda y_{m+2} + (1-\lambda) z_{m+2} = 0$$

$$\begin{aligned} \lambda &\geq 0 \quad y_{m+1} \geq 0 \\ (1-\lambda) &\geq 0 \quad z_{m+1} \geq 0 \\ y_{m+1} &= 0 = z_{m+1} \\ y_{m+2} &= z_{m+2} = 0 \end{aligned}$$

$$\lambda y_n + (1-\lambda) z_n = 0 \quad y_n = z_n = 0$$

so X is an extreme point by contradiction

15: Let S be a close bounded convex polyhedron with p number of extreme points $x_i, i=1, 2, \dots, p$. Then any vector $X \in S$ can be written as :

$$X = \sum_{i=1}^p \lambda_i x_i, \quad \sum_{i=1}^p \lambda_i = 1, \quad \lambda_i \geq 0$$



$$X = \lambda_1 x_1 + \lambda_2 x_2 + \lambda_3 x_3$$

$$\lambda_1, \lambda_2, \lambda_3 \geq 0$$

$$\lambda_1 + \lambda_2 + \lambda_3 = 1$$

16: Let S be a close \neq convex polyhedron. Then the min. of a linear f^n over S is attained at an extreme point of S .

Proof:

$$\begin{aligned} &\text{min: } f = c^T X \\ &\text{s.t. } AX = b \\ &\quad X \geq 0 \end{aligned}$$

$P_2:$ max : $f = c^T X$
 s.t. $AX \geq b$
 $X \geq 0$

We prove by contradiction.

Let x^* be an optimal solution

$$c^T x^* < c^T x_1$$

$$c^T x^* < c^T x_2$$

$$c^T x^* < c^T x_3$$

Min. does not occur at an optimal point.

$$c^T x^* < c^T x_i, \quad i=1, 2, \dots, p$$

$$\text{For } 0 \leq \lambda_i \leq 1, \quad \lambda_i c^T x^* < \lambda_i c^T x_i \quad i=1, 2, \dots, p$$

$$\sum_{i=1}^p \lambda_i c^T x^* < \sum_{i=1}^p \lambda_i c^T x_i, \quad i=1, 2, \dots, p$$

Suppose $\lambda_i = \lambda_i^*, \quad i=p, \quad \& \quad x^* = \sum_{i=1}^p \lambda_i^* x_i \quad \text{so,} \quad \sum_{i=1}^p \lambda_i^* c^T x^* < \sum_{i=1}^p \lambda_i^* c^T x_i$

$$c^T x^* \sum_{i=1}^p \lambda_i < c^T \sum_{i=1}^p \lambda_i^* x_i \rightarrow c^T x^* < c^T x^* \quad (\text{contradiction})$$

x^* has to be an extreme pt.

Eg. 2

$$\text{max: } z = 2x_1 + 3x_2$$

s.t.

$$2x_1 + 3x_2 = 12$$

$$2x_1 + x_2 \geq 8$$

$$x_1, x_2 \geq 0$$

$$x_1 + 2x_2 \leq 20$$

$$x_1 + x_2 = 15$$

$$3x_1 + 2x_2 \geq 30$$

$$x_1, x_2 \geq 0$$

must include
variable
Neither sl
nor surplus
but an
artificial
variable
(FOR SIMPLEX)

$$x_1 + 2x_2 + s_1 = 20, s_1 \geq 0 \quad (\text{slack variable})$$

$$x_1 + x_2 + s_2 = 15, s_2 \geq 0 \quad (\text{If you cannot make } s_2=0, \text{ the problem is infeasible})$$

$$3x_1 + 2x_2 - x_3 + s_3 = 30, s_3 \geq 0 \quad (\text{surplus variable})$$

Artificial variable

min: s_2 to zero

So we have to min: $(s_2 + s_3) \rightarrow \min = 0$

If 0, it is ideal.

Let M be a large +ve real number (Big M)

$$\text{max: } z = 2x_1 + 3x_2 - M(s_2 + s_3)$$

↳ This M is driving out
the artificial variables

$$s_2 = 15 - x_1 - x_2$$

$$s_3 = 30 - 3x_1 - 2x_2 + x_3$$

$$\text{max: } z = 2x_1 + 3x_2 - M(s_2 + s_3)$$

$$= 2x_1 + 3x_2 - M(45 - 4x_1 - 3x_2 + x_3)$$

$$= x_1(2+4M) + x_2(3+3M) - x_3M - 45M$$

Artificial variables - basic variable
Initially, surplus variable cannot be a basic variable.

C_B	B/N	C_N	2	3	0	x_3	X_B
0	α_1	1		2	0		20
-M	α_2	1		1	0		15
-M	α_3	3	2		-1	30	$15/1$
			$-4M$	$-3M$	M		$30/3$
			-2	-3			$-45M$
			Most - ve				

I.R. \Rightarrow

C_B	B/N	C_N	-M	3	0	x_3	X_B
0	α_1		α_2	α_3	x_2	x_3	X_B
-M	α_2				$1/3$	y_3	10
2	α_3				$1/3$	y_3	15
					$2/3$	y_3	10
					$4M+2$	$-M-5$	$-5M+20$
					$\frac{3}{3}$	$\frac{3}{3}$	$\frac{2}{3}$

C_B	B/N	C_N	-M	0	0	x_3	X_B
3	x_2		α_2	α_3	α_1	y_4	$15/2$
-M	α_2				$-1/4$	$1/4$	$5/2$
2	α_3				$1/2$	$-1/2$	5
					$5M+1$	$M+5$	$130-10M$
					$\frac{4}{4}$	$\frac{4}{4}$	$\frac{4}{4}$
						$M-1$	$130-10M$

$$x_1^* = 10, x_2^* = 5, x_3^* = 10$$

$$\delta_1 = \delta_2 = \delta_3 = 0$$

In a program, we have to pass on a value of M. To do that, we go by 2-phase simplex method.

Two-Phase Simplex Method

$$\text{max: } f = 2x_1 + 3x_2 - 0.F.$$

$$s.t. \quad x_1 + 2x_2 \leq 20$$

$$x_1 + x_2 = 15$$

$$3x_1 + 2x_2 \geq 30$$

$$x_1, x_2 \geq 0$$

Phase-I Method

$$x_1 + 2x_2 + \delta_1 = 20$$

$$x_1 + x_2 + \alpha_1 = 15$$

$$3x_1 + 2x_2 - x_3 + \alpha_2 = 30$$

 $\delta_1, \alpha_1, \alpha_2, x_3 \geq 0$

$$\text{Artificial O.F.} \quad \text{min: } A = \alpha_1 + \alpha_2$$

$$\rightarrow \text{max: } -A = -\alpha_1 - \alpha_2$$

C_N	0	0	0	X_B	
C_B	$B \setminus N$	x_1	x_2	x_3	
0	δ_1	1	2	0	20
-1	a_1	1	1	0	15
-1	a_2	(3)	2	-1	30
		-4	-3	1	-45

$-a_1 - a_2 + \alpha_1 + \alpha_2$

+ α_3

20

15

10

After iterations,
phase I will terminate.
If $-a_1 - a_2 = 0$ the feasible,
if not infeasible.

C_N	-1	0	0	X_B	
C_B	$B \setminus N$	a_2	x_2	x_3	
0	δ_1	$-1/3$	$4/3$	$1/3$	10
-1	a_1	$-1/3$	$1/3$	$1/3$	5
0	x_4	$1/3$	$2/3$	$-1/3$	10
		$4/3$	$-1/3$	$-1/3$	-5

As soon as
you have
removed
 a_1, a_2
or this 0.
we move to
phase II.

C_N	-1	0	0	X_B	
C_B	$B \setminus N$	a_2	δ_1	x_3	
0	x_2	$-1/4$	$3/4$	$1/4$	$15/2$
-1	a_1	$-1/4$	$-1/4$	$1/4$	$5/2$
0	x_4	$1/2$	$-1/2$	$-1/2$	5
		$5/4$	$1/4$	$-1/4$	$-5/2$
		-1	0	-1	

we drop these A.N. columns
we have removed
the artificial
variables.

C_N	$B \setminus N$	a_2	δ_1	a_1	X_B	
C_B	$B \setminus N$	x_2	0	1	x_1	
0	x_3	-1	0	-1	4	10
0	x_4	0	0	-1	2	10
0		*		0	X1	0

$Z = 2x_1 + 3x_2$

In the previous table Phase II Table

C_B	$B \setminus$	0		x_B
		δ_1	1st	
3	x_2	1		5
0	x_3	-1		10
2	x_1	-1		10
		(1)		35

since it is +ve,
it is optimum.

$$x_1^* = 10$$

$$x_2^* = 5 \quad f^* = 35$$

Complete

Duality theory for LPP

Primal Program (P):

$$\text{Max : } Z = \sum_{i=1}^m c_i x_i$$

w.r.t. the above primal problem (P) we find dual problem (D) as D:

$$\text{min : } Z' = \sum_{i=1}^m b_i y_i$$

s.t.

$$\sum_{j=1}^n a_{ij} y_j \geq c_i, \quad i = 1, 2, 3, \dots, m$$

$$y_i \geq 0, \quad i = 1, 2, 3, \dots, m$$

with respect

example :

max:

5,

If you

per

per

respect to above primal problem (P)

ple:

$$\text{Max: } Z = 2x_1 + 3x_2 + x_3$$

$$\text{s.t. } x_1 + x_2 + x_3 \leq 5$$

$$4x_1 + 6x_2 + 2x_3 \leq 15$$

$$x_1, x_2, x_3 \geq 0$$

Primal LPP

check if $x_1=0, x_2=5/4, x_3=15/4$ is an

$$\text{optimal soln} \quad Z = \frac{15}{4} + \frac{15}{4} = 7.5$$

dual LPP

$$\text{min } Z = 5y_1 + 15y_2$$

$$\text{s.t. } y_1 + 4y_2 \geq 2$$

$$y_1 + 6y_2 \geq 3$$

$$y_1 + 2y_2 \geq 1 \quad y_1, y_2 \geq 0$$

Complementary slackness principle

w.r.t. x_1, x_2, x_3 , we find the value of

$$y_1 \& y_2$$

If primal is feasible, dual is also feasible.

Primal has optimal, dual also does

solve this by graphical

$$y_1^* = 0, y_2^* = 1/2 \quad \text{get value of } Z \\ Z^* = 15/2$$

Purpose of this duality problem - check for the optimal soln (will be used in transportation problem)

$$\underline{\text{LPP:}} \quad \text{max: } Z = \sum_{j=1}^n g_j y_j$$

$$\text{Primal LPP s.t. } \sum_{j=1}^n a_{ij} y_j \leq b_i, \quad i=1, 2, \dots, n$$

$$y_j \geq 0, \quad j=1, 2, \dots, n$$

$$\min: -Z = -\sum_{j=1}^n g_j y_j$$

$$\sum_{j=1}^n a_{ij} y_j + s_i^2 - b_i = 0 \quad i=1, 2, \dots, m$$

$$s_i^2 \geq 0 \quad i=1, 2, \dots, m$$

$$-y_j \leq 0 \Rightarrow -y_j + t_j^2 = 0, \quad j=1, 2, \dots, n$$

$$t_j^2 \geq 0, \quad j=1, 2, \dots, n, \quad \mu_1, \mu_2, \dots, \mu_n$$

Constraints \leq
so $\lambda_1, \lambda_2, \dots, \lambda_m \geq 0$
if constraint =
 λ_s will be

$$\min: L(\lambda, \mu, \lambda, \mu, \tau)$$

$$= -\sum_{j=1}^n g_j y_j + \sum_{i=1}^m \lambda_i (\sum_{j=1}^n a_{ij} y_j + s_i^2 - b_i) + \sum_{j=1}^n \mu_j (-y_j + t_j^2)$$

$$\frac{\partial L}{\partial y_j} = 0, \quad j=1, 2, \dots, n$$

$$\frac{\partial L}{\partial \lambda_i} = 0, \quad i=1, 2, \dots, m$$

$$\frac{\partial L}{\partial \mu_j} = 0 \quad j=1, 2, \dots, n$$

$$\frac{\partial L}{\partial t_j} = 0 \quad j=1, 2, \dots, n$$

$$\frac{\partial L}{\partial \kappa_j} = 0 \quad j=1, 2, \dots, n$$

$$\frac{\partial L}{\partial x_{ij}} = 0, \quad -g + \sum_{i=1}^m \lambda_i a_{ij} - \mu_j = 0 \quad \forall j \quad \mu_j \geq 0 \quad \forall j$$

$$\Rightarrow -g + \sum_{i=1}^m \lambda_i a_{ij} \geq 0$$

$$\textcircled{1} \quad \boxed{\sum_{i=1}^m \lambda_i a_{ij} \geq g \quad j=1, 2, \dots, n}$$

$$\Rightarrow \sum_{i=1}^m a_{ij} y_i \geq g \quad (j=1, 2, \dots, n)$$

$$\frac{\partial L}{\partial \lambda_i} = 0 \Rightarrow 2s_i \lambda_i = 0 \quad \forall i \Rightarrow 2s_i^2 \lambda_i = 0$$

$$s_i^2 = b_i - \sum_{j=1}^n a_{ij} x_j$$

$$\textcircled{2} \quad \boxed{2(b_i - \sum_{j=1}^n a_{ij} x_j) y_i = 0 \quad \forall i}$$

$$\frac{\partial L}{\partial \lambda_i} = 0 \Rightarrow \sum_{j=1}^n a_{ij} x_j + s_i^2 - b_i = 0$$

$$\Rightarrow \boxed{\sum_{j=1}^n a_{ij} x_j \leq b_i, \quad i=1, 2, \dots, m}$$

$$\frac{\partial L}{\partial \mu_j} = 0 \Rightarrow -x_j + k_j^2 = 0 \Rightarrow x_j \geq 0 \quad \forall j$$

$$\boxed{k_j^2 = x_j \quad \forall j}$$

$$\frac{\partial L}{\partial t_j} = 0 \Rightarrow 2t_j \mu_j = 0$$

$$\Rightarrow 2k_j^2 \mu_j = 0 \Rightarrow \boxed{2x_j \mu_j = 0}$$

$$\sum_{i=1}^m a_{ij} \lambda_i \geq g \quad \forall j \Rightarrow g \leq \sum_{i=1}^m a_{ij} \lambda_i \quad j=1, 2, \dots, n$$

$$g x_j \leq x_j (\sum_{i=1}^m a_{ij} \lambda_i)$$

$$\sum_{j=1}^n g_j y_j \leq \sum_{j=1}^n y_j \left(\sum_{i=1}^m a_{ij} \lambda_i \right)$$

$$z = \sum_{j=1}^n g_j y_j$$

$$\sum_{j=1}^n g_j y_j \leq \sum_{i=1}^m \lambda_i \left(\sum_{j=1}^n a_{ij} y_j \right) \quad j = 1, 2, \dots, n$$

$$z \leq \sum_{i=1}^m \lambda_i b_i$$

$$\text{max : } z \leq \min \sum_{i=1}^m \lambda_i b_i = z' \quad (\text{Weak duality})$$

$$\text{max : } z = \min z' \quad (\text{Strong duality})$$

Dual LPP

$$\min z' = \sum_{i=1}^m \lambda_i b_i \quad \lambda_i = y_i \\ i = 1, 2, \dots, m$$

$$\text{s.t. } \sum_{i=1}^m a_{ij} \lambda_i \geq g_j \quad j = 1, 2, \dots, n$$

$$\lambda_1, \lambda_2, \dots, \lambda_m \geq 0$$

$$\left(\sum_{j=1}^n a_{ij} y_j - b_i \right) y_i = 0 \quad i = 1, 2, \dots, m$$

$$\left(\sum_{i=1}^m a_{ij} y_i - g_j \right) y_j = 0, \quad j = 1, 2, \dots, n$$

max value of primal is the min. of the dual
dual of the dual is the primal problem

$\frac{d}{dt} \cdot \frac{dy_1}{dx} = 0$

$\frac{d}{dt} \cdot \frac{dy_2}{dx} = 0$

$\frac{d}{dt} \cdot \frac{dy_3}{dx} = 0$

$\frac{dy_1}{dx}$

$\frac{dy_2}{dx}$

$\frac{dy_3}{dx}$

$\frac{d^2y_1}{dx^2} = 0$

$\frac{d^2y_2}{dx^2} = 0$ or $\frac{d^2y_2}{dx^2} = 1$ $\frac{d^2y_2}{dx^2} = -1$

$\frac{d^2y_3}{dx^2} = 0$ or $\frac{d^2y_3}{dx^2} = 1$ $\frac{d^2y_3}{dx^2} = -1$

$\frac{d^3y_1}{dx^3} = 0$

the other are implied w/

max LPP

$$\text{max: } z = c^T x$$

$$\text{s.t. } Ax \leq b$$

$$x \geq 0$$

$$\text{max: } z = \sum_{j=1}^n c_j x_j$$

$$\text{s.t. } \sum_{j=1}^n a_{ij} x_j \leq b_i \quad i=1, 2, \dots, n$$

$$x_1, x_2, \dots, x_n \geq 0$$

Dual LPP

$$\text{min: } z' = b^T y$$

$$\text{s.t. } A^T y \geq c$$

$$y \geq 0$$

$$\text{min: } z' = \sum_{i=1}^m b_i y_i$$

$$\text{s.t. } \sum_{i=1}^m a_{ij} y_i \geq g \quad i=1, 2, \dots, n$$

$$y_1, y_2, \dots, y_m \geq 0$$

$$\text{min: } z' \geq \text{max: } z$$

(weak duality thm.)

$$\text{min: } z' = \text{max: } z$$

(strong duality thm.)

Check if $\bar{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 60 \\ 25 \end{pmatrix}$ is an optimal solⁿ of the LPP.

$$\text{max } z = \text{min: } z'$$

$$(x_1 + x_2 - 100) y_1 = 0 \rightarrow y_1 = 0$$

$$\text{min } z' = 100y_1 + 110y_2 + 160y_3$$

$$(x_1 + 2x_2 - 110) y_2 = 0 \quad y_2 = 0$$

$$\text{s.t. } y_1 + y_2 + y_3 \geq 1$$

$$(x_1 + 4x_2 - 160) y_3 = 0 \quad y_3 = 0$$

$$y_1 + 2y_2 + 4y_3 \geq 3$$

$$(y_1 + y_2 + y_3 - 1) x_1 = 0$$

$$y_1 + y_2 + y_3 \geq 6$$

$$(y_1 + 2y_2 + 4y_3 - 3) x_2 = 0$$

$$\begin{array}{l}
 y_1 + y_2 + y_3 = 1 \\
 y_1 + 2y_2 + 4y_3 = 3
 \end{array}
 \quad
 \begin{array}{l}
 y_2 + y_3 = 1 \rightarrow y_1 = 0 \\
 2y_2 + 4y_3 = 3 \quad y_2 = \frac{1}{2} \\
 y_3 = \frac{1}{2}
 \end{array}$$

$$z' = (110 + 160) \frac{1}{2} = 135$$

Example 2 Now changing the example

y_2 & y_3 will be free (equality conditions)

Example 3 : Primal problem (P)

$$\text{min} : z = y_1 + 3y_2$$

$$\text{s.t. } y_1 + y_2 \geq 100$$

$$y_1 + 2y_2 \geq 110$$

$$y_1 + 4y_2 \geq 160$$

$$y_1, y_2 \geq 0$$

Dual problem (D)

$$\text{max} : z' = 100y_1 + 110y_2 + 160y_3$$

$$\text{s.t. } y_1 + y_2 + y_3 \leq 1$$

$$y_1 + 2y_2 + 4y_3 \leq 3$$

for this problem,

let's say I'm checking
60 & 25

$$60 + 25 \not\geq 100$$

Not fulfilled

$$\text{min} : z = \text{max} : z' \\ (140)$$

$$(x_1 + x_2 - 100)y_1 = 0$$

$$(x_1 + 2x_2 - 110)y_2 = 0$$

$$(x_1 + 4x_2 - 160)y_3 = 0$$

$$(y_1 + y_2 + y_3 - 1)x_1 = 0$$

$$(y_1 + 2y_2 + 4y_3 - 3)x_2 = 0$$

$$z' = 100 \times \frac{1}{3} + 160 \times \frac{2}{3} = \frac{420}{3} = 140$$

so it is an optimal soln

$$\begin{array}{l} \rightarrow \\ 3 \\ \downarrow \\ y_1 = 0 \\ y_2 = 1/2 \\ y_3 = 1/2 \end{array}$$

$$\text{max: } z = a_1 x_1 + a_2 x_2 + a_3 x_3$$

$$a_{11} x_1 + a_{12} x_2 + a_{13} x_3 \leq b_1$$

$$a_{21} x_1 + a_{22} x_2 + a_{23} x_3 = b_2$$

$$-(a_{31} x_1 + a_{32} x_2 + a_{33} x_3 \geq b_3)$$

$x_1, x_2, x_3 \geq 0$ if at all

changing the inequation

Type I inequation

so
res
tric
ted

x_1, x_2, x_3 are free

Dual:

$$\text{min: } z' = b_1 y_1 + b_2 y_2 - b_3 y_3$$

$$a_{11} y_1 + a_{21} y_2 - a_{31} y_3 \geq q \quad \begin{array}{l} \text{All will} \\ \text{be changed} \end{array} \quad y_1 \geq 0, \quad y_3 \geq 0$$

$$a_{12} y_1 + a_{22} y_2 - a_{32} y_3 \geq c_2 \quad \begin{array}{l} \text{to} \\ \text{equality} \end{array} \quad y_2 \text{ is free}$$

$$a_{13} y_1 + a_{23} y_2 - a_{33} y_3 \geq c_3$$

$x_1 \geq 0, x_3 \geq 0$

problem,
I'm checking

0.2.25

+25 × 100

bt fulfilled

min: $z = \max: z'$
(40)

$$\text{max: } z = a_1 x_1 + a_2 x_2 + a_3 x_3$$

$$a_{11} x_1 + a_{12} x_2 + a_{13} x_3 = b_1$$

$$a_{11} x_1 + a_{12} x_2 + a_{13} x_3 \leq b_1$$

$$a_{21} x_1 + a_{22} x_2 + a_{23} x_3 = b_2$$

$$-a_{11} x_1 - a_{12} x_2 - a_{13} x_3 \leq -b_1$$

$$a_{31} x_1 + a_{32} x_2 + a_{33} x_3 = b_3$$

$$a_{21} x_1 + a_{22} x_2 + a_{23} x_3 \leq b_2$$

$$-a_{31} x_1 - a_{32} x_2 - a_{33} x_3 \leq -b_3$$

$x_1, x_2, x_3 \geq 0$

(Now they are no more free)

$t_1, t_2, t_3, t_4 \geq 0$

Dual

$$\text{min: } z' = b_1 (t_1 - t_2) + b_2 (t_3 - t_4)$$

let
 $y_1 = t_1 - t_2$

$$\text{s.t. } a_{11} (t_1 - t_2) + a_{21} (t_3 - t_4) \geq q$$

$y_2 = t_3 - t_4$

$$a_{12} (t_1 - t_2) + a_{22} (t_3 - t_4) \geq c_2$$

y_1, y_2 are
free

$$a_{13} (t_1 - t_2) + a_{23} (t_3 - t_4) \geq c_3$$

$y_1 = 1/2$

$y_3 = 2/3$

$\frac{20}{3} = 140$

1. 1st

Dual

$$\text{min: } z' = b_1 y_1 + b_2 y_2$$

$$\text{s.t. } a_{11} y_1 + a_{21} y_2 \geq c_1$$

$$a_{12} y_1 + a_{22} y_2 \geq c_2$$

$$a_{13} y_1 + a_{23} y_2 \geq c_3$$

y_1, y_2 are free.

$$\text{min: } z = x_1 + 3x_2$$

$$\text{s.t. } x_1 + x_2 \geq 10$$

$$x_1 + 2x_2 \geq 11$$

$$x_1 + 4x_2 \geq 16$$

$$x_1, x_2 \geq 0$$

If there is type I inequation, we can introduce slack variable.

$$\text{max: } -z = -x_1 - 3x_2$$

$$-x_1 - x_2 \leq -10$$

$$-x_1 - 2x_2 \leq -11$$

$$-x_1 - 4x_2 \leq -16$$

$$x_1, x_2 \geq 0$$

$$-x_1 - x_2 + x_3 = -10$$

$$-x_1 - 2x_2 + x_4 = -11$$

$$-x_1 - 4x_2 + x_5 = -16$$

If x_1 & x_2 are

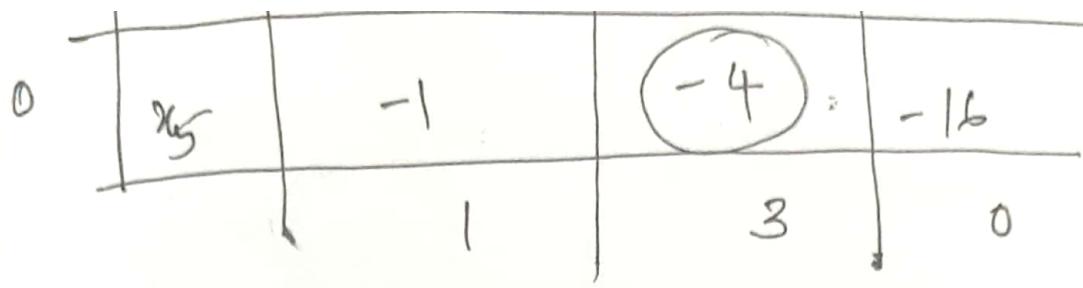
NBV

$$x_3 = -10 \quad \text{Infeasible}$$

$$x_4 = -11$$

$$x_5 = -16$$

An indication that problem may be unfeasible



$$\min\left(\left|\frac{3}{4}\right|, \left|-\frac{1}{4}\right|\right)$$

we apply dual simplex. In primal simplex, -ve in the last row
we take +ve ratios

In dual simplex, we take -ve ratios

	x_5	x_B	
0	$\frac{-1}{4}$	-6	-ve, so not optimal
0	$\frac{-2}{4}$	-3	basic variables
-3	$\frac{1}{4}$	4	have to be +ve
	$\frac{3}{4}$	-12	

	x_3	x_5	x_B	
-1	$\frac{-4}{3}$	$\frac{1}{3}$	8	$\binom{8}{2}$
0	$\frac{-2}{3}$	$\frac{-1}{3}$	1	No Big M
-3	$\frac{1}{3}$	$\frac{1}{3}$	2	No artificial variables.
	$\frac{2}{3}$	$\frac{2}{3}$	-14	We have used dual simplex method.

Primal simplex Method

$$IR \rightarrow z_j - g_j < 0$$

$$x_B \geq 0$$

$$\text{pivot element } (p) > 0$$

Dual simplex Method

$$I.R \rightarrow z_j - g_j > 0$$

$$x_B \leq 0$$

pivot element

$$(p) < 0$$

Primal simplex Tableau

$$\text{max: } Z = 2x_1 + 3x_2$$

$$\text{s.t. } x_1 + x_2 + x_3 = 10$$

$$x_1 + 2x_2 + x_4 = 11$$

$$x_1 + 4x_2 + x_5 = 16$$

$$x_1, x_2 \geq 0$$

C_B	C_N	x_1	x_2	x_3	x_4	x_5	X_B
0	x_3	1	1				10
0	x_4	1	2				11
0	x_5	1	4				16
		-1	-3				0

In type 2, we must use artificial variables.

$$\text{min: } Z = 2x_1 + 3x_2 + 4x_3$$

$$\text{s.t. } x_1 + x_2 + x_3 \geq 100$$

$$2x_1 + x_2 + 3x_3 \geq 200$$

$$x_1, x_2, x_3 \geq 0$$

To avoid use of artificial variables, it can be changed to

$$\text{max: } -Z = -2x_1 - 3x_2 - 4x_3$$

Dual simplex

$$-x_1 - x_2 - x_3 + x_4 = -100$$

$$-2x_1 - x_2 - 3x_3 + x_5 = -200$$

$$x_1, x_2, x_3, x_4, x_5 \geq 0$$

CN	-2	-3	-4	
x_4	x_1	x_2	x_3	X_B
x_4	-1	-1	-1	-100
x_5	$\boxed{-2}$	-1	-3	-200 ✓
	2, +3	4	0	→ No -ve element here.

$\min\left(\left|\frac{4}{-3}\right|, \left|\frac{3}{-1}\right|, \left|\frac{2}{-2}\right|\right)$
 $= (4/3, 3, 1)$

Product from Form Inverse of a Matrix:

$$B = I_m = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & & \\ 0 & 0 & & \\ \vdots & \vdots & & \\ 0 & 0 & & 1 \end{bmatrix} \quad B^{-1} = B$$

Let $A = \begin{bmatrix} 5 & 1 \\ 9 & 2 \end{bmatrix} \quad A^{-1} = ?$

$$B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = B^{-1}$$

column changed

$$B_1 = \begin{bmatrix} 5 & 0 \\ 9 & 1 \end{bmatrix} \quad \text{let } B_1^{-1} = E_1 B^{-1} = E_1$$

Interested to know how
 E_1 & E_2 looks like.

entering variable
 basic variable
 outgoing variable
 non-basic variable.

$$B_2 = \begin{bmatrix} 5 & 1 \\ 9 & 2 \end{bmatrix} \quad B_2^{-1} = E_2 B_1^{-1} = E_2 E_1$$

$$B_2 = A \Rightarrow A^{-1} = E_2 E_1$$

$$e_1 = B^{-1}G = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 5 \\ 9 \end{pmatrix} = \begin{pmatrix} 5 \\ 9 \end{pmatrix}$$

$$y_1 = \begin{pmatrix} 1/5 & \\ -9/5 & \end{pmatrix} \begin{matrix} \text{behaving} \\ \text{like a} \\ \text{pivot} \end{matrix}$$

$$\text{let } E_1 = \begin{bmatrix} 1/5 & 0 \\ -9/5 & 1 \end{bmatrix} = B_1^{-1}$$

$$e_2 = B_1^{-1} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 1/5 & 0 \\ -9/5 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1/5 \\ 1/5 \end{pmatrix}$$

$$y_2 = \begin{pmatrix} -1 \\ 5 \end{pmatrix}$$

$$E_2 = \begin{bmatrix} 1 & -1 \\ 0 & 5 \end{bmatrix}$$

$$A^{-1} = B_2^{-1} = E_2 E_1 = \begin{bmatrix} 1 & -1 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} 1/5 & 0 \\ -9/5 & 1 \end{bmatrix}$$

↓
represent as product
form of 2 matrix.

$$= \begin{bmatrix} 2 & -1 \\ -9 & 5 \end{bmatrix}$$

N.B.V

$$B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3 = B^{-1}$$

We can change any 1 column.

If this becomes B.V, it enters into either of the 3 columns.

$$B_1 = \begin{pmatrix} a_1 & 0 & 0 \\ a_2 & 1 & 0 \\ a_3 & 0 & 1 \end{pmatrix} \quad B_1^{-1} = ?$$

Generally,
pivot element
 $a_1, a_2, a_3 \neq 0$ is non zero.

$$\text{or } B_1 = \begin{pmatrix} 1 & a_1 & 0 \\ 0 & a_2 & 0 \\ 0 & a_3 & 1 \end{pmatrix} \quad B_1^{-1} = \begin{pmatrix} 1 & 0 & a_1 \\ 0 & 1 & a_2 \\ 0 & b & a_3 \end{pmatrix}$$

$$\begin{bmatrix} 1/a_1 & 0 & 0 \\ -a_2/a_1 & 1 & 0 \\ -a_3/a_1 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & -a_1/a_2 & 0 \\ 0 & 1 & 0 \\ 0 & -a_3/a_2 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 & -a_1/a_3 \\ 0 & 1 & -a_2/a_3 \\ 0 & 0 & 1/a_3 \end{bmatrix}$$

Let B is the original Basis Matrix ($B = B^{-1}$)

B_{new} be the new basis matrix which is identical

to B except column r .

Let C is the r th column vector of B_{new}

Let $e = B^{-1}C$ where $e_i = -\frac{e_i}{e_r}, i \neq r$

$$\text{Let } \eta = \begin{pmatrix} \eta_1 \\ \eta_2 \\ \vdots \\ \eta_m \end{pmatrix} \quad \eta_r = e_r, \quad i = r$$

$$\eta = \begin{pmatrix} -e_1/e_r \\ -e_2/e_r \\ \vdots \\ \eta_r \\ -e_{r+1}/e_r \\ \vdots \\ -e_m/e_r \end{pmatrix}$$

$$B_{\text{new}}^{-1} = E_r B^{-1}$$

$$= \begin{pmatrix} 1 & 0 & -e_1/e_r & 0 & \dots \\ 0 & 1 & -e_2/e_r & 0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \eta_r & 0 & \dots \\ & & \vdots & \vdots & \vdots \\ & & -e_{r+1}/e_r & \dots & \vdots \end{pmatrix} B^{-1}$$

where E_r is an identity matrix except its r th column.
 r th column is replaced by the η .

$$A = \begin{pmatrix} 2 & 1 & 2 \\ 2 & 3 & 1 \\ 1 & 1 & 1 \end{pmatrix} \quad B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = B^{-1}$$

If writing a code, we consider 1, 2, 3
 3, 2, 1 ...

$$B_1 = \begin{pmatrix} 2 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

↗ identity matrix

$$B_1^{-1} = E_1 \quad B^{-1} = E_1$$

$$B_2 = \begin{pmatrix} 2 & 1 & 0 \\ 2 & 3 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

$$B_2^{-1} = E_2 B_1^{-1} = E_2 E_1$$

$$B_3 = \begin{pmatrix} 2 & 1 & 2 \\ 2 & 3 & 1 \\ 1 & 1 & 1 \end{pmatrix} \quad A^{-1} = B_3^{-1} = E_3 B_2^{-1} = E_3 E_2 E_1$$

$$A^{-1} = B_{m,m}^{-1} \cdot E_m E_{m-1} \dots E_1$$

$$e_1 = B^{-1} g = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

$$M = \begin{pmatrix} 1/2 \\ -1 \\ -1/2 \end{pmatrix}$$

$$E_1 = \begin{bmatrix} 1/2 & 0 & 0 \\ -1 & 1 & 0 \\ -1/2 & 0 & 1 \end{bmatrix}$$

$$e_2 = B_1^{-1} \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1/2 & 0 & 0 \\ -1 & 1 & 0 \\ -1/2 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1/2 \\ 2 \\ 1/2 \end{pmatrix}$$

$$\gamma_2 = \begin{pmatrix} -1/4 \\ 1/2 \\ -1/4 \end{pmatrix}$$

$$E_2 = \begin{bmatrix} 1 & -1/4 & 0 \\ 0 & 1/2 & 0 \\ 0 & -1/4 & 1 \end{bmatrix}$$

$$B_2^{-1} = E_2 B_1^{-1} = E_2 E_1$$

$$= \begin{pmatrix} 1 & -1/4 & 0 \\ 0 & 1/2 & 0 \\ 0 & -1/4 & 1 \end{pmatrix} \begin{pmatrix} 1/2 & 0 & 0 \\ -1 & 1 & 0 \\ -1/2 & 0 & 1 \end{pmatrix}$$

$$B_3^{-1} = E_3 B_2^{-1} = E_3 E_2 E_1$$

We are not going to find inverse using this method. However we will be using it in Revised simplex method.

Type I inequalities. Plain simplex can be used.

$$\text{max: } Z = x_1 + 3x_2$$

$$\begin{array}{ll} \text{s.t. } x_1 + x_2 \leq 10 & x_1 + x_2 + x_3 = 10 \\ x_1 + 2x_2 \leq 11 & x_1 + 2x_2 + x_4 = 11 \\ x_1 + 4x_2 \leq 16 & x_1 + 4x_2 + x_5 = 16 \\ x_1, x_2 \geq 0 & x_3, x_4, x_5 \geq 0 \end{array}$$

	C_N	1	3	0	0	0	X_B
C_B	BV	x_1	x_2	x_3	x_4	x_5	
0	x_3	1	1	1	0	0	10
0	x_4	1	2	0	1	0	11
0	$\sqrt{x_5}$	1	4	0	0	1	16
		-1	-3				

$$B_{\text{new}} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 4 \end{pmatrix}$$

$$E_1 B^{-1} = E_1 = \begin{pmatrix} 1 & 0 & -1/4 \\ 0 & 1 & -2/4 \\ 0 & 0 & 1/4 \end{pmatrix}$$